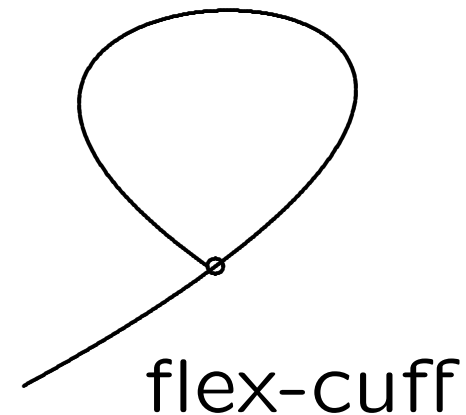
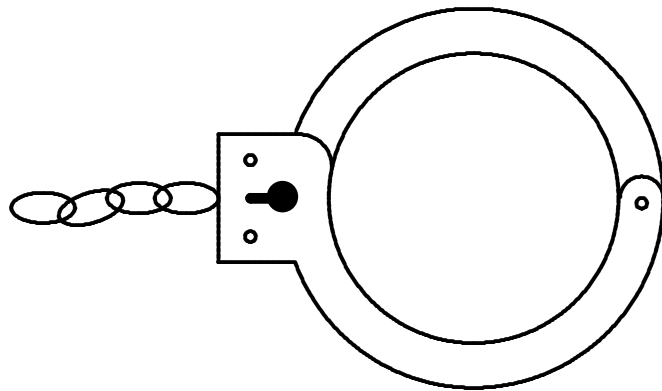


To hold a convex body by a frame

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- Is it possible to hold a cube by a circular handcuff?
- How about for other convex bodies?
- By a flex-cuff or handcuffs of other shapes?



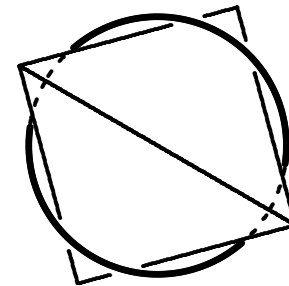
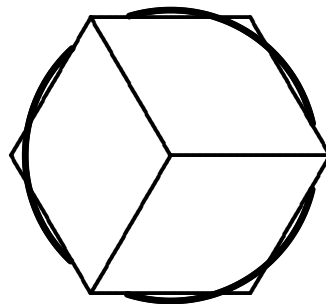
- A **frame** is the (rigid) boundary curve of a convex disk in a plane.
- A frame F is said to **hold** a convex body K if
 - (1) F is **attached** to K , that is,

$$F \cap \text{int}(K) = \emptyset, \text{conv}(F) \cap \text{int}(K) \neq \emptyset, \text{ and}$$
 - (2) F cannot **slip out** of K by a rigid motion with keeping $F \cap \text{int}(K) = \emptyset$.

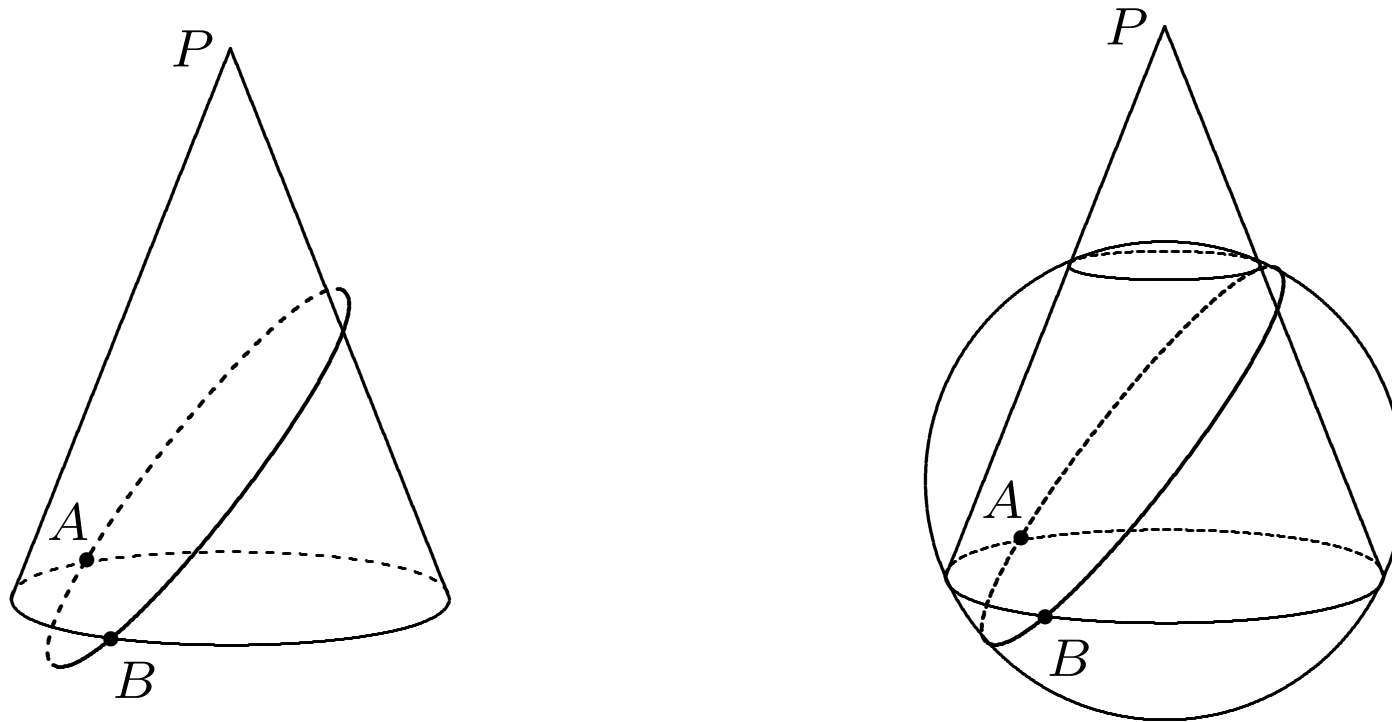
1. Circular frame

A convex body is called **circle-free** if no **circle** can hold it.

- Every ball is circle-free.
- A cube and a regular tetrahedron are not circle-free.



Example. Every circular cone is circle-free.



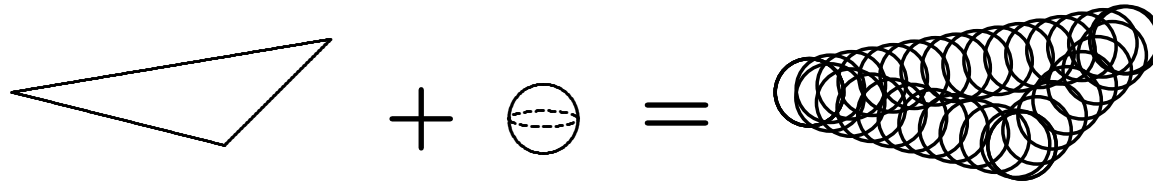
Theorem (T. Zamfirescu 1995)

The set of circle-free convex bodies in \mathbb{R}^3 is a nowhere dense subset of the set of all convex bodies in \mathbb{R}^3 with Hausdorff metric.

Thus, circle-free convex bodies are rare.

Theorem (M 2011)

For every planar compact convex set X and a ball \mathbf{B} in \mathbb{R}^3 , the convex body $X + \mathbf{B}$ (Minkowski sum) is circle-free.



Problem. Is it true that for every circle-free convex body K , the set $K + \mathbf{B}$ is also circle-free?

Symmetrization Lemma. Let Γ_0 be a holding circle of a convex polyhedron such that

- (1) $\text{conv}(\Gamma_0)$ divides its vertex set into U, V ,
- (2) both U and V are symmetric to themselves w.r.t. a fixed plane H .

Then there is a continuous family of holding circles Γ_t ($0 \leq t \leq 1$) such that

$$\text{diam}(\Gamma_t) \leq \text{diam}(\Gamma_0), \Gamma_t \cap H = \Gamma_0 \cap H,$$

and Γ_1 is symmetric to itself w.r.t. H .

2. Holding circles of Platonic solids

Theorem (Itoh, Tanoue, Zamfirescu 2006)

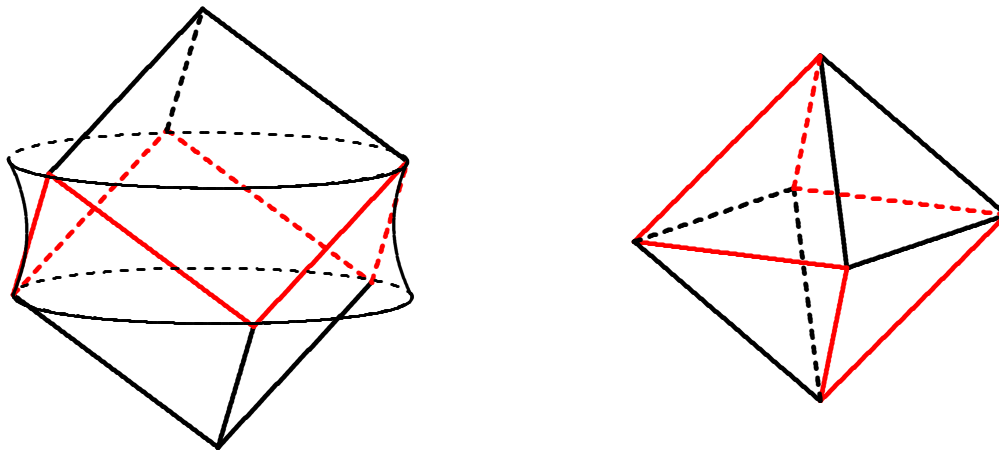
A circle of diameter d can hold a regular tetrahedron of unit edge if and only if

$$1/\sqrt{2} \leq d < \phi_t \approx 0.896$$

where ϕ_t is the min value of $\frac{2(x^2 - x + 1)}{\sqrt{3x^2 - 4x + 4}}$.

Hyperboloidal Restriction.

If the plane of a holding circle cuts the edges on a hyperboloid of revolution, the order of intersections of the circle and the edges is restricted by the alternation of inside-outside.



Lemma. If a circle Γ holds a cube, then $\text{conv}(\Gamma)$ cuts all faces of the cube.

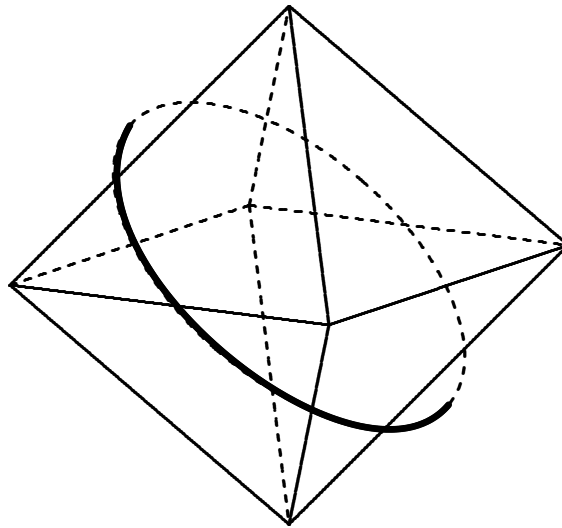
Theorem (M 2010).

A circle Γ of diameter d can hold a unit cube if and only if $\sqrt{2} \leq d < \phi_c \approx 1.535$, where ϕ_c is the min value of $\frac{\sqrt{2}(x^2+2)}{\sqrt{x^2+2x+3}}$.

Proof is by SL, HR, Lemma, and computations.

For a regular octahedron, the following holds.

Lemma. If Γ holds a regular octahedron, then $\text{conv}(\Gamma)$ separates its two faces.



Using the lemma, we can prove the following.

Theorem (M 2010)

A circle of diameter d can hold a regular octahedron of unit edge if and only if

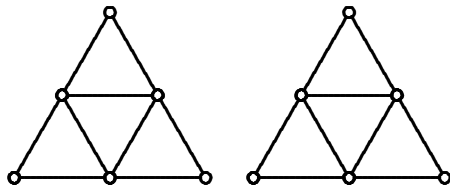
$$1 \leq d < \phi_0 \approx 1.1066,$$

where ϕ_0 is the min value of $\frac{2(x^2+1)}{\sqrt{3x^2+2x+3}}$.

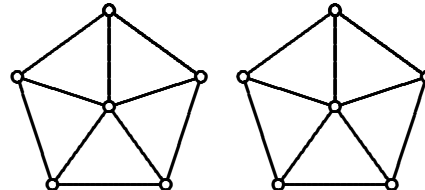
Y. Tanoue got the same result independently.

Lemma.

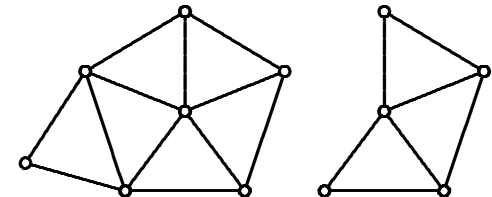
If a circle Γ holds a regular icosahedron I , then $\text{conv}(\Gamma)$ divides the graph of I into one of the following pairs:



(1)

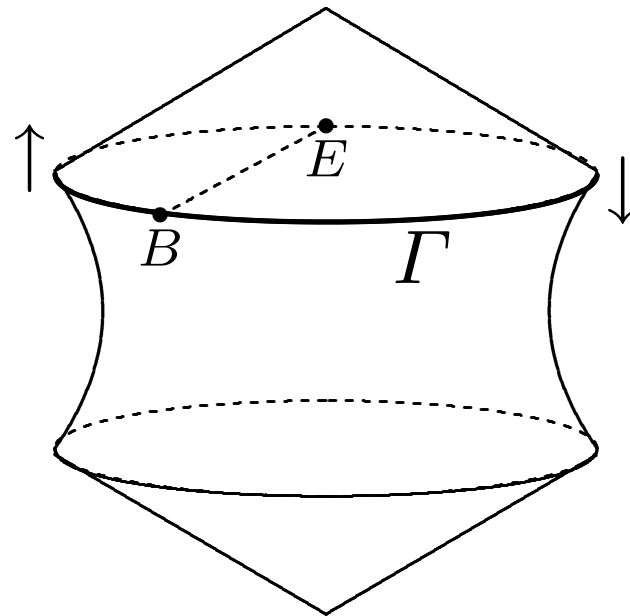
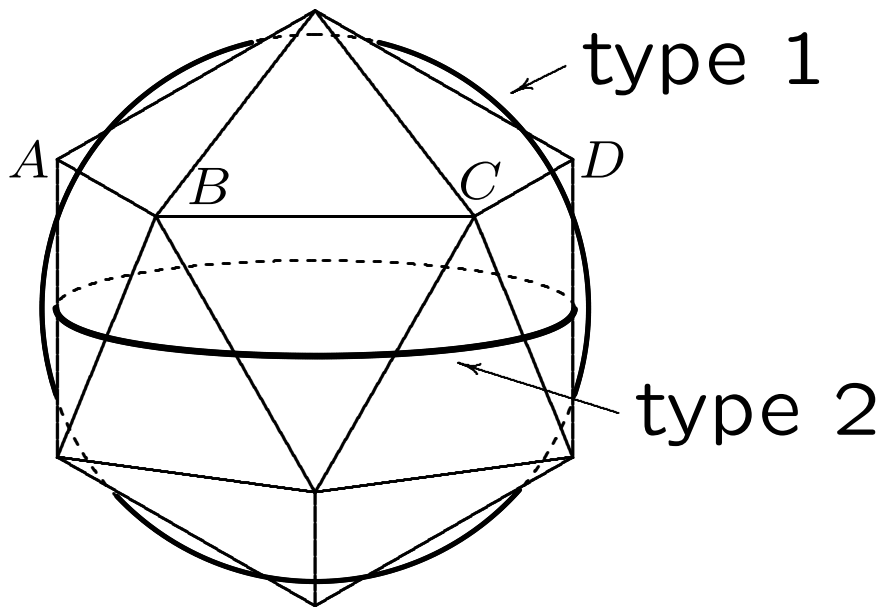


(2)



(3)

Corresponding to (1), (2), (3), holding circles are called type 1, type 2, type 3, respectively.



To get a type 3 circle, rotate the circum-circle Γ of $ABCDE$ around \overleftrightarrow{BE} so that $conv(\Gamma)$ goes above A , push down the circle a bit, squeeze it.

Theorem.

A regular icosahedron of unit edge has three types holding circles. The min diameter of type 1 circle is $\sqrt{3} \approx 1.7320$, and the min diameter of type 2 circle is $\tau := \frac{1+\sqrt{5}}{2} \approx 1.6180$.

There is a holding circle that can vary between types 2 and 3 by going over a vertex. The min diameter of such circle is $d_* \approx 1.6816$, the min value of $\frac{\tau^2 + (1-x)^2}{\sqrt{\tau^2 + (1-x)^2 - (x/2)^2}}$.

Theorem.

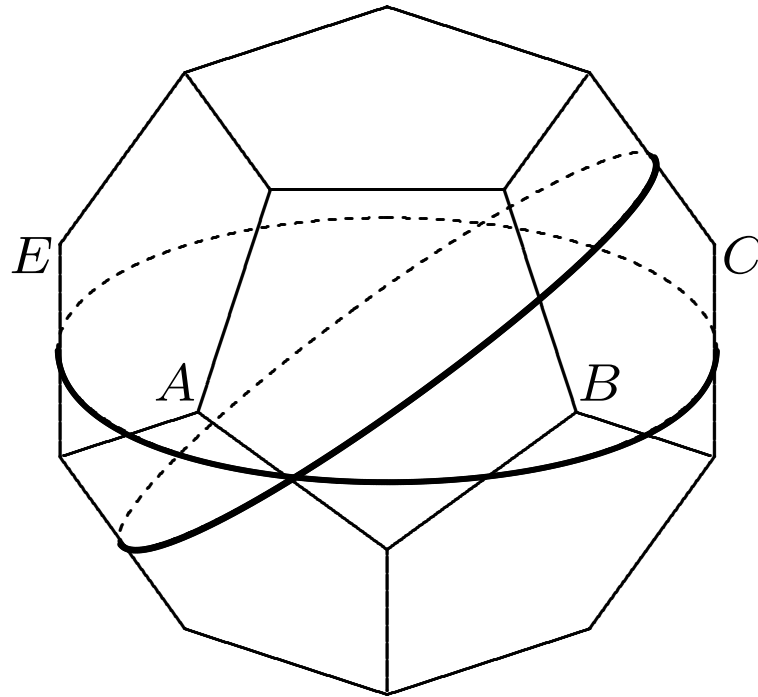
The circum-circle of a regular pentagon of unit side (diameter $2\sqrt{\tau/\sqrt{5}} \approx 1.7013$) cannot hold a regular icosahedron of unit edge.

Since $\tau < 1.7013 < \sqrt{3}$, the set of diameters of all holding circles (**DHC**) of a regular icosahedron has 2 connected components.

Theorem.

A regular dodecahedron of unit edge can be held by a circle of diameter $\tau^2 \approx 2.6180$ in two different ways, where $\tau = \frac{1+\sqrt{5}}{2}$.

There are holding circles Γ of a dodecahedron such that $\text{conv}(\Gamma)$ divides the vertex set unevenly.



Two holding circles of a regular dodecahedron.

Problem. Find all types of circles that hold a regular dodecahedron. Determine DHC for a regular icosahedron/dodecahedron of unit edge.

Problem. Is there a convex body whose DHC has more than 2 connected components?

3. The case of regular pyramids

- For a regular pyramid, define its **slope** ρ by

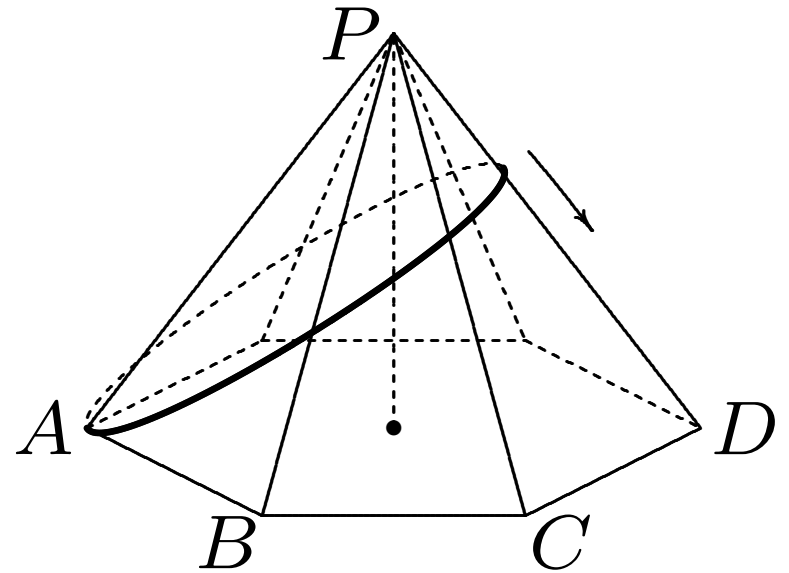
$$\rho := \frac{\text{height}}{\text{circum-radius of the base}}$$

Theorem (M 2011)

Every regular pyramid with $\rho \geq 1$ can be held by a circle.

Proof (Outline).

Slide the circle slightly in the direction \overrightarrow{PD} , and then squeeze its radius. The resulting circle cannot slip out of the pyramid.



Theorem (M 2011)

For every $0 < \varepsilon < 1$, there is a circle-free regular pyramid with $\rho = 1 - \varepsilon$.

If $m > 2\pi/\varepsilon^2$, then a regular pyramid with base regular $4m$ -gon and $\rho = 1 - \varepsilon$ is circle-free.

Theorem (Tanoue 2009, M 2011)

A regular pyramid with equilateral triangular base can be held by a circle if and only if

$$\rho > \sqrt{(3\sqrt{17} - 5)/32} \approx 0.4799.$$

Y. Tanoue proved the if part.

Theorem (M 2011)

A regular pyramid with square base can be held by a circle if and only if

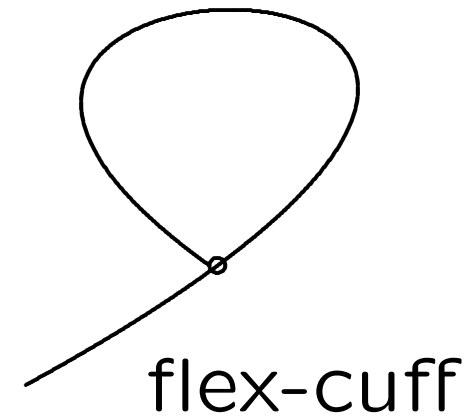
$$\rho > \sqrt{(\sqrt{33} - 3)/4} \approx 0.828.$$

The Great Pyramid of Giza has base-edge $230m$, height $140m$. Since $140\sqrt{2}/230 \approx 0.860 > 0.828$, it can be held by a circle.

4. Strings and frames of other shapes

Theorem (A. Fruchard 2009)

A loop of string winding on a convex body can slip out of the convex body. (Hence a flex-cuff cannot hold a convex body.)



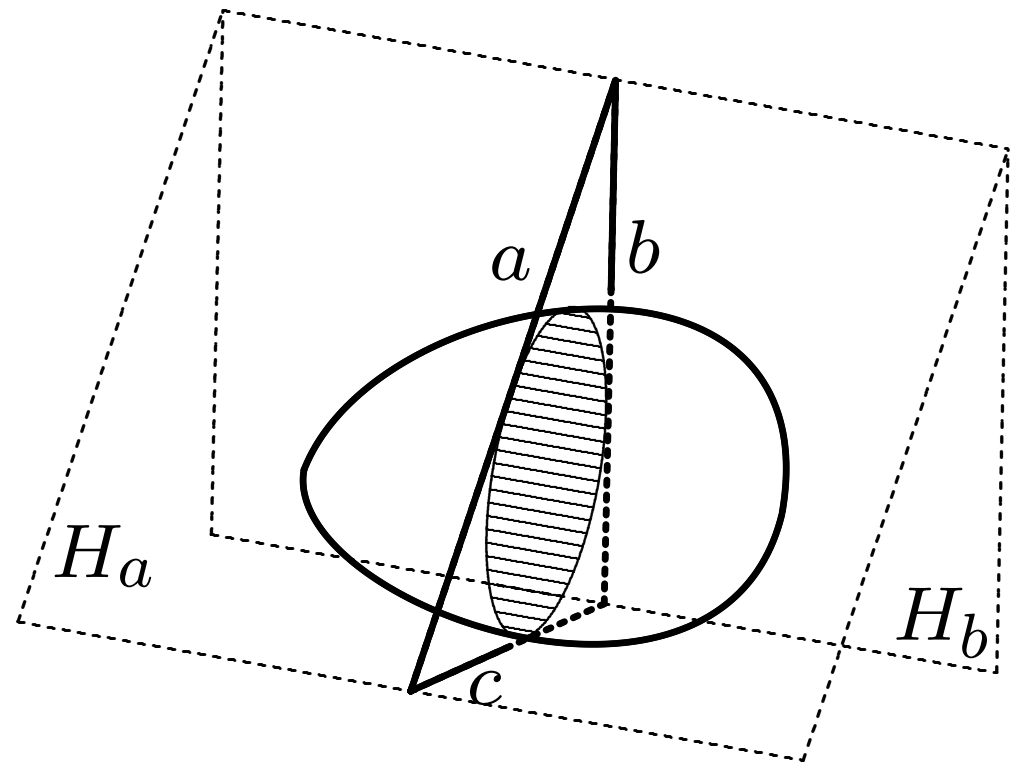
Proof by Fruchard (For convex polyhedron P):
By contradiction. Let L be the shortest loop that cannot slip out of P . Then, L draws a geodesic on ∂P , and never passes through a vertex of P . It is possible to develop (unfold) ∂P on the plane so that the track of L becomes a line-segment between two parallel edges. Slide this line-segment between the parallel edges. This corresponds to a motion of L on ∂P . Then, L eventually hits a vertex, a contradiction. □

Theorem (Bárány, Tokushige, M. 2011)

No triangular frame can hold a convex body.

Proof.

H_a, H_b, H_c enclose either a triangular cone or a triangular prism. Hence the convex body can slip out. \square



- A frame F is said to **fix** a convex body K if F holds K in such a way that when K is fixed, F is confined in a fixed plane.

Theorem (Bárány, Tokushige, M 2011)

Every non-triangular frame can fix some tetrahedron.