

Upper tail scaling limit of continuum path measures in KPZ

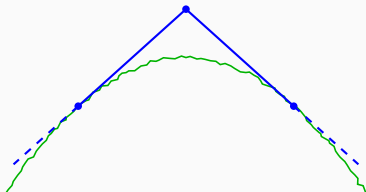
Milind Hegde

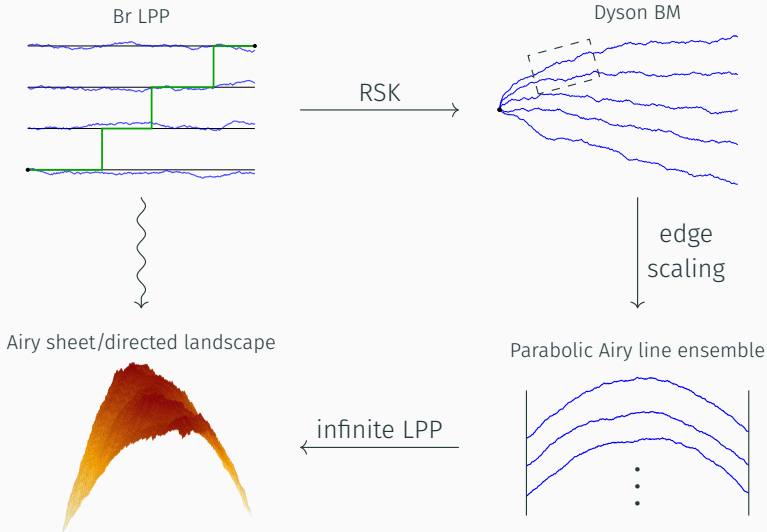
(based on joint works with Shirshendu Ganguly and Lingfu Zhang)

Columbia University

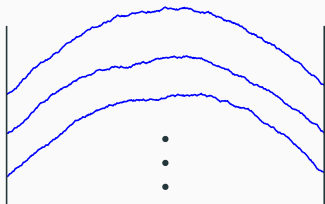
KPZ Meets KPZ Workshop, Fields Institute

March 6, 2024





How are the geometry of the landscape and Airy line ensemble related?

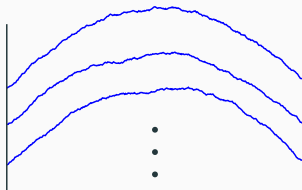


We will focus on the geometry of both when we condition the top curve \mathcal{P}_1 to be **large** at various points.

The Brownian Gibbs property

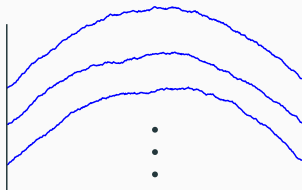
The resampling property

Why embed $\mathcal{P}_1(\cdot) = \mathcal{L}(0, 0; \cdot, 1)$ as the top/lowest-indexed curve in \mathcal{P} ?



The resampling property

Why embed $\mathcal{P}_1(\cdot) = \mathcal{L}(0, 0; \cdot, 1)$ as the top/lowest-indexed curve in \mathcal{P} ?

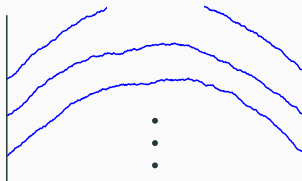


\mathcal{P} has a resampling property, the [Brownian Gibbs](#) property.

It says the conditional distribution of \mathcal{P}_1 on an interval is a [non-intersecting Brownian bridge](#) (of rate 2).

The resampling property

Why embed $\mathcal{P}_1(\cdot) = \mathcal{L}(0, 0; \cdot, 1)$ as the top/lowest-indexed curve in \mathcal{P} ?

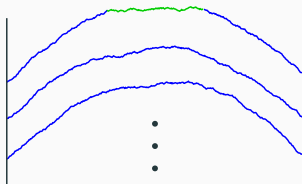


\mathcal{P} has a resampling property, the **Brownian Gibbs** property.

It says the conditional distribution of \mathcal{P}_1 on an interval is a **non-intersecting Brownian bridge** (of rate 2).

The resampling property

Why embed $\mathcal{P}_1(\cdot) = \mathcal{L}(0, 0; \cdot, 1)$ as the top/lowest-indexed curve in \mathcal{P} ?

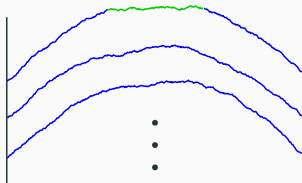


\mathcal{P} has a resampling property, the **Brownian Gibbs** property.

It says the conditional distribution of \mathcal{P}_1 on an interval is a **non-intersecting Brownian bridge** (of rate 2).

The resampling property

Why embed $\mathcal{P}_1(\cdot) = \mathcal{L}(0, 0; \cdot, 1)$ as the top/lowest-indexed curve in \mathcal{P} ?



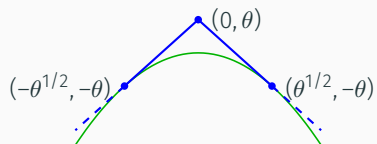
A useful heuristic to keep in mind:

\mathcal{P}_1 is like a Brownian bridge conditioned to stay above a parabola $-x^2$ with which it shares endpoints.

The geometry of the line ensemble

Main results: geometry under one-point conditioning

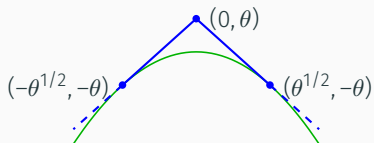
Define $\text{Triangle}_\theta : [-\theta^{1/2}, \theta^{1/2}]$ to be



The linear portions of Triangle_θ are *tangent* to $-x^2$ at $\pm\theta^{1/2}$.

Main results: geometry under one-point conditioning

Define $\text{Triangle}_\theta : [-\theta^{1/2}, \theta^{1/2}]$ to be



The linear portions of Triangle_θ are *tangent* to $-x^2$ at $\pm\theta^{1/2}$.

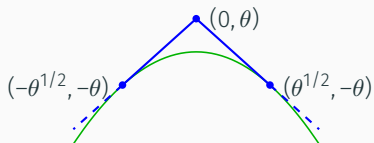
Theorem (Ganguly-H.)

There exist θ_0 and $c > 0$ such that, for all $t \geq 1$, $\theta > \theta_0$, and $M > 0$,

$$\mathbb{P} \left(\sup_{x \in [-\theta^{1/2}, \theta^{1/2}]} |\mathcal{P}_1(x) - \text{Triangle}_\theta(x)| > M\theta^{1/4} \mid \mathcal{P}_1(0) = \theta \right) \leq \exp(-cM^2).$$

Main results: geometry under one-point conditioning

Define $\text{Triangle}_\theta : [-\theta^{1/2}, \theta^{1/2}]$ to be



The linear portions of Triangle_θ are *tangent* to $-x^2$ at $\pm\theta^{1/2}$.

Theorem (Ganguly-H.)

There exist θ_0 and $c > 0$ such that, for all $t \geq 1$, $\theta > \theta_0$, and $M > 0$,

$$\mathbb{P} \left(\sup_{x \in [-\theta^{1/2}, \theta^{1/2}]} |\mathcal{P}_1(x) - \text{Triangle}_\theta(x)| > M\theta^{1/4} \mid \mathcal{P}_1(0) = \theta \right) \leq \exp(-cM^2).$$

- $\theta^{1/4}$ is the Brownian fluctuation scale on an interval of size $\theta^{1/2}$ and is optimal.

A quantitative consequence: one-point upper tail asymptotics

From the limit shape, one can obtain sharp asymptotics for the upper tail:

Theorem (Ganguly-H.)

There exist $C < \infty$ and θ_0 such that, for all $\theta > \theta_0$,

$$\exp\left(-\frac{4}{3}\theta^{3/2} - C\theta^{3/4}\right) \leq \frac{1}{d\theta} \mathbb{P}(\mathcal{P}_1(0) \in d\theta) \leq \exp\left(-\frac{4}{3}\theta^{3/2} + C\theta^{3/4}\right).$$

As an immediate consequence, the same bounds also hold for $\mathbb{P}(\mathcal{P}_1(0) > \theta)$.

A quantitative consequence: one-point upper tail asymptotics

From the limit shape, one can obtain sharp asymptotics for the upper tail:

Theorem (Ganguly-H.)

There exist $C < \infty$ and θ_0 such that, for all $\theta > \theta_0$,

$$\exp\left(-\frac{4}{3}\theta^{3/2} - C\theta^{3/4}\right) \leq \frac{1}{d\theta} \mathbb{P}(\mathcal{P}_1(0) \in d\theta) \leq \exp\left(-\frac{4}{3}\theta^{3/2} + C\theta^{3/4}\right).$$

As an immediate consequence, the same bounds also hold for $\mathbb{P}(\mathcal{P}_1(0) > \theta)$.

By more refined coupling arguments, we also get a comparison statement:

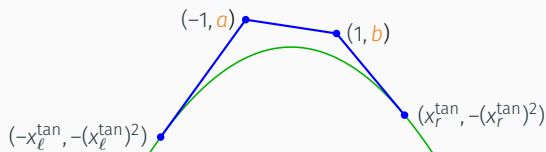
Theorem (Ganguly-H.-Zhang)

There exist $C < \infty$ and θ_0 such that, for all $\delta > 0$ and $\theta > \theta_0$,

$$\frac{\mathbb{P}(\mathcal{P}_1(0) \geq \theta + \delta)}{\mathbb{P}(\mathcal{P}_1(0) \geq \theta)} = \exp\left(-2\delta\theta^{1/2} + O(\delta L^{-1/4})\right).$$

Main results: geometry under two-point conditioning

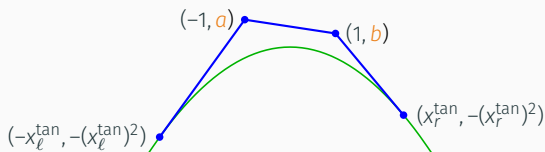
Define $\text{Quad}_{a,b} : [-x_\ell^{\text{tan}}, x_r^{\text{tan}}]$ to be



The values of x_ℓ^{tan} and x_r^{tan} are such that the tangency conditions are met.

Main results: geometry under two-point conditioning

Define $\text{Quad}_{a,b} : [-x_\ell^{\text{tan}}, x_r^{\text{tan}}]$ to be



The values of x_ℓ^{tan} and x_r^{tan} are such that the tangency conditions are met.

Theorem (Ganguly-H.)

Assuming some *non-degeneracy* conditions on a and b , there exists $c > 0$ such that, for all $t \geq 1$, $M > 0$, and large enough a, b ,

$$\mathbb{P} \left(\sup_{x \in [-x_\ell^{\text{tan}}, x_r^{\text{tan}}]} \mathcal{P}_1(x) - \text{Quad}_{a,b}(x) > M(a^{1/4} + b^{1/4}) \mid \mathcal{P}_1(-1) = a, \mathcal{P}_1(1) = b \right) \leq \exp(-cM^2).$$

Theorem (Ganguly-H.)

For $t \geq 1$ and if a, b are large enough and satisfy the non-degeneracy condition, then

$$\begin{aligned} & \mathbb{P}(\mathcal{P}_1(-1) \geq a, \mathcal{P}_1(1) \geq b) \\ &= \exp\left(-\frac{1}{24} \left[16 \left((1+a)^{3/2} + (1+b)^{3/2}\right) + 3(a-b)^2 + 24(a+b) + 32\right] + \text{error}\right). \end{aligned}$$

The error term has explicit upper and lower bounds.

Theorem (Ganguly-H.)

For $t \geq 1$ and if a, b are large enough and satisfy the non-degeneracy condition, then

$$\begin{aligned} & \mathbb{P}(\mathcal{P}_1(-1) \geq a, \mathcal{P}_1(1) \geq b) \\ &= \exp\left(-\frac{1}{24} \left[16 \left((1+a)^{3/2} + (1+b)^{3/2}\right) + 3(a-b)^2 + 24(a+b) + 32\right] + \text{error}\right). \end{aligned}$$

The error term has explicit upper and lower bounds.

- A similar bound also holds at $\pm K$ in place of ± 1 , or in general any two points (using stationarity).

Because of connections to statistical mechanics models, it is known that \mathcal{P}_1 enjoys the **FKG inequality**, so that, for all a and b ,

$$\mathbb{P}\left(\mathcal{P}_1(-K^{1/2}) > a, \mathcal{P}_1(K^{1/2}) > b\right) \geq \mathbb{P}\left(\mathcal{P}_1(-K^{1/2}) > a\right) \cdot \mathbb{P}\left(\mathcal{P}_1(K^{1/2}) > b\right).$$

A multi-point question: Sharpness of FKG

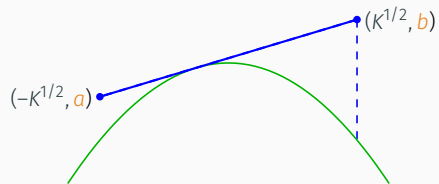
Because of connections to statistical mechanics models, it is known that \mathcal{P}_1 enjoys the **FKG inequality**, so that, for all a and b ,

$$\mathbb{P}\left(\mathcal{P}_1(-K^{1/2}) > a, \mathcal{P}_1(K^{1/2}) > b\right) \geq \mathbb{P}\left(\mathcal{P}_1(-K^{1/2}) > a\right) \cdot \mathbb{P}\left(\mathcal{P}_1(K^{1/2}) > b\right).$$

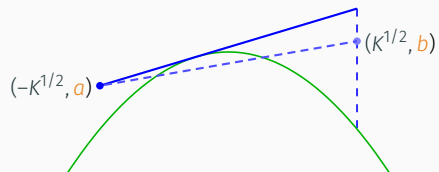
But in many applications the inequality is suboptimal.

Is FKG **sharp** for any values of a and b , and, if so, which ones?

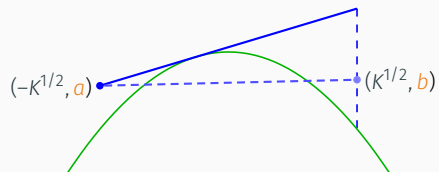
Corollary: Geometric condition for sharpness of FKG



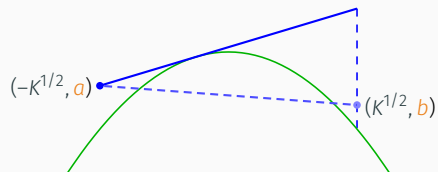
Corollary: Geometric condition for sharpness of FKG



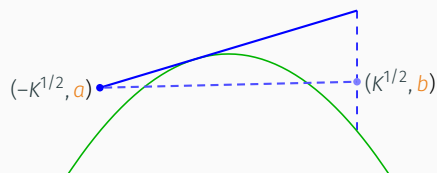
Corollary: Geometric condition for sharpness of FKG



Corollary: Geometric condition for sharpness of FKG



Corollary: Geometric condition for sharpness of FKG

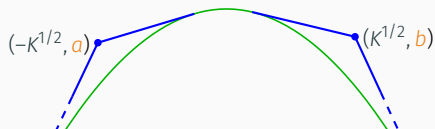


Corollary (Ganguly-H.)

Let K be fixed. If the line joining $(-K^{1/2}, a)$ and $(K^{1/2}, b)$ is tangent to or intersects $-x^2$ inside $[-K^{1/2}, K^{1/2}]$, then

$$\begin{aligned}\mathbb{P}\left(\mathcal{P}_1(-K^{1/2}) > a, \mathcal{P}_1(K^{1/2}) > b\right) &= \exp\left(-\frac{4}{3}[(K+a)^{3/2} + (K+b)^{3/2}] + \text{error}\right) \\ &\approx \mathbb{P}(\mathcal{P}_1(-K^{1/2}) > a) \cdot \mathbb{P}(\mathcal{P}_1(K^{1/2}) > b).\end{aligned}$$

Corollary: Geometric condition for sharpness of FKG



Corollary (Ganguly-H.)

Let K be fixed. If the line joining $(-K^{1/2}, a)$ and $(K^{1/2}, b)$ is tangent to or intersects $-x^2$ inside $[-K^{1/2}, K^{1/2}]$, then

$$\begin{aligned}\mathbb{P}\left(\mathcal{P}_1(-K^{1/2}) > a, \mathcal{P}_1(K^{1/2}) > b\right) &= \exp\left(-\frac{4}{3}[(K+a)^{3/2} + (K+b)^{3/2}] + \text{error}\right) \\ &\approx \mathbb{P}(\mathcal{P}_1(-K^{1/2}) > a) \cdot \mathbb{P}(\mathcal{P}_1(K^{1/2}) > b).\end{aligned}$$

Geometry of the landscape and geodesic

Qualitative features under the upper tail conditioning

How does the landscape change under the conditioning
 $\mathcal{P}_1(0) = \mathcal{L}(0, 0; 0, 1) > \theta$?



Qualitative features under the upper tail conditioning

How does the landscape change under the conditioning $\mathcal{P}_1(0) = \mathcal{L}(0, 0; 0, 1) > \theta$?

An **energy-entropy** tradeoff occurs: larger fluctuations give the geodesic more choice of paths, but the cost grows with θ .

So the path measure will become more **rigid**, i.e., have much smaller transversal fluctuations. (It also becomes a “highway” for geodesics to nearby points.)

Heuristically, a uniformly (on some scale) random path is chosen and made to be the geodesic.



The scaling limit of the geodesic under upper tail conditioning

Let $\Gamma_\theta : [0, 1] \rightarrow \mathbb{R}$ be the **geodesic** in the directed landscape from $(0, 0)$ to $(0, 1)$, conditioned on $\mathcal{L}(0, 0; 0, 1) > \theta$.

Theorem (Ganguly-H.-Zhang)

$\theta^{1/4} \Gamma_\theta \xrightarrow{d} \frac{1}{2} B$ in the uniform topology with $B =$ standard *Brownian bridge*.

Note that we identify the fluctuation scale to be $\theta^{-1/4}$ as well as the scaling limit.

The scaling limit of the geodesic under upper tail conditioning

Let $\Gamma_\theta : [0, 1] \rightarrow \mathbb{R}$ be the **geodesic** in the directed landscape from $(0, 0)$ to $(0, 1)$, conditioned on $\mathcal{L}(0, 0; 0, 1) > \theta$.

Theorem (Ganguly-H.-Zhang)

$\theta^{1/4} \Gamma_\theta \xrightarrow{d} \frac{1}{2} B$ in the uniform topology with $B =$ standard *Brownian bridge*.

Note that we identify the fluctuation scale to be $\theta^{-1/4}$ as well as the scaling limit.

This result had been conjectured by Zhipeng Liu, who proved the one-point scale and one-point convergence using exact formulas.

A similar result had earlier been conjectured by Basu-Ganguly for the geodesic in exponential LPP under a **large deviation** conditioning.

Heuristics and proof ideas

Why is the fluctuation scale $\theta^{-1/4}$?

Why is the fluctuation scale $\theta^{-1/4}$?

- $\mathcal{P}_1(x) + x^2 = \mathcal{L}(0, 0; x, 1) + x^2$ is stationary in x .
- So the geodesic fluctuating by ε means it suffers a loss of $O(\varepsilon^2)$.

The source of the $\theta^{-1/4}$ scale

Why is the fluctuation scale $\theta^{-1/4}$?

- $\mathcal{P}_1(x) + x^2 = \mathcal{L}(0, 0; x, 1) + x^2$ is stationary in x .
- So the geodesic fluctuating by ε means it suffers a loss of $O(\varepsilon^2)$.
- Under the conditioning of being $> \theta$, this loss has to be made up; akin to $\mathcal{P}_1(0) > \theta + O(\varepsilon^2)$ (by stationarity).
- But $\frac{\mathbb{P}(\mathcal{P}_1(0) > \theta + O(\varepsilon^2))}{\mathbb{P}(\mathcal{P}_1(0) > \theta)} \approx \exp(-C\varepsilon^2\theta^{1/2})$.
- This is $O(1)$ exactly when $\varepsilon = O(\theta^{-1/4})$.

The source of the Brownian bridge

Recall that

$$\Gamma_\theta(s) = \operatorname{argmax}_y (\mathcal{L}(0, 0; y, s) + \mathcal{L}(y, s; 0, 1))$$

under the conditioning $\mathcal{L}(0, 0; 0, 1) = \max_y (\mathcal{L}(0, 0; y, s) + \mathcal{L}(y, s; 0, 1)) > \theta$.

The tent picture suggests that $\mathcal{L}(0, 0; y, s)$ and $\mathcal{L}(y, s; 0, 1)$ are like independent Brownian bridges on $[-\theta^{1/2}, \theta^{1/2}]$.

The source of the Brownian bridge

Recall that

$$\Gamma_\theta(s) = \operatorname{argmax}_y (\mathcal{L}(0, 0; y, s) + \mathcal{L}(y, s; 0, 1))$$

under the conditioning $\mathcal{L}(0, 0; 0, 1) = \max_y (\mathcal{L}(0, 0; y, s) + \mathcal{L}(y, s; 0, 1)) > \theta$.

The tent picture suggests that $\mathcal{L}(0, 0; y, s)$ and $\mathcal{L}(y, s; 0, 1)$ are like **independent Brownian bridges** on $[-\theta^{1/2}, \theta^{1/2}]$.

So the maximizer density at y is essentially the density that the Brownian bridge will reach L at y .

The source of the Brownian bridge

Recall that

$$\Gamma_\theta(s) = \operatorname{argmax}_y (\mathcal{L}(0, 0; y, s) + \mathcal{L}(y, s; 0, 1))$$

under the conditioning $\mathcal{L}(0, 0; 0, 1) = \max_y (\mathcal{L}(0, 0; y, s) + \mathcal{L}(y, s; 0, 1)) > \theta$.

The tent picture suggests that $\mathcal{L}(0, 0; y, s)$ and $\mathcal{L}(y, s; 0, 1)$ are like independent Brownian bridges on $[-\theta^{1/2}, \theta^{1/2}]$.

So the maximizer density at y is essentially the density that the Brownian bridge will reach L at y .

The variance at $y = L^{-1/2}(L^{1/2} + y)(L^{1/2} - y) = L^{1/2} - y^2L^{-1/2}$, so density at y is proportional to

$$\exp\left(-c \frac{L^2}{L^{1/2} - y^2L^{-1/2}}\right) = \exp\left(-cL^{3/2} - cy^2L^{1/2} + O(L^{-1/2})\right).$$

This is Gaussian on scale $L^{-1/4}$!

The source of the Brownian bridge

- One-point Gaussianity follows essentially from the comparison theorem. For multi-point, also need some **decoupling & independence**.

The source of the Brownian bridge

- One-point Gaussianity follows essentially from the comparison theorem. For multi-point, also need some **decoupling & independence**.
- These are provided by **coalescence**.



The source of the Brownian bridge

- One-point Gaussianity follows essentially from the comparison theorem. For multi-point, also need some **decoupling & independence**.

- These are provided by **coalescence**.

- $(\Gamma(s), \Gamma(t)) = \operatorname{argmax}_{z_1, z_2} \mathcal{L}(0, 0; z_1, s) + \mathcal{L}(z_1, s; z_2, t) + \mathcal{L}(z_2, t; 0, 1)$



The source of the Brownian bridge

- One-point Gaussianity follows essentially from the comparison theorem. For multi-point, also need some **decoupling & independence**.
- These are provided by **coalescence**.
- $(\Gamma(s), \Gamma(t)) = \operatorname{argmax}_{z_1, z_2} \mathcal{L}(0, 0; z_1, s) + \mathcal{L}(z_1, s; z_2, t) + \mathcal{L}(z_2, t; 0, 1)$
- Coalescence gives quadrangle equality:
 $\mathcal{L}(z_1, s; z_2, t) + \mathcal{L}(0, s; 0, t) = \mathcal{L}(z_1, s; 0, t) + \mathcal{L}(0, s; z_2, t)$
- The double argmax separates into **two single argmaxes**.



The source of the Brownian bridge

- One-point Gaussianity follows essentially from the comparison theorem. For multi-point, also need some **decoupling & independence**.
- These are provided by **coalescence**.
- $(\Gamma(s), \Gamma(t)) = \operatorname{argmax}_{z_1, z_2} \mathcal{L}(0, 0; z_1, s) + \mathcal{L}(z_1, s; z_2, t) + \mathcal{L}(z_2, t; 0, 1)$
- Coalescence gives quadrangle equality:
 $\mathcal{L}(z_1, s; z_2, t) + \mathcal{L}(0, s; 0, t) = \mathcal{L}(z_1, s; 0, t) + \mathcal{L}(0, s; z_2, t)$
- The double argmax separates into **two single argmaxes**.
- Heuristically, coalescence also implies the two process on the RHS are (approximately) **independent**.
- The proof of independence relies crucially on **shift invariance** of \mathcal{L} or free energy fields.



Let $\Gamma_\theta^{\text{ann}} : [0, 1] \rightarrow \mathbb{R}$ be a sample from the **annealed polymer measure** from $(0, 0)$ to $(0, 1)$ in the CDRP, under the conditioning that the free energy $> \theta$.

Theorem (Ganguly-H.-Zhang)

$\theta^{1/4} \Gamma_\theta^{\text{ann}} \xrightarrow{d} \frac{1}{2} B$ in the uniform topology with $B =$ standard Brownian bridge.

Let $\Gamma_\theta^{\text{ann}} : [0, 1] \rightarrow \mathbb{R}$ be a sample from the **annealed polymer measure** from $(0, 0)$ to $(0, 1)$ in the CDRP, under the conditioning that the free energy $> \theta$.

Theorem (Ganguly-H.-Zhang)

$\theta^{1/4} \Gamma_\theta^{\text{ann}} \xrightarrow{d} \frac{1}{2}B$ in the uniform topology with $B =$ standard Brownian bridge.

What about the **quenched** situation? The polymer measure concentrates in a $O(\theta^{-1/2})$ window around a random “backbone” $\Gamma_\theta^{\text{back}}$, and $\theta^{-1/4} \Gamma_\theta^{\text{back}} \xrightarrow{d} \frac{1}{2}B$.

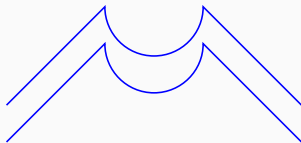
- Using geometric methods + Brownian Gibbs properties, we can obtain the **shape** of the weight profile of \mathcal{L} under **upper tail** events.
- These also give sharp upper tail **asymptotics** and probability **comparison** statements.
- With these + “tent” picture, can prove that geodesic/polymer measure rescaled by $\theta^{-1/4}$ converges to a **Brownian bridge**, under upper tail.
- Further, the polymer measure fluctuates on scale $\theta^{-1/2}$ around a random “**backbone**” curve.

Thank you!

A convex consequence

A key idea is that the resampling in terms of Brownian bridges implies that the limit shapes should be **convex**.

Indeed, suppose the limit shape of the top curve is not convex in some neighbourhood. This pushes the **second curve** down on the interval.

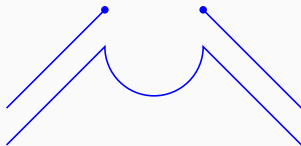


A convex consequence

A key idea is that the resampling in terms of Brownian bridges implies that the limit shapes should be **convex**.

Indeed, suppose the limit shape of the top curve is not convex in some neighbourhood. This pushes the **second curve** down on the interval.

Then **resample** the **top curve** on that interval. *Since the non-convexity means the second curve is far away, Brownian bridge naturally avoids it.*



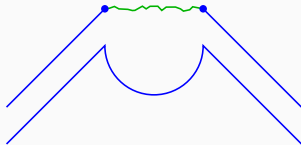
A convex consequence

A key idea is that the resampling in terms of Brownian bridges implies that the limit shapes should be **convex**.

Indeed, suppose the limit shape of the top curve is not convex in some neighbourhood. This pushes the **second curve** down on the interval.

Then **resample** the **top curve** on that interval. *Since the non-convexity means the second curve is far away, Brownian bridge naturally avoids it.*

Unconditioned Brownian bridge approximately follows a straight line, so can't recreate the earlier non-convexity. A contradiction!



A convex consequence

A key idea is that the resampling in terms of Brownian bridges implies that the limit shapes should be **convex**.

Indeed, suppose the limit shape of the top curve is not convex in some neighbourhood. This pushes the **second curve** down on the interval.

Then **resample** the **top curve** on that interval. *Since the non-convexity means the second curve is far away, Brownian bridge naturally avoids it.*

Unconditioned Brownian bridge approximately follows a straight line, so can't recreate the earlier non-convexity. A contradiction!

