

Singular Foliations

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM .

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM .

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

$$\forall X, Y \in \mathcal{F}_x: \quad [X, Y] \in \mathcal{F}_x$$

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

$$\forall X, Y \in \mathcal{F}_x: \quad [X, Y] \in \mathcal{F}_x$$

For $p \in M$, let $T_p\mathcal{F} \subset T_pM$ denote the subspace $\{X_1(p), \dots, X_k(p)\}$ (where $\{X_i\}$ generates the stalk).

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

$$\forall X, Y \in \mathcal{F}_x: \quad [X, Y] \in \mathcal{F}_x$$

For $p \in M$, let $T_p\mathcal{F} \subset T_pM$ denote the subspace $\{X_1(p), \dots, X_k(p)\}$ (where $\{X_i\}$ generates the stalk).

Note that $p \rightarrow \dim T_p\mathcal{F}$ is an upper semi-continuous function.

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

$$\forall X, Y \in \mathcal{F}_x: \quad [X, Y] \in \mathcal{F}_x$$

For $p \in M$, let $T_p\mathcal{F} \subset T_pM$ denote the subspace $\{X_1(p), \dots, X_k(p)\}$ (where $\{X_i\}$ generates the stalk).

Note that $p \rightarrow \dim T_p\mathcal{F}$ is an upper semi-continuous function.

The *dimension* of \mathcal{F} is generic dimension of $T_p\mathcal{F}$

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

$$\forall X, Y \in \mathcal{F}_x: \quad [X, Y] \in \mathcal{F}_x$$

For $p \in M$, let $T_p\mathcal{F} \subset T_pM$ denote the subspace $\{X_1(p), \dots, X_k(p)\}$ (where $\{X_i\}$ generates the stalk).

Note that $p \rightarrow \dim T_p\mathcal{F}$ is an upper semi-continuous function.

The *dimension* of \mathcal{F} is generic dimension of $T_p\mathcal{F}$

A leaf of \mathcal{F} is a maximal connected immersed submanifold $L \subset M$ such that

$$\forall p \in L: \quad T_pL = T_p\mathcal{F}$$

Singular Foliations

We consider an n -dimensional analytic manifold M (real or complex)

An **analytic distribution** \mathcal{D} on M is a coherent subsheaf of the sheaf of sections of TM.

At each point p , the stalk \mathcal{D}_p is generated by a finite set of germs of vector fields $\{X_1, \dots, X_k\}$.

A **(singular) foliation** is an analytic distribution \mathcal{F} which is *involutive*

Namely,

$$\forall X, Y \in \mathcal{F}_x: \quad [X, Y] \in \mathcal{F}_x$$

For $p \in M$, let $T_p\mathcal{F} \subset T_pM$ denote the subspace $\{X_1(p), \dots, X_k(p)\}$ (where $\{X_i\}$ generates the stalk).

Note that $p \rightarrow \dim T_p\mathcal{F}$ is an upper semi-continuous function.

The *dimension* of \mathcal{F} is generic dimension of $T_p\mathcal{F}$

A leaf of \mathcal{F} is a maximal connected immersed submanifold $L \subset M$ such that

$$\forall p \in L: \quad T_pL = T_p\mathcal{F}$$

Integrability Theorem (Sussman): There exists a leaf of \mathcal{F} through each point $p \in M$.

Classical Frobenius Theorem: Let $p \in M$ be such that \mathcal{F} locally defines a **subbundle of the tangent bundle TM** (i.e. $T\mathcal{F}$ is locally of constant dimension d).

Classical Frobenius Theorem: Let $p \in M$ be such that \mathcal{F} locally defines a **subbundle of the tangent bundle** TM (i.e. $T\mathcal{F}$ is locally of constant dimension d).

Then, there exists local coordinates (x_1, \dots, x_n) such that

Classical Frobenius Theorem: Let $p \in M$ be such that \mathcal{F} locally defines a **subbundle of the tangent bundle** TM (i.e. $T\mathcal{F}$ is locally of constant dimension d).

Then, there exists local coordinates (x_1, \dots, x_n) such that

The leaves of \mathcal{F} are locally given by

$$x_{d+1} = \dots = x_n = \text{const}$$

where $d = \dim T_p\mathcal{F}$.

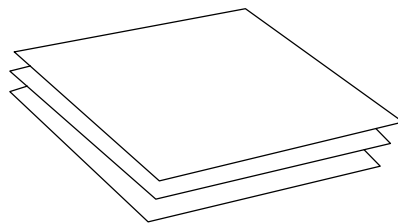
Classical Frobenius Theorem: Let $p \in M$ be such that \mathcal{F} locally defines a **subbundle of the tangent bundle TM** (i.e. $T\mathcal{F}$ is locally of constant dimension d).

Then, there exists local coordinates (x_1, \dots, x_n) such that

The leaves of \mathcal{F} are locally given by

$$x_{d+1} = \dots = x_n = \text{const}$$

where $d = \dim T_p\mathcal{F}$.



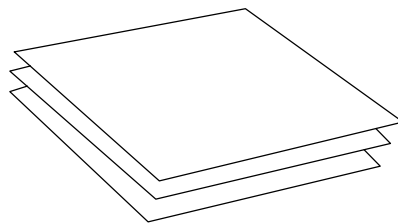
Classical Frobenius Theorem: Let $p \in M$ be such that \mathcal{F} locally defines a **subbundle of the tangent bundle TM** (i.e. $T\mathcal{F}$ is locally of constant dimension d).

Then, there exists local coordinates (x_1, \dots, x_n) such that

The leaves of \mathcal{F} are locally given by

$$x_{d+1} = \dots = x_n = \text{const}$$

where $d = \dim T_p\mathcal{F}$.



Singular example (with degeneracy of the rank): \mathcal{D} is generated by $x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}$ and $\frac{\partial}{\partial z}$

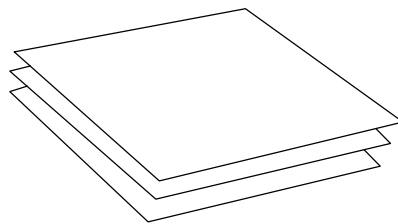
Classical Frobenius Theorem: Let $p \in M$ be such that \mathcal{F} locally defines a **subbundle of the tangent bundle TM** (i.e. $T\mathcal{F}$ is locally of constant dimension d).

Then, there exists local coordinates (x_1, \dots, x_n) such that

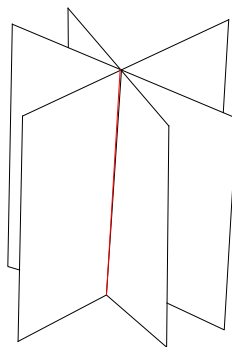
The leaves of \mathcal{F} are locally given by

$$x_{d+1} = \dots = x_n = \text{const}$$

where $d = \dim T_p\mathcal{F}$.



Singular example (with degeneracy of the rank): \mathcal{D} is generated by $x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}$ and $\frac{\partial}{\partial z}$



In this course, we will be mostly interested in **foliations by curves**

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

- 1) $(U_i)_{i \in I}$ is an open covering of M
- 2) ∂_i is an analytic vector field in U_i

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

for some non-zero analytic function $\varphi_{ij} \in \mathcal{O}^*(U_i \cap U_j)$.

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

for some non-zero analytic function $\varphi_{ij} \in \mathcal{O}^*(U_i \cap U_j)$.

Each ∂_i will be called a *local generator* of \mathcal{F} .

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

for some non-zero analytic function $\varphi_{ij} \in \mathcal{O}^*(U_i \cap U_j)$.

Each ∂_i will be called a *local generator* of \mathcal{F} .

More generally, each vector field ∂ with domain an open set $U \subset M$ is a local generator if

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

for some non-zero analytic function $\varphi_{ij} \in \mathcal{O}^*(U_i \cap U_j)$.

Each ∂_i will be called a *local generator* of \mathcal{F} .

More generally, each vector field ∂ with domain an open set $U \subset M$ is a local generator if

$$\partial|_{U_i \cap U} = \varphi_i \partial_i$$

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

for some non-zero analytic function $\varphi_{ij} \in \mathcal{O}^*(U_i \cap U_j)$.

Each ∂_i will be called a *local generator* of \mathcal{F} .

More generally, each vector field ∂ with domain an open set $U \subset M$ is a local generator if

$$\partial|_{U_i \cap U} = \varphi_i \partial_i$$

for some $\varphi_i \in \mathcal{O}^*(U_i \cap U)$.

In this course, we will be mostly interested in **foliations by curves**

In this context, we can assume the subsheaf \mathcal{D} to be locally generated by a single vector field.

A singular **foliation by curves** \mathcal{F} on M is defined by a collection $\{(U_i, \partial_i)\}_{i \in I}$ where

1) $(U_i)_{i \in I}$ is an open covering of M

2) ∂_i is an analytic vector field in U_i

Such that, for each $i, j \in I$, we have

$$\partial_i = \varphi_{ij} \partial_j$$

for some non-zero analytic function $\varphi_{ij} \in \mathcal{O}^*(U_i \cap U_j)$.

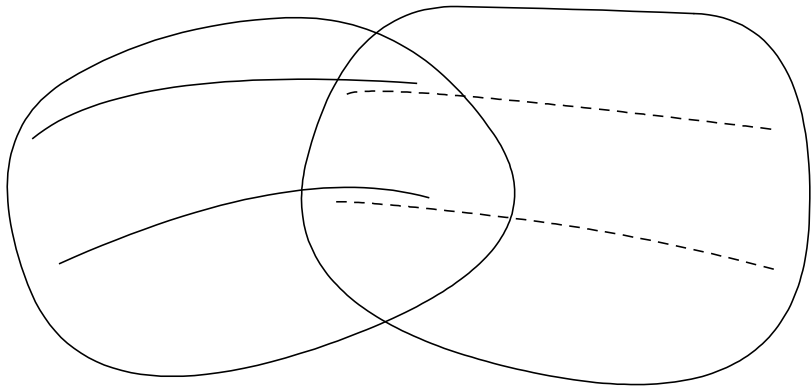
Each ∂_i will be called a *local generator* of \mathcal{F} .

More generally, each vector field ∂ with domain an open set $U \subset M$ is a local generator if

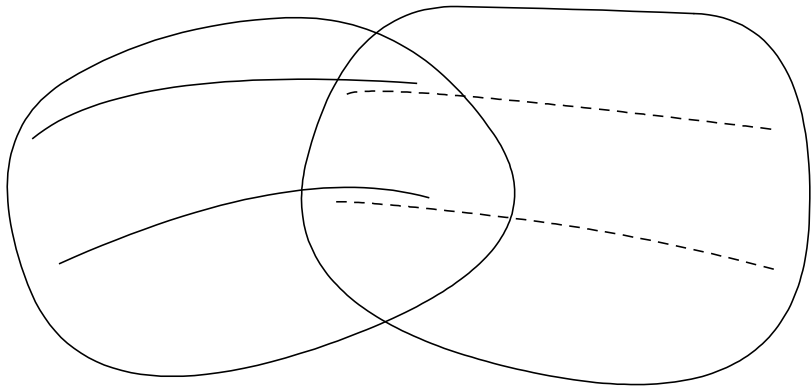
$$\partial|_{U_i \cap U} = \varphi_i \partial_i$$

for some $\varphi_i \in \mathcal{O}^*(U_i \cap U)$.

Remark: In general, we cannot expect to have a single global generator for a foliation.

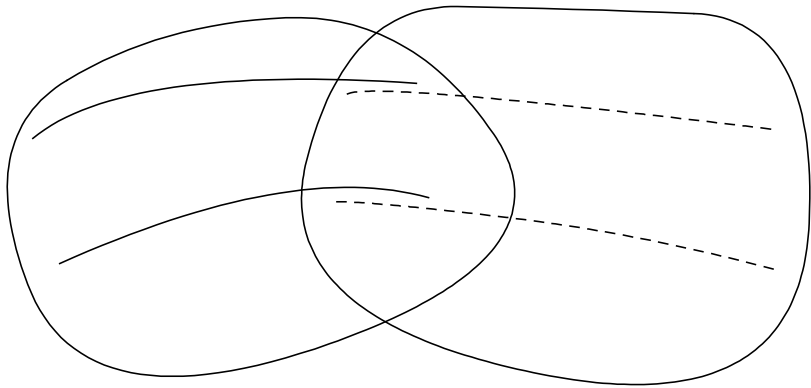


We authorize reparametrizations of time
for the solution curves



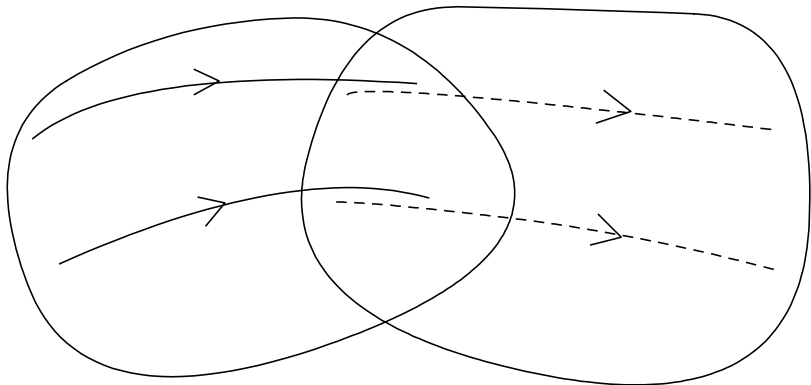
We authorize reparametrizations of time
for the solution curves

In the real analytic setting, we usually demand that $\varphi_{ij} > 0$.



We authorize reparametrizations of time
for the solution curves

In the real analytic setting, we usually demand that $\varphi_{ij} > 0$.



In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with a_1, \dots, a_n analytic functions.

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with a_1, \dots, a_n analytic functions.

The **singular set** of \mathcal{F} is the locally defined by the vanishing locus of the ideal generated by (a_1, \dots, a_n)

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with a_1, \dots, a_n analytic functions.

The **singular set** of \mathcal{F} is the locally defined by the vanishing locus of the ideal generated by (a_1, \dots, a_n)

$$\text{Sing}(\mathcal{F}) = Z(a_1, \dots, a_n)$$

Some simple examples...

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with a_1, \dots, a_n analytic functions.

The **singular set** of \mathcal{F} is the locally defined by the vanishing locus of the ideal generated by (a_1, \dots, a_n)

$$\text{Sing}(\mathcal{F}) = Z(a_1, \dots, a_n)$$

Some simple examples...

Example 1:

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with a_1, \dots, a_n analytic functions.

The **singular set** of \mathcal{F} is the locally defined by the vanishing locus of the ideal generated by (a_1, \dots, a_n)

$$\text{Sing}(\mathcal{F}) = Z(a_1, \dots, a_n)$$

Some simple examples...

Example 1:

$$\partial = f(x) \frac{\partial}{\partial x}$$

In local coordinates $x = (x_1, \dots, x_n)$, each local generator can be written

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with a_1, \dots, a_n analytic functions.

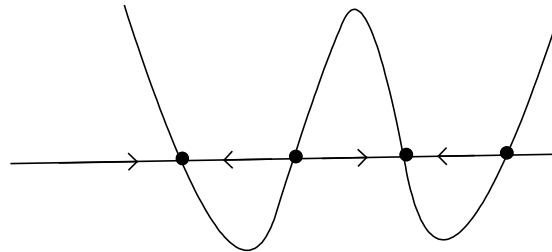
The **singular set** of \mathcal{F} is the locally defined by the vanishing locus of the ideal generated by (a_1, \dots, a_n)

$$\text{Sing}(\mathcal{F}) = Z(a_1, \dots, a_n)$$

Some simple examples...

Example 1:

$$\partial = f(x) \frac{\partial}{\partial x}$$



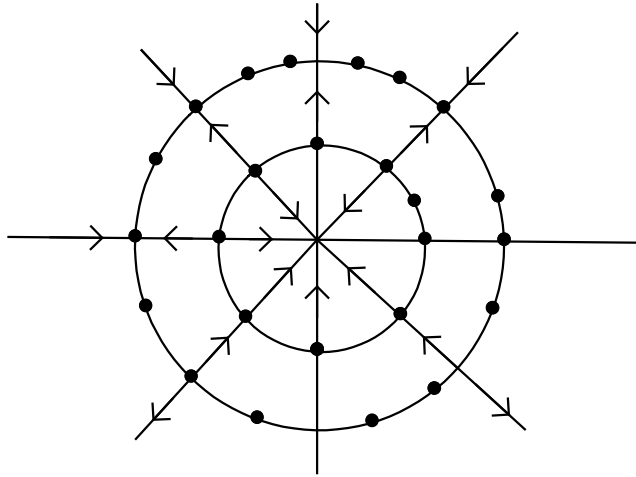
Example 2:

Example 2:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)$$

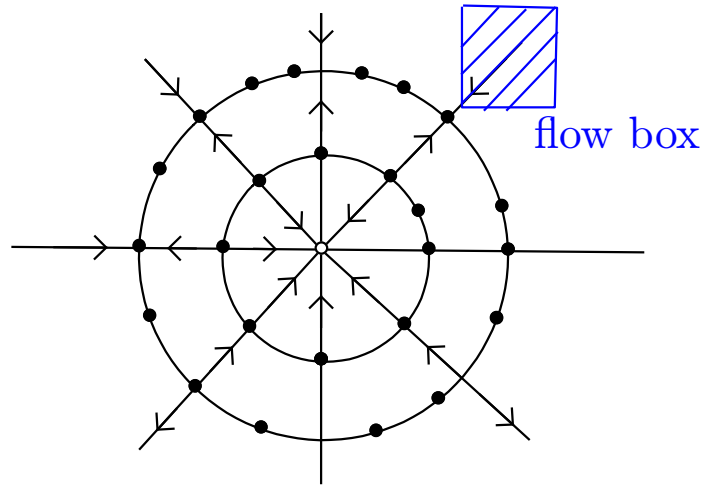
Example 2:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)$$



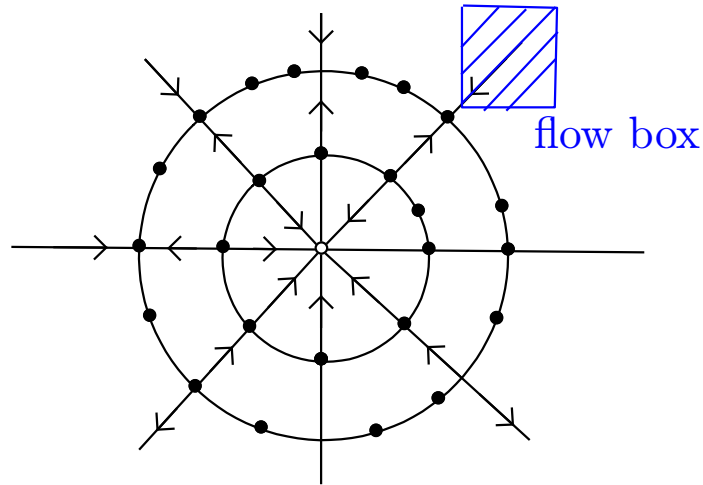
Example 2:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)$$



Example 2:

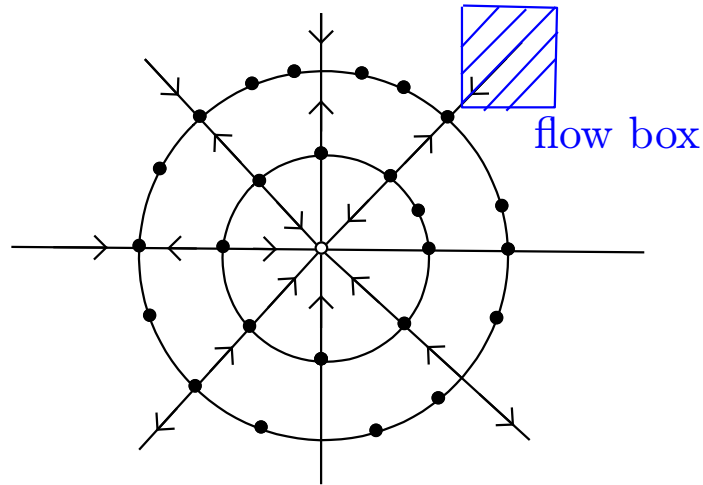
$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)$$



In these examples, $\text{Sing}(\mathcal{F})$ is a codimension one analytic subset.

Example 2:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)$$

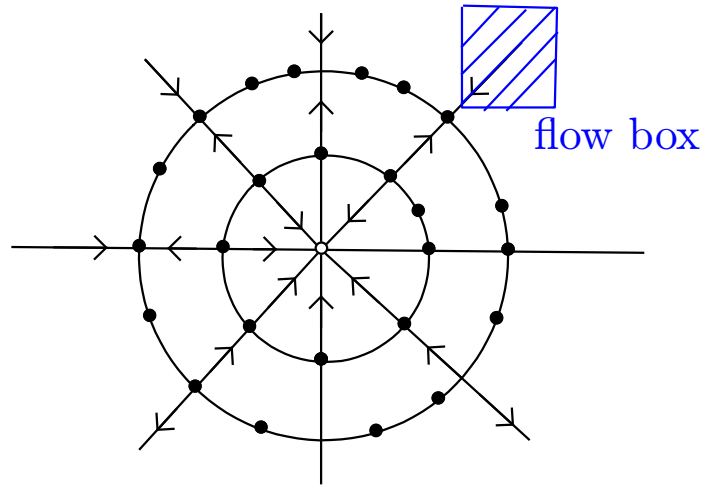


In these examples, $\text{Sing}(\mathcal{F})$ is a codimension one analytic subset.

We could potentially consider the so-called **saturated** foliation \mathcal{F}^{sat} , defined by $\frac{1}{f} \partial$

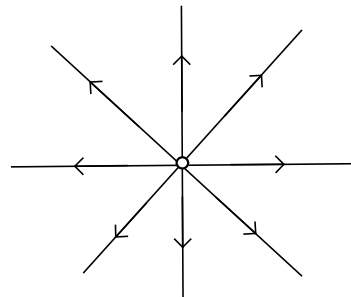
Example 2:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right)$$



In these examples, $\text{Sing}(\mathcal{F})$ is a codimension one analytic subset.

We could potentially consider the so-called **saturated** foliation \mathcal{F}^{sat} , defined by $\frac{1}{f} \partial$



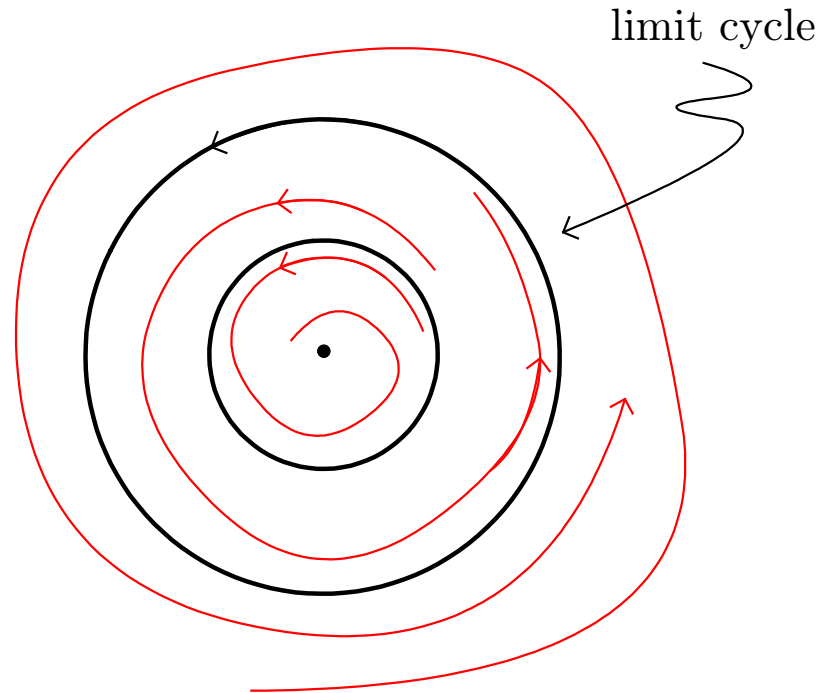
Example 3:

Example 3:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) + \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right)$$

Example 3:

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) + \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right)$$



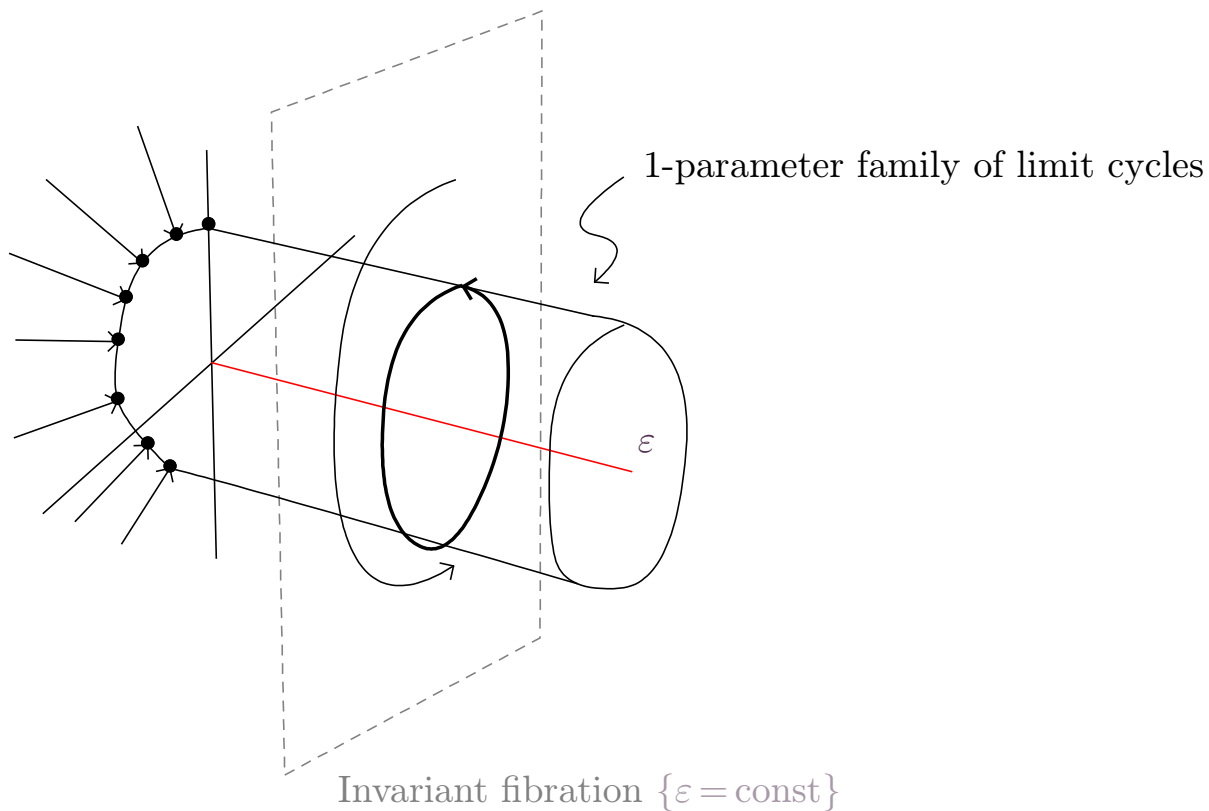
Example 4: (“singular perturbation problems”) \mathbb{R}^3 with coordinates (x, y, ε)

Example 4: (“singular perturbation problems”) \mathbb{R}^3 with coordinates (x, y, ε)

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) + \varepsilon \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right)$$

Example 4: (“singular perturbation problems”) \mathbb{R}^3 with coordinates (x, y, ε)

$$\partial = f(x^2 + y^2) \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) + \varepsilon \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right)$$



Basic goals (in decreasing degrees of ambition)

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically

Basic goals (in decreasing degrees of ambition)

1) Classify foliations analytically

2) Classify foliations C^k or topologically

Basic goals (in decreasing degrees of ambition)

1) Classify foliations analytically

2) Classify foliations C^k or topologically

3) Determine the asymptotic behaviour of a typical leaf.

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically
- 2) Classify foliations C^k or topologically
- 3) Determine the asymptotic behaviour of a typical leaf.
- 4) Obtain statistical information: e.g. invariant/ergodic transverse measures.

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically
- 2) Classify foliations C^k or topologically
- 3) Determine the asymptotic behaviour of a typical leaf.
- 4) Obtain statistical information: e.g. invariant/ergodic transverse measures.

Local description: The foliation is locally trivial on $M \setminus \text{Sing}(\mathcal{F})$.

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically
- 2) Classify foliations C^k or topologically
- 3) Determine the asymptotic behaviour of a typical leaf.
- 4) Obtain statistical information: e.g. invariant/ergodic transverse measures.

Local description: The foliation is locally trivial on $M \setminus \text{Sing}(\mathcal{F})$.

We would like to understand the foliation in the **vicinity** of its singular points.

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically
- 2) Classify foliations C^k or topologically
- 3) Determine the asymptotic behaviour of a typical leaf.
- 4) Obtain statistical information: e.g. invariant/ergodic transverse measures.

Local description: The foliation is locally trivial on $M \setminus \text{Sing}(\mathcal{F})$.

We would like to understand the foliation in the **vicinity** of its singular points.

Thom: *The singularities are the **organizing centers** of the dynamics .*

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically
- 2) Classify foliations C^k or topologically
- 3) Determine the asymptotic behaviour of a typical leaf.
- 4) Obtain statistical information: e.g. invariant/ergodic transverse measures.

Local description: The foliation is locally trivial on $M \setminus \text{Sing}(\mathcal{F})$.

We would like to understand the foliation in the **vicinity** of its singular points.

Thom: *The singularities are the **organizing centers** of the dynamics .*

As a first step, we would like to describe the transverse behaviour of the foliation by looking at its so-called

Basic goals (in decreasing degrees of ambition)

- 1) Classify foliations analytically
- 2) Classify foliations C^k or topologically
- 3) Determine the asymptotic behaviour of a typical leaf.
- 4) Obtain statistical information: e.g. invariant/ergodic transverse measures.

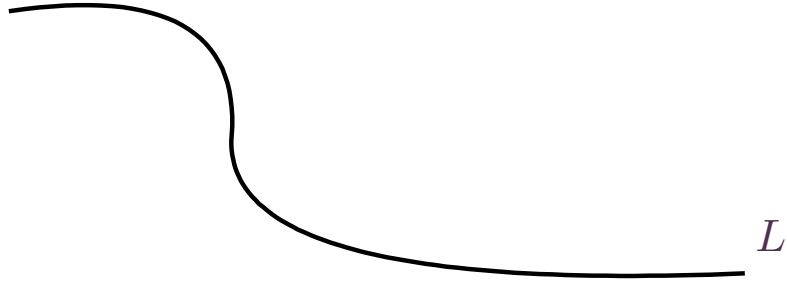
Local description: The foliation is locally trivial on $M \setminus \text{Sing}(\mathcal{F})$.

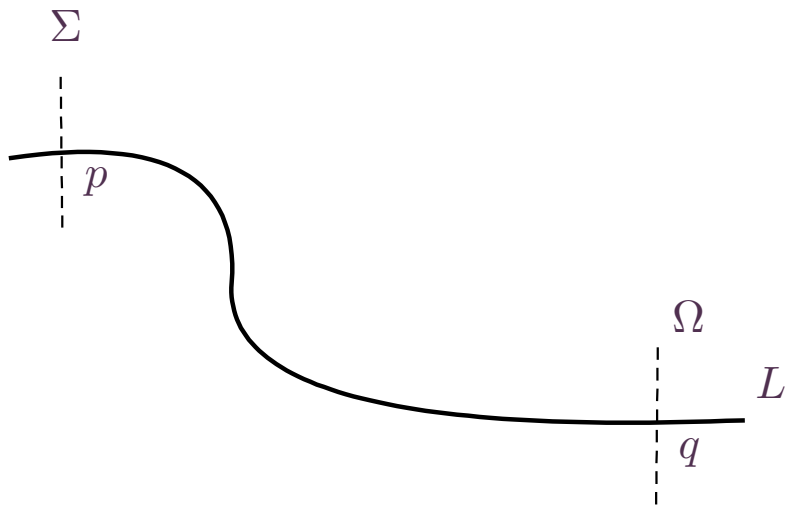
We would like to understand the foliation in the **vicinity** of its singular points.

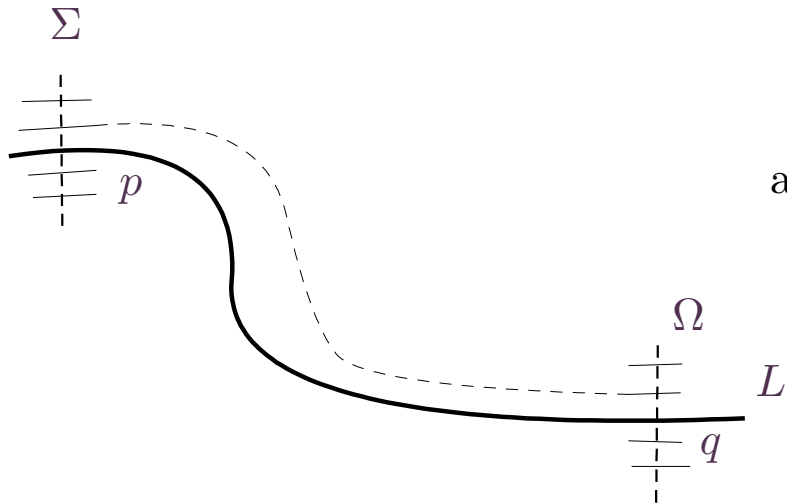
Thom: *The singularities are the **organizing centers** of the dynamics .*

As a first step, we would like to describe the transverse behaviour of the foliation by looking at its so-called

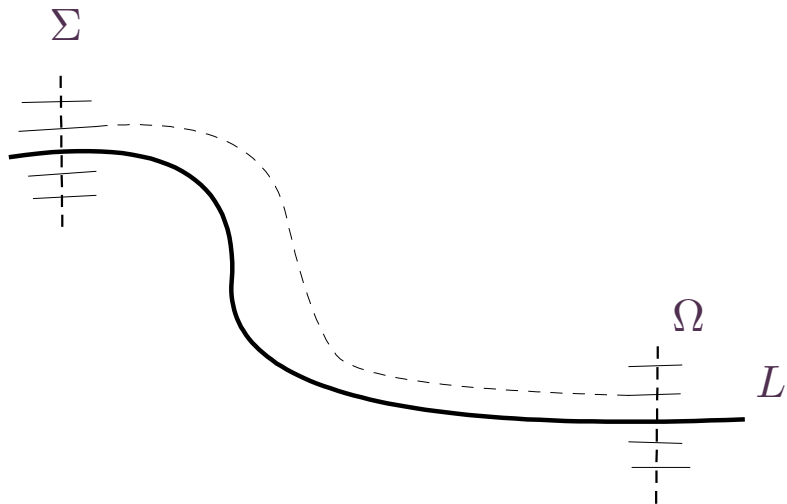
Holonomy Groupoid







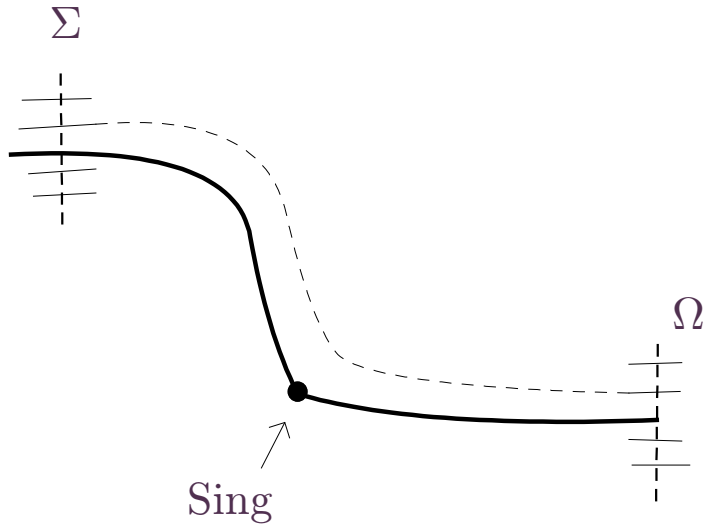
any path $p \rightarrow q$ on L can be lifted to nearby leafs



$$\text{hol}: (\Sigma, p) \rightarrow (\Omega, q)$$

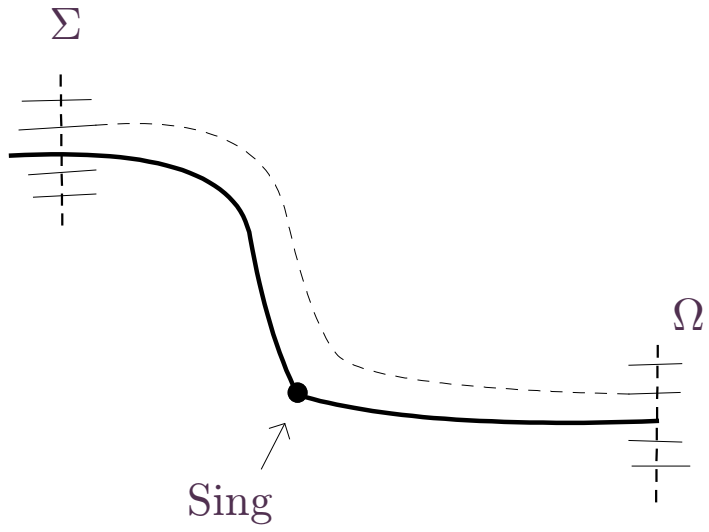
$$\text{hol} \in \text{Diff}^\omega(\Sigma \rightarrow \Omega)$$

Adding a singularity on the path...



$\text{hol} \notin \text{Diff}^\omega(\Sigma, \Omega)$

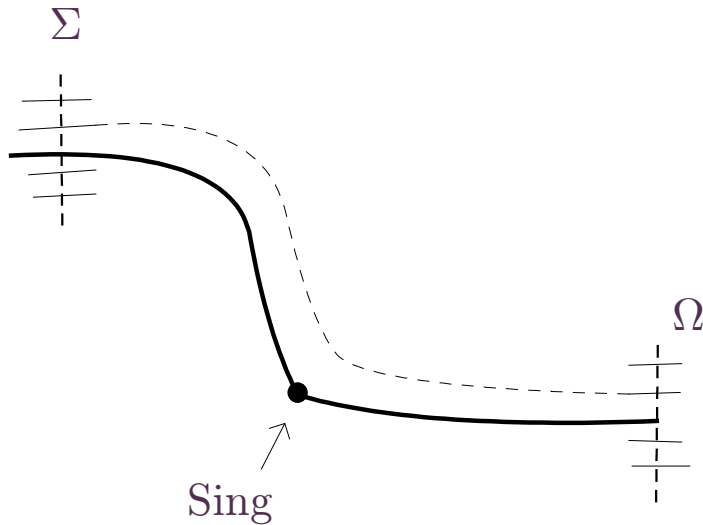
Adding a singularity on the path...



$\text{hol} \notin \text{Diff}^\omega(\Sigma, \Omega)$

In general, there is an intrinsic **multivaluedness** for such map.

Adding a singularity on the path...

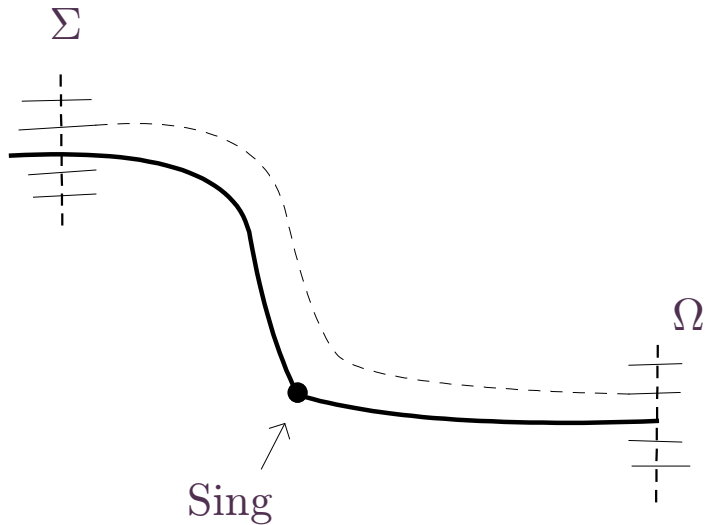


$\text{hol} \notin \text{Diff}^\omega(\Sigma, \Omega)$

In general, there is an intrinsic **multivaluedness** for such map.

This is a very well-studied problem for foliations in surfaces.

Adding a singularity on the path...



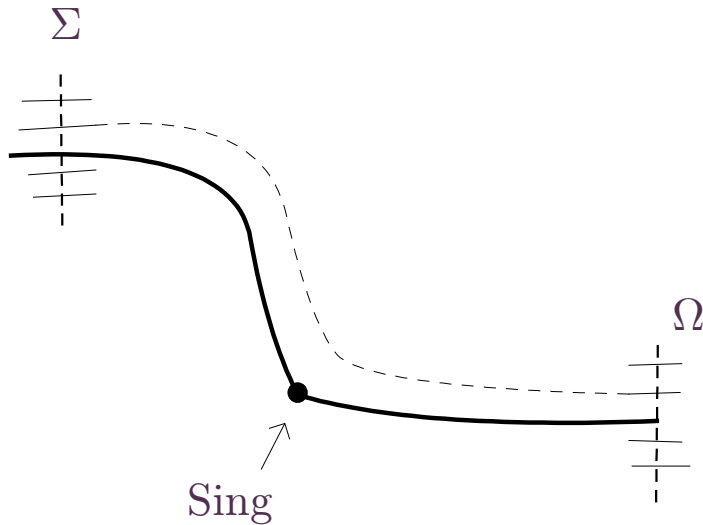
$\text{hol} \notin \text{Diff}^\omega(\Sigma, \Omega)$

In general, there is an intrinsic **multivaluedness** for such map.

This is a very well-studied problem for foliations in surfaces.

It is in the heart of the Hilbert's XVIth's problem.

Adding a singularity on the path...



$\text{hol} \notin \text{Diff}^\omega(\Sigma, \Omega)$

In general, there is an intrinsic **multivaluedness** for such map.

This is a very well-studied problem for foliations in surfaces.

It is in the heart of the Hilbert's XVIth's problem.

(see the course of Patrick...)

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Namely, in local coordinates $x = (x_1, \dots, x_n)$ we can write

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Namely, in local coordinates $x = (x_1, \dots, x_n)$ we can write

$$\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$$

with $a_1, \dots, a_n \in \mathcal{O}$ and ∂ defines a linear \mathbb{C} -endomorphism of \mathcal{O} by

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Namely, in local coordinates $x = (x_1, \dots, x_n)$ we can write

$$\partial = a_1 \frac{\partial}{\partial x_1} + \cdots + a_n \frac{\partial}{\partial x_n}$$

with $a_1, \dots, a_n \in \mathcal{O}$ and ∂ defines a linear \mathbb{C} -endomorphism of \mathcal{O} by

$$f \longmapsto \partial f = a_1 \frac{\partial f}{\partial x_1} + \cdots + a_n \frac{\partial f}{\partial x_n}$$

which moreover satisfies the Leibniz rule $\partial(fg) = (\partial f)g + f(\partial g)$. We note $\partial \in \text{Der}(\mathcal{O})$.

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Namely, in local coordinates $x = (x_1, \dots, x_n)$ we can write

$$\partial = a_1 \frac{\partial}{\partial x_1} + \cdots + a_n \frac{\partial}{\partial x_n}$$

with $a_1, \dots, a_n \in \mathcal{O}$ and ∂ defines a linear \mathbb{C} -endomorphism of \mathcal{O} by

$$f \longmapsto \partial f = a_1 \frac{\partial f}{\partial x_1} + \cdots + a_n \frac{\partial f}{\partial x_n}$$

which moreover satisfies the Leibniz rule $\partial(fg) = (\partial f)g + f(\partial g)$. We note $\partial \in \text{Der}(\mathcal{O})$.

The germ is **singular** if a_1, \dots, a_n vanish at p (i.e. $a_1, \dots, a_n \in \mathfrak{m}$)

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Namely, in local coordinates $x = (x_1, \dots, x_n)$ we can write

$$\partial = a_1 \frac{\partial}{\partial x_1} + \cdots + a_n \frac{\partial}{\partial x_n}$$

with $a_1, \dots, a_n \in \mathcal{O}$ and ∂ defines a linear \mathbb{C} -endomorphism of \mathcal{O} by

$$f \longmapsto \partial f = a_1 \frac{\partial f}{\partial x_1} + \cdots + a_n \frac{\partial f}{\partial x_n}$$

which moreover satisfies the Leibniz rule $\partial(fg) = (\partial f)g + f(\partial g)$. We note $\partial \in \text{Der}(\mathcal{O})$.

The germ is **singular** if a_1, \dots, a_n vanish at p (i.e. $a_1, \dots, a_n \in \mathfrak{m}$)

This is equivalent to require that

$$\partial(\mathfrak{m}) \subset \mathfrak{m}, \quad \text{where } \mathfrak{m} = (x_1, \dots, x_n)\mathcal{O}$$

Elementary germs - and some words about classical normal forms... (over \mathbb{C})

A germ of vector field ∂ at $p \in M$ defines a derivation of the local ring $(\mathcal{O}, \mathfrak{m}) = (\mathcal{O}_p, \mathfrak{m}_p)$.

Namely, in local coordinates $x = (x_1, \dots, x_n)$ we can write

$$\partial = a_1 \frac{\partial}{\partial x_1} + \cdots + a_n \frac{\partial}{\partial x_n}$$

with $a_1, \dots, a_n \in \mathcal{O}$ and ∂ defines a linear \mathbb{C} -endomorphism of \mathcal{O} by

$$f \longmapsto \partial f = a_1 \frac{\partial f}{\partial x_1} + \cdots + a_n \frac{\partial f}{\partial x_n}$$

which moreover satisfies the Leibniz rule $\partial(fg) = (\partial f)g + f(\partial g)$. We note $\partial \in \text{Der}(\mathcal{O})$.

The germ is **singular** if a_1, \dots, a_n vanish at p (i.e. $a_1, \dots, a_n \in \mathfrak{m}$)

This is equivalent to require that

$$\partial(\mathfrak{m}) \subset \mathfrak{m}, \quad \text{where } \mathfrak{m} = (x_1, \dots, x_n)\mathcal{O}$$

(i.e. that $\partial \in \text{End}_{\mathbb{C}}(\mathcal{O})$ stabilizes the maximal ideal)

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Proof. Choose a local coordinate $f \in \mathfrak{m}$ such that $\partial f = u$ (unit).

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Proof. Choose a local coordinate $f \in \mathfrak{m}$ such that $\partial f = u$ (unit).

Let us assume that $u = 1$ to simplify.

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Proof. Choose a local coordinate $f \in \mathfrak{m}$ such that $\partial f = u$ (unit).

Let us assume that $u = 1$ to simplify.

We complete f to a local system of coordinates (f, g_1, \dots, g_{n-1}) ,

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Proof. Choose a local coordinate $f \in \mathfrak{m}$ such that $\partial f = u$ (unit).

Let us assume that $u = 1$ to simplify.

We complete f to a local system of coordinates (f, g_1, \dots, g_{n-1}) ,

and consider the linear operator $\mathcal{O} \rightarrow \mathcal{O}$ given by

$$\Phi = I - f\partial + \dots + (-1)^n \frac{f^n}{n!} \partial^n + \dots$$

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Proof. Choose a local coordinate $f \in \mathfrak{m}$ such that $\partial f = u$ (unit).

Let us assume that $u = 1$ to simplify.

We complete f to a local system of coordinates (f, g_1, \dots, g_{n-1}) ,

and consider the linear operator $\mathcal{O} \rightarrow \mathcal{O}$ given by

$$\Phi = I - f\partial + \dots + (-1)^n \frac{f^n}{n!} \partial^n + \dots$$

Notice that, for all $h \in \mathcal{O}$,

$$\partial(\Phi h) = \partial \sum_{n \geq 0} (-1)^n \frac{f^n}{n!} \partial^n h = 0$$

Non-singular case: Assume that $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Flow-box Theorem Then, there exists local analytic coordinates (f, g_1, \dots, g_{n-1}) such that

$$\partial f = 1 \quad \text{and} \quad \partial g_1 = \dots = \partial g_{n-1} = 0$$

i.e. $\partial = \frac{\partial}{\partial f}$.

Proof. Choose a local coordinate $f \in \mathfrak{m}$ such that $\partial f = u$ (unit).

Let us assume that $u = 1$ to simplify.

We complete f to a local system of coordinates (f, g_1, \dots, g_{n-1}) ,

and consider the linear operator $\mathcal{O} \rightarrow \mathcal{O}$ given by

$$\Phi = I - f\partial + \dots + (-1)^n \frac{f^n}{n!} \partial^n + \dots$$

Notice that, for all $h \in \mathcal{O}$,

$$\partial(\Phi h) = \partial \sum_{n \geq 0} (-1)^n \frac{f^n}{n!} \partial^n h = 0$$

Therefore $f, \Phi(g_1), \dots, \Phi(g_{n-1})$ is the required new coordinate system.

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

which is compatible with projections $\pi_{kl}: J^k \rightarrow J^l$ ($k > l$).

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

which is compatible with projections $\pi_{kl}: J^k \rightarrow J^l$ ($k > l$).

By considering the inverse limit (under Krull completion), of the classical Jordan decompositions of the finite dimensional endomorphisms ∂_k , we obtain a unique **Jordan decomposition**

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

which is compatible with projections $\pi_{kl}: J^k \rightarrow J^l$ ($k > l$).

By considering the inverse limit (under Krull completion), of the classical Jordan decompositions of the finite dimensional endomorphisms ∂_k , we obtain a unique **Jordan decomposition**

$$\partial = \partial_s + \partial_n, \quad [\partial_s, \partial_n] = 0$$

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

which is compatible with projections $\pi_{kl}: J^k \rightarrow J^l$ ($k > l$).

By considering the inverse limit (under Krull completion), of the classical Jordan decompositions of the finite dimensional endomorphisms ∂_k , we obtain a unique **Jordan decomposition**

$$\partial = \partial_s + \partial_n, \quad [\partial_s, \partial_n] = 0$$

where

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

which is compatible with projections $\pi_{kl}: J^k \rightarrow J^l$ ($k > l$).

By considering the inverse limit (under Krull completion), of the classical Jordan decompositions of the finite dimensional endomorphisms ∂_k , we obtain a unique **Jordan decomposition**

$$\partial = \partial_s + \partial_n, \quad [\partial_s, \partial_n] = 0$$

where

- ∂_s is semi-simple
- ∂_n is asymptotically nilpotent (i.e. nilpotent restricted to each jet space).

Singular case: Assume that now that $\partial(\mathfrak{m}) \subset \mathfrak{m}$.

Then, (by Leibniz' rule) $\partial(\mathfrak{m}^{k+1}) \subset \mathfrak{m}^{k+1}$ for each $k \in \mathbb{N}$, and ∂ induces an sequence of endomorphism $\{\partial_k\}_k$ on the jet spaces

$$J^k = \mathcal{O} / \mathfrak{m}^{k+1}$$

which is compatible with projections $\pi_{kl}: J^k \rightarrow J^l$ ($k > l$).

By considering the inverse limit (under Krull completion), of the classical Jordan decompositions of the finite dimensional endomorphisms ∂_k , we obtain a unique **Jordan decomposition**

$$\partial = \partial_s + \partial_n, \quad [\partial_s, \partial_n] = 0$$

where

- ∂_s is semi-simple
- ∂_n is asymptotically nilpotent (i.e. nilpotent restricted to each jet space).

Moreover, ∂_s and ∂_n are derivations of $\hat{\mathcal{O}} = \varprojlim J^k$ (see Jean Martinet - Exposé Bourbaki'81).

By the semi-simplicity of ∂_s , we have direct sum decompositions

$$\forall k \in \mathbb{N}: \quad J^k = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_{\alpha}(J^k, \partial_s)$$

By the semi-simplicity of ∂_s , we have direct sum decompositions

$$\forall k \in \mathbb{N}: \quad J^k = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_\alpha(J^k, \partial_s)$$

where $\text{Gr}_\alpha(J^k, \partial) = \{f \in J^k \mid \partial f = \alpha f\}$.

By the semi-simplicity of ∂_s , we have direct sum decompositions

$$\forall k \in \mathbb{N}: \quad J^k = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_\alpha(J^k, \partial_s)$$

where $\text{Gr}_\alpha(J^k, \partial) = \{f \in J^k \mid \partial f = \alpha f\}$.

with the compatibility condition

By the semi-simplicity of ∂_s , we have direct sum decompositions

$$\forall k \in \mathbb{N}: \quad J^k = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_\alpha(J^k, \partial_s)$$

where $\text{Gr}_\alpha(J^k, \partial) = \{f \in J^k \mid \partial f = \alpha f\}$.

with the compatibility condition

$$\forall k > l: \quad \pi_{kl}(\text{Gr}_\alpha(J^k, \partial_s)) = \text{Gr}_\alpha(J^l, \partial_s)$$

derived from the commutative diagram

By the semi-simplicity of ∂_s , we have direct sum decompositions

$$\forall k \in \mathbb{N}: \quad J^k = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_\alpha(J^k, \partial_s)$$

where $\text{Gr}_\alpha(J^k, \partial) = \{f \in J^k \mid \partial f = \alpha f\}$.

with the compatibility condition

$$\forall k > l: \quad \pi_{kl}(\text{Gr}_\alpha(J^k, \partial_s)) = \text{Gr}_\alpha(J^l, \partial_s)$$

derived from the commutative diagram

$$\begin{array}{ccc} J^k & \xrightarrow{\partial_k} & J^k \\ \pi_{k,k-1} \downarrow & & \downarrow \pi_{k,k-1} \\ J^{k-1} & \xrightarrow{\partial_{k-1}} & J^{k-1} \end{array}$$

Definition. A germ of vector field ∂ is *elementary* if:

Definition. A germ of vector field ∂ is *elementary* if:

- either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ (i.e. in appropriate local coordinates $\partial = \frac{\partial}{\partial x}$)

Definition. A germ of vector field ∂ is *elementary* if:

- either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ (i.e. in appropriate local coordinates $\partial = \frac{\partial}{\partial x}$)
- Or $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and

Definition. A germ of vector field ∂ is *elementary* if:

- either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ (i.e. in appropriate local coordinates $\partial = \frac{\partial}{\partial x}$)
- Or $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and

$$\partial_s \neq 0$$

Definition. A germ of vector field ∂ is *elementary* if:

- either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ (i.e. in appropriate local coordinates $\partial = \frac{\partial}{\partial x}$)
- Or $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and

$$\partial_s \neq 0$$

Poincaré-Dulac normalisation: (over \mathbb{C}) Suppose that $\partial(\mathfrak{m}) \subset \mathfrak{m}$. Then, there exists formal coordinates (x_1, \dots, x_n) which diagonalize the semi-simple part of ∂ , namely such that

$$\partial_s = \sum_i \lambda_i x_i \frac{\partial}{\partial x_i}$$

Definition. A germ of vector field ∂ is *elementary* if:

- either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ (i.e. in appropriate local coordinates $\partial = \frac{\partial}{\partial x}$)
- Or $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and

$$\partial_s \neq 0$$

Poincaré-Dulac normalisation: (over \mathbb{C}) Suppose that $\partial(\mathfrak{m}) \subset \mathfrak{m}$. Then, there exists formal coordinates (x_1, \dots, x_n) which diagonalize the semi-simple part of ∂ , namely such that

$$\partial_s = \sum_i \lambda_i x_i \frac{\partial}{\partial x_i}$$

In these coordinates, each eigenspace of the direct sum decomposition

$$\hat{\mathcal{O}} = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_{\alpha}(\hat{\mathcal{O}}, \partial_s)$$

Definition. A germ of vector field ∂ is *elementary* if:

- either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ (i.e. in appropriate local coordinates $\partial = \frac{\partial}{\partial x}$)
- Or $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and

$$\partial_s \neq 0$$

Poincaré-Dulac normalisation: (over \mathbb{C}) Suppose that $\partial(\mathfrak{m}) \subset \mathfrak{m}$. Then, there exists formal coordinates (x_1, \dots, x_n) which diagonalize the semi-simple part of ∂ , namely such that

$$\partial_s = \sum_i \lambda_i x_i \frac{\partial}{\partial x_i}$$

In these coordinates, each eigenspace of the direct sum decomposition

$$\hat{\mathcal{O}} = \bigoplus_{\alpha \in \mathbb{C}} \text{Gr}_{\alpha}(\hat{\mathcal{O}}, \partial_s)$$

is generated (over \mathbb{C}) by the monomials $x^k = x_1^{k_1} \dots x_n^{k_n}$ such that $\langle k, \lambda \rangle = \alpha$.

What can we say about ∂_n ?

What can we say about ∂_n ?

The set of diagonal vector fields

$$L(\mu) = \sum_{i=1}^n \mu_i x_i \frac{\partial}{\partial x_i}, \quad \mu \in \mathbb{C}^n$$

forms an abelian Lie \mathbb{C} -subalgebra, i.e. $[L(\mu), L(\lambda)] = 0$.

What can we say about ∂_n ?

The set of diagonal vector fields

$$L(\mu) = \sum_{i=1}^n \mu_i x_i \frac{\partial}{\partial x_i}, \quad \mu \in \mathbb{C}^n$$

forms an abelian Lie \mathbb{C} -subalgebra, i.e. $[L(\mu), L(\lambda)] = 0$.

We say that it is a **maximal toral subalgebra** of $\text{Der}(\mathcal{O})$.

What can we say about ∂_n ?

The set of diagonal vector fields

$$L(\mu) = \sum_{i=1}^n \mu_i x_i \frac{\partial}{\partial x_i}, \quad \mu \in \mathbb{C}^n$$

forms an abelian Lie \mathbb{C} -subalgebra, i.e. $[L(\mu), L(\lambda)] = 0$.

We say that it is a **maximal toral subalgebra** of $\text{Der}(\mathcal{O})$.

Writing $\partial = \partial_s + \partial_n$, and assuming $\partial_s = L(\lambda)$ (as in the Theorem), the commutativity relation

$$[\partial_s, \partial_n] = 0$$

implies that ∂_n can be expanded as

$$\partial_n = \sum_k x^k L(\mu_k)$$

What can we say about ∂_n ?

The set of diagonal vector fields

$$L(\mu) = \sum_{i=1}^n \mu_i x_i \frac{\partial}{\partial x_i}, \quad \mu \in \mathbb{C}^n$$

forms an abelian Lie \mathbb{C} -subalgebra, i.e. $[L(\mu), L(\lambda)] = 0$.

We say that it is a **maximal toral subalgebra** of $\text{Der}(\mathcal{O})$.

Writing $\partial = \partial_s + \partial_n$, and assuming $\partial_s = L(\lambda)$ (as in the Theorem), the commutativity relation

$$[\partial_s, \partial_n] = 0$$

implies that ∂_n can be expanded as

$$\partial_n = \sum_k x^k L(\mu_k)$$

where k ranges over the subset $\mathbb{Z}^n \setminus \{0\}$ such that $\langle \lambda, k \rangle = 0$. These are the **resonant monomials**.

Example. (1:1) saddle. Consider a vector field having an initial expansion (in arbitrary coordinates)

Example. (1:1) saddle. Consider a vector field having an initial expansion (in arbitrary coordinates)

$$\partial = (x + \dots) \frac{\partial}{\partial x} - (y + \dots) \frac{\partial}{\partial y}$$

Then, $\text{Spec}(\partial|_{J^1}) = \{1, -1\}$ and the resonant monomials are $(xy)^k$, $k \in \mathbb{Z}$.

Example. (1:1) saddle. Consider a vector field having an initial expansion (in arbitrary coordinates)

$$\partial = (x + \dots) \frac{\partial}{\partial x} - (y + \dots) \frac{\partial}{\partial y}$$

Then, $\text{Spec}(\partial|_{J^1}) = \{1, -1\}$ and the resonant monomials are $(xy)^k$, $k \in \mathbb{Z}$.

The Poincaré-Dulac Theorem says that, up to a formal change of coordinates, we can write

$$\partial = \underbrace{\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right)}_{\partial_s} + \underbrace{\sum_{k \geq 1} (xy)^k \left(a_k x \frac{\partial}{\partial x} + b_k y \frac{\partial}{\partial y} \right)}_{\partial_n}$$

where $u = xy$ is the generator of the subring $\ker(\partial_s)$. By further reductions, we can write

$$(1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right) \quad \text{or} \quad (1 + F) \left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right)$$

for some $F \in \mathbb{C}[[u]]$ of order ≥ 1 , $n \geq 1$ and $\rho \in \mathbb{C}$.

Application: Integrability of Poincaré-Dulac normal forms

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Consider the new variables $u = xy$, $v = x/y$ and get

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Consider the new variables $u = xy$, $v = x/y$ and get

$$\partial(u) = 2 \frac{u^{n+1}}{1 + \rho u^n}, \quad \partial(v) = 2v$$

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Consider the new variables $u = xy$, $v = x/y$ and get

$$\partial(u) = 2 \frac{u^{n+1}}{1 + \rho u^n}, \quad \partial(v) = 2v$$

which is a fully integrable system.

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Consider the new variables $u = xy$, $v = x/y$ and get

$$\partial(u) = 2 \frac{u^{n+1}}{1 + \rho u^n}, \quad \partial(v) = 2v$$

which is a fully integrable system.

The corresponding differential system is given by

$$\left(\frac{1}{u^{n+1}} + \rho \frac{1}{u} \right) du = \frac{dv}{v}$$

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Consider the new variables $u = xy$, $v = x/y$ and get

$$\partial(u) = 2 \frac{u^{n+1}}{1 + \rho u^n}, \quad \partial(v) = 2v$$

which is a fully integrable system.

The corresponding differential system is given by

$$\left(\frac{1}{u^{n+1}} + \rho \frac{1}{u} \right) du = \frac{dv}{v}$$

and, by direct integration,

$$I = \frac{1}{nu^n} + \rho \ln u - \ln v$$

Application: Integrability of Poincaré-Dulac normal forms

$$\partial = (1 + F) \left(\left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) + \frac{u^n}{1 + \rho u^n} \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \right)$$

Up to *reparametrization of time*, we can assume that $F = 0$.

Consider the new variables $u = xy$, $v = x/y$ and get

$$\partial(u) = 2 \frac{u^{n+1}}{1 + \rho u^n}, \quad \partial(v) = 2v$$

which is a fully integrable system.

The corresponding differential system is given by

$$\left(\frac{1}{u^{n+1}} + \rho \frac{1}{u} \right) du = \frac{dv}{v}$$

and, by direct integration,

$$I = \frac{1}{n u^n} + \rho \ln u - \ln v$$

is a first integral of the vector field (namely, $\partial I = 0$). It is an element of $\mathbb{R}_{\text{an,exp}}$.

Example: $(\lambda: \mu)$ -saddle.

Example: $(\lambda: \mu)$ -saddle.

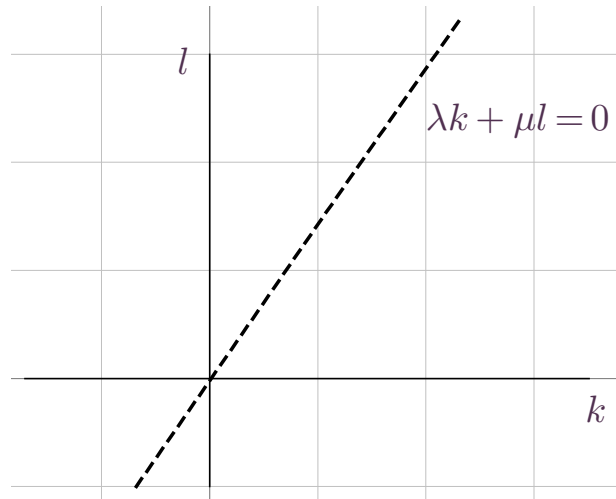
$$\partial = (\lambda x + \dots) \frac{\partial}{\partial x} - (\mu y + \dots) \frac{\partial}{\partial y}$$

Then, $\text{Spec}(\partial|_{J^1}) = \{\lambda, -\mu\}$

Example: $(\lambda: \mu)$ -saddle.

$$\partial = (\lambda x + \dots) \frac{\partial}{\partial x} - (\mu y + \dots) \frac{\partial}{\partial y}$$

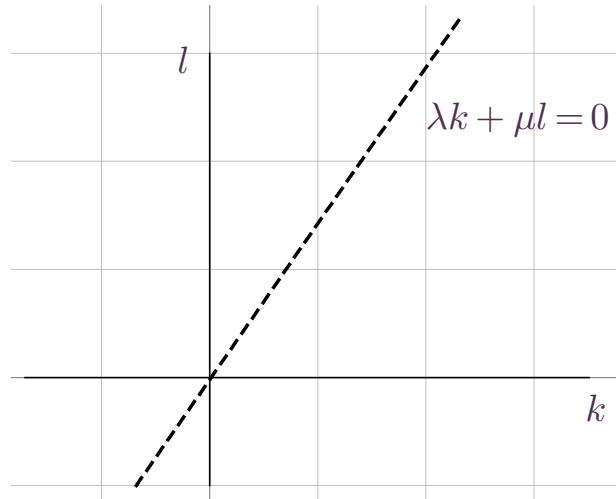
Then, $\text{Spec}(\partial|_{J^1}) = \{\lambda, -\mu\}$



Example: $(\lambda: \mu)$ -saddle.

$$\partial = (\lambda x + \dots) \frac{\partial}{\partial x} - (\mu y + \dots) \frac{\partial}{\partial y}$$

Then, $\text{Spec}(\partial|_{J^1}) = \{\lambda, -\mu\}$



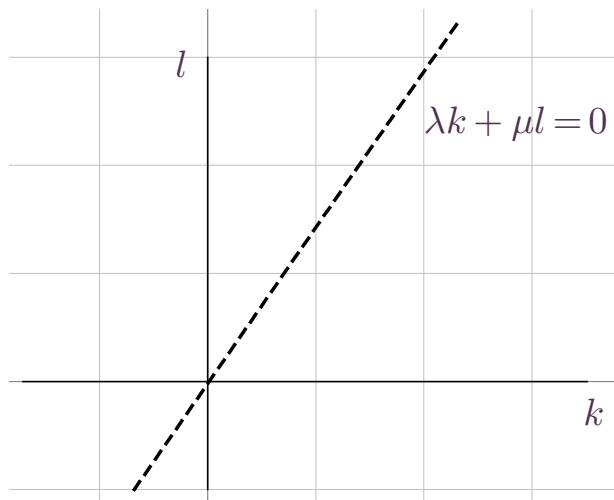
If $\lambda/\mu \notin \mathbb{Q}$ then the Poincaré-Dulac normal form is

$$\partial = \lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y}$$

Example: $(\lambda: \mu)$ -saddle.

$$\partial = (\lambda x + \dots) \frac{\partial}{\partial x} - (\mu y + \dots) \frac{\partial}{\partial y}$$

Then, $\text{Spec}(\partial|_{J^1}) = \{\lambda, -\mu\}$



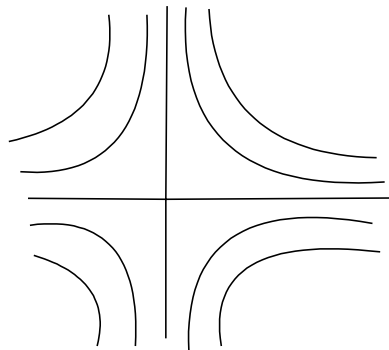
If $\lambda/\mu \notin \mathbb{Q}$ then the Poincaré-Dulac normal form is

$$\partial = \lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y}$$

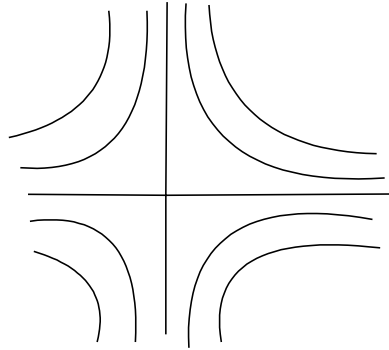
and the first integral is simply $I = x^\mu y^\lambda$.

Two saddles $(\lambda: \mu)$ and $(\lambda': \mu')$ have exactly the same topological phase portrait over \mathbb{R}^2

Two saddles $(\lambda: \mu)$ and $(\lambda': \mu')$ have exactly the same topological phase portrait over \mathbb{R}^2

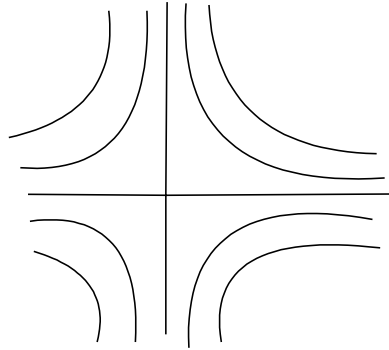


Two saddles $(\lambda: \mu)$ and $(\lambda': \mu')$ have exactly the same topological phase portrait over \mathbb{R}^2

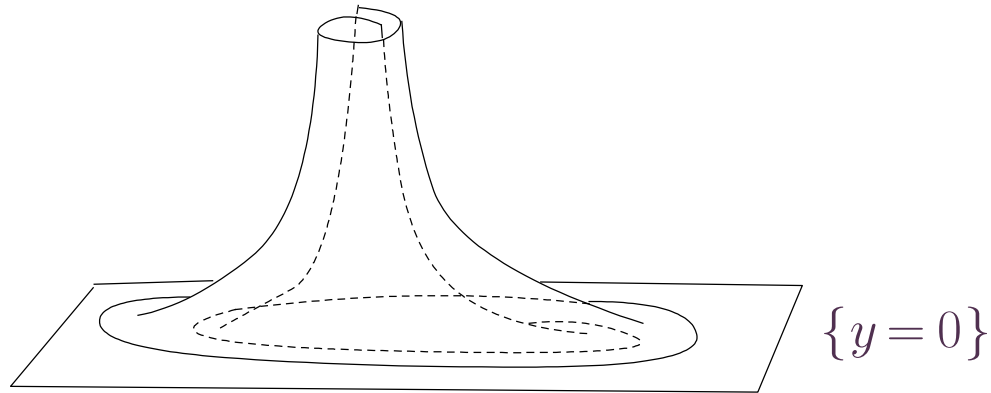


but they are completely different over \mathbb{C}^2 for $\lambda/\mu \neq \lambda'/\mu'$.

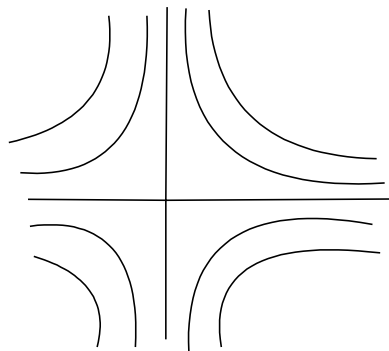
Two saddles $(\lambda: \mu)$ and $(\lambda': \mu')$ have exactly the same topological phase portrait over \mathbb{R}^2



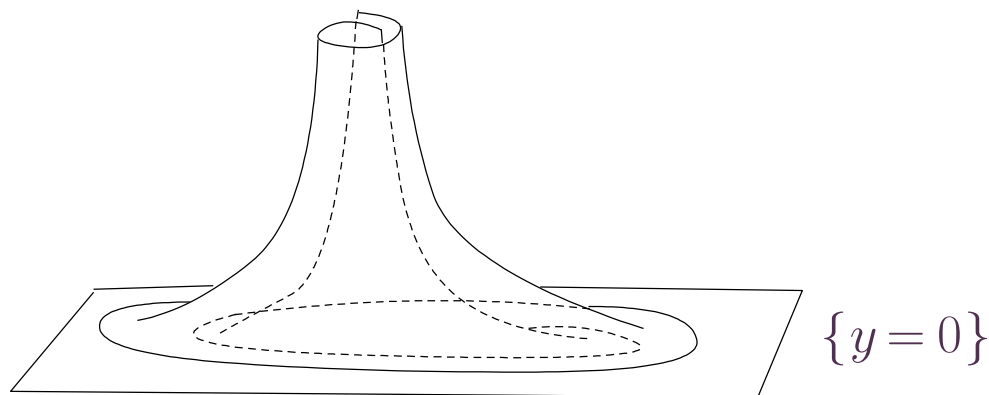
but they are completely different over \mathbb{C}^2 for $\lambda/\mu \neq \lambda'/\mu'$.



Two saddles $(\lambda: \mu)$ and $(\lambda': \mu')$ have exactly the same topological phase portrait over \mathbb{R}^2

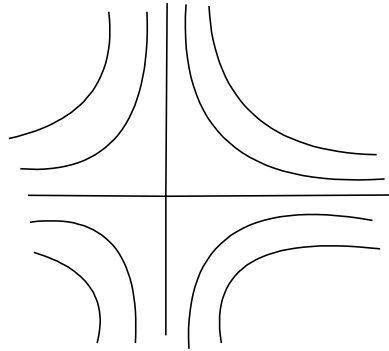


but they are completely different over \mathbb{C}^2 for $\lambda/\mu \neq \lambda'/\mu'$.

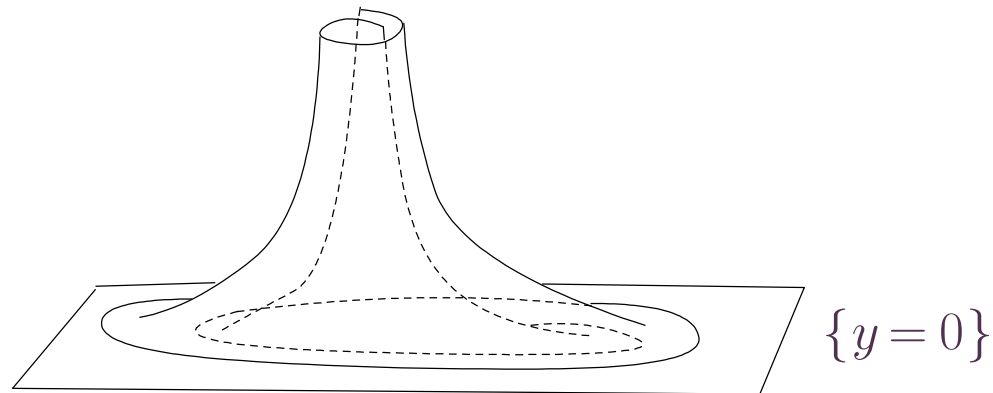


Over \mathbb{C}^2 : There are several **rigidity phenomena**

Two saddles $(\lambda: \mu)$ and $(\lambda': \mu')$ have exactly the same topological phase portrait over \mathbb{R}^2



but they are completely different over \mathbb{C}^2 for $\lambda/\mu \neq \lambda'/\mu'$.



Over \mathbb{C}^2 : There are several **rigidity phenomena**

E.g. Some analytic invariants are topologically determined (for instance, linearizability).

Transverse behaviour of the foliation in the vicinity of a saddle point.

Transverse behaviour of the foliation in the vicinity of a saddle point.

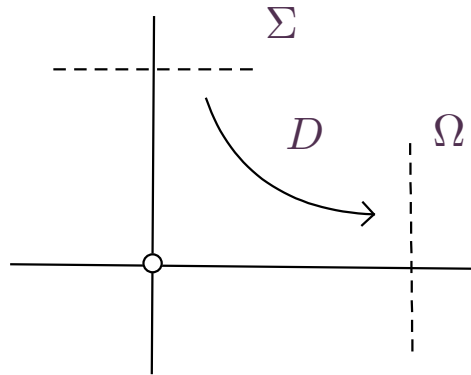
There are two holonomy maps of interest:

1)

Transverse behaviour of the foliation in the vicinity of a saddle point.

There are two holonomy maps of interest:

1)



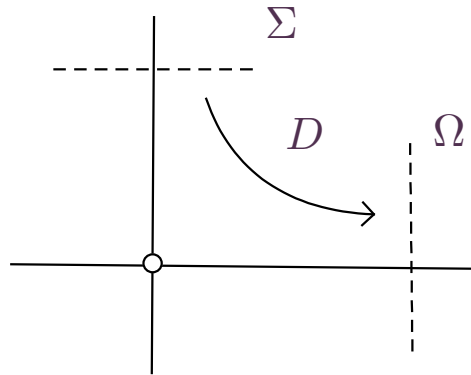
Corner transition map

2) In the complex setting...

Transverse behaviour of the foliation in the vicinity of a saddle point.

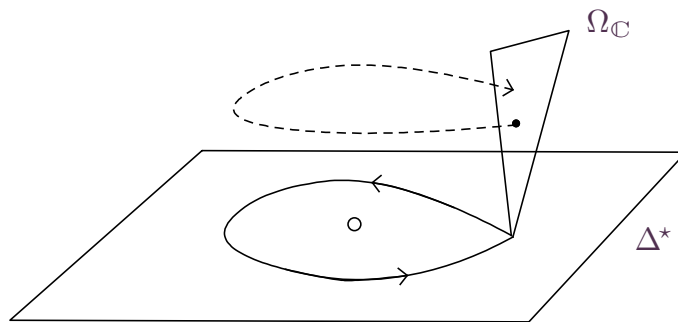
There are two holonomy maps of interest:

1)



Corner transition map

2) In the complex setting...

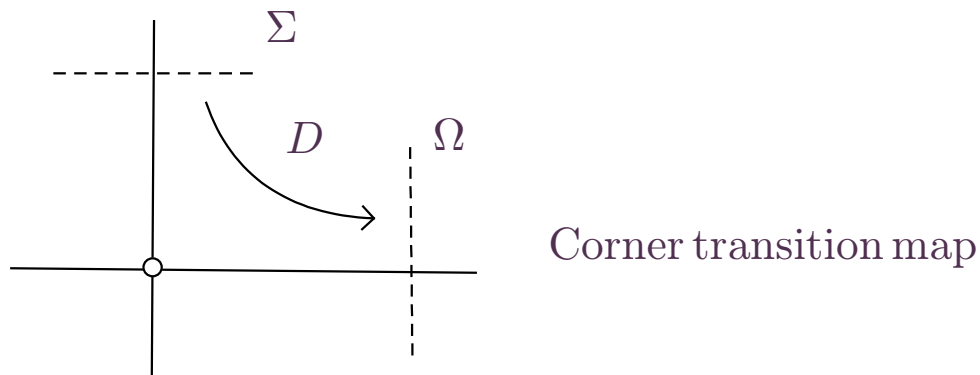


“The” Holonomy map

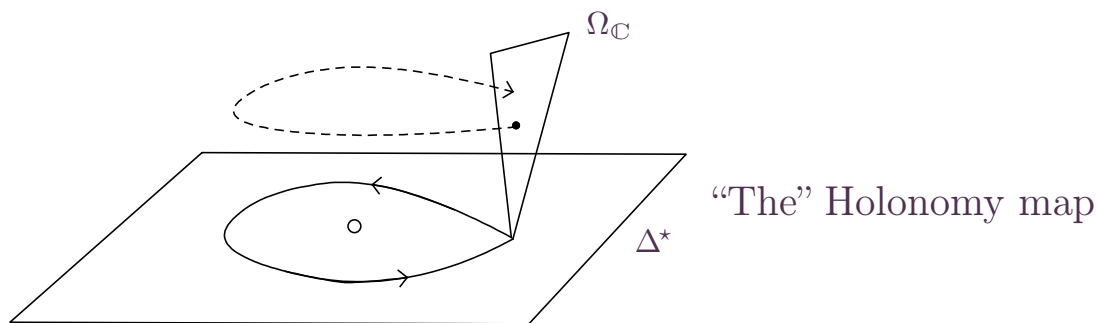
Transverse behaviour of the foliation in the vicinity of a saddle point.

There are two holonomy maps of interest:

1)



2) In the complex setting...



We can recover the (orbital) analytic class of the saddle from the analytic class of one of these maps (once we fix the ratio μ/λ)

Definition: Two germs of vector fields

$$\partial, \tilde{\partial} \in \text{Der}(\mathcal{O})$$

(seen as derivations of the local ring)

Definition: Two germs of vector fields

$$\partial, \tilde{\partial} \in \text{Der}(\mathcal{O})$$

(seen as derivations of the local ring)

are **analytically conjugated** if there exists an automorphism

$$\varphi \in \text{Aut}(\mathcal{O})$$

(i.e. an \mathbb{C} -endomorphism of the local ring such that $\varphi(fg) = \varphi(f)\varphi(g)$) such that

$$\varphi^{-1} \partial \varphi = \tilde{\partial}$$

Definition: Two germs of vector fields

$$\partial, \tilde{\partial} \in \text{Der}(\mathcal{O})$$

(seen as derivations of the local ring)

are **analytically conjugated** if there exists an automorphism

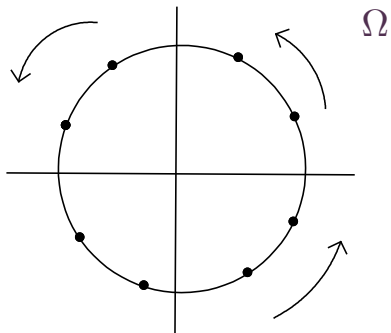
$$\varphi \in \text{Aut}(\mathcal{O})$$

(i.e. an \mathbb{C} -endomorphism of the local ring such that $\varphi(fg) = \varphi(f)\varphi(g)$) such that

$$\varphi^{-1} \partial \varphi = \tilde{\partial}$$

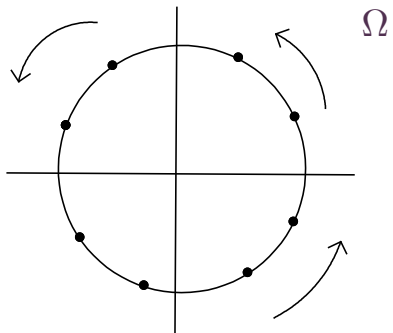
Definition: Two germs of vector fields $\partial, \tilde{\partial}$ are **orbitally analytic equivalent** if there exists a unit $u \in \mathbb{C}\{x\}$ such that ∂ is analytically conjugated to $u \tilde{\partial}$.

Dynamics of the complex holonomy map as an element of $\text{Diff}(\mathbb{C}, 0)$

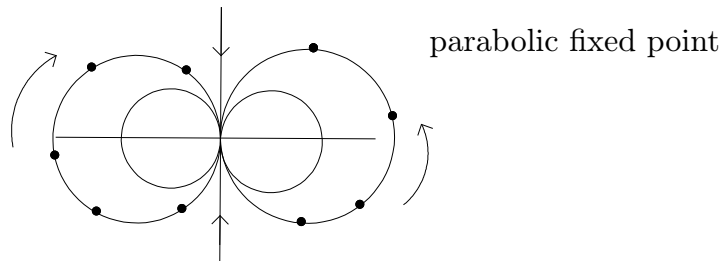


rotation

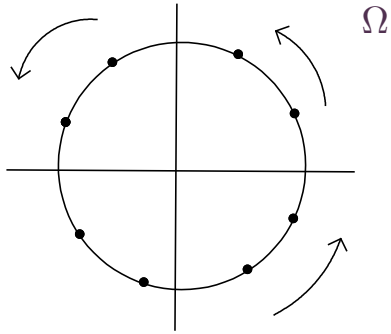
Dynamics of the complex holonomy map as an element of $\text{Diff}(\mathbb{C}, 0)$



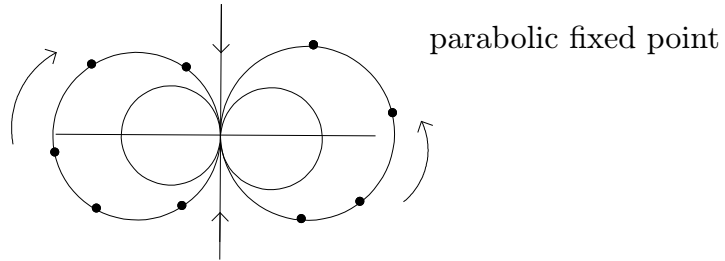
rotation



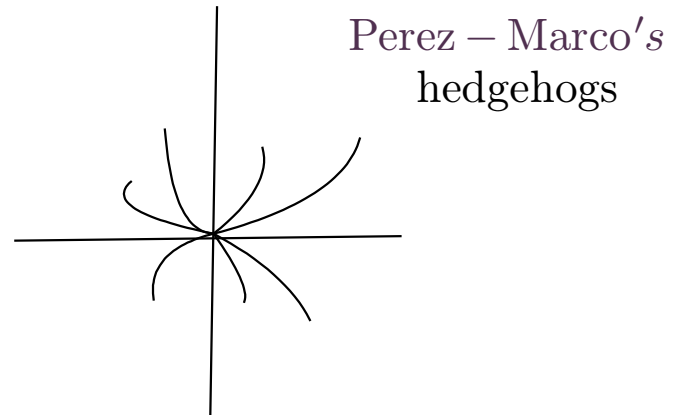
Dynamics of the complex holonomy map as an element of $\text{Diff}(\mathbb{C}, 0)$



rotation



parabolic fixed point



Classification Problem: “Describe” the orbits of the action of $\text{Aut}(\mathbb{C}\{x\})$ on $\text{Der}(\mathbb{C}\{x\})$ by conjugation

$$(\varphi, \partial) \longmapsto \varphi \cdot \partial = \varphi^{-1} \partial \varphi$$

Classification Problem: “Describe” the orbits of the action of $\text{Aut}(\mathbb{C}\{x\})$ on $\text{Der}(\mathbb{C}\{x\})$ by conjugation

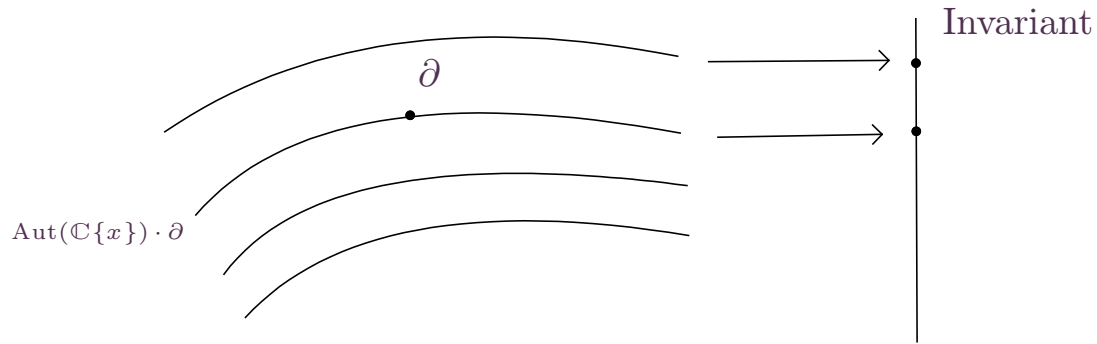
$$(\varphi, \partial) \longmapsto \varphi \cdot \partial = \varphi^{-1} \partial \varphi$$

I.e. local analytic changes of coordinates.

Classification Problem: “Describe” the orbits of the action of $\text{Aut}(\mathbb{C}\{x\})$ on $\text{Der}(\mathbb{C}\{x\})$ by conjugation

$$(\varphi, \partial) \longmapsto \varphi \cdot \partial = \varphi^{-1} \partial \varphi$$

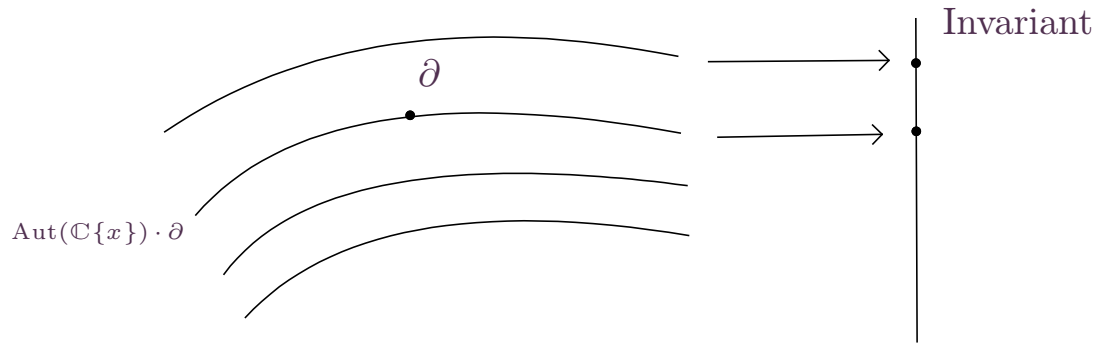
I.e. local analytic changes of coordinates.



Classification Problem: “Describe” the orbits of the action of $\text{Aut}(\mathbb{C}\{x\})$ on $\text{Der}(\mathbb{C}\{x\})$ by conjugation

$$(\varphi, \partial) \longmapsto \varphi \cdot \partial = \varphi^{-1} \partial \varphi$$

I.e. local analytic changes of coordinates.

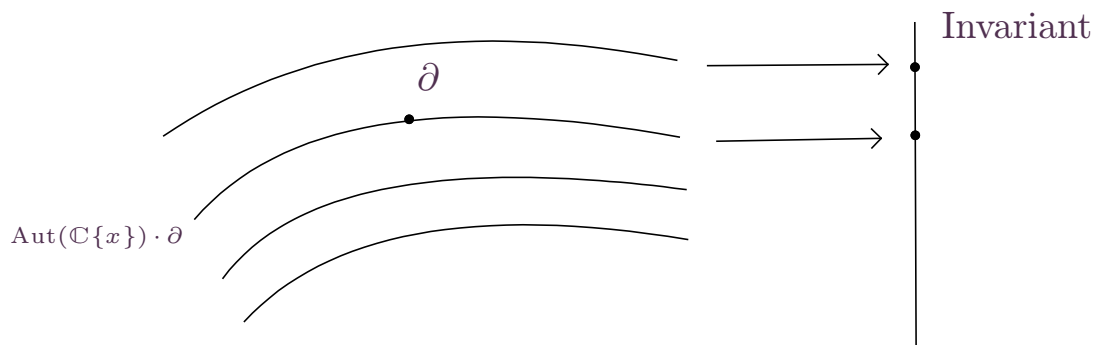


$$\partial \sim \tilde{\partial} \iff \text{Invariant}(\partial) = \text{Invariant}(\tilde{\partial})$$

Classification Problem: “Describe” the orbits of the action of $\text{Aut}(\mathbb{C}\{x\})$ on $\text{Der}(\mathbb{C}\{x\})$ by conjugation

$$(\varphi, \partial) \longmapsto \varphi \cdot \partial = \varphi^{-1} \partial \varphi$$

I.e. local analytic changes of coordinates.



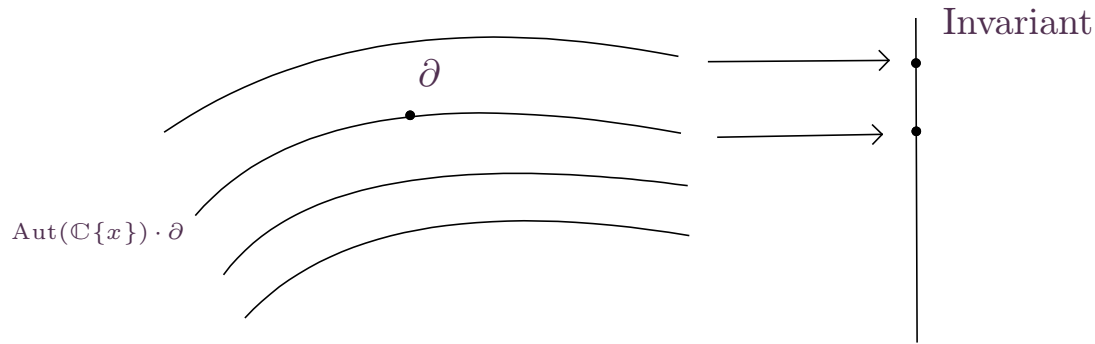
$$\partial \sim \tilde{\partial} \iff \text{Invariant}(\partial) = \text{Invariant}(\tilde{\partial})$$

The problem is reasonably well-understood for **elementary singularities in dimension two** (modulo some very hard *small divisor problems*) see e.g. Dulac, Ecalle, Ilyashenko, Martinet, Ramis, Yoccoz and Perez Marco, ... works.

Classification Problem: “Describe” the orbits of the action of $\text{Aut}(\mathbb{C}\{x\})$ on $\text{Der}(\mathbb{C}\{x\})$ by conjugation

$$(\varphi, \partial) \longmapsto \varphi \cdot \partial = \varphi^{-1} \partial \varphi$$

I.e. local analytic changes of coordinates.



$$\partial \sim \tilde{\partial} \iff \text{Invariant}(\partial) = \text{Invariant}(\tilde{\partial})$$

The problem is reasonably well-understood for **elementary singularities in dimension two** (modulo some very hard *small divisor problems*) see e.g. Dulac, Ecalle, Ilyashenko, Martinet, Ramis, Yoccoz and Perez Marco, ... works.

This problem is much less understood for vector fields higher dimensions.

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveyau-Moussu 1988) The cuspidal singularity

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveau-Moussu 1988) The cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

"Almost" first integral. $f(x, y) = y^2 - x^3$

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveau-Moussu 1988) The cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

"Almost" first integral. $f(x, y) = y^2 - x^3$

$$\partial_s = 0, \quad \text{Jac}_{(0,0)} = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix}$$

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveau-Moussu 1988) The cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

"Almost" first integral. $f(x, y) = y^2 - x^3$

$$\partial_s = 0, \quad \text{Jac}_{(0,0)} = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix}$$

For Δ of **(2,3)-quasi homogeneous order** ≥ 2 , there exists a local analytic coordinate change such that, up to division by a unit,

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveau-Moussu 1988) The cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

"Almost" first integral. $f(x, y) = y^2 - x^3$

$$\partial_s = 0, \quad \text{Jac}_{(0,0)} = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix}$$

For Δ of **(2,3)-quasi homogeneous order** ≥ 2 , there exists a local analytic coordinate change such that, up to division by a unit,

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + r(x, y) \left(2x \frac{\partial}{\partial x} + 3y \frac{\partial}{\partial y} \right), \quad r \in \mathfrak{m}$$

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveau-Moussu 1988) The cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

"Almost" first integral. $f(x, y) = y^2 - x^3$

$$\partial_s = 0, \quad \text{Jac}_{(0,0)} = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix}$$

For Δ of **(2,3)-quasi homogeneous order** ≥ 2 , there exists a local analytic coordinate change such that, up to division by a unit,

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + r(x, y) \left(2x \frac{\partial}{\partial x} + 3y \frac{\partial}{\partial y} \right), \quad r \in \mathfrak{m}$$

$$\partial(f) = 6r f.$$

What about the local transverse behaviour in the vicinity of non-**elementary** singularities?

Example: (Cerveau-Moussu 1988) The cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

"Almost" first integral. $f(x, y) = y^2 - x^3$

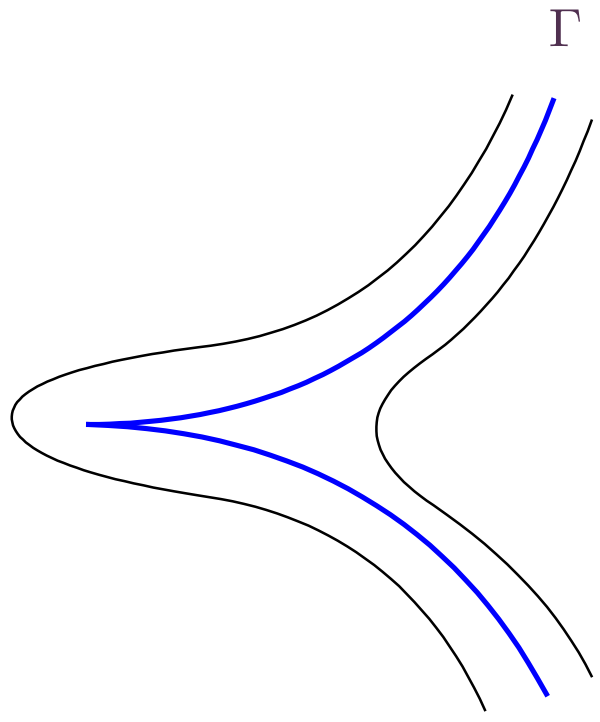
$$\partial_s = 0, \quad \text{Jac}_{(0,0)} = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix}$$

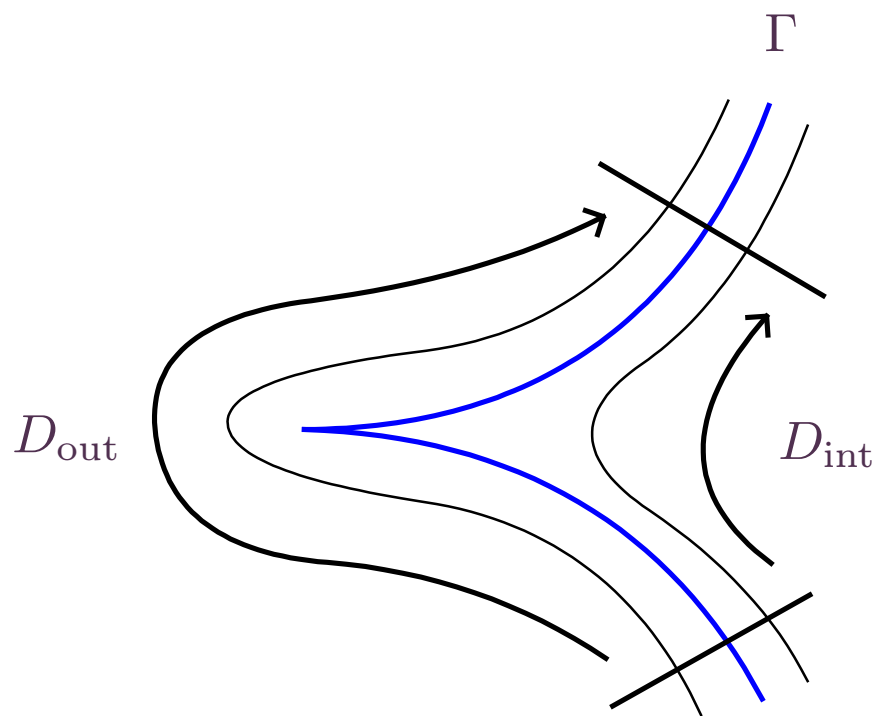
For Δ of **(2,3)-quasi homogeneous order** ≥ 2 , there exists a local analytic coordinate change such that, up to division by a unit,

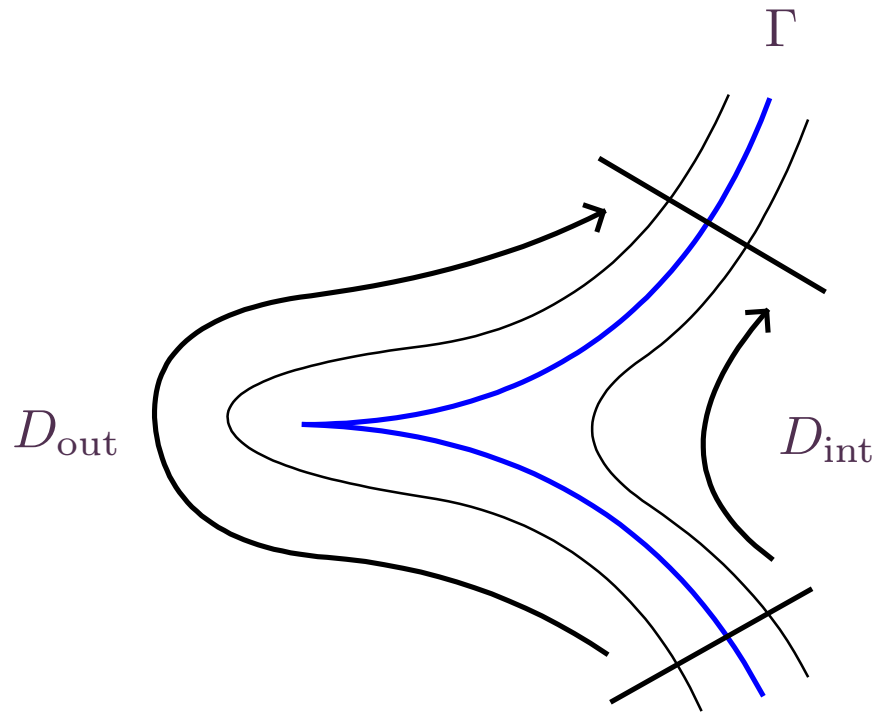
$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + r(x, y) \left(2x \frac{\partial}{\partial x} + 3y \frac{\partial}{\partial y} \right), \quad r \in \mathfrak{m}$$

$$\partial(f) = 6r f.$$

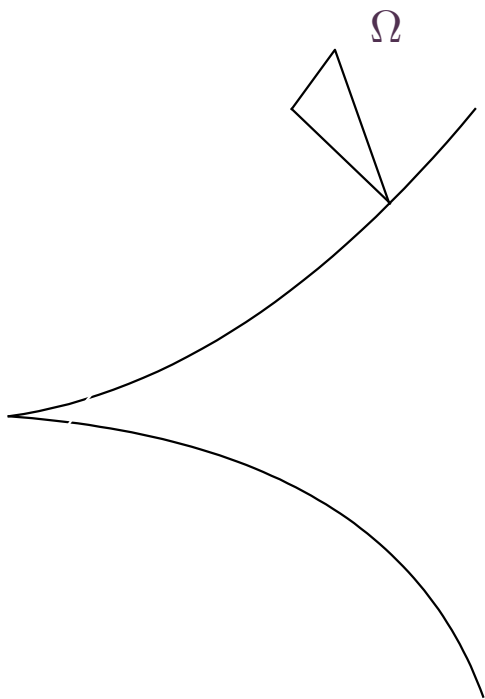
The cusp $\Gamma = \{f = 0\}$ is an invariant curve.

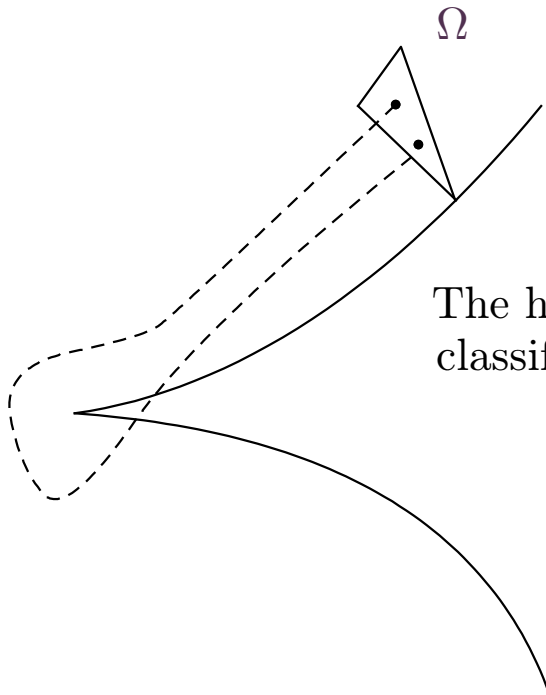






There are two **distinct** corner transition maps.





The holonomy map **does not** classify the singularity

Resolution of the cuspidal foliation. We consider the dual 1-form to simplify

Resolution of the cuspidal foliation. We consider the dual 1-form to simplify

$$d(y^2 - x^3) \left\langle \right.$$

Resolution of the cuspidal foliation. We consider the dual 1-form to simplify

$$d(y^2 - x^3) \begin{array}{c} \nearrow \\ \searrow \end{array}$$

Blow-up 1: $x \rightarrow x, \quad y \rightarrow xy$

$$d(x^2(y^2 - x)) \begin{array}{c} \circlearrowleft \\ \nearrow \\ \searrow \end{array}$$

Resolution of the cuspidal foliation. We consider the dual 1-form to simplify

$$d(y^2 - x^3) \quad \text{<}$$

Blow-up 1: $x \rightarrow x, \quad y \rightarrow xy$

$$d(x^2(y^2 - x)) \quad \text{○<}$$

Blow-up 2: $x \rightarrow xy, \quad y \rightarrow y$

$$d(x^2y^3(y - x)) \quad \text{○&○}$$

Resolution of the cuspidal foliation. We consider the dual 1-form to simplify

$$d(y^2 - x^3) \quad \text{<}$$

Blow-up 1: $x \rightarrow x, \quad y \rightarrow xy$

$$d(x^2(y^2 - x)) \quad \text{○ <}$$

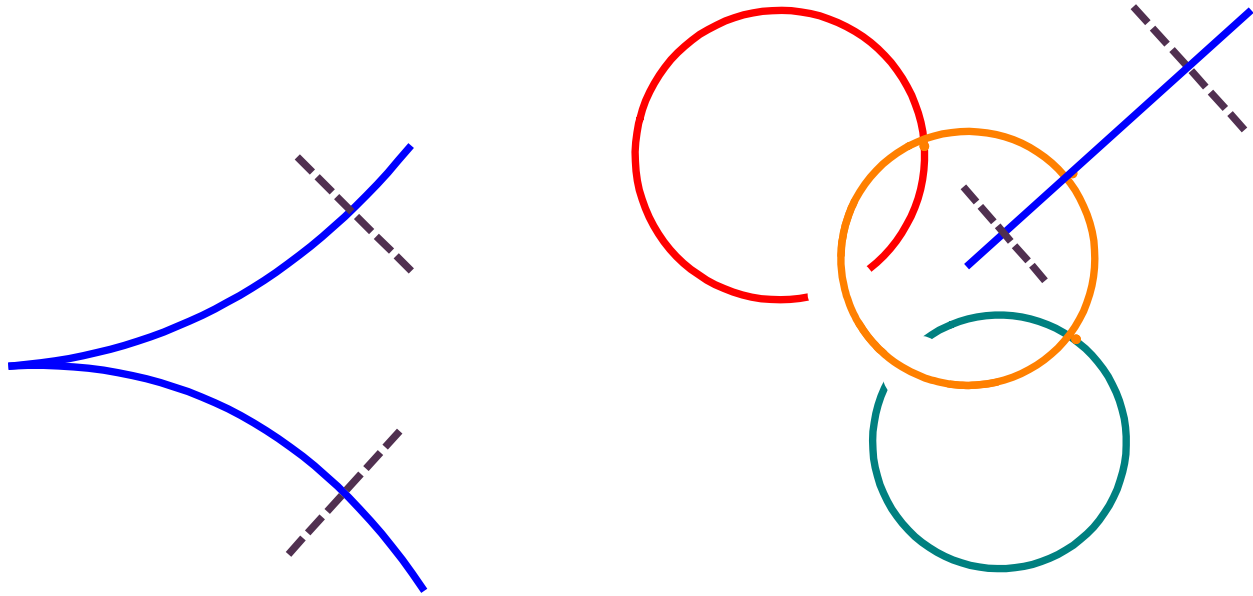
Blow-up 2: $x \rightarrow xy, \quad y \rightarrow y$

$$d(x^2y^3(y - x)) \quad \text{○ ○ /}$$

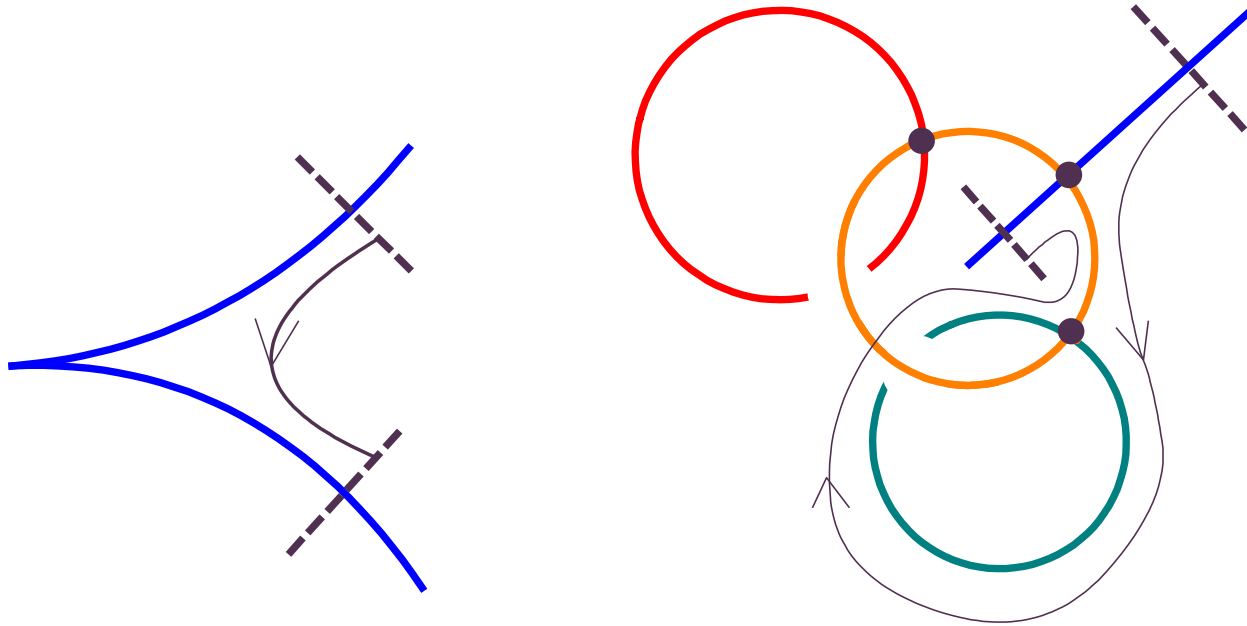
Blow-up 3: $x \rightarrow x, \quad y \rightarrow xy$

$$d(x^6y^3(y - 1)) \quad \text{○ (3:1) ○ (1:6) ○ (1:2) /}$$

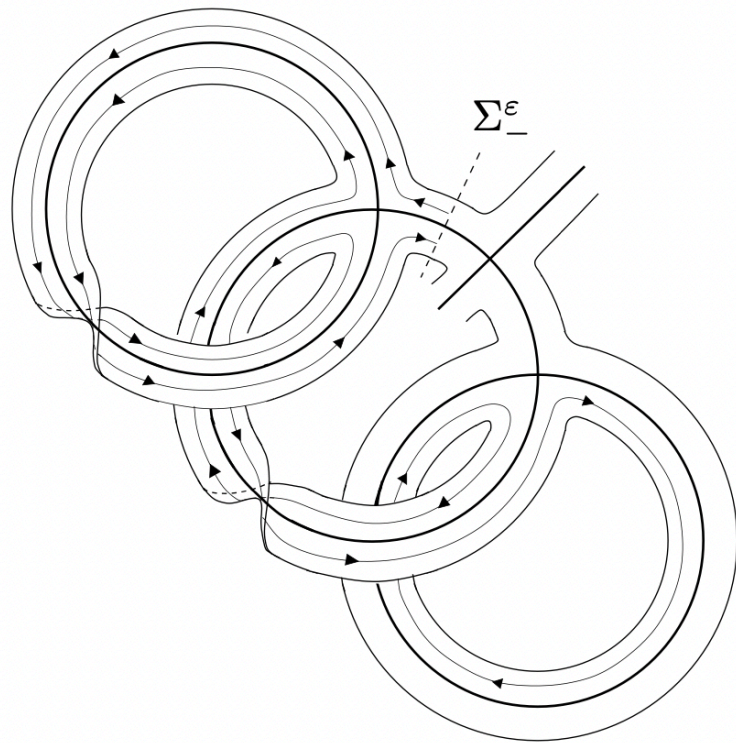
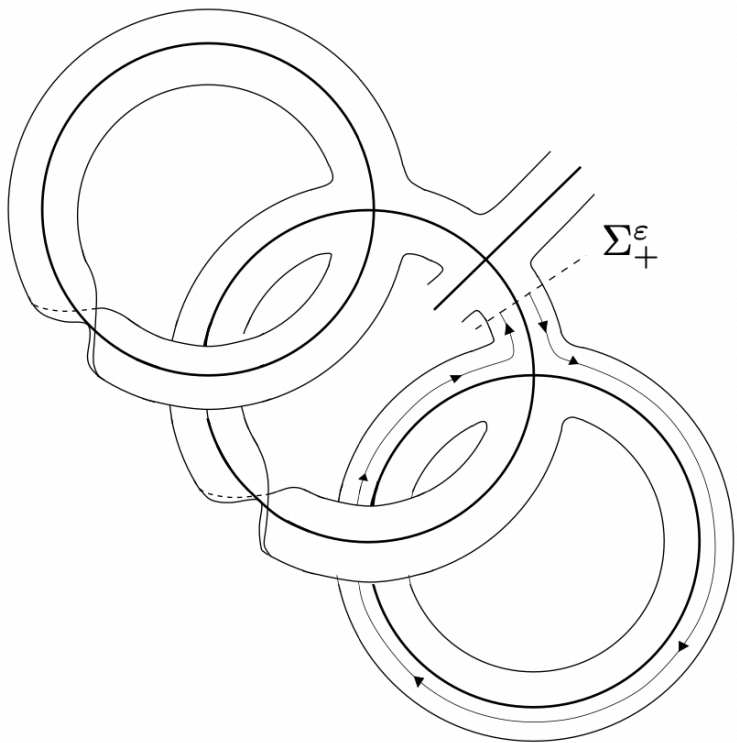
All singularities are now elementary saddles.



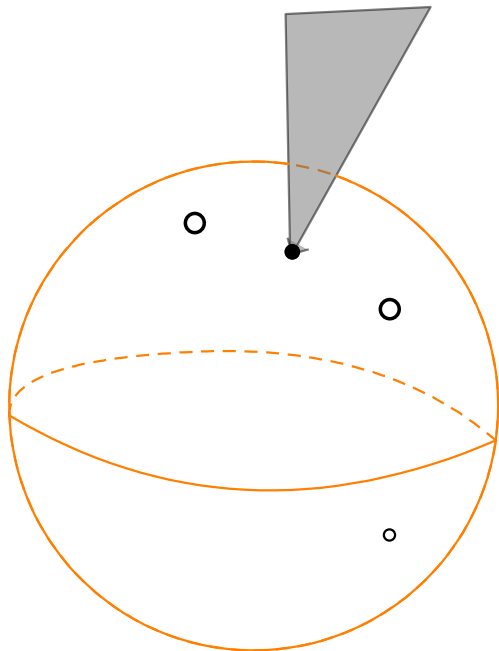
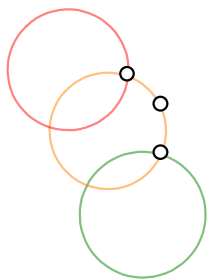
All singularities are now elementary saddles.



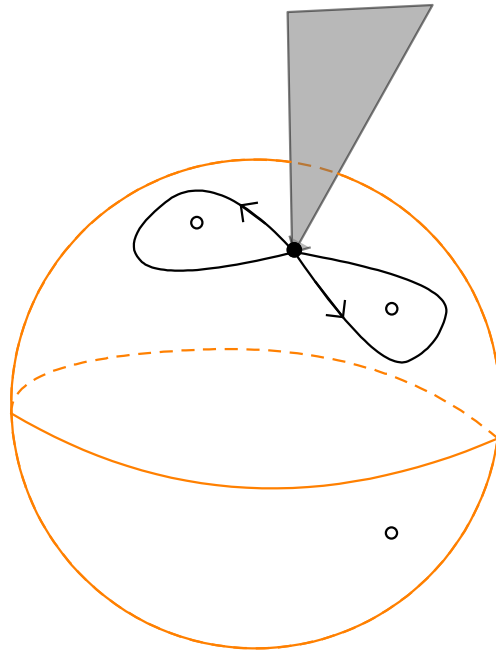
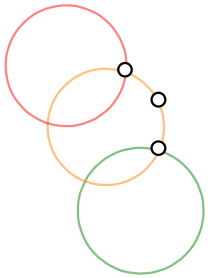
The foliation is now organized in a neighborhood of the exceptional divisor..



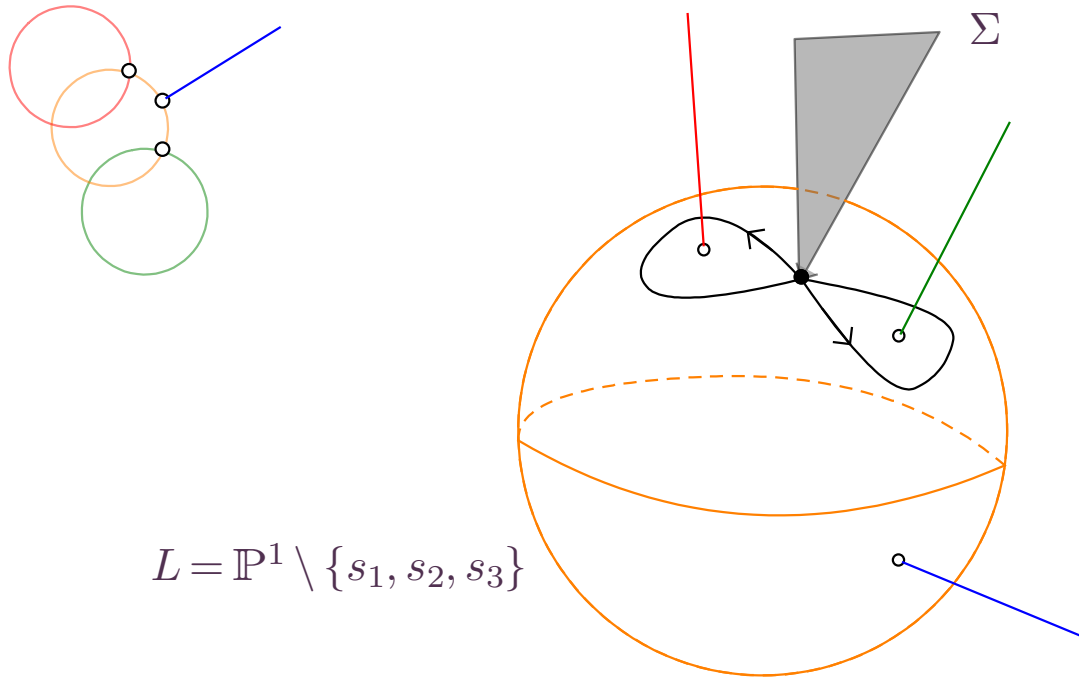
Can we recover the analytic moduli from the transverse behaviour?



Can we recover the analytic moduli from the transverse behaviour?



Can we recover the analytic moduli from the transverse behaviour?



(Moussu) The vanishing holonomy $\text{Hol}(\mathcal{F}, L) = \langle f, g \in \text{Diff}(\mathbb{C}, 0) \mid f^2 = g^3 = \text{id} \rangle$ characterizes the analytic class of the germ of foliation.

Nilpotent locus for foliations by curves

Nilpotent locus for foliations by curves

The *nilpotent locus* of a foliated manifold is the subset $\text{Nilp}(M, \mathcal{F})$ of points where \mathcal{F} is not elementary.

Nilpotent locus for foliations by curves

The *nilpotent locus* of a foliated manifold is the subset $\text{Nilp}(M, \mathcal{F})$ of points where \mathcal{F} is not elementary.

Claim: $\text{Nilp}(M, \mathcal{F})$ is an analytic (or algebraic) subset of M .

(in fact, $p \in \text{Nilp}(M, \mathcal{F}) \iff \partial(\mathfrak{m}_p) \subset \mathfrak{m}_p$ and $\partial_1 \in \text{End}_{\mathbb{C}}(\mathfrak{m}_p / \mathfrak{m}_p^2)$ is a nilpotent endomorphism, for ∂ some arbitrarily chosen local generator).

Nilpotent locus for foliations by curves

The *nilpotent locus* of a foliated manifold is the subset $\text{Nilp}(M, \mathcal{F})$ of points where \mathcal{F} is not elementary.

Claim: $\text{Nilp}(M, \mathcal{F})$ is an analytic (or algebraic) subset of M .

(in fact, $p \in \text{Nilp}(M, \mathcal{F}) \iff \partial(\mathfrak{m}_p) \subset \mathfrak{m}_p$ and $\partial_1 \in \text{End}_{\mathbb{C}}(\mathfrak{m}_p / \mathfrak{m}_p^2)$ is a nilpotent endomorphism, for ∂ some arbitrarily chosen local generator).

Alternatively,

$$p \in \text{Nilp}(M, \mathcal{F}) \iff \forall k \in \mathbb{N} \exists n \in \mathbb{N} : (\partial_k)^n = 0$$

where $\partial_k: J^k \rightarrow J^k$ is the induced derivation on the k^{th} jet.

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Definition: We say that \mathcal{F} is **adapted** to E each irreducible component is invariant by \mathcal{F} .

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Definition: We say that \mathcal{F} is **adapted** to E if each irreducible component is invariant by \mathcal{F} .

More precisely, for each point $p \in M$, consider

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Definition: We say that \mathcal{F} is **adapted** to E each irreducible component is invariant by \mathcal{F} .

More precisely, for each point $p \in M$, consider

- ∂ a local generator of \mathcal{F} , and

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Definition: We say that \mathcal{F} is **adapted** to E each irreducible component is invariant by \mathcal{F} .

More precisely, for each point $p \in M$, consider

- ∂ a local generator of \mathcal{F} , and
- f an equation for a local irreducible component of E ,

Then

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Definition: We say that \mathcal{F} is **adapted** to E each irreducible component is invariant by \mathcal{F} .

More precisely, for each point $p \in M$, consider

- ∂ a local generator of \mathcal{F} , and
- f an equation for a local irreducible component of E ,

Then

$$\forall i \in \mathbb{N} \quad : \quad \partial(\langle f^i \rangle) \subset \langle f^i \rangle$$

Suppose that (M, \mathcal{F}) is further equipped with a normal crossings divisor E .

Definition: We say that \mathcal{F} is **adapted** to E each irreducible component is invariant by \mathcal{F} .

More precisely, for each point $p \in M$, consider

- ∂ a local generator of \mathcal{F} , and
- f an equation for a local irreducible component of E ,

Then

$$\forall i \in \mathbb{N} \quad : \quad \partial(\langle f^i \rangle) \subset \langle f^i \rangle$$

We further say that \mathcal{F} is **tightly adapted** to D if there exists an index i such that

$$\partial(\langle f^i \rangle) \not\subset \langle f^{i+1} \rangle$$

In other words, for $E = (x_1 \dots x_k = 0)$,

$$\partial = \sum_{i=1}^k a_i \left(x_i \frac{\partial}{\partial x_i} \right) + \sum_{i=k+1}^n a_i \frac{\partial}{\partial x_i}$$

with $a_1, \dots, a_n \in \mathbb{C}\{x\}$ such that $\langle a_1, \dots, a_n \rangle \not\subset \langle x_i \rangle$, for each $i = 1, \dots, k$.

Example: $E = (x=0)$

Example: $E = (x=0)$

$$\partial = ax \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

Example: $E = (x=0)$

$$\partial = ax \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

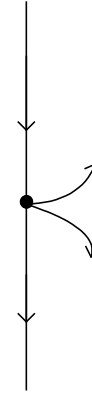
with $\langle a, b \rangle \notin \langle x \rangle$

Example: $E = (x=0)$

$$\partial = ax \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

with $\langle a, b \rangle \not\subset \langle x \rangle$

$b \neq 0$: The generic point on the divisor is non-singular

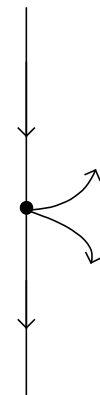


Example: $E = (x=0)$

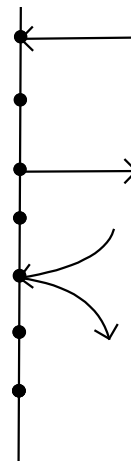
$$\partial = ax \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

with $\langle a, b \rangle \not\subset \langle x \rangle$

$b \neq 0$: The generic point on the divisor is non-singular



$b = 0$: The generic point on the divisor is an elementary singularity

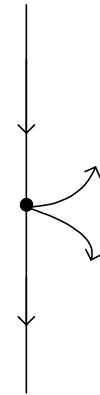


Example: $E = (x=0)$

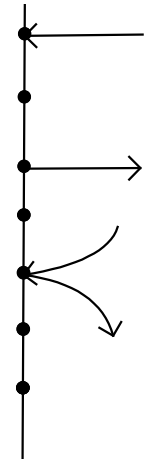
$$\partial = ax \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

with $\langle a, b \rangle \not\subset \langle x \rangle$

$b \neq 0$: The generic point on the divisor is non-singular



$b = 0$: The generic point on the divisor is an elementary singularity



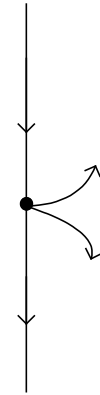
(The singular set of the foliation can have codimension one components)

Example: $E = (x=0)$

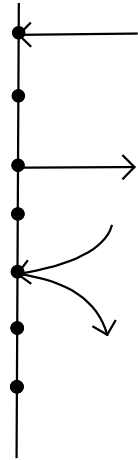
$$\partial = ax \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

with $\langle a, b \rangle \not\subset \langle x \rangle$

$b \neq 0$: The generic point on the divisor is non-singular



$b = 0$: The generic point on the divisor is an elementary singularity



(The singular set of the foliation can have codimension one components)

\mathcal{F} is tightly adapted to $E \iff$ no irreducible component of E lies on $\text{Nilp}(M, \mathcal{F})$

The problem of elimination of the nilpotent locus

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and
- A singular foliation by curves \mathcal{F} which is tightly adapted to E .

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and
- A singular foliation by curves \mathcal{F} which is tightly adapted to E .

such that $\text{Nilp}(M, \mathcal{F})$ has codimension greater or equal than two.

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and
- A singular foliation by curves \mathcal{F} which is tightly adapted to E .

such that $\text{Nilp}(M, \mathcal{F})$ has codimension greater or equal than two.

Problem: For each relatively compact subset $M_0 \subset M$, find a finite sequence of blowing-ups

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and
- A singular foliation by curves \mathcal{F} which is tightly adapted to E .

such that $\text{Nilp}(M, \mathcal{F})$ has codimension greater or equal than two.

Problem: For each relatively compact subset $M_0 \subset M$, find a finite sequence of blowing-ups

$$(M_0, E_0, \mathcal{F}_0) \xleftarrow{\pi_1} \cdots \xleftarrow{\pi_n} (M_n, E_n, \mathcal{F}_n)$$

such that:

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and
- A singular foliation by curves \mathcal{F} which is tightly adapted to E .

such that $\text{Nilp}(M, \mathcal{F})$ has codimension greater or equal than two.

Problem: For each relatively compact subset $M_0 \subset M$, find a finite sequence of blowing-ups

$$(M_0, E_0, \mathcal{F}_0) \xleftarrow{\pi_1} \cdots \xleftarrow{\pi_n} (M_n, E_n, \mathcal{F}_n)$$

such that:

- 1) The center C_i of π_i has normal crossings with E_i and is contained in $\text{Nilp}(M_i, \mathcal{F}_i)$

The problem of elimination of the nilpotent locus

A singularly foliated manifold is a triple (M, E, \mathcal{F}) formed by a manifold M , equipped with

- A normal crossings divisor E and
- A singular foliation by curves \mathcal{F} which is tightly adapted to E .

such that $\text{Nilp}(M, \mathcal{F})$ has codimension greater or equal than two.

Problem: For each relatively compact subset $M_0 \subset M$, find a finite sequence of blowing-ups

$$(M_0, E_0, \mathcal{F}_0) \xleftarrow{\pi_1} \cdots \xleftarrow{\pi_n} (M_n, E_n, \mathcal{F}_n)$$

such that:

- 1) The center C_i of π_i has normal crossings with E_i and is contained in $\text{Nilp}(M_i, \mathcal{F}_i)$
- 2) $\text{Nilp}(M_n, \mathcal{F}_n) = \emptyset$.

How to compute the transform of a foliation by blowing-up?

How to compute the transform of a foliation by blowing-up?

via local generators, In local coordinates

How to compute the transform of a foliation by blowing-up?

via local generators, In local coordinates

$$x_1 \rightarrow x_1, \quad x_2 \rightarrow x_1 x_2 \quad \dots \quad x_n \rightarrow x_1 x_n$$

It is easier to compute the strict transform of the **logarithmic basis** $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$.

How to compute the transform of a foliation by blowing-up?

via local generators, In local coordinates

$$x_1 \rightarrow x_1, \quad x_2 \rightarrow x_1 x_2 \quad \dots \quad x_n \rightarrow x_1 x_n$$

It is easier to compute the strict transform of the **logarithmic basis** $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$.

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow x_1 \frac{\partial}{\partial x_1} - x_2 \frac{\partial}{\partial x_1} - \dots - x_n \frac{\partial}{\partial x_n}$$

How to compute the transform of a foliation by blowing-up?

via local generators, In local coordinates

$$x_1 \rightarrow x_1, \quad x_2 \rightarrow x_1 x_2 \quad \dots \quad x_n \rightarrow x_1 x_n$$

It is easier to compute the strict transform of the **logarithmic basis** $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$.

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow x_1 \frac{\partial}{\partial x_1} - x_2 \frac{\partial}{\partial x_1} - \dots - x_n \frac{\partial}{\partial x_1}$$

$$x_2 \frac{\partial}{\partial x_2} \longrightarrow x_2 \frac{\partial}{\partial x_2}, \quad \dots \quad , \quad x_n \frac{\partial}{\partial x_n} \longrightarrow x_n \frac{\partial}{\partial x_n}$$

(or via the dual basis of logarithmic one-forms $\left\{ \frac{dx_1}{x_1}, \dots, \frac{dx_n}{x_n} \right\}$)

How to compute the transform of a foliation by blowing-up?

via local generators, In local coordinates

$$x_1 \rightarrow x_1, \quad x_2 \rightarrow x_1 x_2 \quad \dots \quad x_n \rightarrow x_1 x_n$$

It is easier to compute the strict transform of the **logarithmic basis** $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$.

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow x_1 \frac{\partial}{\partial x_1} - x_2 \frac{\partial}{\partial x_1} - \dots - x_n \frac{\partial}{\partial x_1}$$

$$x_2 \frac{\partial}{\partial x_2} \longrightarrow x_2 \frac{\partial}{\partial x_2}, \quad \dots \quad , \quad x_n \frac{\partial}{\partial x_n} \longrightarrow x_n \frac{\partial}{\partial x_n}$$

(or via the dual basis of logarithmic one-forms $\left\{ \frac{dx_1}{x_1}, \dots, \frac{dx_n}{x_n} \right\}$)

Example: $(\lambda: \mu)$ – linear saddle, $\lambda, \mu > 0$

Example: $(\lambda: \mu)$ – linear saddle, $\lambda, \mu > 0$

$$\lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y} \quad (\lambda: \mu)$$

Under the substitution $x \rightarrow x, y \rightarrow xy$

Example: $(\lambda: \mu)$ – linear saddle, $\lambda, \mu > 0$

$$\lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y} \quad (\lambda: \mu)$$

Under the substitution $x \rightarrow x, y \rightarrow xy$

$$\lambda \left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) - \mu y \frac{\partial}{\partial y} \quad (\lambda: \lambda + \mu)$$

Under the substitution $x \rightarrow xy, y \rightarrow y$

Example: $(\lambda: \mu)$ – linear saddle, $\lambda, \mu > 0$

$$\lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y} \quad (\lambda: \mu)$$

Under the substitution $x \rightarrow x, y \rightarrow xy$

$$\lambda \left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) - \mu y \frac{\partial}{\partial y} \quad (\lambda: \lambda + \mu)$$

Under the substitution $x \rightarrow xy, y \rightarrow y$

$$\lambda x \frac{\partial}{\partial x} - \mu \left(y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} \right) \quad (\lambda + \mu: \mu)$$

Example: $(\lambda: \mu)$ – linear saddle, $\lambda, \mu > 0$

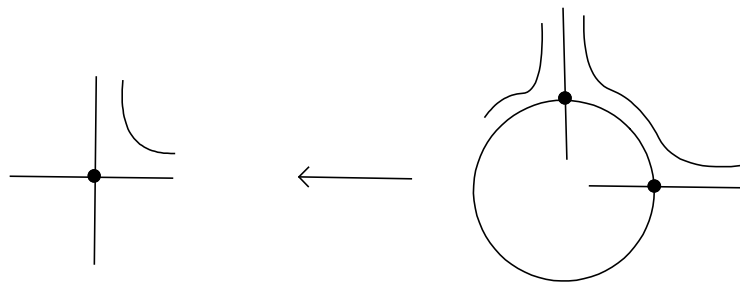
$$\lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y} \quad (\lambda: \mu)$$

Under the substitution $x \rightarrow x, y \rightarrow xy$

$$\lambda \left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) - \mu y \frac{\partial}{\partial y} \quad (\lambda: \lambda + \mu)$$

Under the substitution $x \rightarrow xy, y \rightarrow y$

$$\lambda x \frac{\partial}{\partial x} - \mu \left(y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} \right) \quad (\lambda + \mu: \mu)$$



Example: $(\lambda: \mu)$ – linear saddle, $\lambda, \mu > 0$

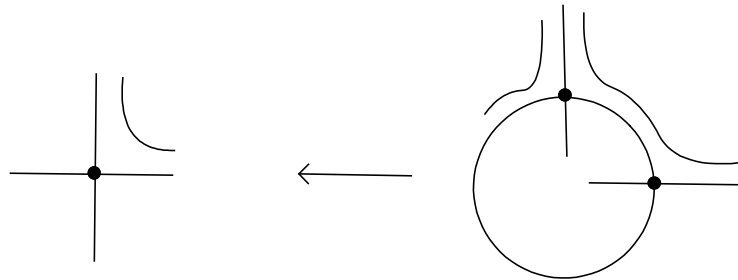
$$\lambda x \frac{\partial}{\partial x} - \mu y \frac{\partial}{\partial y} \quad (\lambda: \mu)$$

Under the substitution $x \rightarrow x, y \rightarrow xy$

$$\lambda \left(x \frac{\partial}{\partial x} - y \frac{\partial}{\partial y} \right) - \mu y \frac{\partial}{\partial y} \quad (\lambda: \lambda + \mu)$$

Under the substitution $x \rightarrow xy, y \rightarrow y$

$$\lambda x \frac{\partial}{\partial x} - \mu \left(y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} \right) \quad (\lambda + \mu: \mu)$$



We can never get rid of saddle points...

Example: node

Example: node

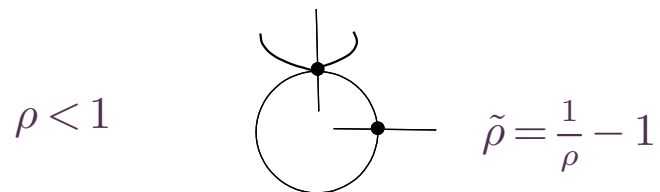
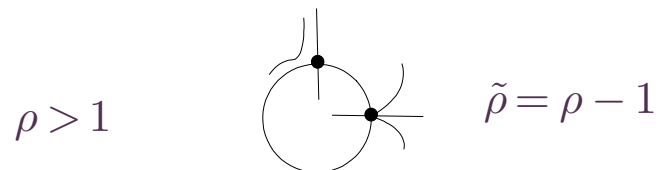
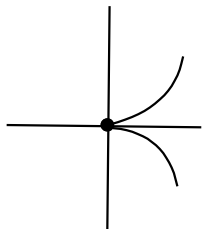
$$x \frac{\partial}{\partial x} + \rho y \frac{\partial}{\partial y} \quad , \quad \rho > 0$$

Example: node

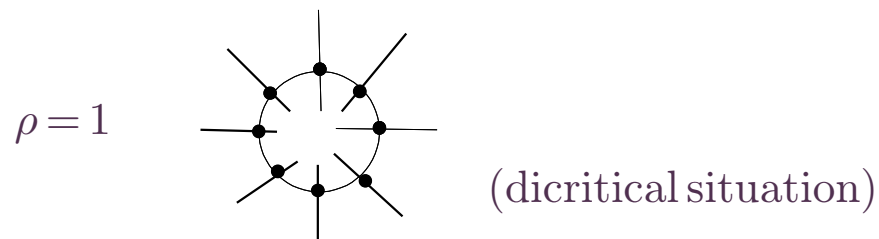
$$x \frac{\partial}{\partial x} + \rho y \frac{\partial}{\partial y} \quad , \quad \rho > 0$$

Example: node

$$x \frac{\partial}{\partial x} + \rho y \frac{\partial}{\partial y} \quad , \quad \rho > 0$$

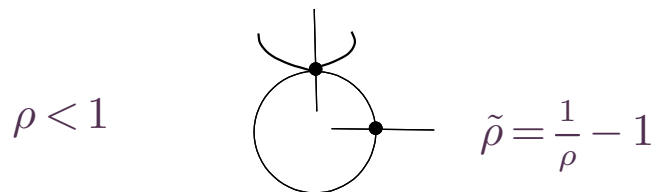
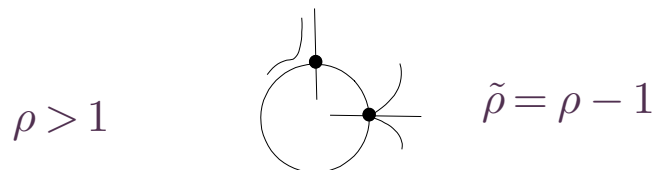
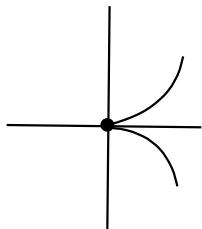


$$\rho = \rho_0 + \frac{1}{\rho_1 + \frac{1}{\dots}}$$

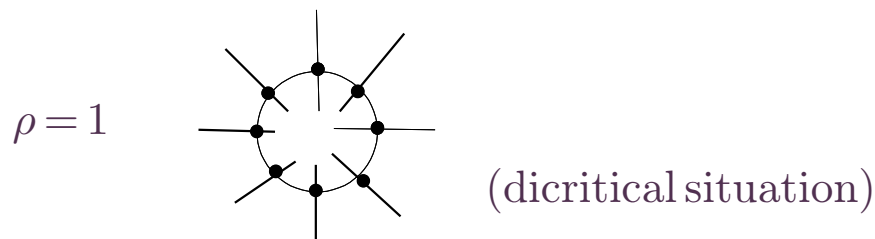


Example: node

$$x \frac{\partial}{\partial x} + \rho y \frac{\partial}{\partial y} \quad , \quad \rho > 0$$



$$\rho = \rho_0 + \frac{1}{\rho_1 + \frac{1}{\dots}}$$



We can never get rid of a node if $\rho \notin \mathbb{Q}$.

Example: saddle-nodes

Example: saddle-nodes

$$x^k x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \quad k \geq 1$$

Example: saddle-nodes

$$x^k x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \quad k \geq 1$$

Example: saddle-nodes

$$x^k x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \quad k \geq 1$$

After m directional blowing-ups: $x \rightarrow x, y \rightarrow xy$

$$x^k \left(x \frac{\partial}{\partial x} - m y \frac{\partial}{\partial y} \right) + y \frac{\partial}{\partial y}$$

This model is completely stable. It is a final model.

Example: saddle-nodes

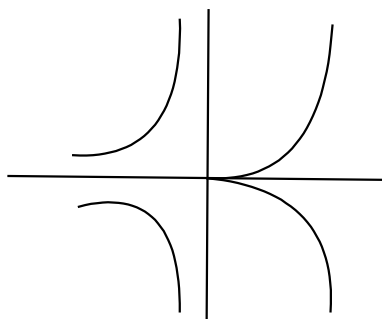
$$x^k x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \quad k \geq 1$$

After m directional blowing-ups: $x \rightarrow x, y \rightarrow xy$

$$x^k \left(x \frac{\partial}{\partial x} - m y \frac{\partial}{\partial y} \right) + y \frac{\partial}{\partial y}$$

This model is completely stable. It is a final model.

First integral $h = (x^m y) \exp\left(\frac{1}{kx^k}\right)$

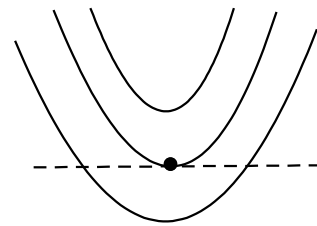
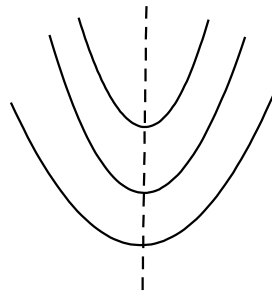
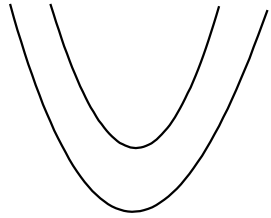


Blowing-up centers with tangencies with the foliation can create non-elementary points.

$$\partial = \frac{\partial}{\partial x} + x^k \frac{\partial}{\partial y}, \quad k \geq 1$$

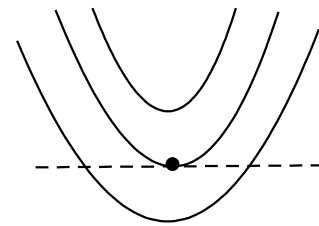
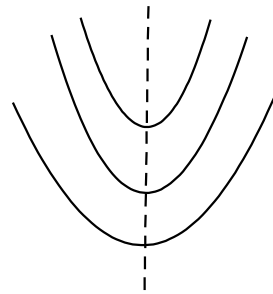
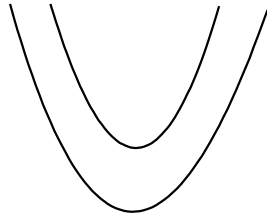
Blowing-up centers with tangencies with the foliation can create non-elementary points.

$$\partial = \frac{\partial}{\partial x} + x^k \frac{\partial}{\partial y}, \quad k \geq 1$$



Blowing-up centers with tangencies with the foliation can create non-elementary points.

$$\partial = \frac{\partial}{\partial x} + x^k \frac{\partial}{\partial y}, \quad k \geq 1$$

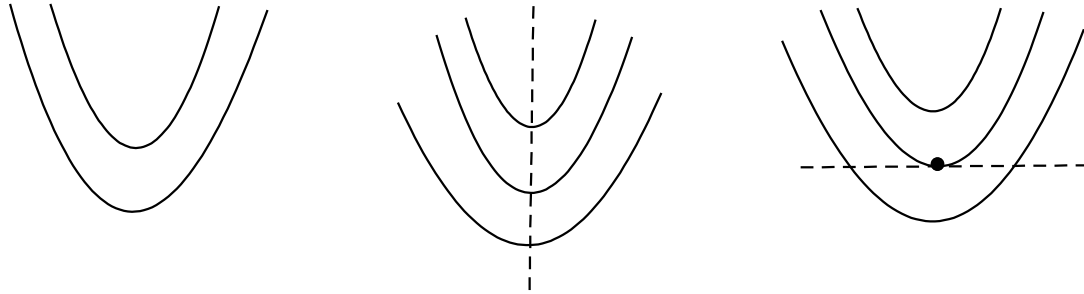


In logarithmic basis:

$$x^{-1} \left(x \frac{\partial}{\partial x} \right) + x^k y^{-1} \left(y \frac{\partial}{\partial y} \right)$$

Blowing-up centers with tangencies with the foliation can create non-elementary points.

$$\partial = \frac{\partial}{\partial x} + x^k \frac{\partial}{\partial y}, \quad k \geq 1$$



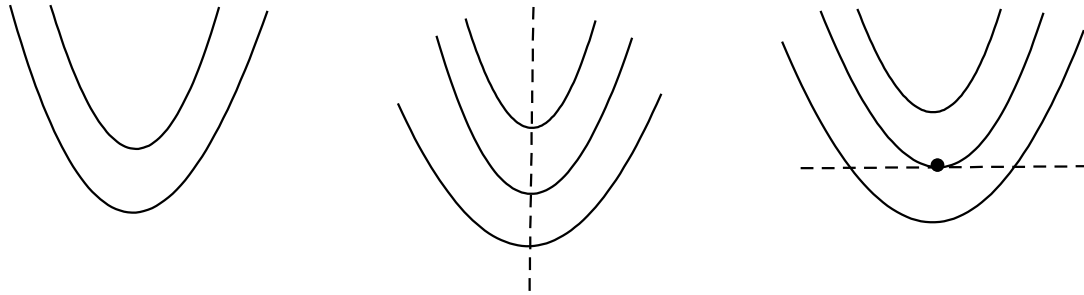
In logarithmic basis:

$$x^{-1} \left(x \frac{\partial}{\partial x} \right) + x^k y^{-1} \left(y \frac{\partial}{\partial y} \right)$$

Center ($x = 0$): $\tilde{\partial} = x \partial = x \frac{\partial}{\partial x} + x^{k+1} \frac{\partial}{\partial y}$

Blowing-up centers with tangencies with the foliation can create non-elementary points.

$$\partial = \frac{\partial}{\partial x} + x^k \frac{\partial}{\partial y}, \quad k \geq 1$$



In logarithmic basis:

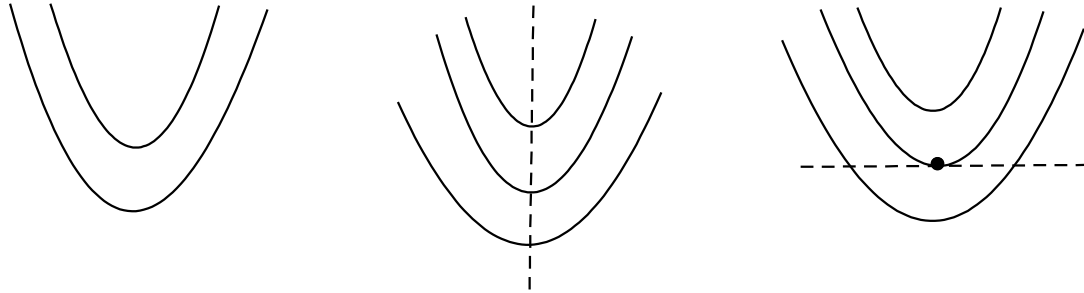
$$x^{-1} \left(x \frac{\partial}{\partial x} \right) + x^k y^{-1} \left(y \frac{\partial}{\partial y} \right)$$

Center ($x = 0$): $\tilde{\partial} = x \partial = x \frac{\partial}{\partial x} + x^{k+1} \frac{\partial}{\partial y}$

Center ($y = 0$): $\tilde{\partial} = y \partial = y \frac{\partial}{\partial x} + x^k \left(y \frac{\partial}{\partial y} \right)$ (nilpotent singularity)

Blowing-up centers with tangencies with the foliation can create non-elementary points.

$$\partial = \frac{\partial}{\partial x} + x^k \frac{\partial}{\partial y}, \quad k \geq 1$$



In logarithmic basis:

$$x^{-1} \left(x \frac{\partial}{\partial x} \right) + x^k y^{-1} \left(y \frac{\partial}{\partial y} \right)$$

Center ($x = 0$): $\tilde{\partial} = x \partial = x \frac{\partial}{\partial x} + x^{k+1} \frac{\partial}{\partial y}$

Center ($y = 0$): $\tilde{\partial} = y \partial = y \frac{\partial}{\partial x} + x^k \left(y \frac{\partial}{\partial y} \right)$ (nilpotent singularity)

Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

But... It is false for $\dim M \geq 3$.

Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

But... It is false for $\dim M \geq 3$.

Example of Sanz and Sancho-Salas:

Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

But... It is false for $\dim M \geq 3$.

Example of Sanz and Sancho-Salas:

$$\partial = \left(y \frac{\partial}{\partial x} + xz \frac{\partial}{\partial y} \right) + \beta z \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) - z \left(-x \frac{\partial}{\partial x} + 2z \frac{\partial}{\partial z} \right)$$

is tangent to the Whitney umbrella $W = y^2 - zx^2$.

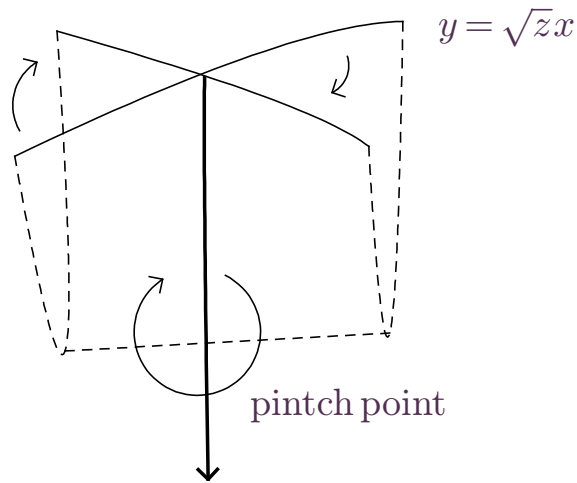
Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

But... It is false for $\dim M \geq 3$.

Example of Sanz and Sancho-Salas:

$$\partial = \left(y \frac{\partial}{\partial x} + x z \frac{\partial}{\partial y} \right) + \beta z \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) - z \left(-x \frac{\partial}{\partial x} + 2z \frac{\partial}{\partial z} \right)$$

is tangent to the Whitney umbrella $W = y^2 - zx^2$.



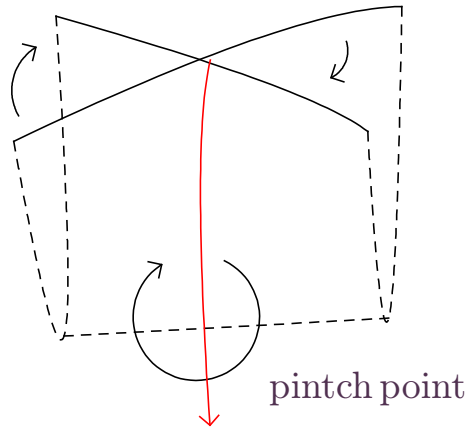
Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

But... It is false for $\dim M \geq 3$.

Example of Sanz and Sancho-Salas:

$$\partial = \left(y \frac{\partial}{\partial x} + xz \frac{\partial}{\partial y} \right) + \beta z \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) - z \left(-x \frac{\partial}{\partial x} + 2z \frac{\partial}{\partial z} \right) + \lambda z \frac{\partial}{\partial x}$$

with $\beta \notin \frac{1}{2}\mathbb{Z}_{>0}$, $\lambda \in \mathbb{C}^*$.



Formal expansion of the “handle”

$$y = \tau(z) = \sum \tau_n z^n, \quad \tau_n \sim \lambda (n!)^2$$

$$x = \xi(z) = \sum \xi_n z^n, \quad \xi_n \sim \lambda (n!)^2$$

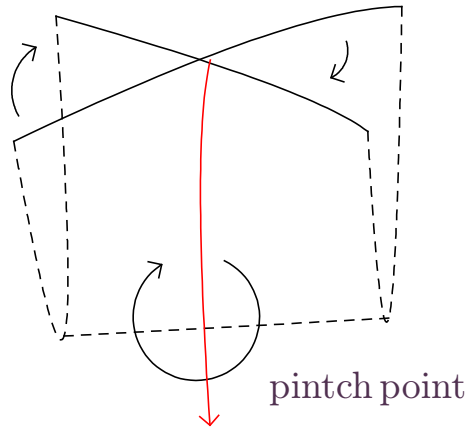
Theorem of Bendixson-Seidenberg. The elimination of nilpotent points holds for singularly foliated **surfaces**.

But... It is false for $\dim M \geq 3$.

Example of Sanz and Sancho-Salas:

$$\partial = \left(y \frac{\partial}{\partial x} + xz \frac{\partial}{\partial y} \right) + \beta z \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) - z \left(-x \frac{\partial}{\partial x} + 2z \frac{\partial}{\partial z} \right) + \lambda z \frac{\partial}{\partial x}$$

with $\beta \notin \frac{1}{2}\mathbb{Z}_{>0}$, $\lambda \in \mathbb{C}^*$.



Formal expansion of the “handle”

$$y = \tau(z) = \sum \tau_n z^n, \quad \tau_n \sim \lambda (n!)^2$$

$$x = \xi(z) = \sum \xi_n z^n, \quad \xi_n \sim \lambda (n!)^2$$

We cannot take the handle as a blowing-up center because it is non-analytic.

Weighted blowing-up

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

$$x \rightarrow \text{orbit through } x$$

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

$$x \rightarrow \text{orbit through } x$$

We consider the graph of the quotient mapping as a subset of $\mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

$$x \rightarrow \text{orbit through } x$$

We consider the graph of the quotient mapping as a subset of $\mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$

$$\text{Graph}(\pi) \subset \mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$$

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

$$x \rightarrow \text{orbit through } x$$

We consider the graph of the quotient mapping as a subset of $\mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$

$$\text{Graph}(\Phi) \subset \mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$$

The blowed-up space is its Zariski-closure

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

$$x \rightarrow \text{orbit through } x$$

We consider the graph of the quotient mapping as a subset of $\mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$

$$\text{Graph}(\Phi) \subset \mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$$

The blowed-up space is its Zariski-closure

$$\tilde{M} = \overline{\text{Graph}(\Phi)}^{\text{Zar}}$$

Weighted blowing-up

Fix some $\omega \in (\mathbb{Z}_{>0})^n$ and consider the orbits of the action of \mathbb{C}^* on $\mathbb{C}^n \setminus \{0\}$ by

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_n} x_n)$$

The orbit space is the so-called *weighted projective space*

$$\pi: \mathbb{C}^n \setminus \{0\} \longrightarrow \mathbb{P}_\omega^{n-1}$$

$$x \rightarrow \text{orbit through } x$$

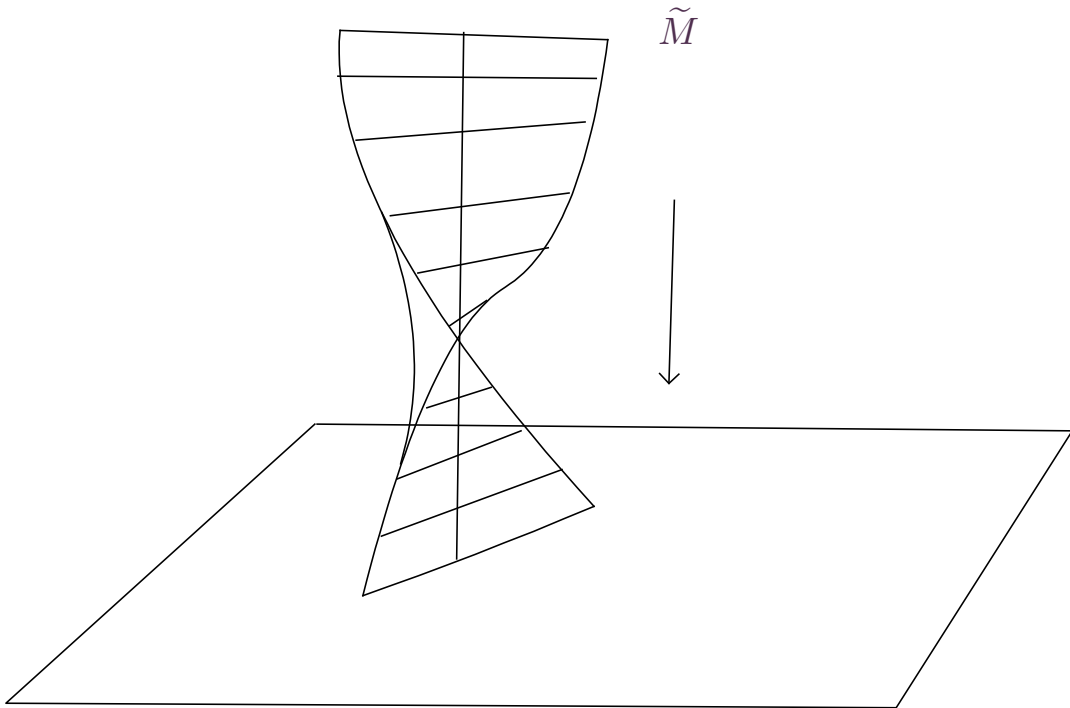
We consider the graph of the quotient mapping as a subset of $\mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$

$$\text{Graph}(\Phi) \subset \mathbb{C}^n \times \mathbb{P}_\omega^{n-1}$$

The blowed-up space is its Zariski-closure

$$\tilde{M} = \overline{\text{Graph}(\Phi)}^{\text{Zar}}$$

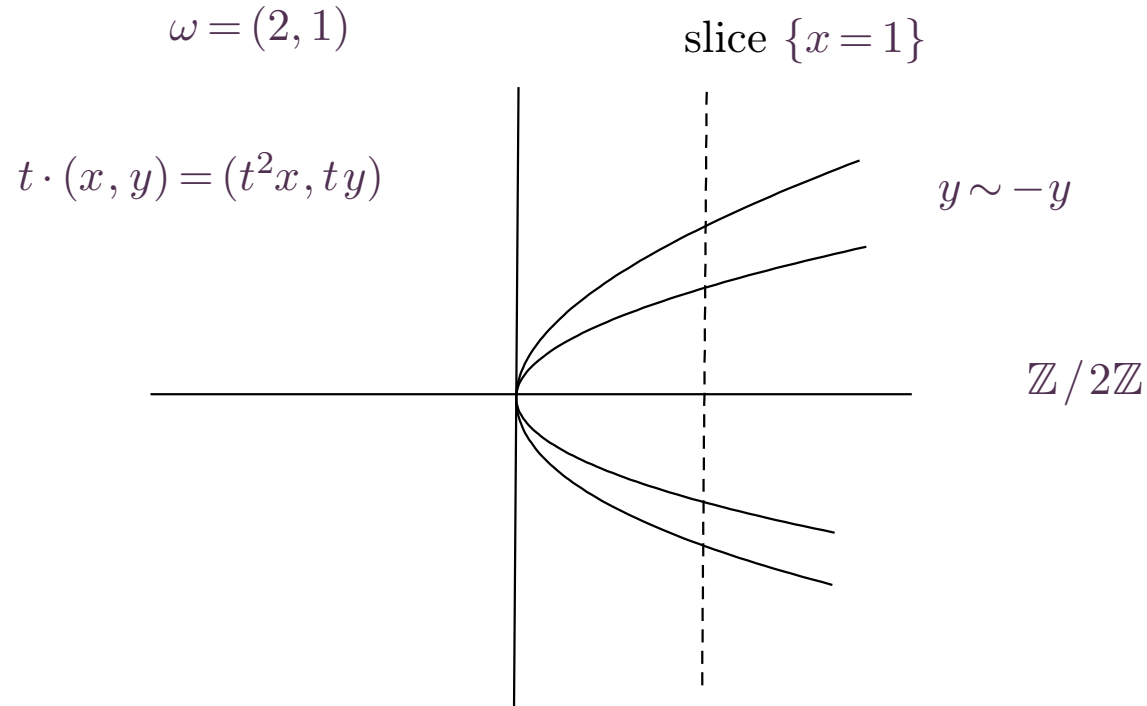
and the projection $\pi: \tilde{M} \rightarrow \mathbb{C}^n$ is the weighted blowing-up of the origin in \mathbb{C}^n .



Structure of \mathbb{P}_ω^{n-1} : The hyperplanes $\{x_i = 1\}$ are slices for the torus action modulo the action of a group of symmetries.

Structure of \mathbb{P}_ω^{n-1} : The hyperplanes $\{x_i = 1\}$ are slices for the torus action modulo the action of a group of symmetries.

Example



We have to take into account the quotient by $\mathbb{Z}/2\mathbb{Z}$.

The charts of a weighted-blowing up

The charts of a weighted-blowing up

The x_1 -directional chart is given by

The charts of a weighted-blowing up

The x_1 -directional chart is given by

$$\begin{aligned}x_1 &\rightarrow y_1^{\omega_1} \\x_2 &\rightarrow y_1^{\omega_1} y_2 \\&\vdots \\x_n &\rightarrow y_1^{\omega_n} y_n\end{aligned}$$

The charts of a weighted-blowing up

The x_1 -directional chart is given by

$$\begin{aligned}x_1 &\rightarrow y_1^{\omega_1} \\x_2 &\rightarrow y_1^{\omega_1} y_2 \\&\vdots \\x_n &\rightarrow y_1^{\omega_n} y_n\end{aligned}$$

We interpret (y_1, \dots, y_n) as an **orbifold chart** on \tilde{M} . Namely the affine space \mathbb{C}^n equipped with an action of the cyclic group $\mathbb{Z}/\omega_1\mathbb{Z}$, defined by

$$y_1 \rightarrow \xi y_1, \quad \text{For } 2 \leq k \leq n: \quad y_k \rightarrow \xi^{-\omega_k} y_k$$

where ξ is a ω_1^{th} -primitive root of unity. The other charts are defined analogously.

The charts of a weighted-blowing up

The x_1 -directional chart is given by

$$\begin{aligned}x_1 &\rightarrow y_1^{\omega_1} \\x_2 &\rightarrow y_1^{\omega_1} y_2 \\&\vdots \\x_n &\rightarrow y_1^{\omega_n} y_n\end{aligned}$$

We interpret (y_1, \dots, y_n) as an **orbifold chart** on \tilde{M} . Namely the affine space \mathbb{C}^n equipped with an action of the cyclic group $\mathbb{Z}/\omega_1\mathbb{Z}$, defined by

$$y_1 \rightarrow \xi y_1, \quad \text{For } 2 \leq k \leq n: \quad y_k \longrightarrow \xi^{-\omega_k} y_k$$

where ξ is a ω_1^{th} -primitive root of unity. The other charts are defined analogously.

The glueing of these charts equipments \tilde{M} with the structure of an **orbifold**.

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

An *orbifold chart* on M is given by triple (U, G, ϕ) where U is a connected open subset of \mathbb{R}^n (or \mathbb{C}^n), G is a finite subgroup of $\text{Diff}(U)$ and $\phi: U \rightarrow M$ is an open map

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

An *orbifold chart* on M is given by triple (U, G, ϕ) where U is a connected open subset of \mathbb{R}^n (or \mathbb{C}^n), G is a finite subgroup of $\text{Diff}(U)$ and $\phi: U \rightarrow M$ is an open map

which induces a homeomorphism $U/G \rightarrow \phi(U)$.

An *embedding* $\lambda: (V, H, \psi) \hookrightarrow (U, G, \phi)$ between orbifold charts on M is an embedding $\lambda: V \rightarrow U$ such that $\phi \circ \lambda = \psi$ (this induces an injective homomorphism $H \rightarrow G$).

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

An *orbifold chart* on M is given by triple (U, G, ϕ) where U is a connected open subset of \mathbb{R}^n (or \mathbb{C}^n), G is a finite subgroup of $\text{Diff}(U)$ and $\phi: U \rightarrow M$ is an open map which induces a homeomorphism $U/G \rightarrow \phi(U)$.

An *embedding* $\lambda: (V, H, \psi) \hookrightarrow (U, G, \phi)$ between orbifold charts on M is an embedding $\lambda: V \rightarrow U$ such that $\phi \circ \lambda = \psi$ (this induces an injective homomorphism $H \rightarrow G$).

Two orbifold charts (U, G, ϕ) and (V, H, ψ) on M are *compatible* if for any $z \in \phi(U) \cap \psi(V)$ there exists an orbifold chart (W, K, θ) defined near z and embeddings

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

An *orbifold chart* on M is given by triple (U, G, ϕ) where U is a connected open subset of \mathbb{R}^n (or \mathbb{C}^n), G is a finite subgroup of $\text{Diff}(U)$ and $\phi: U \rightarrow M$ is an open map

which induces a homeomorphism $U/G \rightarrow \phi(U)$.

An *embedding* $\lambda: (V, H, \psi) \hookrightarrow (U, G, \phi)$ between orbifold charts on M is an embedding $\lambda: V \rightarrow U$ such that $\phi \circ \lambda = \psi$ (this induces an injective homomorphism $H \rightarrow G$).

Two orbifold charts (U, G, ϕ) and (V, H, ψ) on M are *compatible* if for any $z \in \phi(U) \cap \psi(V)$ there exists an orbifold chart (W, K, θ) defined near z and embeddings

$$(W, K, \theta) \hookrightarrow (U, G, \phi), \quad (W, K, \theta) \hookrightarrow (V, H, \psi)$$

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

An *orbifold chart* on M is given by triple (U, G, ϕ) where U is a connected open subset of \mathbb{R}^n (or \mathbb{C}^n), G is a finite subgroup of $\text{Diff}(U)$ and $\phi: U \rightarrow M$ is an open map

which induces a homeomorphism $U/G \rightarrow \phi(U)$.

An *embedding* $\lambda: (V, H, \psi) \hookrightarrow (U, G, \phi)$ between orbifold charts on M is an embedding $\lambda: V \rightarrow U$ such that $\phi \circ \lambda = \psi$ (this induces an injective homomorphism $H \rightarrow G$).

Two orbifold charts (U, G, ϕ) and (V, H, ψ) on M are *compatible* if for any $z \in \phi(U) \cap \psi(V)$ there exists an orbifold chart (W, K, θ) defined near z and embeddings

$$(W, K, \theta) \hookrightarrow (U, G, \phi), \quad (W, K, \theta) \hookrightarrow (V, H, \psi)$$

An orbifold atlas on M is a collection $\mathcal{U} = \{(U_i, G_i, \phi_i)\}_{i \in I}$ of pairwise compatible orbifold charts such that $\{\phi(U_i)\}_{i \in I}$ forms an open cover of M .

Orbifolds (in one slide) (cf. Moerdijk, Mrcun - *Introduction to foliations and Lie groupoids*)

Let M be a paracompact Hausdorff space.

An *orbifold chart* on M is given by triple (U, G, ϕ) where U is a connected open subset of \mathbb{R}^n (or \mathbb{C}^n), G is a finite subgroup of $\text{Diff}(U)$ and $\phi: U \rightarrow M$ is an open map

which induces a homeomorphism $U/G \rightarrow \phi(U)$.

An *embedding* $\lambda: (V, H, \psi) \hookrightarrow (U, G, \phi)$ between orbifold charts on M is an embedding $\lambda: V \rightarrow U$ such that $\phi \circ \lambda = \psi$ (this induces an injective homomorphism $H \rightarrow G$).

Two orbifold charts (U, G, ϕ) and (V, H, ψ) on M are *compatible* if for any $z \in \phi(U) \cap \psi(V)$ there exists an orbifold chart (W, K, θ) defined near z and embeddings

$$(W, K, \theta) \hookrightarrow (U, G, \phi), \quad (W, K, \theta) \hookrightarrow (V, H, \psi)$$

An orbifold atlas on M is a collection $\mathcal{U} = \{(U_i, G_i, \phi_i)\}_{i \in I}$ of pairwise compatible orbifold charts such that $\{\phi(U_i)\}_{i \in I}$ forms an open cover of M .

An **orbifold** is a pair (M, \mathcal{U}) where M is paracompact Hausdorff topological space and \mathcal{U} is a maximal orbifold atlas on M .

A sub-variety $Y \subset M$ is a **sub-orbifold** if for each point $p \in Y$ there exists a local chart (U, G, ϕ) such that $\phi^{-1}(Y \cap U)$ is a G -invariant submanifold of U .

Important: 1) The local group actions are part of the structure.

Important: 1) The local group actions are part of the structure.

“Remember the group”

Important: 1) The local group actions are part of the structure.

“Remember the group”

2) The underlying topological space can be a singular.

Important: 1) The local group actions are part of the structure.

“Remember the group”

2) The underlying topological space can be a singular.

Example: $X = \mathbb{C}^2/G$, $G = \mathbb{Z}/2\mathbb{Z}$

Important: 1) The local group actions are part of the structure.

“Remember the group”

2) The underlying topological space can be a singular.

Example: $X = \mathbb{C}^2 / G$, $G = \mathbb{Z} / 2\mathbb{Z}$

$$(x, y) \longrightarrow (-x, -y)$$

Important: 1) The local group actions are part of the structure.

“Remember the group”

2) The underlying topological space can be a singular.

Example: $X = \mathbb{C}^2 / G$, $G = \mathbb{Z} / 2\mathbb{Z}$

$$(x, y) \longrightarrow (-x, -y)$$

$X = \text{Spec } \mathbb{C}[x, y]^G$ (ring of invariants)

$$\mathbb{C}[x, y]^G = \mathbb{C}[x^2, xy, y^2]$$

$$X = \text{spec } \mathbb{C}[u, v, w] / (v^2 - uw)$$

X is the quadratic cone.

General idea: The weighted blowing-up allows to take into account some *natural* quasi-homogeneous filtration of the initial object.

General idea: The weighted blowing-up allows to take into account some *natural* quasi-homogeneous filtration of the initial object.

Example: Let us blow-up the origin in \mathbb{C}^3 with weight $\omega = (1, 2, 2)$ and look at the pull-back of the Whitney umbrella $w = y^2 - zx^2$

General idea: The weighted blowing-up allows to take into account some *natural* quasi-homogeneous filtration of the initial object.

Example: Let us blow-up the origin in \mathbb{C}^3 with weight $\omega = (1, 2, 2)$ and look at the pull-back of the Whitney umbrella $w = y^2 - zx^2$

In the z -directional chart we obtain

$$x \rightarrow zx, \quad y \rightarrow z^2 y, \quad z \rightarrow z^2$$

General idea: The weighted blowing-up allows to take into account some *natural* quasi-homogeneous filtration of the initial object.

Example: Let us blow-up the origin in \mathbb{C}^3 with weight $\omega = (1, 2, 2)$ and look at the pull-back of the Whitney umbrella $w = y^2 - zx^2$

In the z -directional chart we obtain

$$x \rightarrow zx, \quad y \rightarrow z^2 y, \quad z \rightarrow z^2$$

and $w = z^4(y^2 - x^2)$ becomes a normal crossings divisor.

General idea: The weighted blowing-up allows to take into account some *natural* quasi-homogeneous filtration of the initial object.

Example: Let us blow-up the origin in \mathbb{C}^3 with weight $\omega = (1, 2, 2)$ and look at the pull-back of the Whitney umbrella $w = y^2 - zx^2$

In the z -directional chart we obtain

$$x \rightarrow zx, \quad y \rightarrow z^2 y, \quad z \rightarrow z^2$$

and $w = z^4(y^2 - x^2)$ becomes a normal crossings divisor.

This is the orbifold chart $(\mathbb{C}^3, \mathbb{Z}/2\mathbb{Z}, \phi)$, where the action is $(x, y, z) \rightarrow (-x, y, -z)$

General idea: The weighted blowing-up allows to take into account some *natural* quasi-homogeneous filtration of the initial object.

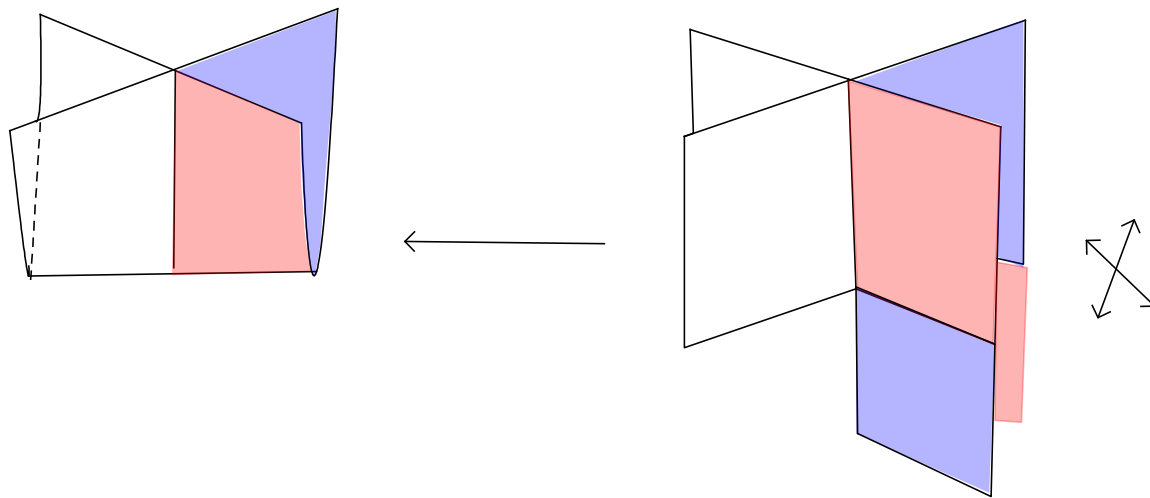
Example: Let us blow-up the origin in \mathbb{C}^3 with weight $\omega = (1, 2, 2)$ and look at the pull-back of the Whitney umbrella $w = y^2 - zx^2$

In the z -directional chart we obtain

$$x \rightarrow zx, \quad y \rightarrow z^2 y, \quad z \rightarrow z^2$$

and $w = z^4(y^2 - x^2)$ becomes a normal crossings divisor.

This is the orbifold chart $(\mathbb{C}^3, \mathbb{Z}/2\mathbb{Z}, \phi)$, where the action is $(x, y, z) \rightarrow (-x, y, -z)$



Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

The **spherical blowing-up** of \mathbb{R}^n at the origin with weight ω is the real analytic map

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1} \longrightarrow \mathbb{R}^n$$

given by $\Phi(t, \bar{x}) = t^\omega \bar{x}$. The exceptional divisor is the **boundary**

$$\text{boundary}(\mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1}) = \{0\} \times \mathbb{S}^{n-1}$$

Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

The **spherical blowing-up** of \mathbb{R}^n at the origin with weight ω is the real analytic map

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1} \longrightarrow \mathbb{R}^n$$

given by $\Phi(t, \bar{x}) = t^\omega \bar{x}$. The exceptional divisor is the **boundary**

$$\text{boundary}(\mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1}) = \{0\} \times \mathbb{S}^{n-1}$$

In general, we require the blowing-up center to have normal crossings with the boundary.

Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

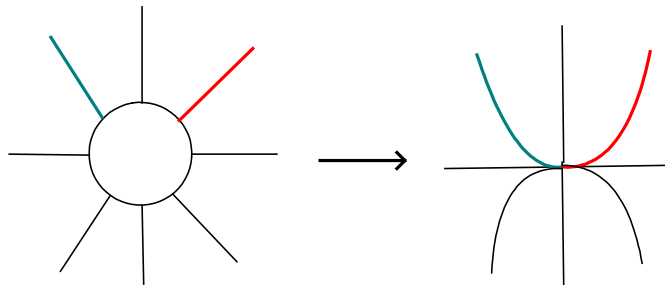
The **spherical blowing-up** of \mathbb{R}^n at the origin with weight ω is the real analytic map

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1} \longrightarrow \mathbb{R}^n$$

given by $\Phi(t, \bar{x}) = t^\omega \bar{x}$. The exceptional divisor is the **boundary**

$$\text{boundary}(\mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1}) = \{0\} \times \mathbb{S}^{n-1}$$

In general, we require the blowing-up center to have normal crossings with the boundary.



Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

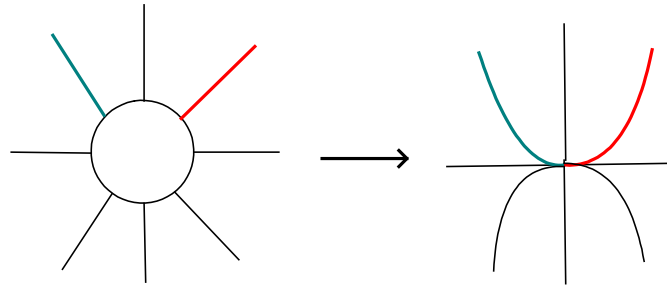
The **spherical blowing-up** of \mathbb{R}^n at the origin with weight ω is the real analytic map

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1} \longrightarrow \mathbb{R}^n$$

given by $\Phi(t, \bar{x}) = t^\omega \bar{x}$. The exceptional divisor is the **boundary**

$$\text{boundary}(\mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1}) = \{0\} \times \mathbb{S}^{n-1}$$

In general, we require the blowing-up center to have normal crossings with the boundary.



(advantage: stay in the category of smooth manifolds)

Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

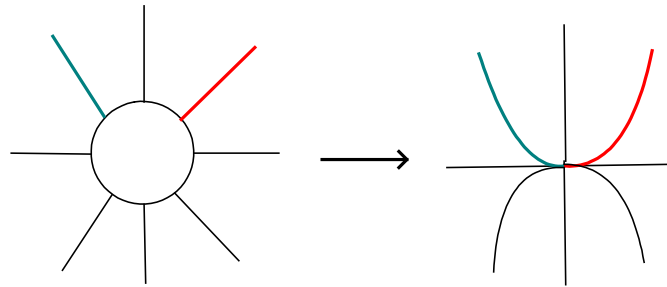
The **spherical blowing-up** of \mathbb{R}^n at the origin with weight ω is the real analytic map

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1} \longrightarrow \mathbb{R}^n$$

given by $\Phi(t, \bar{x}) = t^\omega \bar{x}$. The exceptional divisor is the **boundary**

$$\text{boundary}(\mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1}) = \{0\} \times \mathbb{S}^{n-1}$$

In general, we require the blowing-up center to have normal crossings with the boundary.



(advantage: stay in the category of smooth manifolds)

(drawback: we “forget the group” and potentially lose information about the local symmetries)

Over \mathbb{R} : We can alternatively work in the category of **manifold with corners**

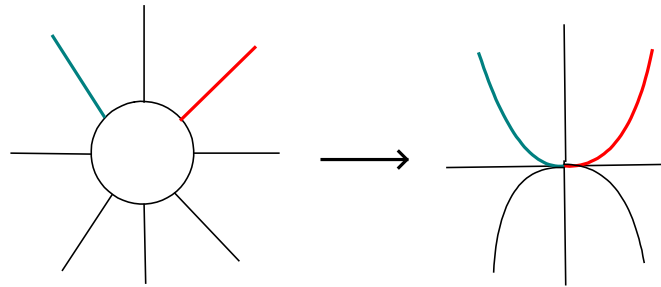
The **spherical blowing-up** of \mathbb{R}^n at the origin with weight ω is the real analytic map

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1} \longrightarrow \mathbb{R}^n$$

given by $\Phi(t, \bar{x}) = t^\omega \bar{x}$. The exceptional divisor is the **boundary**

$$\text{boundary}(\mathbb{R}_{\geq 0} \times \mathbb{S}^{n-1}) = \{0\} \times \mathbb{S}^{n-1}$$

In general, we require the blowing-up center to have normal crossings with the boundary.



(advantage: stay in the category of smooth manifolds)

(drawback: we “forget the group” and potentially lose information about the local symmetries)

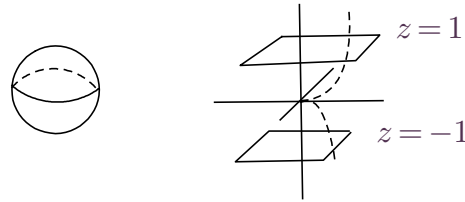
(c.f. Melrose’s “Analysis on manifolds with corners” - online)

Example: Spherical blowing-up of the (real) Whitney umbrella

Example: Spherical blowing-up of the (real) Whitney umbrella

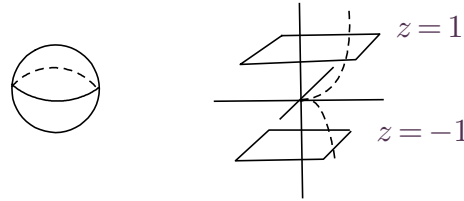
$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^2 \longrightarrow \mathbb{R}^3$$

Two z -directional “slices”:



Example: Spherical blowing-up of the (real) Whitney umbrella

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^2 \longrightarrow \mathbb{R}^3$$

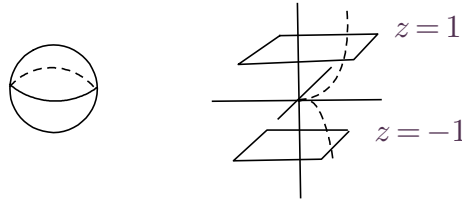


Two z -directional “slices”:

$$\{z > 0\}\text{-chart:} \quad x \rightarrow zx, \quad y \rightarrow z^2y, \quad z \rightarrow z^2: \quad f = z^4(y^2 - x^2)$$

Example: Spherical blowing-up of the (real) Whitney umbrella

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^2 \longrightarrow \mathbb{R}^3$$



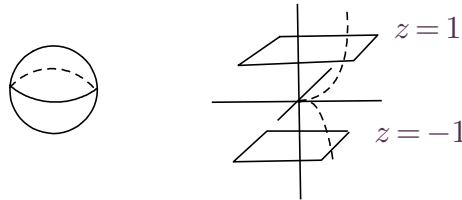
Two z -directional “slices”:

$$\{z > 0\}\text{-chart:} \quad x \rightarrow zx, \quad y \rightarrow z^2y, \quad z \rightarrow z^2: \quad f = z^4(y^2 - x^2)$$

$$\{z < 0\}\text{-chart:} \quad x \rightarrow z^2x, \quad y \rightarrow z^2y, \quad z \rightarrow -z^2: \quad f = z^4(y^2 + x^2)$$

Example: Spherical blowing-up of the (real) Whitney umbrella

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^2 \longrightarrow \mathbb{R}^3$$



Two z -directional “slices”:

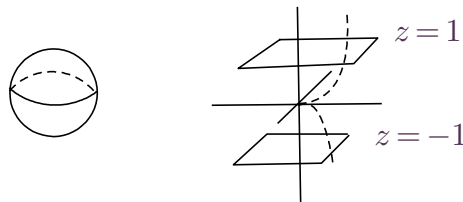
$$\{z > 0\}\text{-chart:} \quad x \rightarrow zx, \quad y \rightarrow z^2y, \quad z \rightarrow z^2: \quad f = z^4(y^2 - x^2)$$

$$\{z < 0\}\text{-chart:} \quad x \rightarrow z^2x, \quad y \rightarrow z^2y, \quad z \rightarrow -z^2: \quad f = z^4(y^2 + x^2)$$

$$\{x > 0\}\text{-chart:} \quad x \rightarrow \pm x, \quad y \rightarrow x^2y, \quad z \rightarrow x^2z: \quad f = x^4(y^2 - z)$$

Example: Spherical blowing-up of the (real) Whitney umbrella

$$\Phi: \mathbb{R}_{\geq 0} \times \mathbb{S}^2 \longrightarrow \mathbb{R}^3$$

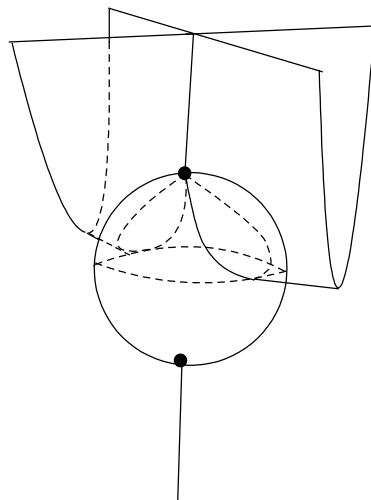


Two z-directional “slices”:

$$\{z > 0\}\text{-chart:} \quad x \rightarrow zx, \quad y \rightarrow z^2y, \quad z \rightarrow z^2: \quad f = z^4(y^2 - x^2)$$

$$\{z < 0\}\text{-chart:} \quad x \rightarrow z^2x, \quad y \rightarrow z^2y, \quad z \rightarrow -z^2: \quad f = z^4(y^2 + x^2)$$

$$\{x > 0\}\text{-chart:} \quad x \rightarrow \pm x, \quad y \rightarrow x^2y, \quad z \rightarrow x^2z: \quad f = x^4(y^2 - z)$$



Weighted blowing-up along global centers

Weighted blowing-up along global centers

If we consider the torus action

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_k} x_k, x_{k+1}, \dots, x_n)$$

Then the above construction leads to a local blowing-up with center $C = Z(x_1, \dots, x_k)$.

Weighted blowing-up along global centers

If we consider the torus action

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_k} x_k, x_{k+1}, \dots, x_n)$$

Then the above construction leads to a local blowing-up with center $C = Z(x_1, \dots, x_k)$.

We need to understand how to glue-up these local actions in order to obtain globally defined blowing-up with center C .

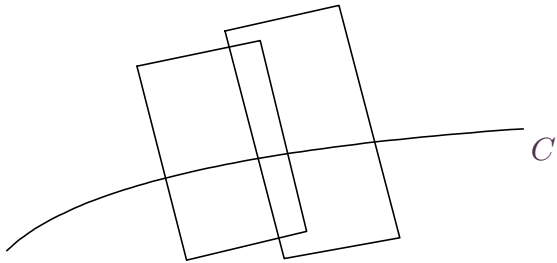
Weighted blowing-up along global centers

If we consider the torus action

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_k} x_k, x_{k+1}, \dots, x_n)$$

Then the above construction leads to a local blowing-up with center $C = Z(x_1, \dots, x_k)$.

We need to understand how to glue-up these local actions in order to obtain globally defined blowing-up with center C .



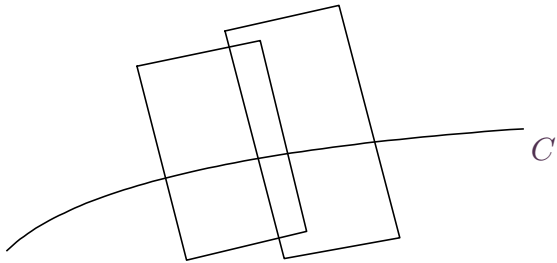
Weighted blowing-up along global centers

If we consider the torus action

$$(t, x) \longmapsto t \cdot x = t^\omega x = (t^{\omega_1} x_1, \dots, t^{\omega_k} x_k, x_{k+1}, \dots, x_n)$$

Then the above construction leads to a local blowing-up with center $C = Z(x_1, \dots, x_k)$.

We need to understand how to glue-up these local actions in order to obtain globally defined blowing-up with center C .



Existence of global Weighted blowing-ups

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

In other words, \mathcal{O}_k is the subring of functions of quasi-homogeneous weight $\geq k$.

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

In other words, \mathcal{O}_k is the subring of functions of quasi-homogeneous weight $\geq k$.

In order to define a quasi-homogeneous blow-up along a submanifold (suborbifold) $C \subset M$, we need to require the existence of a global trivialization of C

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

In other words, \mathcal{O}_k is the subring of functions of quasi-homogeneous weight $\geq k$.

In order to define a quasi-homogeneous blow-up along a submanifold (suborbifold) $C \subset M$, we need to require the existence of a global trivialization of C

Such that the diffeomorphisms between the transition charts respects the local quasi-homogeneous filtration. This is a non-trivial topological restriction.

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

In other words, \mathcal{O}_k is the subring of functions of quasi-homogeneous weight $\geq k$.

In order to define a quasi-homogeneous blow-up along a submanifold (suborbifold) $C \subset M$, we need to require the existence of a global trivialization of C

Such that the diffeomorphisms between the transition charts respects the local quasi-homogeneous filtration. This is a non-trivial topological restriction.

More abstractly: This amounts to the existence of a *global weighted filtration of the structure sheaf*. Namely a sequence of nested of ideal sheafs

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

In other words, \mathcal{O}_k is the subring of functions of quasi-homogeneous weight $\geq k$.

In order to define a quasi-homogeneous blow-up along a submanifold (suborbifold) $C \subset M$, we need to require the existence of a global trivialization of C

Such that the diffeomorphisms between the transition charts respects the local quasi-homogeneous filtration. This is a non-trivial topological restriction.

More abstractly: This amounts to the existence of a *global weighted filtration of the structure sheaf*. Namely a sequence of nested of ideal sheafs

$$\mathcal{O} = F_0 \supset F_1 \supset \cdots$$

Existence of global Weighted blowing-ups

A weighted blowing-up of a point $p \in M$ is fully determined by a **quasi-homogeneous filtration** of the local ring. Namely a filtration

$$\mathcal{O}_p = \mathcal{O}_0 \supset \mathcal{O}_1 \supset \mathcal{O}_2 \supset \cdots \quad \mathcal{O}_k \cdot \mathcal{O}_l \subset \mathcal{O}_{k+l},$$

such that in appropriate coordinates (x_1, \dots, x_n) , we have $x_1 \in \mathcal{O}_{\omega_1}, \dots, x_n \in \mathcal{O}_{\omega_n}$.

In other words, \mathcal{O}_k is the subring of functions of quasi-homogeneous weight $\geq k$.

In order to define a quasi-homogeneous blow-up along a submanifold (suborbifold) $C \subset M$, we need to require the existence of a global trivialization of C

Such that the diffeomorphisms between the transition charts respects the local quasi-homogeneous filtration. This is a non-trivial topological restriction.

More abstractly: This amounts to the existence of a *global weighted filtration of the structure sheaf*. Namely a sequence of nested of ideal sheafs

$$\mathcal{O} = F_0 \supset F_1 \supset \cdots$$

such that $F_i F_j \subset F_{i+j}$ and such that, for each point p on the support, the stalk of this filtration coincides with a quasi-homogeneous filtration as defined above.

Example: $C = Z(x, y) \subset \mathbb{C}^3$

$$\omega = (1, \beta, 0) \in \mathbb{Z}^3$$

$$\beta > 1$$

Example: $C = Z(x, y) \subset \mathbb{C}^3$

$$\omega = (1, \beta, 0) \in \mathbb{Z}^3$$

$$\beta > 1$$

All automorphisms of the form

$$x \rightarrow x + \rho y^m, \quad y \rightarrow y + \xi x^l, \quad l \geq \beta$$

Example: $C = Z(x, y) \subset \mathbb{C}^3$

$$\omega = (1, \beta, 0) \in \mathbb{Z}^3$$

$$\beta > 1$$

All automorphisms of the form

$$x \rightarrow x + \rho y^m, \quad y \rightarrow y + \xi x^l, \quad l \geq \beta$$

preserve the $(1, \beta, 0)$ -filtration of $\mathbb{C}[x, y, z]$.

Example: $C = Z(x, y) \subset \mathbb{C}^3$

$$\omega = (1, \beta, 0) \in \mathbb{Z}^3$$

$$\beta > 1$$

All automorphisms of the form

$$x \rightarrow x + \rho y^m, \quad y \rightarrow y + \xi x^l, \quad l \geq \beta$$

preserve the $(1, \beta, 0)$ -filtration of $\mathbb{C}[x, y, z]$.

More generally, all automorphisms obtained by integrating the Lie algebra (over \mathbb{C}) generated by

$$\left\{ x \frac{\partial}{\partial x}, y \frac{\partial}{\partial y}, x^l \frac{\partial}{\partial y}, y^m \frac{\partial}{\partial x} \mid m \geq 1, l \geq \beta \right\}$$

Weighted blowing-up of vector fields

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Transformation of the logarithmic basis

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Transformation of the logarithmic basis

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow \frac{1}{\omega_1} \left(x_1 \frac{\partial}{\partial x_1} - \omega_2 x_2 \frac{\partial}{\partial x_2} - \cdots - \omega_n x_n \frac{\partial}{\partial x_n} \right)$$

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Transformation of the logarithmic basis

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow \frac{1}{\omega_1} \left(x_1 \frac{\partial}{\partial x_1} - \omega_2 x_2 \frac{\partial}{\partial x_2} - \cdots - \omega_n x_n \frac{\partial}{\partial x_n} \right)$$

$$x_k \frac{\partial}{\partial x_k} \longrightarrow x_k \frac{\partial}{\partial x_k}$$

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Transformation of the logarithmic basis

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow \frac{1}{\omega_1} \left(x_1 \frac{\partial}{\partial x_1} - \omega_2 x_2 \frac{\partial}{\partial x_2} - \cdots - \omega_n x_n \frac{\partial}{\partial x_n} \right)$$

$$x_k \frac{\partial}{\partial x_k} \longrightarrow x_k \frac{\partial}{\partial x_k}$$

Example: $\partial = x \frac{\partial}{\partial x} + n y \frac{\partial}{\partial y}, \quad n \in \mathbb{Z}_{>0}.$

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Transformation of the logarithmic basis

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow \frac{1}{\omega_1} \left(x_1 \frac{\partial}{\partial x_1} - \omega_2 x_2 \frac{\partial}{\partial x_2} - \cdots - \omega_n x_n \frac{\partial}{\partial x_n} \right)$$

$$x_k \frac{\partial}{\partial x_k} \longrightarrow x_k \frac{\partial}{\partial x_k}$$

Example: $\partial = x \frac{\partial}{\partial x} + n y \frac{\partial}{\partial y}$, $n \in \mathbb{Z}_{>0}$.

$$x \rightarrow x, \quad y \rightarrow x^n y$$

$$\partial = x \frac{\partial}{\partial x}$$

Weighted blowing-up of vector fields

$$x_1 \rightarrow x_1^{\omega_1}, \quad \text{For } 2 \leq k \leq n: \quad x_k \rightarrow x_1^{\omega_k} x_k$$

Transformation of the logarithmic basis

$$x_1 \frac{\partial}{\partial x_1} \longrightarrow \frac{1}{\omega_1} \left(x_1 \frac{\partial}{\partial x_1} - \omega_2 x_2 \frac{\partial}{\partial x_2} - \cdots - \omega_n x_n \frac{\partial}{\partial x_n} \right)$$

$$x_k \frac{\partial}{\partial x_k} \longrightarrow x_k \frac{\partial}{\partial x_k}$$

Example: $\partial = x \frac{\partial}{\partial x} + n y \frac{\partial}{\partial y}$, $n \in \mathbb{Z}_{>0}$.

$$x \rightarrow x, \quad y \rightarrow x^n y$$

$$\partial = x \frac{\partial}{\partial x}$$

The solution curves of ∂ are precisely the orbits of the torus action $t \cdot (x, y) = (tx, t^n y)$.

Example: weighted resolution of the cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

Example: weighted resolution of the cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

Based on the quasi-homogeneity the almost first integral $y^2 - x^3$, we consider the blow-up with weight $(2, 3)$.

Example: weighted resolution of the cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

Based on the quasi-homogeneity the almost first integral $y^2 - x^3$, we consider the blow-up with weight $(2, 3)$.

We write ∂ in the logarithmic basis

$$\partial = 2x^{-1}y \left(x \frac{\partial}{\partial x} \right) + 3x^2y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$

Example: weighted resolution of the cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

Based on the quasi-homogeneity the almost first integral $y^2 - x^3$, we consider the blow-up with weight $(2, 3)$.

We write ∂ in the logarithmic basis

$$\partial = 2x^{-1}y \left(x \frac{\partial}{\partial x} \right) + 3x^2y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$

In the x -chart: $x \rightarrow x^2, y \rightarrow x^3y$: (Using the assumption of the $(2, 3)$ -order of Δ)

$$\partial = xy \left(x \frac{\partial}{\partial x} - 3y \frac{\partial}{\partial y} \right) + 3xy^{-1} \left(y \frac{\partial}{\partial y} \right) + x^2\Delta = x \left(xy \frac{\partial}{\partial x} + 3(1 - y^2) \frac{\partial}{\partial y} \right) + x^2\Delta$$

Example: weighted resolution of the cuspidal singularity

$$\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$$

Based on the quasi-homogeneity the almost first integral $y^2 - x^3$, we consider the blow-up with weight $(2, 3)$.

We write ∂ in the logarithmic basis

$$\partial = 2x^{-1}y \left(x \frac{\partial}{\partial x} \right) + 3x^2y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$

In the x -chart: $x \rightarrow x^2, y \rightarrow x^3y$: (Using the assumption of the $(2, 3)$ -order of Δ)

$$\partial = xy \left(x \frac{\partial}{\partial x} - 3y \frac{\partial}{\partial y} \right) + 3xy^{-1} \left(y \frac{\partial}{\partial y} \right) + x^2\Delta = x \left(xy \frac{\partial}{\partial x} + 3(1 - y^2) \frac{\partial}{\partial y} \right) + x^2\Delta$$

The divisor $\{x = 0\}$ is contained in the nilpotent locus. We factor out x and write

$$\partial_1 = xy \frac{\partial}{\partial x} + 3(1 - y^2) \frac{\partial}{\partial y} + \Delta_1$$

In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

The original cuspidal foliation

In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

The original cuspidal foliation

$$\partial = 2x^{-1}y \left(x \frac{\partial}{\partial x} \right) + 3x^2y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$

transforms into

In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

The original cuspidal foliation

$$\partial = 2x^{-1}y\left(x \frac{\partial}{\partial x}\right) + 3x^2y^{-1}\left(y \frac{\partial}{\partial y}\right) + \Delta$$

transforms into

$$\partial = 2x^{-1}y\left(x \frac{\partial}{\partial x}\right) + x^2y\left(y \frac{\partial}{\partial y} - 2x \frac{\partial}{\partial x}\right) + y^2\Delta = y\left(2(1 - x^3)\frac{\partial}{\partial x} + x^2y \frac{\partial}{\partial y}\right) + y^2\Delta$$

In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

The original cuspidal foliation

$$\partial = 2x^{-1}y\left(x\frac{\partial}{\partial x}\right) + 3x^2y^{-1}\left(y\frac{\partial}{\partial y}\right) + \Delta$$

transforms into

$$\partial = 2x^{-1}y\left(x\frac{\partial}{\partial x}\right) + x^2y\left(y\frac{\partial}{\partial y} - 2x\frac{\partial}{\partial x}\right) + y^2\Delta = y\left(2(1-x^3)\frac{\partial}{\partial x} + x^2y\frac{\partial}{\partial y}\right) + y^2\Delta$$

and, factoring out y , we obtain

$$\partial_2 = 2(1-x^3)\frac{\partial}{\partial x} - x^2y\frac{\partial}{\partial y} + \Delta_2$$

In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

The original cuspidal foliation

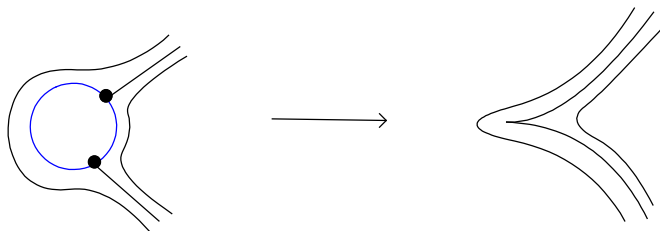
$$\partial = 2x^{-1}y \left(x \frac{\partial}{\partial x} \right) + 3x^2y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$

transforms into

$$\partial = 2x^{-1}y \left(x \frac{\partial}{\partial x} \right) + x^2y \left(y \frac{\partial}{\partial y} - 2x \frac{\partial}{\partial x} \right) + y^2\Delta = y \left(2(1 - x^3) \frac{\partial}{\partial x} + x^2y \frac{\partial}{\partial y} \right) + y^2\Delta$$

and, factoring out y , we obtain

$$\partial_2 = 2(1 - x^3) \frac{\partial}{\partial x} - x^2y \frac{\partial}{\partial y} + \Delta_2$$



In the y -chart: $x \rightarrow y^2x, y \rightarrow y^3$:

The original cuspidal foliation

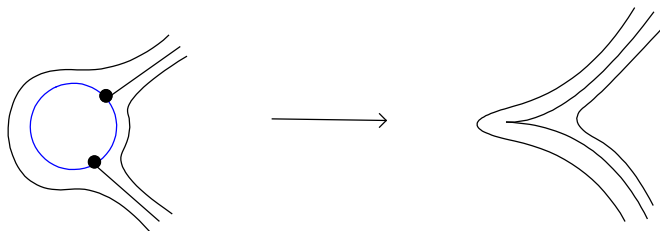
$$\partial = 2x^{-1}y\left(x \frac{\partial}{\partial x}\right) + 3x^2y^{-1}\left(y \frac{\partial}{\partial y}\right) + \Delta$$

transforms into

$$\partial = 2x^{-1}y\left(x \frac{\partial}{\partial x}\right) + x^2y\left(y \frac{\partial}{\partial y} - 2x \frac{\partial}{\partial x}\right) + y^2\Delta = y\left(2(1-x^3)\frac{\partial}{\partial x} + x^2y \frac{\partial}{\partial y}\right) + y^2\Delta$$

and, factoring out y , we obtain

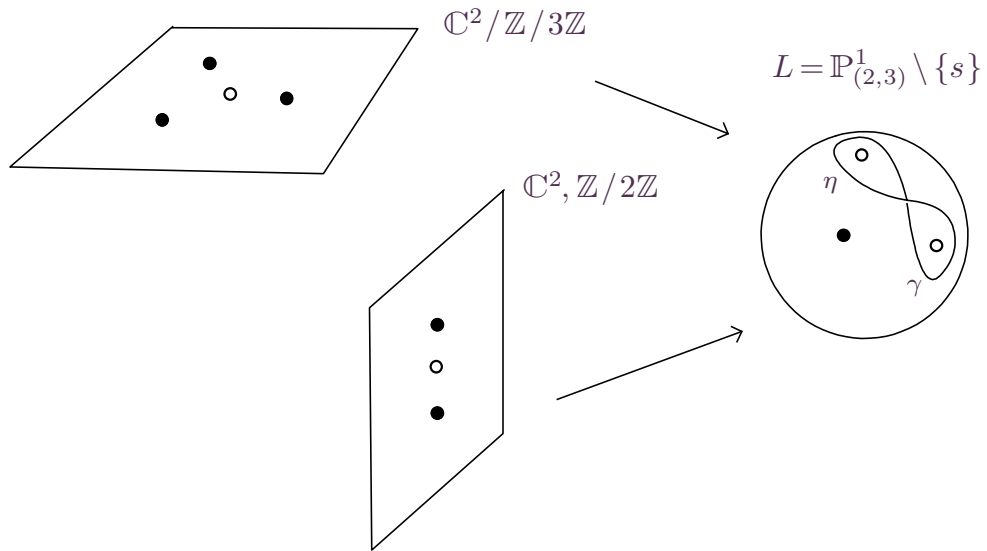
$$\partial_2 = 2(1-x^3)\frac{\partial}{\partial x} - x^2y \frac{\partial}{\partial y} + \Delta_2$$



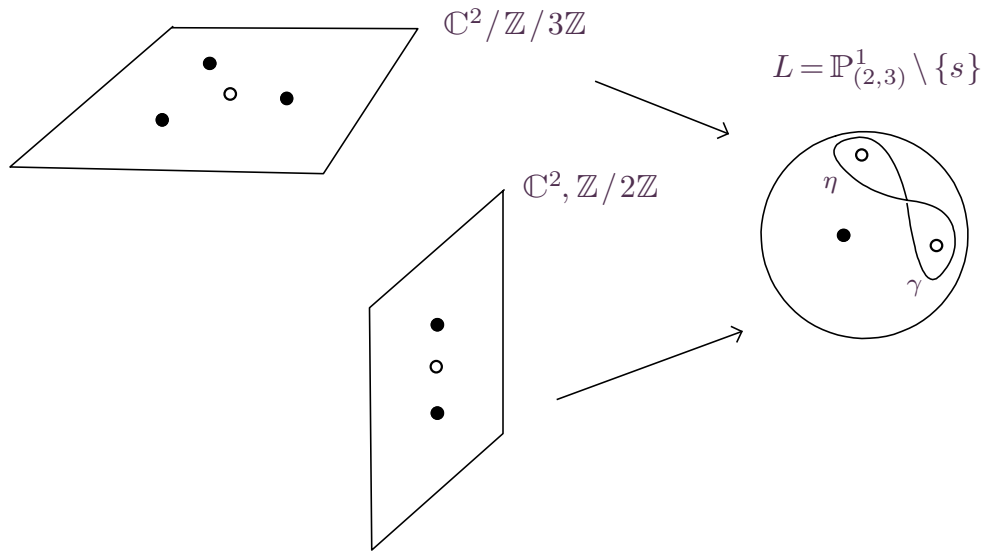
The resulting perturbation Δ is of quadratic order along E (does not change the eigenvalues at the singular point)

Local symmetries of the foliated orbifold

Local symmetries of the foliated orbifold



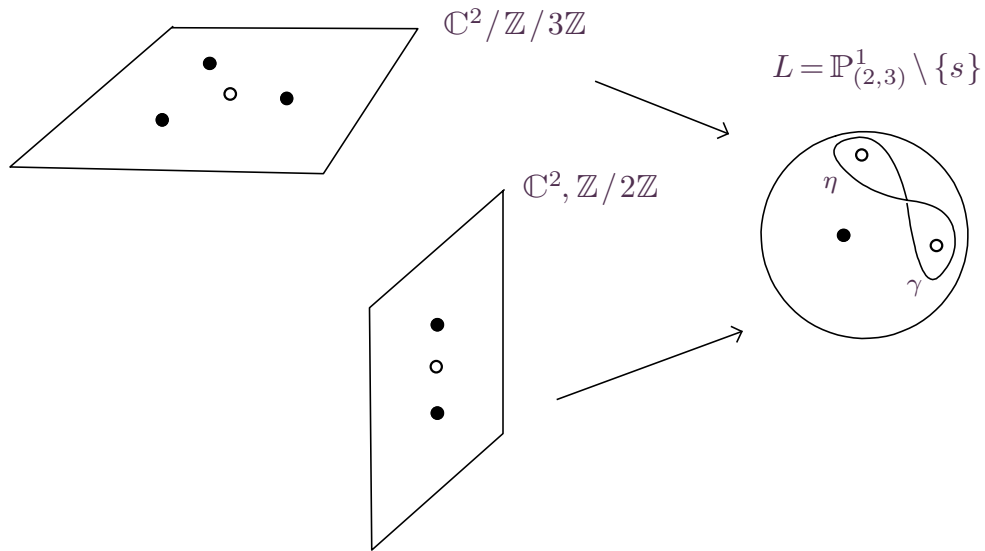
Local symmetries of the foliated orbifold



The fundamental group of the (orbi-)leaf L is

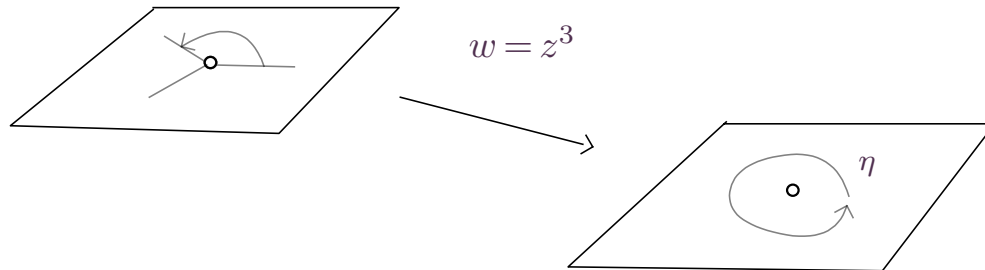
$$\pi_1(L) = \{\gamma, \eta, \rho \mid \gamma^2 = \eta^3 = 1, \rho = \gamma\eta\}$$

Local symmetries of the foliated orbifold



The fundamental group of the (orbi-)leaf L is

$$\pi_1(L) = \{\gamma, \eta, \rho \mid \gamma^2 = \eta^3 = 1, \rho = \gamma\eta\}$$

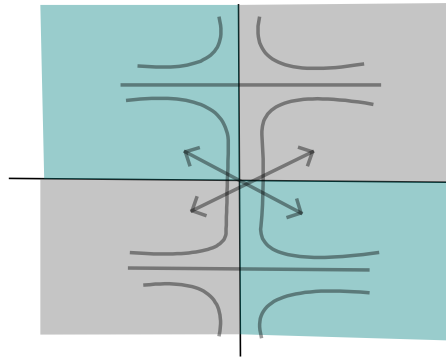


$$\partial_1 = xy \frac{\partial}{\partial x} + 3(1 - y^2) \frac{\partial}{\partial y} \quad \hookrightarrow \mathbb{Z}/2\mathbb{Z}$$

$$\partial_1 = xy \frac{\partial}{\partial x} + 3(1 - y^2) \frac{\partial}{\partial y} \quad \curvearrowright \quad \mathbb{Z}/2\mathbb{Z}$$

$$g \cdot x = -x, \quad g \cdot y \rightarrow -y$$

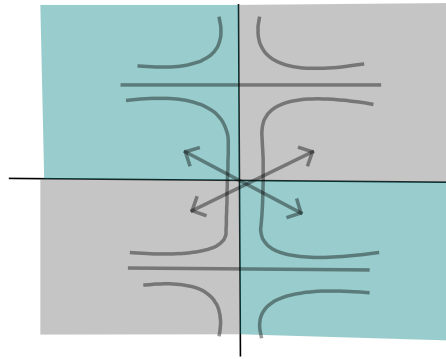
$$g \cdot \partial_1 = -\partial_1$$



$$\partial_1 = xy \frac{\partial}{\partial x} + 3(1 - y^2) \frac{\partial}{\partial y} \quad \curvearrowright \quad \mathbb{Z}/2\mathbb{Z}$$

$$g \cdot x = -x, \quad g \cdot y \rightarrow -y$$

$$g \cdot \partial_1 = -\partial_1$$

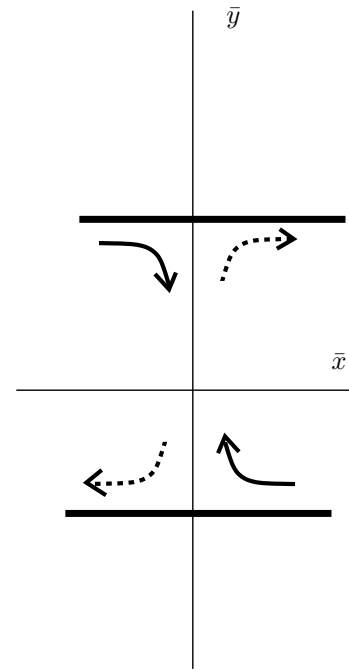
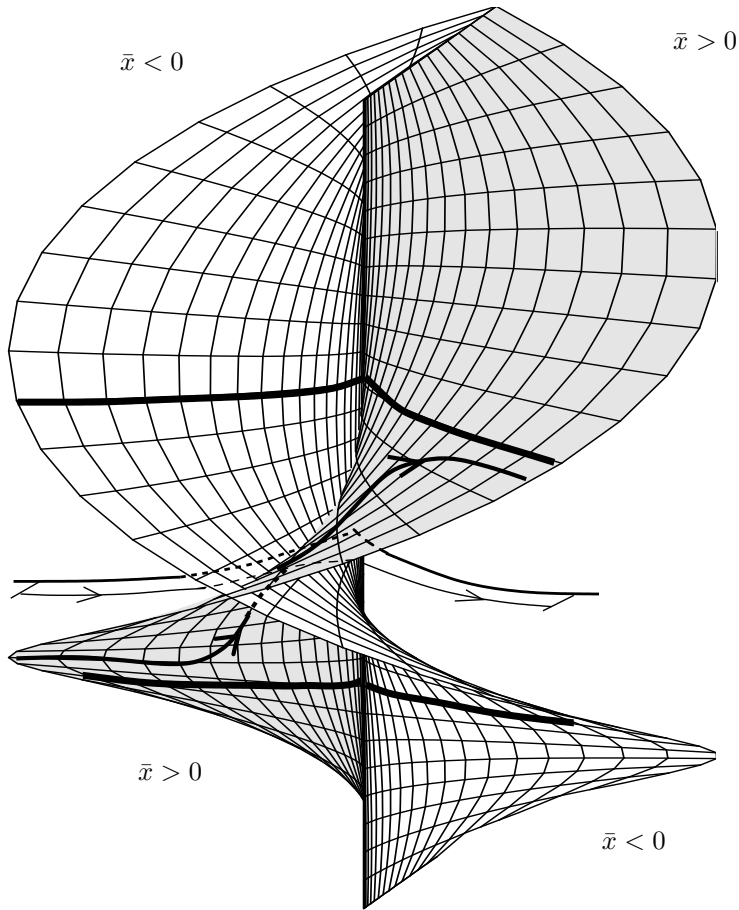


Other chart

$$\partial_2 = 2(1 - x^3) \frac{\partial}{\partial x} - x^2 y \frac{\partial}{\partial y}$$

$$g \cdot x = \xi^{-2} x, \quad g \cdot y = \xi y, \quad (\xi^3 = \text{id})$$

$$g \cdot \partial_2 = \xi^2 \partial_2$$



Elimination of nilpotent points in dimension two - Classical proof

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Suppose that the germ is singular. We can assume that $a, b \in \mathbb{C}\{x, y\}$ have no common factor and consider

$$m(0) = \dim_{\mathbb{C}} \frac{\mathbb{C}\{x, y\}}{(a, b)} \geq 1, \quad \mu(0) = \min_k \{(J^k a, J^k b) \neq (0, 0)\}$$

$(m(0))$ is the *local intersection multiplicity* of the curves $Z(a)$ and $Z(b)$ at 0)

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Suppose that the germ is singular. We can assume that $a, b \in \mathbb{C}\{x, y\}$ have no common factor and consider

$$m(0) = \dim_{\mathbb{C}} \frac{\mathbb{C}\{x, y\}}{(a, b)} \geq 1, \quad \mu(0) = \min_k \{(J^k a, J^k b) \neq (0, 0)\}$$

$(m(0))$ is the *local intersection multiplicity* of the curves $Z(a)$ and $Z(b)$ at 0)

After a blowing-up, the *Noether's formula* give,

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Suppose that the germ is singular. We can assume that $a, b \in \mathbb{C}\{x, y\}$ have no common factor and consider

$$m(0) = \dim_{\mathbb{C}} \frac{\mathbb{C}\{x, y\}}{(a, b)} \geq 1, \quad \mu(0) = \min_k \{(J^k a, J^k b) \neq (0, 0)\}$$

($m(0)$ is the *local intersection multiplicity* of the curves $Z(a)$ and $Z(b)$ at 0)

After a blowing-up, the *Noether's formula* give,

$$\sum m(\tilde{p}_j) = m(0) - l^2 + l + 1$$

where $\{\tilde{p}_j\}$ are the singular points of the blowed-up vector field and

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Suppose that the germ is singular. We can assume that $a, b \in \mathbb{C}\{x, y\}$ have no common factor and consider

$$m(0) = \dim_{\mathbb{C}} \frac{\mathbb{C}\{x, y\}}{(a, b)} \geq 1, \quad \mu(0) = \min_k \{(J^k a, J^k b) \neq (0, 0)\}$$

($m(0)$ is the *local intersection multiplicity* of the curves $Z(a)$ and $Z(b)$ at 0)

After a blowing-up, the *Noether's formula* give,

$$\sum m(\tilde{p}_j) = m(0) - l^2 + l + 1$$

where $\{\tilde{p}_j\}$ are the singular points of the blowed-up vector field and

$$l = \begin{cases} \mu(a, b) & \text{if } \partial \text{ is non-dicritic} \\ \mu(a, b) + 1 & \text{if } \partial \text{ is dicritic} \end{cases}$$

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Suppose that the germ is singular. We can assume that $a, b \in \mathbb{C}\{x, y\}$ have no common factor and consider

$$m(0) = \dim_{\mathbb{C}} \frac{\mathbb{C}\{x, y\}}{(a, b)} \geq 1, \quad \mu(0) = \min_k \{(J^k a, J^k b) \neq (0, 0)\}$$

($m(0)$ is the *local intersection multiplicity* of the curves $Z(a)$ and $Z(b)$ at 0)

After a blowing-up, the *Noether's formula* give,

$$\sum m(\tilde{p}_j) = m(0) - l^2 + l + 1$$

where $\{\tilde{p}_j\}$ are the singular points of the blowed-up vector field and

$$l = \begin{cases} \mu(a, b) & \text{if } \partial \text{ is non-dicritic} \\ \mu(a, b) + 1 & \text{if } \partial \text{ is dicritic} \end{cases}$$

- If $l(0) \geq 2$ then $m(\tilde{p}_j) < m(p)$

Elimination of nilpotent points in dimension two - Classical proof

Van der Essen's proof (c.f. Ilyashenko-Yakovenko's book) We write $\partial = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$

Suppose that the germ is singular. We can assume that $a, b \in \mathbb{C}\{x, y\}$ have no common factor and consider

$$m(0) = \dim_{\mathbb{C}} \frac{\mathbb{C}\{x, y\}}{(a, b)} \geq 1, \quad \mu(0) = \min_k \{(J^k a, J^k b) \neq (0, 0)\}$$

($m(0)$ is the *local intersection multiplicity* of the curves $Z(a)$ and $Z(b)$ at 0)

After a blowing-up, the *Noether's formula* give,

$$\sum m(\tilde{p}_j) = m(0) - l^2 + l + 1$$

where $\{\tilde{p}_j\}$ are the singular points of the blowed-up vector field and

$$l = \begin{cases} \mu(a, b) & \text{if } \partial \text{ is non-dicritic} \\ \mu(a, b) + 1 & \text{if } \partial \text{ is dicritic} \end{cases}$$

- If $l(0) \geq 2$ then $m(\tilde{p}_j) < m(p)$
- If $l(0) = 1$ then this is a special case which has to be treated separately...

Example of “special case”.

$$y \frac{\partial}{\partial x} + x^M \frac{\partial}{\partial y}$$

$$\mu = 1, m = M \geq 3$$

$$x \rightarrow x, \quad y \rightarrow xy$$

$$xy \frac{\partial}{\partial x} + (x^{M-1} - y^2) \frac{\partial}{\partial y}$$

$$\mu = 2, m = M + 1$$

Example of “special case”.

$$y \frac{\partial}{\partial x} + x^M \frac{\partial}{\partial y}$$

$$\mu = 1, m = M \geq 3$$

$$x \rightarrow x, \quad y \rightarrow xy$$

$$xy \frac{\partial}{\partial x} + (x^{M-1} - y^2) \frac{\partial}{\partial y}$$

$$\mu = 2, m = M + 1$$

The “invariant” increases and this case needs to be treated separately...

Example of “special case”.

$$y \frac{\partial}{\partial x} + x^M \frac{\partial}{\partial y}$$

$$\mu = 1, m = M \geq 3$$

$$x \rightarrow x, \quad y \rightarrow xy$$

$$xy \frac{\partial}{\partial x} + (x^{M-1} - y^2) \frac{\partial}{\partial y}$$

$$\mu = 2, m = M + 1$$

The “invariant” increases and this case needs to be treated separately...

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E such that

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E such that

$\text{Nilp}(M, \mathcal{F})$ is of codimension two (i.e. consists of isolated points).

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E such that

$\text{Nilp}(M, \mathcal{F})$ is of codimension two (i.e. consists of isolated points).

Definition: The **local desingularization strategy** at a point $p \in \text{Nilp}(M, \mathcal{F})$ is the choice of a quasi-homogeneous filtration of the local ring.

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E such that

$\text{Nilp}(M, \mathcal{F})$ is of codimension two (i.e. consists of isolated points).

Definition: The **local desingularization strategy** at a point $p \in \text{Nilp}(M, \mathcal{F})$ is the choice of a quasi-homogeneous filtration of the local ring.

Using weighted blowing-ups (modified version of a proof by M.Pelletier).

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E such that

$\text{Nilp}(M, \mathcal{F})$ is of codimension two (i.e. consists of isolated points).

Definition: The **local desingularization strategy** at a point $p \in \text{Nilp}(M, \mathcal{F})$ is the choice of a quasi-homogeneous filtration of the local ring.

which will define the blowing-up...

Intermezzo: The Newton polyhedron of a germ of vector field

Intermezzo: The Newton polyhedron of a germ of vector field

Let us **fix** local coordinates (x_1, \dots, x_n) . We can write $\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$.

Intermezzo: The Newton polyhedron of a germ of vector field

Let us **fix** local coordinates (x_1, \dots, x_n) . We can write $\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$.

Instead, We expand ∂ is the logarithmic basis $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$ as

Intermezzo: The Newton polyhedron of a germ of vector field

Let us **fix** local coordinates (x_1, \dots, x_n) . We can write $\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$.

Instead, We expand ∂ in the logarithmic basis $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$ as

$$\partial = b_1 x_1 \frac{\partial}{\partial x_1} + \dots + b_n x_n \frac{\partial}{\partial x_n},$$

Intermezzo: The Newton polyhedron of a germ of vector field

Let us **fix** local coordinates (x_1, \dots, x_n) . We can write $\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$.

Instead, We expand ∂ in the logarithmic basis $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$ as

$$\partial = b_1 x_1 \frac{\partial}{\partial x_1} + \dots + b_n x_n \frac{\partial}{\partial x_n},$$

where each $b_i = x_i^{-1} a_i$ has potentially a pole along $(x_i = 0)$.

Intermezzo: The Newton polyhedron of a germ of vector field

Let us **fix** local coordinates (x_1, \dots, x_n) . We can write $\partial = a_1 \frac{\partial}{\partial x_1} + \dots + a_n \frac{\partial}{\partial x_n}$.

Instead, We expand ∂ in the logarithmic basis $\left\{ x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\}$ as

$$\partial = b_1 x_1 \frac{\partial}{\partial x_1} + \dots + b_n x_n \frac{\partial}{\partial x_n},$$

where each $b_i = x_i^{-1} a_i$ has potentially a pole along $(x_i = 0)$.

We can reorder the expansion and write the monomial expansion

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

where, we recall, each $L(\mu) = \sum \mu_i x_i \frac{\partial}{\partial x_i}$ is a diagonal vector field, i.e. an element of the \mathbb{C} -maximal toral subalgebra

$$\mathfrak{t} = \left\langle x_1 \frac{\partial}{\partial x_1}, \dots, x_n \frac{\partial}{\partial x_n} \right\rangle$$

defined by (x_1, \dots, x_n) .

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

The **support** of ∂ with (respect to x) is defined by $\text{supp}_x(\partial) = \{k \mid \mu_k \neq 0\}$ and

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

The **support** of ∂ with (respect to x) is defined by $\text{supp}_x(\partial) = \{k \mid \mu_k \neq 0\}$ and

$$\text{New}_x(\partial) = \text{conv}(\text{supp}_x(\partial)) + \mathbb{R}_{\geq 0}^n$$

is the **Newton polyhedron** of ∂ (with respect to the coordinates x).

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

The **support** of ∂ with (respect to x) is defined by $\text{supp}_x(\partial) = \{k \mid \mu_k \neq 0\}$ and

$$\text{New}_x(\partial) = \text{conv}(\text{supp}_x(\partial)) + \mathbb{R}_{\geq 0}^n$$

is the **Newton polyhedron** of ∂ (with respect to the coordinates x).

Example: (cuspidal case) $\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

The **support** of ∂ with (respect to x) is defined by $\text{supp}_x(\partial) = \{k \mid \mu_k \neq 0\}$ and

$$\text{New}_x(\partial) = \text{conv}(\text{supp}_x(\partial)) + \mathbb{R}_{\geq 0}^n$$

is the **Newton polyhedron** of ∂ (with respect to the coordinates x).

Example: (cuspidal case) $\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$

$$\partial = 2 x^{-1} y \left(x \frac{\partial}{\partial x} \right) + 3 x^2 y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$

$$\partial = \sum_{k \in \mathbb{Z}^n} x^k L(\mu_k)$$

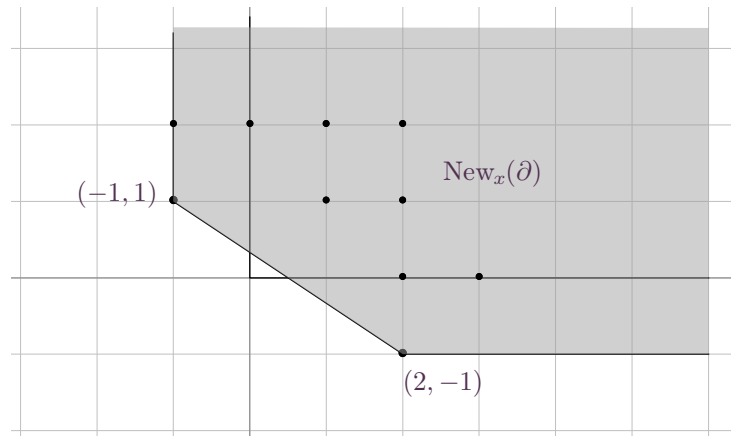
The **support** of ∂ with (respect to x) is defined by $\text{supp}_x(\partial) = \{k \mid \mu_k \neq 0\}$ and

$$\text{New}_x(\partial) = \text{conv}(\text{supp}_x(\partial)) + \mathbb{R}_{\geq 0}^n$$

is the **Newton polyhedron** of ∂ (with respect to the coordinates x).

Example: (cuspidal case) $\partial = 2y \frac{\partial}{\partial x} + 3x^2 \frac{\partial}{\partial y} + \Delta$

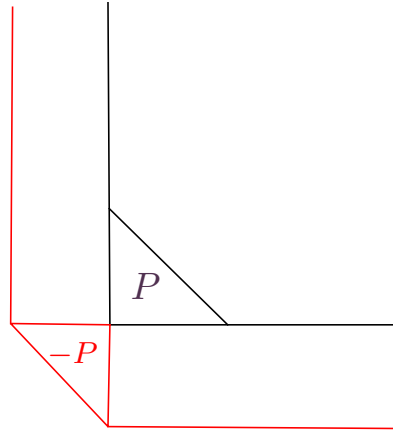
$$\partial = 2 x^{-1} y \left(x \frac{\partial}{\partial x} \right) + 3 x^2 y^{-1} \left(y \frac{\partial}{\partial y} \right) + \Delta$$



Remarks: 1) $\text{New}_x(\partial)$ is always contained in the convex region

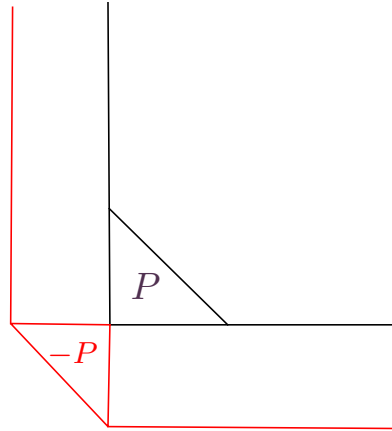
Remarks: 1) $\text{New}_x(\partial)$ is always contained in the convex region

$$\mathcal{N} = -(\underbrace{\{k \in \mathbb{N}_{\geq 0} \mid |k| \leq 1\}}_P) + \mathbb{R}_{\geq 0}^n$$



Remarks: 1) $\text{New}_x(\partial)$ is always contained in the convex region

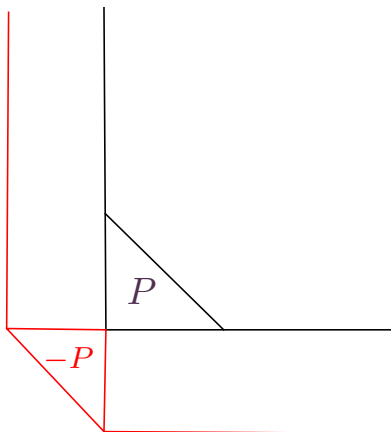
$$\mathcal{N} = -(\underbrace{\{k \in \mathbb{N}_{\geq 0} \mid |k| \leq 1\}}_P) + \mathbb{R}_{\geq 0}^n$$



2) The hypersurface $(x_i = 0)$ is invariant by ∂ if and only if $\text{supp}_x(\partial) \subset \{k : k_i \geq 0\}$.

Remarks: 1) $\text{New}_x(\partial)$ is always contained in the convex region

$$\mathcal{N} = -(\underbrace{\{k \in \mathbb{N}_{\geq 0} \mid |k| \leq 1\}}_P) + \mathbb{R}_{\geq 0}^n$$



2) The hypersurface $(x_i = 0)$ is invariant by ∂ if and only if $\text{supp}_x(\partial) \subset \{k: k_i \geq 0\}$.

3) The hypersurface $(x_i = 0)$ is tightly invariant by ∂ if and only if

$$\text{supp}_x(\partial) \subset \{k: k_i \geq 0\} \quad \wedge \quad \text{supp}_x(\partial) \cap \{k: k_i = 0\} \neq \emptyset$$

Example. $\partial = ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y}$

Example. $\partial = ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y}$

$(x=0)$ invariant $\iff \partial(\langle x \rangle) \subset \langle x \rangle \iff a \in \mathbb{C}\{x, y\} \iff [(k, l) \in \text{supp}(\partial) \implies k \geq 0]$

Example. $\partial = ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y}$

$(x=0)$ invariant $\iff \partial(\langle x \rangle) \subset \langle x \rangle \iff a \in \mathbb{C}\{x, y\} \iff [(k, l) \in \text{supp}(\partial) \implies k \geq 0]$

$(x=0)$ not tightly invariant $\iff (\partial(\langle x \rangle) \subset \langle x \rangle^2)$

Example. $\partial = ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y}$

$(x=0)$ invariant $\iff \partial(\langle x \rangle) \subset \langle x \rangle \iff a \in \mathbb{C}\{x, y\} \iff [(k, l) \in \text{supp}(\partial) \implies k \geq 0]$

$(x=0)$ not tightly invariant $\iff (\partial(\langle x \rangle) \subset \langle x \rangle^2$

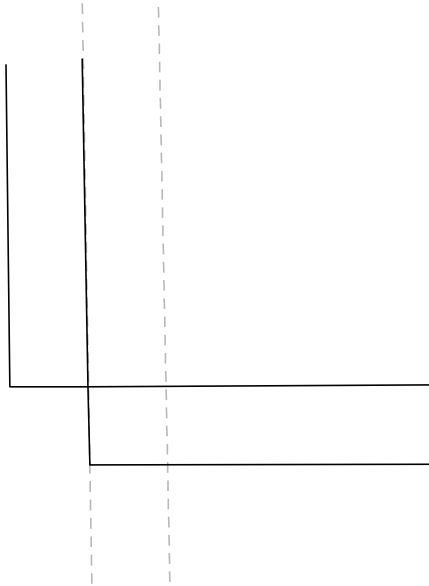
$\iff (ax, bxy) \subset \langle x \rangle^2 \iff [(k, l) \in \text{supp}(\partial) \implies k \geq 1]$

Example. $\partial = ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y}$

$(x=0)$ invariant $\iff \partial(\langle x \rangle) \subset \langle x \rangle \iff a \in \mathbb{C}\{x, y\} \iff [(k, l) \in \text{supp}(\partial) \implies k \geq 0]$

$(x=0)$ not tightly invariant $\iff (\partial(\langle x \rangle) \subset \langle x \rangle^2$

$\iff (ax, bxy) \subset \langle x \rangle^2 \iff [(k, l) \in \text{supp}(\partial) \implies k \geq 1]$



Very classical idea (see Newton, I. 1676):

The resolution of singularities should correspond to a combinatorial game based on the Newton polyhedron.

Very classical idea (see Newton, I. 1676):

The resolution of singularities should correspond to a combinatorial game based on the Newton polyhedron.

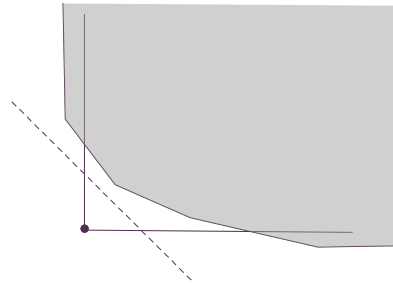
Can we recognize a “final situation” (a.k.a. an elementary germ) by looking at $\text{New}_x(\partial)$?

Very classical idea (see Newton, I. 1676):

The resolution of singularities should correspond to a combinatorial game based on the Newton polyhedron.

Can we recognize a “final situation” (a.k.a. an elementary germ) by looking at $\text{New}_x(\partial)$?

Proposition: $\partial \in \text{Der}(\mathcal{O})$ is a nilpotent germ if and only if there exists a local system of coordinates $x = (x_1, \dots, x_n)$ such that $0 \notin \text{New}_x(\partial)$.

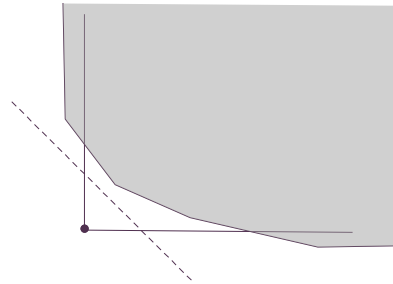


Very classical idea (see Newton, I. 1676):

The resolution of singularities should correspond to a combinatorial game based on the Newton polyhedron.

Can we recognize a “final situation” (a.k.a. an elementary germ) by looking at $\text{New}_x(\partial)$?

Proposition: $\partial \in \text{Der}(\mathcal{O})$ is a nilpotent germ if and only if there exists a local system of coordinates $x = (x_1, \dots, x_n)$ such that $0 \notin \text{New}_x(\partial)$.



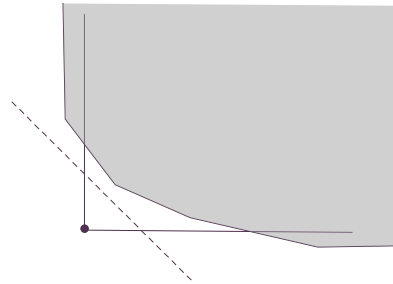
Proof: Assume that $0 \notin \text{New}_x(\partial)$. Then there exists a nonzero $\omega \in \mathbb{Q}_{\geq 0}^n$ and $\alpha \in \mathbb{Q}_{> 0}$ such that

Very classical idea (see Newton, I. 1676):

The resolution of singularities should correspond to a combinatorial game based on the Newton polyhedron.

Can we recognize a “final situation” (a.k.a. an elementary germ) by looking at $\text{New}_x(\partial)$?

Proposition: $\partial \in \text{Der}(\mathcal{O})$ is a nilpotent germ if and only if there exists a local system of coordinates $x = (x_1, \dots, x_n)$ such that $0 \notin \text{New}_x(\partial)$.



Proof: Assume that $0 \notin \text{New}_x(\partial)$. Then there exists a nonzero $\omega \in \mathbb{Q}_{\geq 0}^n$ and $\alpha \in \mathbb{Q}_{> 0}$ such that

$$\text{New}_x(\partial) \subset H = \{\langle \omega, \cdot \rangle \geq \alpha\}$$

(indeed, if some $\omega_i < 0$ then for $v \in \text{supp}_x(\partial)$, $\langle \omega, v + te_i \rangle \rightarrow -\infty$ as $t \rightarrow +\infty$).

We can assume that $\omega \in \mathbb{Z}_{\geq 0}^n \setminus \{0\}$ and consider the quasi-homogeneous graduation of \mathcal{O} associated to the torus action $\lambda: \mathbb{C}^* \rightarrow \text{Aut}(\mathcal{O})$

We can assume that $\omega \in \mathbb{Z}_{\geq 0}^n \setminus \{0\}$ and consider the quasi-homogeneous graduation of \mathcal{O} associated to the torus action $\lambda: \mathbb{C}^* \rightarrow \text{Aut}(\mathcal{O})$

$$\lambda(t) \cdot x_i = t^{\omega_i} x_i, \quad i = 1, \dots, n$$

(or, equivalently, the graduation associated to the infinitesimal semisimple generator $\delta = \sum \omega_i x_i \frac{\partial}{\partial x_i}$). This action is diagonalizable and we have a direct sum decomposition

We can assume that $\omega \in \mathbb{Z}_{\geq 0}^n \setminus \{0\}$ and consider the quasi-homogeneous graduation of \mathcal{O} associated to the torus action $\lambda: \mathbb{C}^* \rightarrow \text{Aut}(\mathcal{O})$

$$\lambda(t) \cdot x_i = t^{\omega_i} x_i, \quad i = 1, \dots, n$$

(or, equivalently, the graduation associated to the infinitesimal semisimple generator $\delta = \sum \omega_i x_i \frac{\partial}{\partial x_i}$). This action is diagonalizable and we have a direct sum decomposition

$$\mathcal{O} = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \delta)$$

where $\text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \{f: \lambda(t) \cdot f = t^{\alpha} f\} = \{f: \delta(f) = \alpha f\}$ is the module of ω -quasi homogeneous germs of degree α .

We can assume that $\omega \in \mathbb{Z}_{\geq 0}^n \setminus \{0\}$ and consider the quasi-homogeneous graduation of \mathcal{O} associated to the torus action $\lambda: \mathbb{C}^* \rightarrow \text{Aut}(\mathcal{O})$

$$\lambda(t) \cdot x_i = t^{\omega_i} x_i, \quad i = 1, \dots, n$$

(or, equivalently, the graduation associated to the infinitesimal semisimple generator $\delta = \sum \omega_i x_i \frac{\partial}{\partial x_i}$). This action is diagonalizable and we have a direct sum decomposition

$$\mathcal{O} = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \delta)$$

where $\text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \{f: \lambda(t) \cdot f = t^{\alpha} f\} = \{f: \delta(f) = \alpha f\}$ is the module of ω -quasi homogeneous germs of degree α .

This induces an action of \mathbb{C}^* on $\text{Der}(\mathcal{O})$ given by conjugation

$$\lambda(t) \cdot \partial = \lambda(t) \partial \lambda(t)^{-1}$$

We can assume that $\omega \in \mathbb{Z}_{\geq 0}^n \setminus \{0\}$ and consider the quasi-homogeneous graduation of \mathcal{O} associated to the torus action $\lambda: \mathbb{C}^* \rightarrow \text{Aut}(\mathcal{O})$

$$\lambda(t) \cdot x_i = t^{\omega_i} x_i, \quad i = 1, \dots, n$$

(or, equivalently, the graduation associated to the infinitesimal semisimple generator $\delta = \sum \omega_i x_i \frac{\partial}{\partial x_i}$). This action is diagonalizable and we have a direct sum decomposition

$$\mathcal{O} = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \delta)$$

where $\text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \{f: \lambda(t) \cdot f = t^{\alpha} f\} = \{f: \delta(f) = \alpha f\}$ is the module of ω -quasi homogeneous germs of degree α .

This induces an action of \mathbb{C}^* on $\text{Der}(\mathcal{O})$ given by conjugation

$$\lambda(t) \cdot \partial = \lambda(t) \partial \lambda(t)^{-1}$$

and equally induces a direct sum decomposition $\text{Der} = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\text{Der}, \lambda)$.

We can assume that $\omega \in \mathbb{Z}_{\geq 0}^n \setminus \{0\}$ and consider the quasi-homogeneous graduation of \mathcal{O} associated to the torus action $\lambda: \mathbb{C}^* \rightarrow \text{Aut}(\mathcal{O})$

$$\lambda(t) \cdot x_i = t^{\omega_i} x_i, \quad i = 1, \dots, n$$

(or, equivalently, the graduation associated to the infinitesimal semisimple generator $\delta = \sum \omega_i x_i \frac{\partial}{\partial x_i}$). This action is diagonalizable and we have a direct sum decomposition

$$\mathcal{O} = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\mathcal{O}, \delta)$$

where $\text{Gr}_{\alpha}(\mathcal{O}, \lambda) = \{f: \lambda(t) \cdot f = t^{\alpha} f\} = \{f: \delta(f) = \alpha f\}$ is the module of ω -quasi homogeneous germs of degree α .

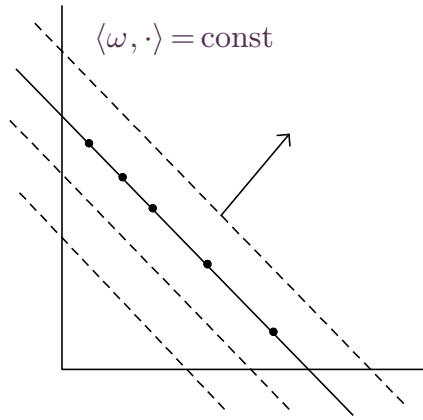
This induces an action of \mathbb{C}^* on $\text{Der}(\mathcal{O})$ given by conjugation

$$\lambda(t) \cdot \partial = \lambda(t) \partial \lambda(t)^{-1}$$

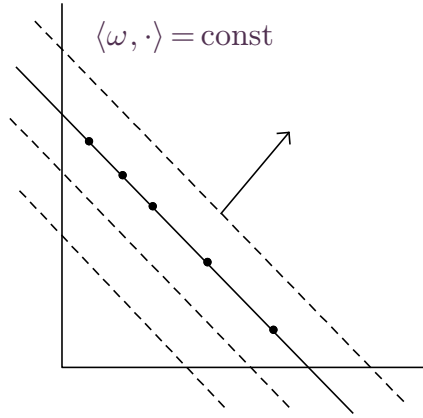
and equally induces a direct sum decomposition $\text{Der} = \bigoplus_{\alpha} \text{Gr}_{\alpha}(\text{Der}, \lambda)$.

And, naturally $\partial \in \text{Gr}_{\alpha}, f \in \text{Gr}_{\beta} \implies \partial f \in \text{Gr}_{\alpha+\beta}$.

$$\partial \in \text{Gr}_\alpha(\text{Der}, \lambda) \iff \text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle = \alpha\}$$



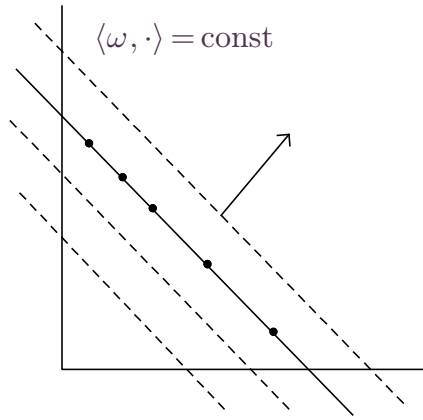
$$\partial \in \text{Gr}_\alpha(\text{Der}, \lambda) \iff \text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle = \alpha\}$$



By the above hypothesis, our original derivation satisfies

$$\text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle \geq \alpha\} \implies \partial \in \text{Gr}_{\geq \alpha}(\text{Der}, \lambda)$$

$$\partial \in \text{Gr}_\alpha(\text{Der}, \lambda) \iff \text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle = \alpha\}$$

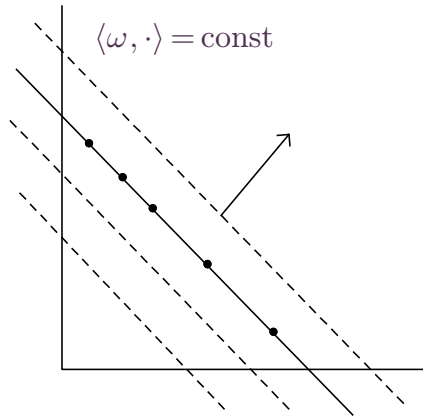


By the above hypothesis, our original derivation satisfies

$$\text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle \geq \alpha\} \implies \partial \in \text{Gr}_{\geq \alpha}(\text{Der}, \lambda)$$

Since this is a filtration, $\partial^2 \in \text{Gr}_{\geq 2\alpha}, \dots, \partial^r \in \text{Gr}_{\geq r\alpha}$ for all $r \geq 1$.

$$\partial \in \text{Gr}_\alpha(\text{Der}, \lambda) \iff \text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle = \alpha\}$$



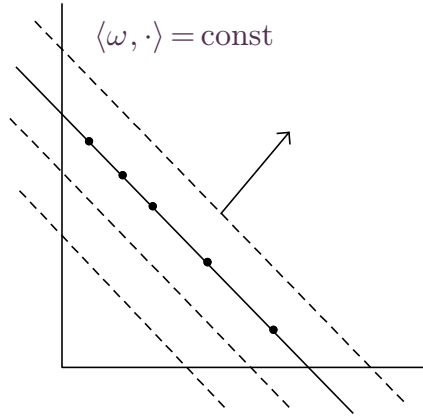
By the above hypothesis, our original derivation satisfies

$$\text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle \geq \alpha\} \implies \partial \in \text{Gr}_{\geq \alpha}(\text{Der}, \lambda)$$

Since this is a filtration, $\partial^2 \in \text{Gr}_{\geq 2\alpha}, \dots, \partial^r \in \text{Gr}_{\geq r\alpha}$ for all $r \geq 1$.

and if $f \in \text{Gr}_{\geq \beta}(\mathcal{O}, \lambda)$ then $\partial^r(f) \in \text{Gr}_{\geq r\alpha + \beta}(\mathcal{O}, \lambda)$.

$$\partial \in \text{Gr}_\alpha(\text{Der}, \lambda) \iff \text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle = \alpha\}$$



By the above hypothesis, our original derivation satisfies

$$\text{supp}_x(\partial) \subset \{k: \langle \omega, k \rangle \geq \alpha\} \implies \partial \in \text{Gr}_{\geq \alpha}(\text{Der}, \lambda)$$

Since this is a filtration, $\partial^2 \in \text{Gr}_{\geq 2\alpha}, \dots, \partial^r \in \text{Gr}_{\geq r\alpha}$ for all $r \geq 1$.

and if $f \in \text{Gr}_{\geq \beta}(\mathcal{O}, \lambda)$ then $\partial^r(f) \in \text{Gr}_{\geq r\alpha + \beta}(\mathcal{O}, \lambda)$.

As a consequence, for $\mathfrak{m} = \langle x_1, \dots, x_m \rangle$ the maximal ideal, for each s there exists a $r \geq 1$ such that

$$\partial^r(\mathfrak{m}^s) \subset \mathfrak{m}^{s+1}$$

(because for $k \in \mathbb{Z}_{\geq 0}^n, |k| \geq \langle \omega, k \rangle / \max \{\omega_i\}$). Hence, ∂ is nilpotent.

Reciprocally, assume that ∂ is nilpotent. Then, $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_S = 0$. There exists a local coordinate system such that $\partial|_{J^1} = \begin{pmatrix} 0 & & & \\ 1 & 0 & & \\ & 1 & \ddots & \\ & & 1 & 0 \end{pmatrix}$, i.e. such that

$$\partial(x_i) = \varepsilon_i x_{i+1} \quad (\text{mod } \mathfrak{m}^2)$$

Reciprocally, assume that ∂ is nilpotent. Then, $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_S = 0$. There exists a local coordinate system such that $\partial|_{J^1} = \begin{pmatrix} 0 & & & \\ 1 & 0 & & \\ & 1 & \ddots & \\ & & 1 & 0 \end{pmatrix}$, i.e. such that

$$\partial(x_i) = \varepsilon_i x_{i+1} \quad (\text{mod } \mathfrak{m}^2)$$

where $\varepsilon_i \in \{0, 1\}$. In other words, in the logarithmic basis, we obtain

$$\partial = \sum_{i \leq n-1} \varepsilon_i x_{i+1} x_i^{-1} \left(x_i \frac{\partial}{\partial x_i} \right) + R$$

Reciprocally, assume that ∂ is nilpotent. Then, $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_S = 0$. There exists a local coordinate system such that $\partial|_{J^1} = \begin{pmatrix} 0 & & & \\ 1 & 0 & & \\ & 1 & \ddots & \\ & & & 1 & 0 \end{pmatrix}$, i.e. such that

$$\partial(x_i) = \varepsilon_i x_{i+1} \quad (\text{mod } \mathfrak{m}^2)$$

where $\varepsilon_i \in \{0, 1\}$. In other words, in the logarithmic basis, we obtain

$$\partial = \sum_{i \leq n-1} \varepsilon_i x_{i+1} x_i^{-1} \left(x_i \frac{\partial}{\partial x_i} \right) + R$$

where R is a derivation with of degree ≥ 1 with respect the usual homogeneous filtration associated to the derivation $h = x_1 \frac{\partial}{\partial x_1} + \cdots + x_n \frac{\partial}{\partial x_n} = L(\mathbf{1})$, with weights $\mathbf{1} = (1, \dots, 1)$.

Reciprocally, assume that ∂ is nilpotent. Then, $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_S = 0$. There exists a local coordinate system such that $\partial|_{J^1} = \begin{pmatrix} 0 & & & \\ 1 & 0 & & \\ & 1 & \ddots & \\ & & 1 & 0 \end{pmatrix}$, i.e. such that

$$\partial(x_i) = \varepsilon_i x_{i+1} \quad (\text{mod } \mathfrak{m}^2)$$

where $\varepsilon_i \in \{0, 1\}$. In other words, in the logarithmic basis, we obtain

$$\partial = \sum_{i \leq n-1} \varepsilon_i x_{i+1} x_i^{-1} \left(x_i \frac{\partial}{\partial x_i} \right) + R$$

where R is a derivation with of degree ≥ 1 with respect the usual homogeneous filtration associated to the derivation $h = x_1 \frac{\partial}{\partial x_1} + \cdots + x_n \frac{\partial}{\partial x_n} = L(\mathbf{1})$, with weights $\mathbf{1} = (1, \dots, 1)$.

We now consider the weight-vector $\rho = (-n/2, \dots, n/2)$, or any other rational vector satisfying.

$$\langle \mathbf{1}, \rho \rangle = 0, \quad \langle \rho, e_{i+1} - e_i \rangle > 0, \quad e_i = (0, \dots, 1, \dots, 0)$$

Reciprocally, assume that ∂ is nilpotent. Then, $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_S = 0$. There exists a local coordinate system such that $\partial|_{J^1} = \begin{pmatrix} 0 & & & \\ 1 & 0 & & \\ & 1 & \ddots & \\ & & 1 & 0 \end{pmatrix}$, i.e. such that

$$\partial(x_i) = \varepsilon_i x_{i+1} \quad (\text{mod } \mathfrak{m}^2)$$

where $\varepsilon_i \in \{0, 1\}$. In other words, in the logarithmic basis, we obtain

$$\partial = \sum_{i \leq n-1} \varepsilon_i x_{i+1} x_i^{-1} \left(x_i \frac{\partial}{\partial x_i} \right) + R$$

where R is a derivation with of degree ≥ 1 with respect the usual homogeneous filtration associated to the derivation $h = x_1 \frac{\partial}{\partial x_1} + \cdots + x_n \frac{\partial}{\partial x_n} = L(\mathbf{1})$, with weights $\mathbf{1} = (1, \dots, 1)$.

We now consider the weight-vector $\rho = (-n/2, \dots, n/2)$, or any other rational vector satisfying.

$$\langle \mathbf{1}, \rho \rangle = 0, \quad \langle \rho, e_{i+1} - e_i \rangle > 0, \quad e_i = (0, \dots, 1, \dots, 0)$$

Then, for all sufficiently small $\varepsilon \in \mathbb{Q}_{>0}$, the semi-simple derivation $\omega = h + \varepsilon L(\rho)$ defines a half-space which separates $\text{New}_x(\partial)$ from 0.

Reciprocally, assume that ∂ is nilpotent. Then, $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_S = 0$. There exists a local coordinate system such that $\partial|_{J^1} = \begin{pmatrix} 0 & & & \\ 1 & 0 & & \\ & 1 & \ddots & \\ & & & 1 & 0 \end{pmatrix}$, i.e. such that

$$\partial(x_i) = \varepsilon_i x_{i+1} \quad (\text{mod } \mathfrak{m}^2)$$

where $\varepsilon_i \in \{0, 1\}$. In other words, in the logarithmic basis, we obtain

$$\partial = \sum_{i \leq n-1} \varepsilon_i x_{i+1} x_i^{-1} \left(x_i \frac{\partial}{\partial x_i} \right) + R$$

where R is a derivation with of degree ≥ 1 with respect the usual homogeneous filtration associated to the derivation $h = x_1 \frac{\partial}{\partial x_1} + \cdots + x_n \frac{\partial}{\partial x_n} = L(\mathbf{1})$, with weights $\mathbf{1} = (1, \dots, 1)$.

We now consider the weight-vector $\rho = (-n/2, \dots, n/2)$, or any other rational vector satisfying.

$$\langle \mathbf{1}, \rho \rangle = 0, \quad \langle \rho, e_{i+1} - e_i \rangle > 0, \quad e_i = (0, \dots, 1, \dots, 0)$$

Then, for all sufficiently small $\varepsilon \in \mathbb{Q}_{>0}$, the semi-simple derivation $\omega = h + \varepsilon L(\rho)$ defines a half-space which separates $\text{New}_x(\partial)$ from 0.

(because for $|k| \geq 2$, $\langle \omega, k \rangle \geq 2 - n\varepsilon|k|$, and $\text{New}_x(\partial)$ has finitely many vertices)

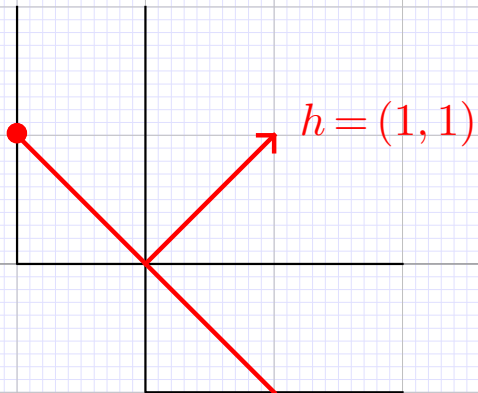
Geometrically, we have used... **The hinge method**



Geometrically, we have used... **The hinge method**



$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$

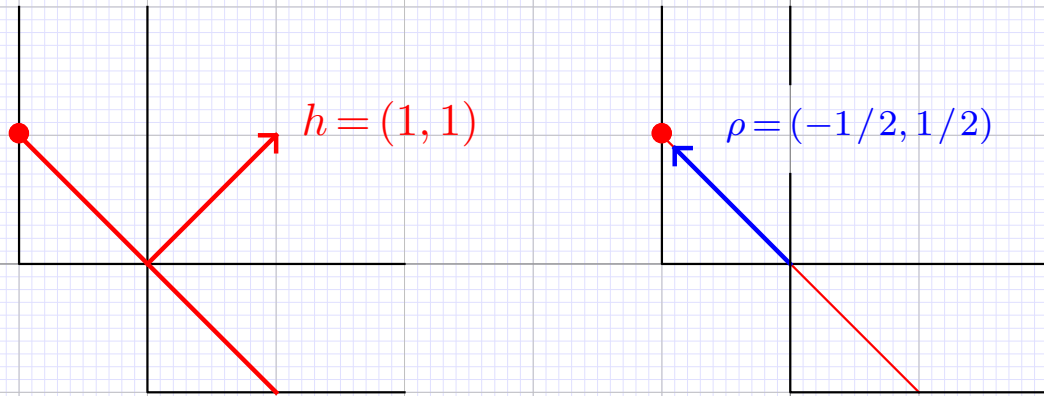


$(1, 1)$ – homogeneous
of degree 0

Geometrically, we have used... **The hinge method**



$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$

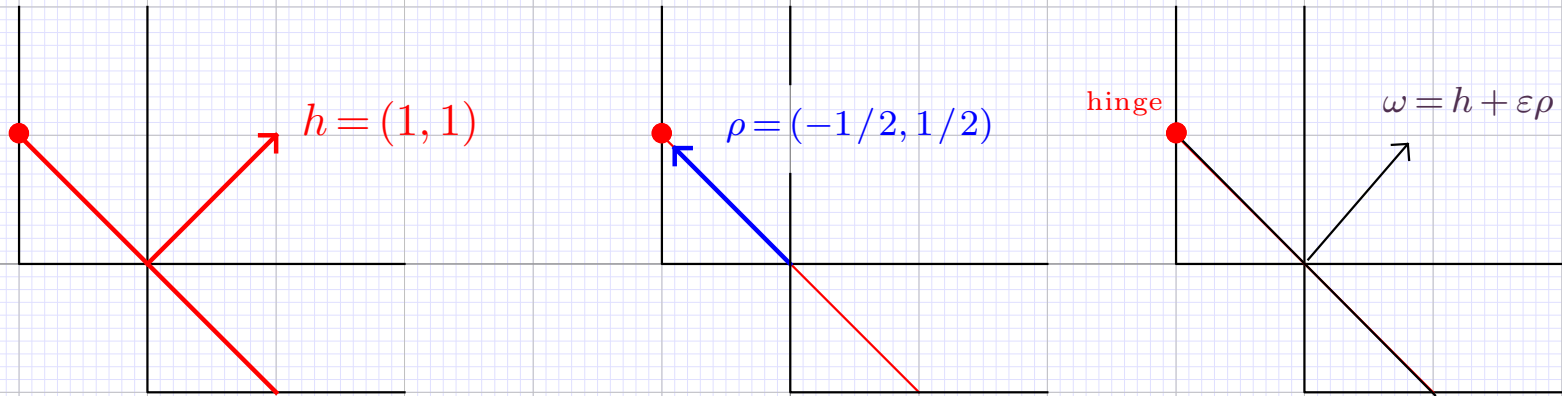


$(1, 1)$ – homogeneous
of degree 0

Geometrically, we have used... **The hinge method**



$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$

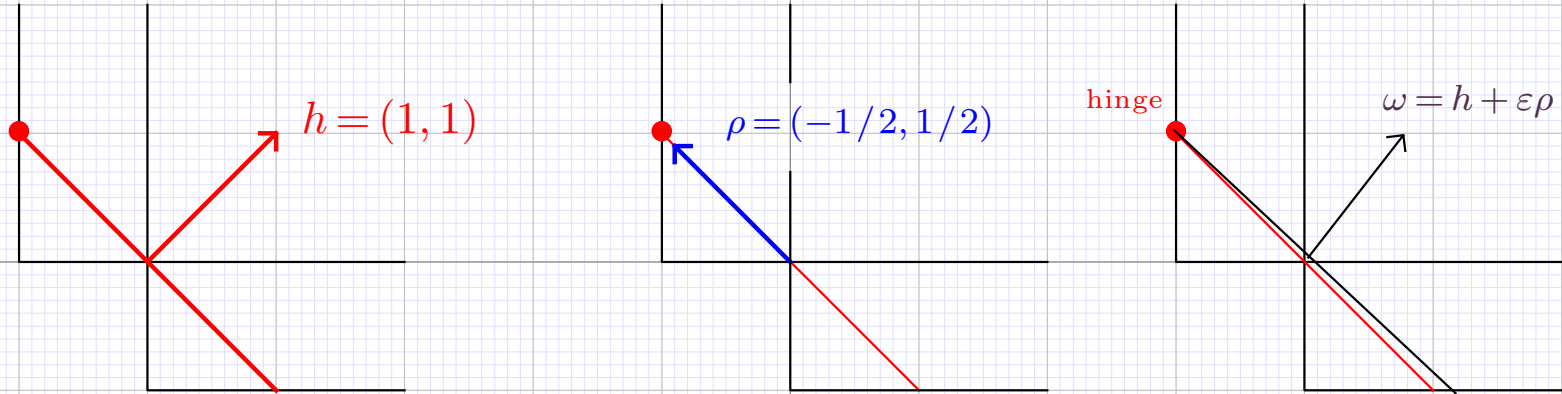


$(1, 1)$ – homogeneous
of degree 0

Geometrically, we have used... **The hinge method**



$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$

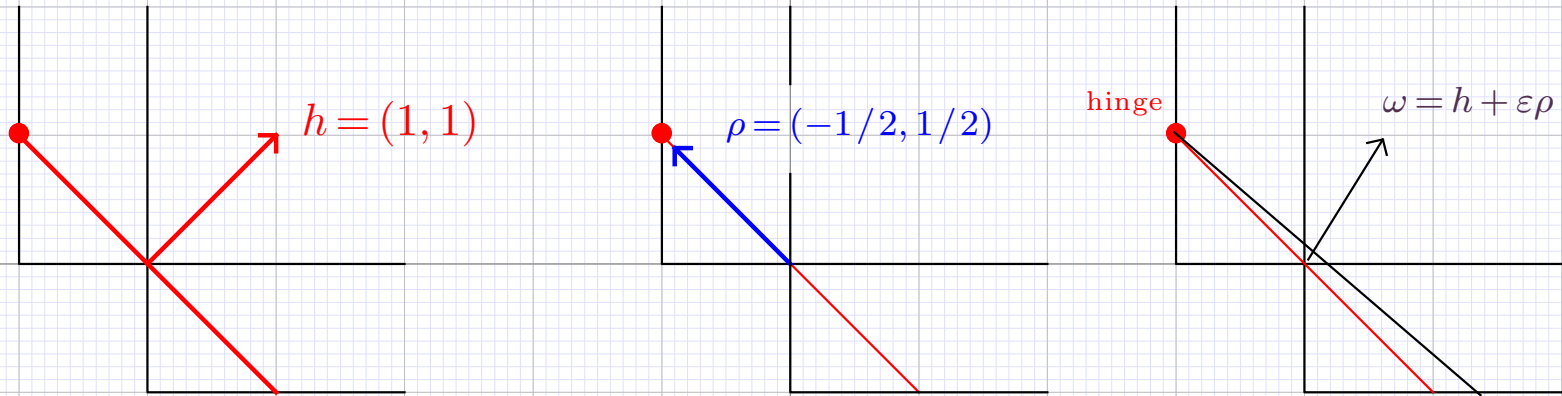


$(1, 1)$ – homogeneous
of degree 0

Geometrically, we have used... **The hinge method**



$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$

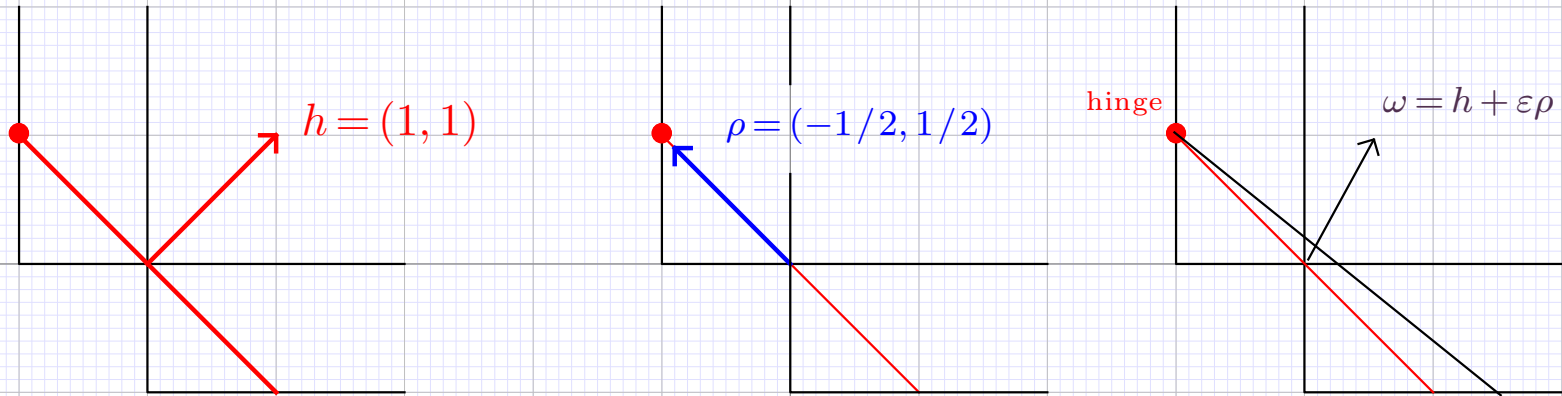


$(1, 1)$ – homogeneous
of degree 0

Geometrically, we have used... **The hinge method**



$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$

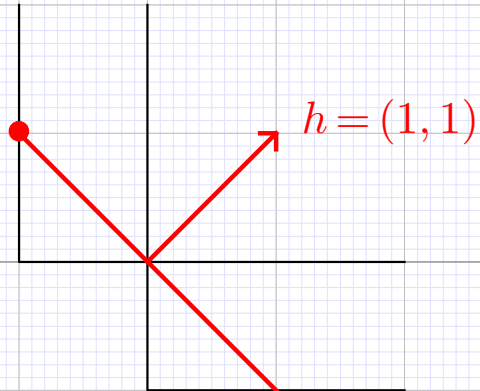


$(1, 1)$ – homogeneous
of degree 0

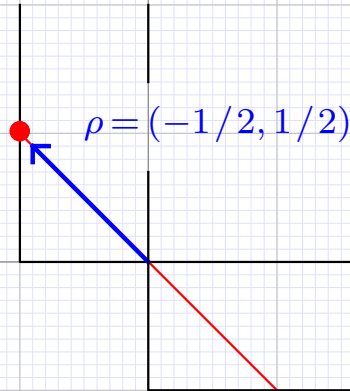
Geometrically, we have used... **The hinge method**



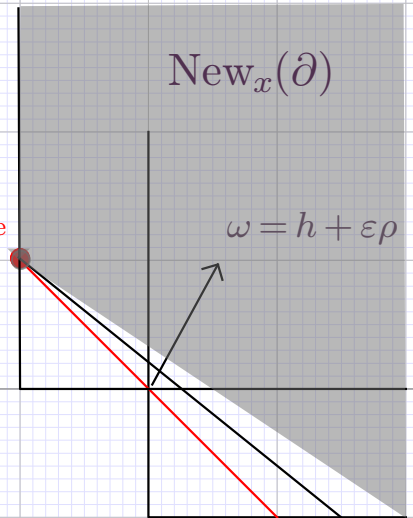
$$x^{-1}y\left(x\frac{\partial}{\partial x}\right)$$



$(1, 1)$ – homogeneous
of degree 0



hinge



$$\partial \in \text{Gr}_{>0}(\text{Der}, \omega)$$

Alternative proof of one of the implications of the Theorem

Alternative proof of one of the implications of the Theorem

Claim: Suppose that ∂ is elementary (i.e. not-nilpotent). Then, for all choices of coordinate systems (x_1, \dots, x_n) ,

$$0 \in \text{New}_x(\partial)$$

Indeed, the hypothesis means that either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ or that $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_s \neq 0$.

Alternative proof of one of the implications of the Theorem

Claim: Suppose that ∂ is elementary (i.e. not-nilpotent). Then, for all choices of coordinate systems (x_1, \dots, x_n) ,

$$0 \in \text{New}_x(\partial)$$

Indeed, the hypothesis means that either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ or that $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_s \neq 0$.

Consider the second case. Then we can find a nonzero $f \in \hat{\mathfrak{m}}$ such that

Alternative proof of one of the implications of the Theorem

Claim: Suppose that ∂ is elementary (i.e. not-nilpotent). Then, for all choices of coordinate systems (x_1, \dots, x_n) ,

$$0 \in \text{New}_x(\partial)$$

Indeed, the hypothesis means that either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ or that $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_s \neq 0$.

Consider the second case. Then we can find a nonzero $f \in \hat{\mathfrak{m}}$ such that

$$\partial(f) = u f$$

for some unit $u \in \hat{\mathcal{O}}$.

Alternative proof of one of the implications of the Theorem

Claim: Suppose that ∂ is elementary (i.e. not-nilpotent). Then, for all choices of coordinate systems (x_1, \dots, x_n) ,

$$0 \in \text{New}_x(\partial)$$

Indeed, the hypothesis means that either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ or that $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_s \neq 0$.

Consider the second case. Then we can find a nonzero $f \in \hat{\mathfrak{m}}$ such that

$$\partial(f) = u f$$

for some unit $u \in \hat{\mathcal{O}}$.

Let Gr be the graduation defined by an arbitrary one-parameter group λ , with positive weights (i.e. such that $\hat{\mathfrak{m}} \subset \text{Gr}_{\geq 0}$). Then $f \in \text{Gr}_{\geq \alpha}$ and $\partial \in \text{Gr}_{\geq \beta}$ implies that $\partial(f) \in \text{Gr}_{\geq \alpha + \beta}$.

Alternative proof of one of the implications of the Theorem

Claim: Suppose that ∂ is elementary (i.e. not-nilpotent). Then, for all choices of coordinate systems (x_1, \dots, x_n) ,

$$0 \in \text{New}_x(\partial)$$

Indeed, the hypothesis means that either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ or that $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_s \neq 0$.

Consider the second case. Then we can find a nonzero $f \in \hat{\mathfrak{m}}$ such that

$$\partial(f) = u f$$

for some unit $u \in \hat{\mathcal{O}}$.

Let Gr be the graduation defined by an arbitrary one-parameter group λ , with positive weights (i.e. such that $\hat{\mathfrak{m}} \subset \text{Gr}_{\geq 0}$). Then $f \in \text{Gr}_{\geq \alpha}$ and $\partial \in \text{Gr}_{\geq \beta}$ implies that $\partial(f) \in \text{Gr}_{\geq \alpha + \beta}$.

By the above choice of f , we conclude that $\beta = 0$ (because $u \in \text{Gr}_{\geq 0} \setminus \text{Gr}_{\geq 1}$)

Alternative proof of one of the implications of the Theorem

Claim: Suppose that ∂ is elementary (i.e. not-nilpotent). Then, for all choices of coordinate systems (x_1, \dots, x_n) ,

$$0 \in \text{New}_x(\partial)$$

Indeed, the hypothesis means that either $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ or that $\partial(\mathfrak{m}) \subset \mathfrak{m}$ and $\partial_s \neq 0$.

Consider the second case. Then we can find a nonzero $f \in \hat{\mathfrak{m}}$ such that


$$\partial(f) = u f$$

for some unit $u \in \hat{\mathcal{O}}$.

Let Gr be the graduation defined by an arbitrary one-parameter group λ , with positive weights (i.e. such that $\hat{\mathfrak{m}} \subset \text{Gr}_{\geq 0}$). Then $f \in \text{Gr}_{\geq \alpha}$ and $\partial \in \text{Gr}_{\geq \beta}$ implies that $\partial(f) \in \text{Gr}_{\geq \alpha + \beta}$.

By the above choice of f , we conclude that $\beta = 0$ (because $u \in \text{Gr}_{\geq 0} \setminus \text{Gr}_{\geq 1}$)

The case $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ is even easier. In fact, $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$ if and only if

$$\exists i \in \{1, \dots, n\}: \quad -e_i = (0, \dots, -1, \dots, 0) \in \text{New}_x(\partial)$$


Example: $\partial = y \frac{\partial}{\partial x} + x^2 \frac{\partial}{\partial y}$. The graduation defined by the one parameter group

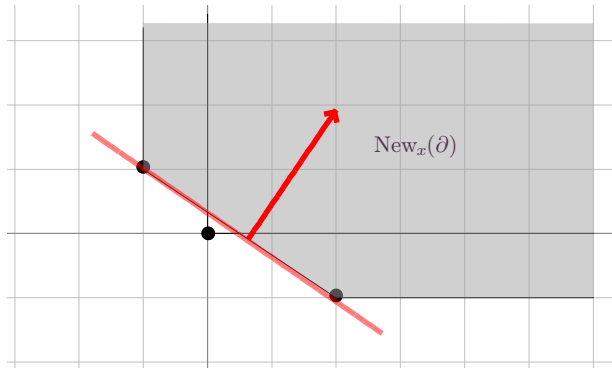
$$t \cdot (x, y) = (t^2 x, t^3 y)$$

is such that $\partial \in \text{Gr}_{\geq 1}$. (write $x^{-1}y \left(x \frac{\partial}{\partial x} \right) + x^2 y^{-1} \left(y \frac{\partial}{\partial y} \right)$ and $x^{-1}y, x^2 y^{-1} \in \text{Gr}_1$)

Example: $\partial = y \frac{\partial}{\partial x} + x^2 \frac{\partial}{\partial y}$. The graduation defined by the one parameter group

$$t \cdot (x, y) = (t^2 x, t^3 y)$$

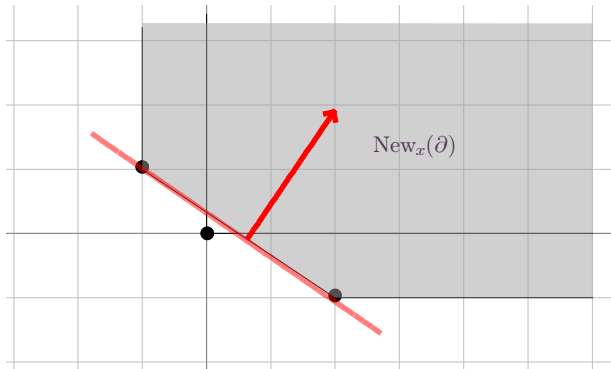
is such that $\partial \in \text{Gr}_{\geq 1}$. (write $x^{-1}y \left(x \frac{\partial}{\partial x} \right) + x^2 y^{-1} \left(y \frac{\partial}{\partial y} \right)$ and $x^{-1}y, x^2 y^{-1} \in \text{Gr}_1$)



Example: $\partial = y \frac{\partial}{\partial x} + x^2 \frac{\partial}{\partial y}$. The graduation defined by the one parameter group

$$t \cdot (x, y) = (t^2 x, t^3 y)$$

is such that $\partial \in \text{Gr}_{\geq 1}$. (write $x^{-1}y \left(x \frac{\partial}{\partial x} \right) + x^2 y^{-1} \left(y \frac{\partial}{\partial y} \right)$ and $x^{-1}y, x^2 y^{-1} \in \text{Gr}_1$)

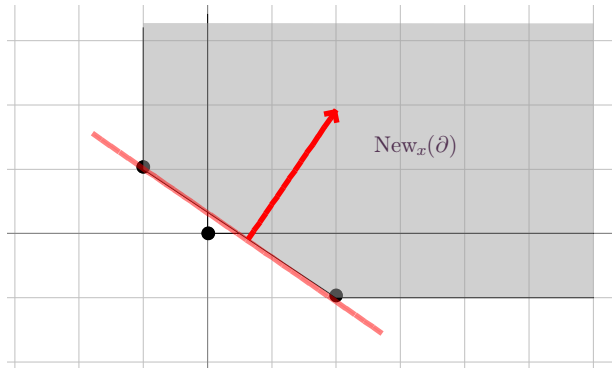


If we make the coordinate change $y \rightarrow y + \xi x$, the action on the polygon corresponds to a “sliding” of the vertices along the $(1, -1)$ direction.

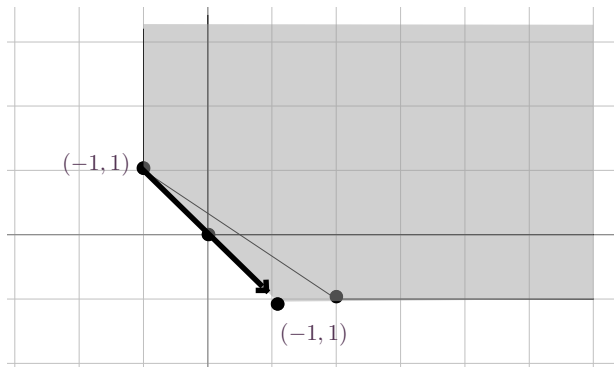
Example: $\partial = y \frac{\partial}{\partial x} + x^2 \frac{\partial}{\partial y}$. The graduation defined by the one parameter group

$$t \cdot (x, y) = (t^2 x, t^3 y)$$

is such that $\partial \in \text{Gr}_{\geq 1}$. (write $x^{-1}y \left(x \frac{\partial}{\partial x} \right) + x^2 y^{-1} \left(y \frac{\partial}{\partial y} \right)$ and $x^{-1}y, x^2 y^{-1} \in \text{Gr}_1$)



If we make the coordinate change $y \rightarrow y + \xi x$, the action on the polygon corresponds to a “sliding” of the vertices along the $(1, -1)$ direction.



In these new coordinates, $0 \in \text{New}_{(x,y)}(\partial)$.

Back to the proof in dimension two

Back to the proof in dimension two

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

Back to the proof in dimension two

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E

Back to the proof in dimension two

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E

Notation: $0 \leq e(p) \leq 2$ is the number of local irreducible components of E at $p \in M$.

Back to the proof in dimension two

Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E

Notation: $0 \leq e(p) \leq 2$ is the number of local irreducible components of E at $p \in M$.

Definition: A coordinate system (x, y) at $p \in E$ is **adapted** if locally $E = (x = 0)$ or $E = (xy = 0)$.

Back to the proof in dimension two

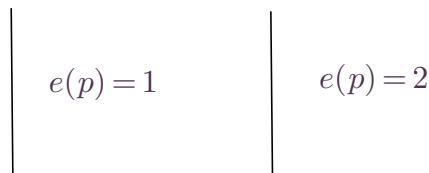
Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E

Notation: $0 \leq e(p) \leq 2$ is the number of local irreducible components of E at $p \in M$.

Definition: A coordinate system (x, y) at $p \in E$ is **adapted** if locally $E = (x = 0)$ or $E = (xy = 0)$.



Back to the proof in dimension two

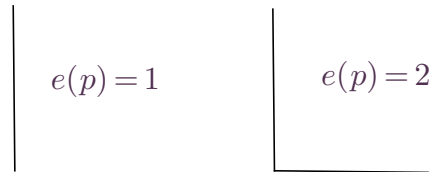
Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E

Notation: $0 \leq e(p) \leq 2$ is the number of local irreducible components of E at $p \in M$.

Definition: A coordinate system (x, y) at $p \in E$ is **adapted** if locally $E = (x = 0)$ or $E = (xy = 0)$.



Inclusion into the divisor: We can always assume that $\text{Nilp}(M, \mathcal{F}) \subset E$ by eventually blowing-up these points with an arbitrary weight.

Back to the proof in dimension two

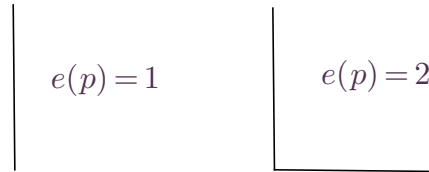
Initial setup: (M, E, \mathcal{F}) , where M is a two-dimensional real analytic manifold with corners,

$$\text{boundary}(M) = E$$

is a normal crossings divisor and \mathcal{F} is a foliation tangent to E

Notation: $0 \leq e(p) \leq 2$ is the number of local irreducible components of E at $p \in M$.

Definition: A coordinate system (x, y) at $p \in E$ is **adapted** if locally $E = (x = 0)$ or $E = (xy = 0)$.



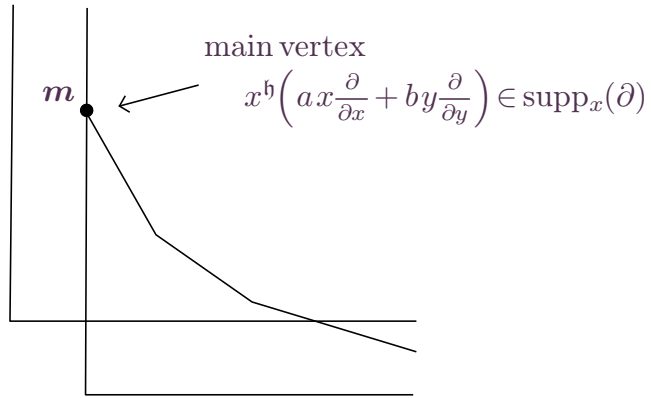
Inclusion into the divisor: We can always assume that $\text{Nilp}(M, \mathcal{F}) \subset E$ by eventually blowing-up these points with an arbitrary weight.

To simplify, we will assume that $e(p) = 1$ for all points $p \in \text{Nilp}(M, \mathcal{F})$.

(otherwise it suffices to slightly modify the invariant by including $e(p)$ lexicographically).

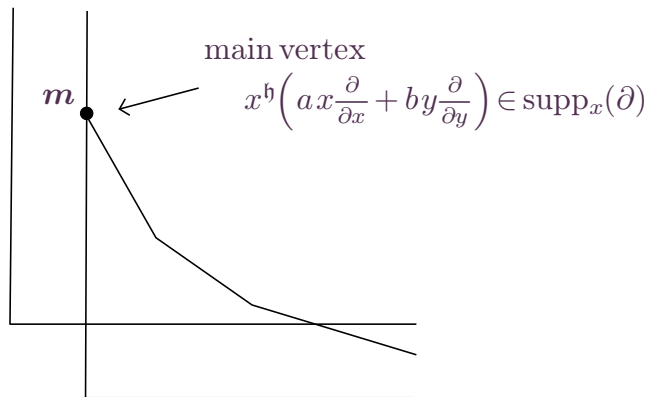
Suppose that $p \in E$. In adapted coordinates (x, y) , the Newton polygon has the form

Suppose that $p \in E$. In adapted coordinates (x, y) , the Newton polygon has the form



Invariance of $(x = 0)$ implies that $\partial \in \text{Gr}_{\geq 0} \left(\cdot, x \frac{\partial}{\partial x} \right)$
 (i.e. $\partial(\langle x \rangle) \subset \langle x \rangle$)

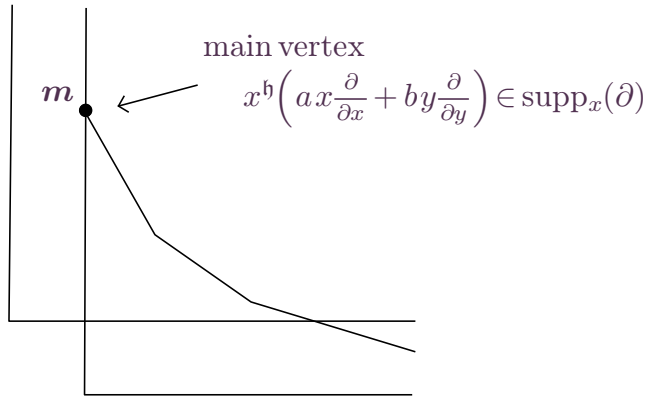
Suppose that $p \in E$. In adapted coordinates (x, y) , the Newton polygon has the form



Invariance of $(x=0)$ implies that $\partial \in \text{Gr}_{\geq 0} \left(\cdot, x \frac{\partial}{\partial x} \right)$
 (i.e. $\partial(\langle x \rangle) \subset \langle x \rangle$)

Claim: $p \in \text{Nilp}(M, \partial) \iff \mathfrak{h} \geq 1$ (which is equivalent to say that $0 \notin \text{New}_{(x,y)}(\partial)$)

Suppose that $p \in E$. In adapted coordinates (x, y) , the Newton polygon has the form

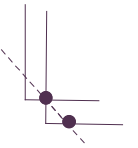


Invariance of $(x = 0)$ implies that $\partial \in \text{Gr}_{\geq 0}(\cdot, x \frac{\partial}{\partial x})$
 (i.e. $\partial(\langle x \rangle) \subset \langle x \rangle$)

Claim: $p \in \text{Nilp}(M, \partial) \iff \mathfrak{h} \geq 1$ (which is equivalent to say that $0 \notin \text{New}_{(x,y)}(\partial)$)

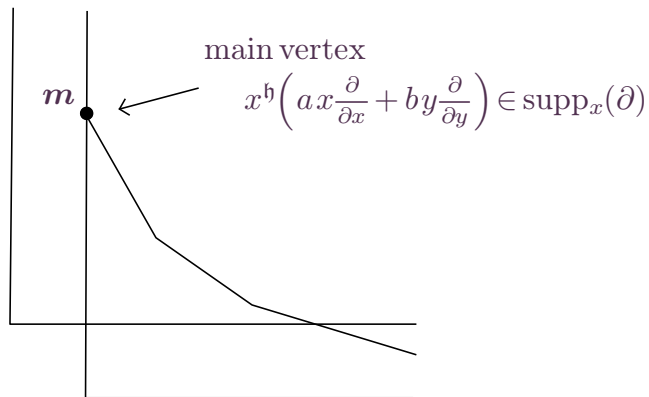
Indeed, if $0 \in \text{New}(\partial)$ then the initial $(1,1)$ -homogeneous part of ∂ would be either

$$b \frac{\partial}{\partial y} \quad (\text{case } h = -1), \quad \text{or} \quad a x \frac{\partial}{\partial x} + b y \frac{\partial}{\partial y} + c x y^{-1} \left(y \frac{\partial}{\partial y} \right) \quad (\text{case } h = 0)$$



where for some constants a, b, c such that $(a, b) \neq (0, 0)$.

Suppose that $p \in E$. In adapted coordinates (x, y) , the Newton polygon has the form

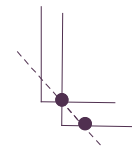


Invariance of $(x = 0)$ implies that $\partial \in \text{Gr}_{\geq 0}(\cdot, x \frac{\partial}{\partial x})$
 (i.e. $\partial(\langle x \rangle) \subset \langle x \rangle$)

Claim: $p \in \text{Nilp}(M, \partial) \iff \mathfrak{h} \geq 1$ (which is equivalent to say that $0 \notin \text{New}_{(x,y)}(\partial)$)

Indeed, if $0 \in \text{New}(\partial)$ then the initial $(1,1)$ -homogeneous part of ∂ would be either

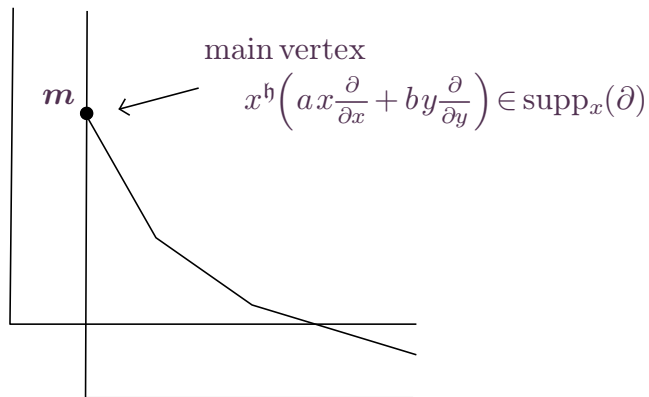
$$b \frac{\partial}{\partial y} \quad (\text{case } h = -1), \quad \text{or} \quad a x \frac{\partial}{\partial x} + b y \frac{\partial}{\partial y} + c x y^{-1} \left(y \frac{\partial}{\partial y} \right) \quad (\text{case } h = 0)$$



where for some constants a, b, c such that $(a, b) \neq (0, 0)$.

- In the first case, $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.

Suppose that $p \in E$. In adapted coordinates (x, y) , the Newton polygon has the form

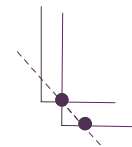


Invariance of $(x=0)$ implies that $\partial \in \text{Gr}_{\geq 0} \left(\cdot, x \frac{\partial}{\partial x} \right)$
 (i.e. $\partial(\langle x \rangle) \subset \langle x \rangle$)

Claim: $p \in \text{Nilp}(M, \partial) \iff \mathfrak{h} \geq 1$ (which is equivalent to say that $0 \notin \text{New}_{(x,y)}(\partial)$)

Indeed, if $0 \in \text{New}(\partial)$ then the initial $(1,1)$ -homogeneous part of ∂ would be either

$$b \frac{\partial}{\partial y} \quad (\text{case } h = -1), \quad \text{or} \quad a x \frac{\partial}{\partial x} + b y \frac{\partial}{\partial y} + c x y^{-1} \left(y \frac{\partial}{\partial y} \right) \quad (\text{case } h = 0)$$



where for some constants a, b, c such that $(a, b) \neq (0, 0)$.

- In the first case, $\partial(\mathfrak{m}) \not\subset \mathfrak{m}$.
- In this second case, it is obvious that $\text{Spec}(\partial_s) = \{a, b\} \neq 0$.

Definition: $\mathfrak{h}_x(\partial) := \mathfrak{h}$ will be called the **height of the main vertex**.

Definition: $\mathfrak{h}_x(\partial) := \mathfrak{h}$ will be called the **height of the main vertex**.

Claim: \mathfrak{h} is does not depend on the choice of (adapted) coordinates.

Definition: $\mathfrak{h}_x(\partial) := \mathfrak{h}$ will be called the **height of the main vertex**.

Claim: \mathfrak{h} does not depend on the choice of (adapted) coordinates.

In fact, the group of local automorphisms (preserving $x = 0$) has the form

$$x \rightarrow x f(x, y), \quad y \rightarrow g(x, y)$$

f unit, $\partial g / \partial y(0, 0) \neq 0$. Its Lie algebra is generated by vector fields with support in

$$x^k y^l x \frac{\partial}{\partial x}, \quad x^u y^v y \frac{\partial}{\partial y}, \quad k + l \geq 0, u + v \geq 0$$

$k, l \geq 0$ and $v \geq -1$. This Lie algebra lies in $\text{Gr}_{\geq 0}\left(\cdot, x \frac{\partial}{\partial x}\right) \cap \text{Gr}_{\geq 0}\left(\cdot, x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}\right)$.

Definition: $\mathfrak{h}_x(\partial) := \mathfrak{h}$ will be called the **height of the main vertex**.

Claim: \mathfrak{h} does not depend on the choice of (adapted) coordinates.

In fact, the group of local automorphisms (preserving $x = 0$) has the form

$$x \rightarrow x f(x, y), \quad y \rightarrow g(x, y)$$

f unit, $\partial g / \partial y(0, 0) \neq 0$. Its Lie algebra is generated by vector fields with support in

$$x^k y^l x \frac{\partial}{\partial x}, \quad x^u y^v y \frac{\partial}{\partial y}, \quad k + l \geq 0, u + v \geq 0$$

$k, l \geq 0$ and $v \geq -1$. This Lie algebra lies in $\text{Gr}_{\geq 0}\left(\cdot, x \frac{\partial}{\partial x}\right) \cap \text{Gr}_{\geq 0}\left(\cdot, x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}\right)$.

Hence, the main vertex is preserved.

Definition: $\mathfrak{h}_x(\partial) := \mathfrak{h}$ will be called the **height of the main vertex**.

Claim: \mathfrak{h} does not depend on the choice of (adapted) coordinates.

In fact, the group of local automorphisms (preserving $x = 0$) has the form

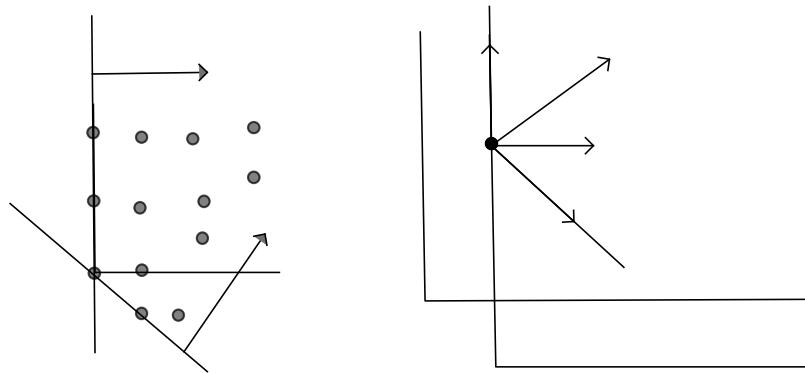
$$x \rightarrow x f(x, y), \quad y \rightarrow g(x, y)$$

f unit, $\partial g / \partial y(0, 0) \neq 0$. Its Lie algebra is generated by vector fields with support in

$$x^k y^l x \frac{\partial}{\partial x}, \quad x^u y^v y \frac{\partial}{\partial y}, \quad k + l \geq 0, u + v \geq 0$$

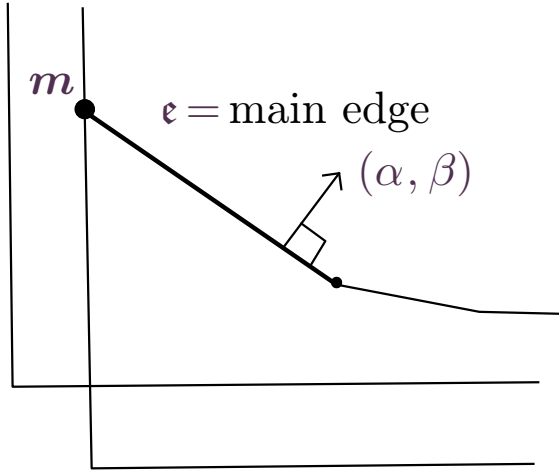
$k, l \geq 0$ and $v \geq -1$. This Lie algebra lies in $\text{Gr}_{\geq 0}(\cdot, x \frac{\partial}{\partial x}) \cap \text{Gr}_{\geq 0}(\cdot, x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y})$.

Hence, the main vertex is preserved.

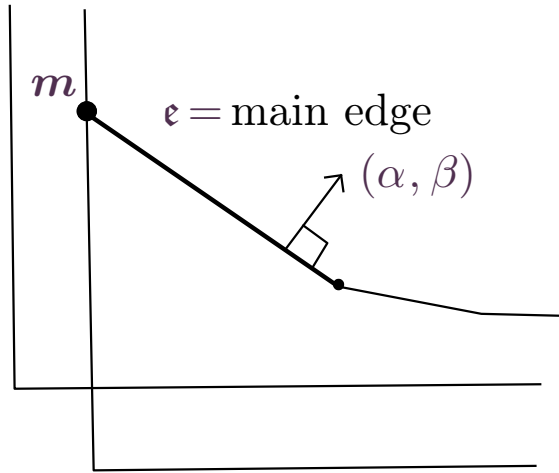


Final touch (and essential idea to generalize to dim.3)

Final touch (and essential idea to generalize to dim.3)



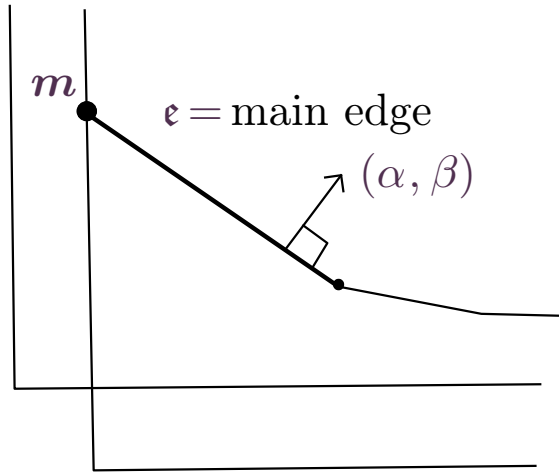
Final touch (and essential idea to generalize to dim.3)



Definition: The main edge of $\text{New}(\partial)$ is the edge ϵ determined by the intersection

$$\text{New} \cap \{(i, j) : j = \mathfrak{h} - 1/2\}$$

Final touch (and essential idea to generalize to dim.3)

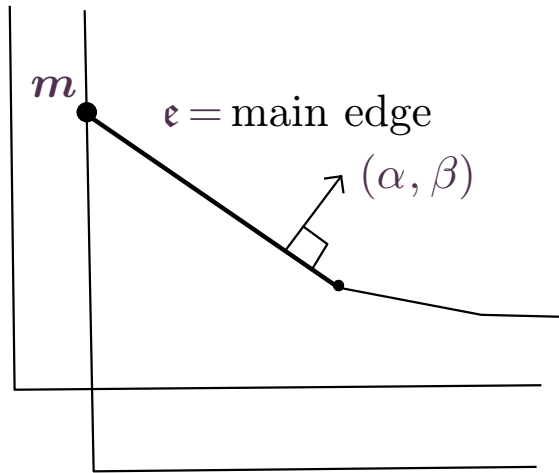


Definition: The main edge of $\text{New}(\partial)$ is the edge \mathfrak{e} determined by the intersection

$$\text{New} \cap \{(i, j) : j = \mathfrak{h} - 1/2\}$$

Important: Notice that $\mathfrak{e} = \mathfrak{e}_x(\partial)$ potentially depends on the choice of coordinates.

Final touch (and essential idea to generalize to dim.3)



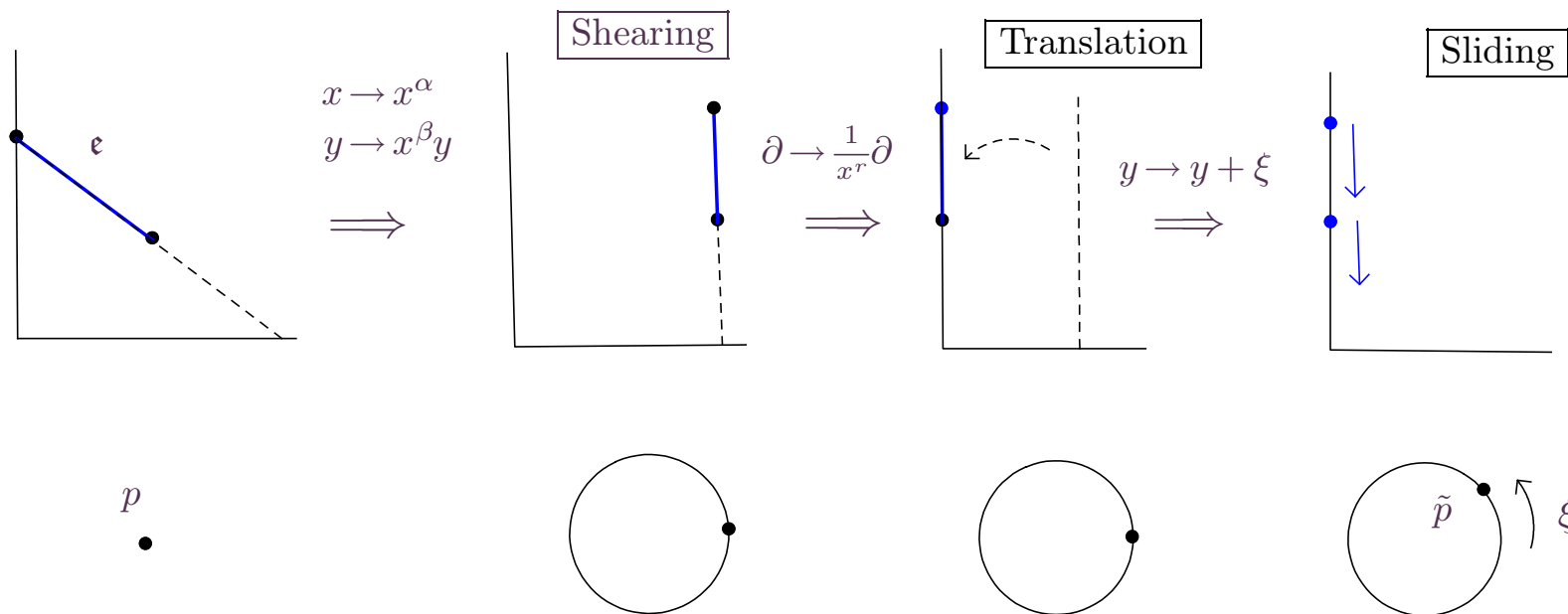
Definition: The main edge of $\text{New}(\partial)$ is the edge \mathfrak{e} determined by the intersection

$$\text{New} \cap \{(i, j) : j = \mathfrak{h} - 1/2\}$$

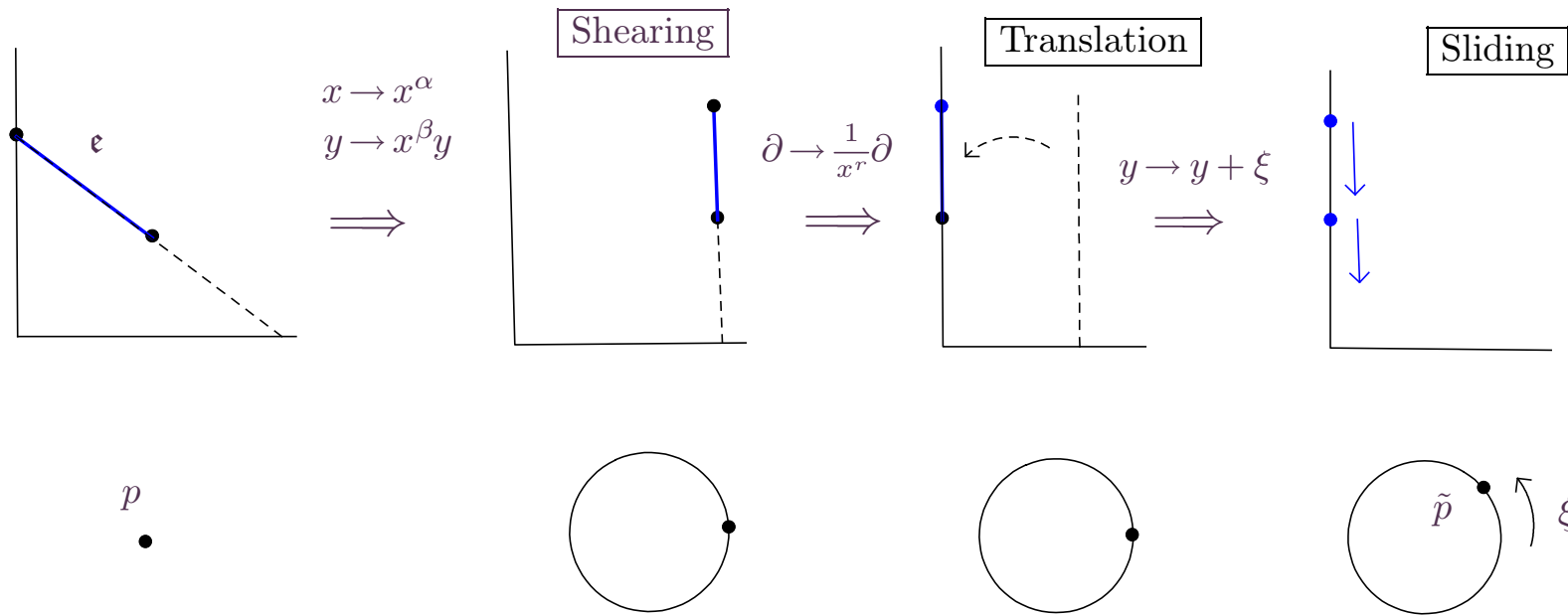
Important: Notice that $\mathfrak{e} = \mathfrak{e}_x(\partial)$ potentially depends on the choice of coordinates.

Let $\text{wt}(\mathfrak{e}) = \alpha x \frac{\partial}{\partial x} + \beta y \frac{\partial}{\partial x}$ denote the irreducible weight-vector determined by \mathfrak{e} .

Action of the blowing-up with weight (α, β) on the polygon

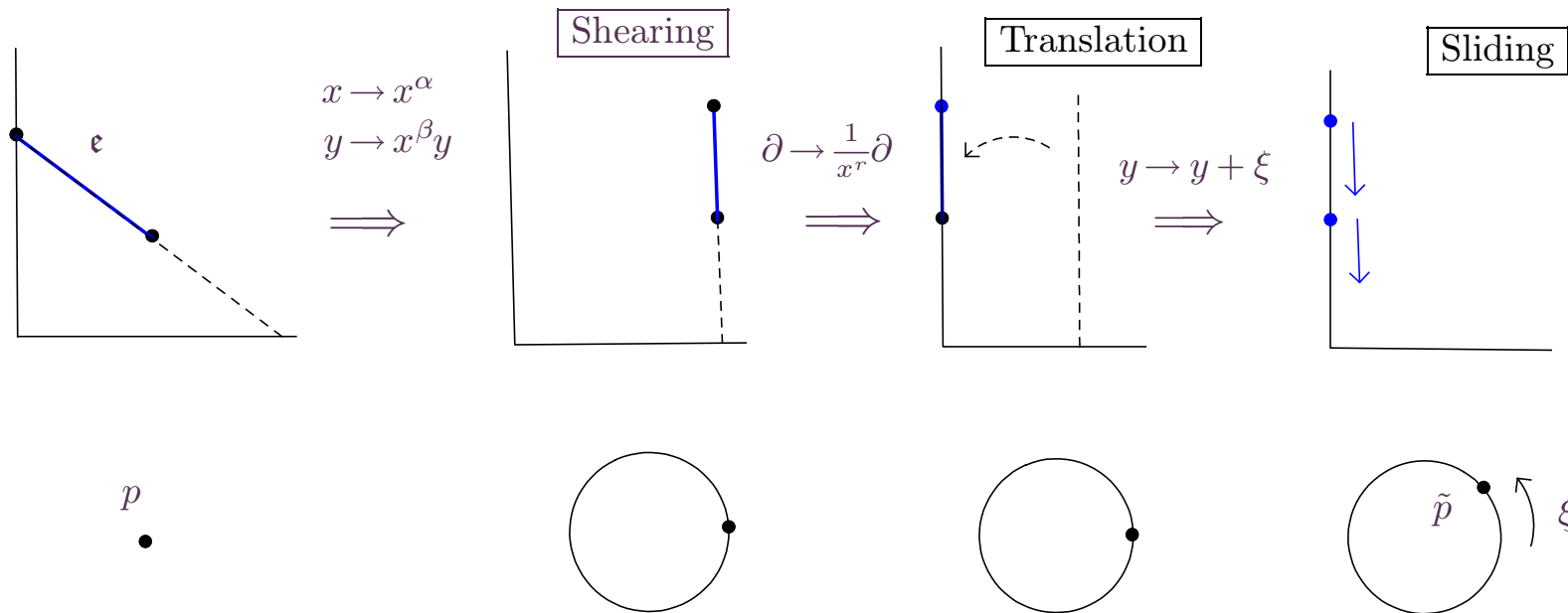


Action of the blowing-up with weight (α, β) on the polygon



We would like to prove that, for each $\tilde{p} \in \Phi^{-1}(p)$, $\tilde{h} \leq h - 1$ (i.e. the invariant decreases)

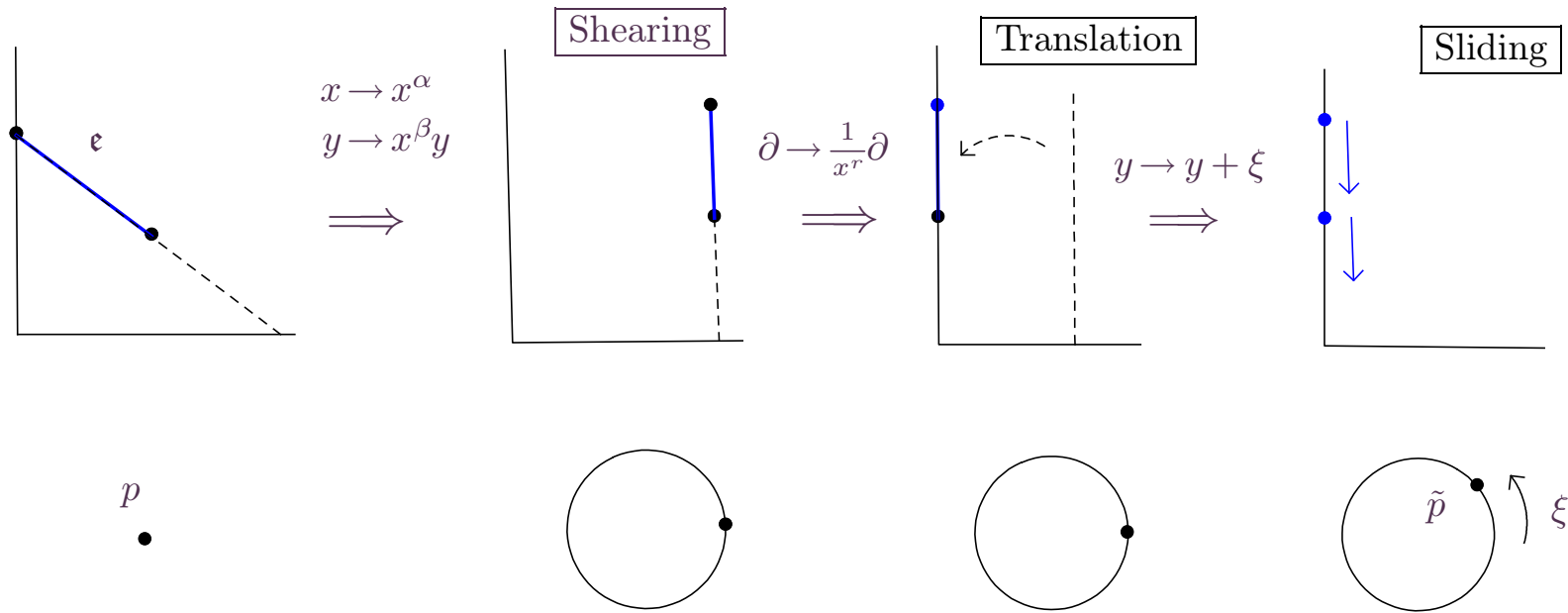
Action of the blowing-up with weight (α, β) on the polygon



We would like to prove that, for each $\tilde{p} \in \Phi^{-1}(p)$, $\tilde{h} \leq h - 1$ (i.e. the invariant decreases)

This is obvious for $\tilde{p} = (1:0) \in \mathbb{P}^1 \dots$ But...

Action of the blowing-up with weight (α, β) on the polygon



We would like to prove that, for each $\tilde{p} \in \Phi^{-1}(p)$, $\tilde{h} \leq h - 1$ (i.e. the invariant decreases)

This is obvious for $\tilde{p} = (1:0) \in \mathbb{P}^1 \dots$ But...

We can have a full compensation phenomena in the “sliding phase”.

Example: $\partial = (y + \xi x^k) \left(\lambda \left(x \frac{\partial}{\partial x} - \xi k x^k \frac{\partial}{\partial y} \right) + \mu (y + \xi x^k) \frac{\partial}{\partial y} \right)$, $(\lambda, \mu) \neq 0$, $\mathfrak{h}, k \geq 1$, $\xi \neq 0$

Example: $\partial = (y + \xi x^k) \mathfrak{h} \left(\lambda \left(x \frac{\partial}{\partial x} - \xi k x^k \frac{\partial}{\partial y} \right) + \mu (y + \xi x^k) \frac{\partial}{\partial y} \right)$, $(\lambda, \mu) \neq 0$, $\mathfrak{h}, k \geq 1$, $\xi \neq 0$

(up to a unit, this is the **unique** family where full compensation happens)

Example: $\partial = (y + \xi x^k)^\mathfrak{h} \left(\lambda \left(x \frac{\partial}{\partial x} - \xi k x^k \frac{\partial}{\partial y} \right) + \mu (y + \xi x^k) \frac{\partial}{\partial y} \right)$, $(\lambda, \mu) \neq 0$, $\mathfrak{h}, k \geq 1$, $\xi \neq 0$

(up to a unit, this is the **unique** family where full compensation happens)

$\partial \in \text{Gr}_{k\mathfrak{h}}(\text{Der}, \omega)$, where $\omega = x \frac{\partial}{\partial x} + ky \frac{\partial}{\partial y}$ (i.e. $[\omega, \partial] = k\mathfrak{h} \partial$)

Blow-up: $x \rightarrow x, \quad y \rightarrow x^k y$

$$(y + \xi x^k)^\mathfrak{h} \longrightarrow x^{k\mathfrak{h}} (y + \xi)^\mathfrak{h}$$

$$x \frac{\partial}{\partial x} \longrightarrow \left(x \frac{\partial}{\partial x} - ky \frac{\partial}{\partial y} \right), \quad x^k \frac{\partial}{\partial y} \longrightarrow \frac{\partial}{\partial y}$$

Example: $\partial = (y + \xi x^k)^\mathfrak{h} \left(\lambda \left(x \frac{\partial}{\partial x} - \xi k x^k \frac{\partial}{\partial y} \right) + \mu (y + \xi x^k) \frac{\partial}{\partial y} \right)$, $(\lambda, \mu) \neq 0$, $\mathfrak{h}, k \geq 1$, $\xi \neq 0$

(up to a unit, this is the **unique** family where full compensation happens)

$\partial \in \text{Gr}_{k\mathfrak{h}}(\text{Der}, \omega)$, where $\omega = x \frac{\partial}{\partial x} + ky \frac{\partial}{\partial y}$ (i.e. $[\omega, \partial] = k\mathfrak{h} \partial$)

Blow-up: $x \rightarrow x$, $y \rightarrow x^k y$

$$(y + \xi x^k)^\mathfrak{h} \longrightarrow x^{k\mathfrak{h}} (y + \xi)^\mathfrak{h}$$

$$x \frac{\partial}{\partial x} \longrightarrow \left(x \frac{\partial}{\partial x} - ky \frac{\partial}{\partial y} \right), \quad x^k \frac{\partial}{\partial y} \longrightarrow \frac{\partial}{\partial y}$$

$$(y + \xi x^k) \frac{\partial}{\partial y} \longrightarrow (y + \xi) \frac{\partial}{\partial y}$$

Example: $\partial = (y + \xi x^k)^\mathfrak{h} \left(\lambda \left(x \frac{\partial}{\partial x} - \xi k x^k \frac{\partial}{\partial y} \right) + \mu (y + \xi x^k) \frac{\partial}{\partial y} \right)$, $(\lambda, \mu) \neq 0$, $\mathfrak{h}, k \geq 1$, $\xi \neq 0$

(up to a unit, this is the **unique** family where full compensation happens)

$\partial \in \text{Gr}_{k\mathfrak{h}}(\text{Der}, \omega)$, where $\omega = x \frac{\partial}{\partial x} + ky \frac{\partial}{\partial y}$ (i.e. $[\omega, \partial] = k\mathfrak{h} \partial$)

Blow-up: $x \rightarrow x$, $y \rightarrow x^k y$

$$(y + \xi x^k)^\mathfrak{h} \longrightarrow x^{k\mathfrak{h}} (y + \xi)^\mathfrak{h}$$

$$x \frac{\partial}{\partial x} \longrightarrow \left(x \frac{\partial}{\partial x} - ky \frac{\partial}{\partial y} \right), \quad x^k \frac{\partial}{\partial y} \longrightarrow \frac{\partial}{\partial y}$$

$$(y + \xi x^k) \frac{\partial}{\partial y} \longrightarrow (y + \xi) \frac{\partial}{\partial y}$$

$$\tilde{\partial} = x^{-k\mathfrak{h}} \partial = (y + \xi)^\mathfrak{h} \left(\lambda x \frac{\partial}{\partial x} + (\mu - k\lambda)(y + \xi) \frac{\partial}{\partial y} \right)$$

Example: $\partial = (y + \xi x^k)^\mathfrak{h} \left(\lambda \left(x \frac{\partial}{\partial x} - \xi k x^k \frac{\partial}{\partial y} \right) + \mu (y + \xi x^k) \frac{\partial}{\partial y} \right)$, $(\lambda, \mu) \neq 0$, $\mathfrak{h}, k \geq 1$, $\xi \neq 0$

(up to a unit, this is the **unique** family where full compensation happens)

$\partial \in \text{Gr}_{k\mathfrak{h}}(\text{Der}, \omega)$, where $\omega = x \frac{\partial}{\partial x} + ky \frac{\partial}{\partial y}$ (i.e. $[\omega, \partial] = k\mathfrak{h} \partial$)

Blow-up: $x \rightarrow x, \quad y \rightarrow x^k y$

$$(y + \xi x^k)^\mathfrak{h} \longrightarrow x^{k\mathfrak{h}} (y + \xi)^\mathfrak{h}$$

$$x \frac{\partial}{\partial x} \longrightarrow \left(x \frac{\partial}{\partial x} - ky \frac{\partial}{\partial y} \right), \quad x^k \frac{\partial}{\partial y} \longrightarrow \frac{\partial}{\partial y}$$

$$(y + \xi x^k) \frac{\partial}{\partial y} \longrightarrow (y + \xi) \frac{\partial}{\partial y}$$

$$\tilde{\partial} = x^{-k\mathfrak{h}} \partial = (y + \xi)^\mathfrak{h} \left(\lambda x \frac{\partial}{\partial x} + (\mu - k\lambda)(y + \xi) \frac{\partial}{\partial y} \right)$$

Translation $y \rightarrow y - \xi$

$$\tilde{\partial} = y^\mathfrak{h} \left(\mu x \frac{\partial}{\partial x} + (\lambda - k\mu) y \frac{\partial}{\partial y} \right) \implies \boxed{\tilde{\mathfrak{h}} = \mathfrak{h}}$$

How to prevent this? The main edge e should be stable.

How to prevent this? The main edge ϵ should be stable.

Definition. We say that $\text{New}_{(x,y)}(\partial)$ is **edge-unstable** if there exists a polynomial change of coordinates of the form

How to prevent this? The main edge \mathfrak{e} should be stable.

Definition. We say that $\text{New}_{(x,y)}(\partial)$ is **edge-unstable** if there exists a polynomial change of coordinates of the form

$$y \rightarrow y + \xi x^{\frac{\beta}{\alpha}} =: y_1$$

such that $\text{New}_{(x,y_1)}(\partial) \cap \mathfrak{e} = \{\mathfrak{m}\}$. Otherwise, we say that $\text{New}_{(x,y)}(\partial)$ are **edge-stable**.

How to prevent this? The main edge \mathfrak{e} should be stable.

Definition. We say that $\text{New}_{(x,y)}(\partial)$ is **edge-unstable** if there exists a polynomial change of coordinates of the form

$$y \rightarrow y + \xi x^{\frac{\beta}{\alpha}} =: y_1$$

such that $\text{New}_{(x,y_1)}(\partial) \cap \mathfrak{e} = \{\mathfrak{m}\}$. Otherwise, we say that $\text{New}_{(x,y)}(\partial)$ are **edge-stable**.

Notice that $\text{New}_{(x,y)}(\partial)$ is always edge-stable if $\beta/\alpha \notin \mathbb{Z}_{\geq 1}$.

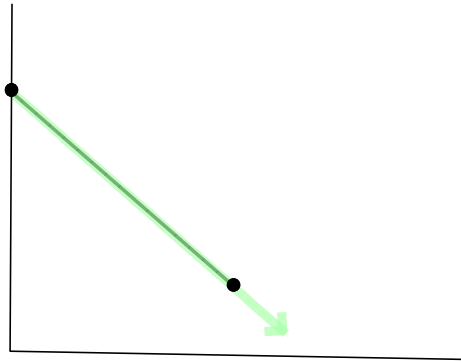
How to prevent this? The main edge \mathfrak{e} should be stable.

Definition. We say that $\text{New}_{(x,y)}(\partial)$ is **edge-unstable** if there exists a polynomial change of coordinates of the form

$$y \rightarrow y + \xi x^{\frac{\beta}{\alpha}} =: y_1$$

such that $\text{New}_{(x,y_1)}(\partial) \cap \mathfrak{e} = \{\mathfrak{m}\}$. Otherwise, we say that $\text{New}_{(x,y)}(\partial)$ are **edge-stable**.

Notice that $\text{New}_{(x,y)}(\partial)$ is always edge-stable if $\beta/\alpha \notin \mathbb{Z}_{\geq 1}$.



The above map slides the monomials in the direction of the main edge.

Theorem (Local resolution) Suppose that $\text{New}_{(x,y)}(\partial)$ is edge stable, and let

$$\Phi: \tilde{M} \rightarrow M$$

be the blowing-up of $p \in \text{Nilp}(M, \mathcal{F})$ with weight $\text{wt}(\mathfrak{e})$. Then,

Theorem (Local resolution) Suppose that $\text{New}_{(x,y)}(\partial)$ is edge stable, and let

$$\Phi: \tilde{M} \rightarrow M$$

be the blowing-up of $p \in \text{Nilp}(M, \mathcal{F})$ with weight $\text{wt}(\mathfrak{e})$. Then,

$$\forall \tilde{p} \in \Phi^{-1}(p): \quad \tilde{\mathfrak{h}} \leq \mathfrak{h} - 1.$$

Theorem (Local resolution) Suppose that $\text{New}_{(x,y)}(\partial)$ is edge stable, and let

$$\Phi: \tilde{M} \rightarrow M$$

be the blowing-up of $p \in \text{Nilp}(M, \mathcal{F})$ with weight $\text{wt}(\mathfrak{e})$. Then,

$$\forall \tilde{p} \in \Phi^{-1}(p): \quad \tilde{\mathfrak{h}} \leq \mathfrak{h} - 1.$$

(very simple) Proof: Firstly, we do not have to care about the y -directional chart

$$x \rightarrow y^\alpha x, \quad y \rightarrow y^\beta$$

Theorem (Local resolution) Suppose that $\text{New}_{(x,y)}(\partial)$ is edge stable, and let

$$\Phi: \tilde{M} \rightarrow M$$

be the blowing-up of $p \in \text{Nilp}(M, \mathcal{F})$ with weight $\text{wt}(\mathfrak{e})$. Then,

$$\forall \tilde{p} \in \Phi^{-1}(p): \quad \tilde{\mathfrak{h}} \leq \mathfrak{h} - 1.$$

(very simple) Proof: Firstly, we do not have to care about the y -directional chart

$$x \rightarrow y^\alpha x, \quad y \rightarrow y^\beta$$

as $\tilde{p} = (0:1)$ will always be elementary.

Theorem (Local resolution) Suppose that $\text{New}_{(x,y)}(\partial)$ is edge stable, and let

$$\Phi: \tilde{M} \rightarrow M$$

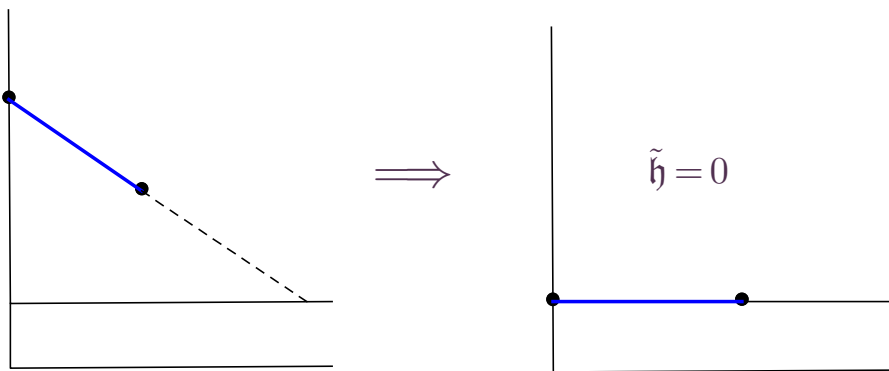
be the blowing-up of $p \in \text{Nilp}(M, \mathcal{F})$ with weight $\text{wt}(\mathfrak{e})$. Then,

$$\forall \tilde{p} \in \Phi^{-1}(p): \quad \tilde{\mathfrak{h}} \leq \mathfrak{h} - 1.$$

(very simple) Proof: Firstly, we do not have to care about the y -directional chart

$$x \rightarrow y^\alpha x, \quad y \rightarrow y^\beta$$

as $\tilde{p} = (0:1)$ will always be elementary.



We look the x -directional chart

$$x \rightarrow x^\alpha, \quad y \rightarrow x^\beta y$$

Suppose that $\tilde{\mathfrak{h}} = \mathfrak{h}$. Then, there should exist a non-zero constant ξ such that the translation (in blowed-up coordinates)

$$y \rightarrow y + \xi$$

gives a Newton polyhedron with main vertex $\tilde{\mathfrak{m}} = \mathfrak{m}$. We split into two cases:

We look the x -directional chart

$$x \rightarrow x^\alpha, \quad y \rightarrow x^\beta y$$

Suppose that $\tilde{\mathfrak{h}} = \mathfrak{h}$. Then, there should exist a non-zero constant ξ such that the translation (in blowed-up coordinates)

$$y \rightarrow y + \xi$$

gives a Newton polyhedron with main vertex $\tilde{\mathfrak{m}} = \mathfrak{m}$. We split into two cases:

- $\beta/\alpha \in \mathbb{Q}_{>0} \setminus \mathbb{Z}_{>0}$.

We look the x -directional chart

$$x \rightarrow x^\alpha, \quad y \rightarrow x^\beta y$$

Suppose that $\tilde{\mathfrak{h}} = \mathfrak{h}$. Then, there should exist a non-zero constant ξ such that the translation (in blowed-up coordinates)

$$y \rightarrow y + \xi$$

gives a Newton polyhedron with main vertex $\tilde{\mathfrak{m}} = \mathfrak{m}$. We split into two cases:

- $\beta/\alpha \in \mathbb{Q}_{>0} \setminus \mathbb{Z}_{>0}$.
- $\beta/\alpha \in \mathbb{Z}_{>0}$

We look the x -directional chart

$$x \rightarrow x^\alpha, \quad y \rightarrow x^\beta y$$

Suppose that $\tilde{\mathfrak{h}} = \mathfrak{h}$. Then, there should exist a non-zero constant ξ such that the translation (in blowed-up coordinates)

$$y \rightarrow y + \xi$$

gives a Newton polyhedron with main vertex $\tilde{\mathfrak{m}} = \mathfrak{m}$. We split into two cases:

- $\beta/\alpha \in \mathbb{Q}_{>0} \setminus \mathbb{Z}_{>0}$.
- $\beta/\alpha \in \mathbb{Z}_{>0}$

In the latter case, the above map corresponds (in the original coordinates), to the polynomial map $y \rightarrow y + \xi x^{\beta/\alpha}$ (just write $y \rightarrow x^{-\beta} y, x \rightarrow x^{1/\alpha}$).

We look the x -directional chart

$$x \rightarrow x^\alpha, \quad y \rightarrow x^\beta y$$

Suppose that $\tilde{\mathfrak{h}} = \mathfrak{h}$. Then, there should exist a non-zero constant ξ such that the translation (in blowed-up coordinates)

$$y \rightarrow y + \xi$$

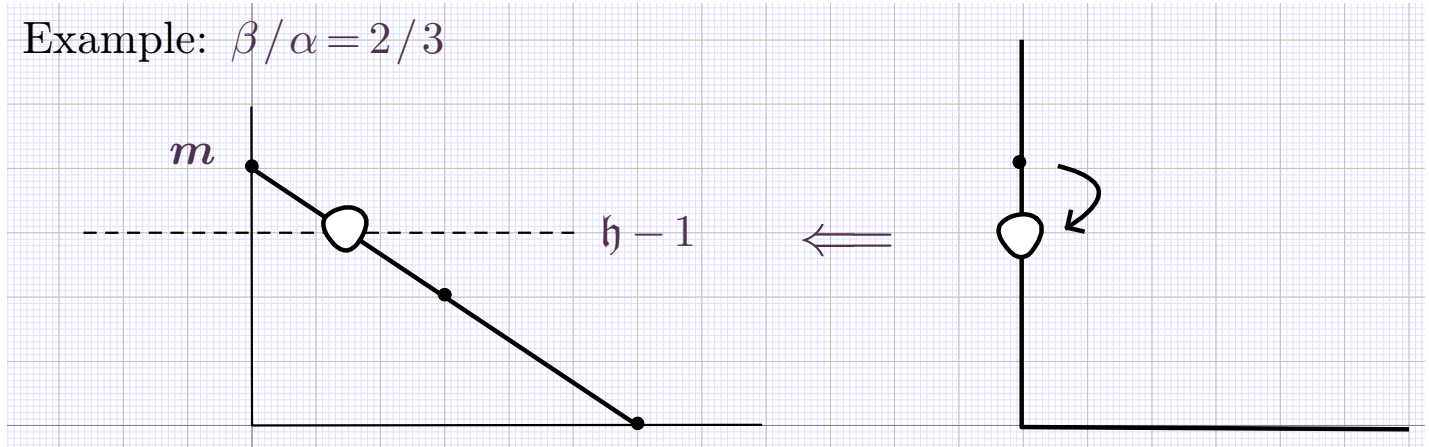
gives a Newton polyhedron with main vertex $\tilde{\mathfrak{m}} = \mathfrak{m}$. We split into two cases:

- $\beta/\alpha \in \mathbb{Q}_{>0} \setminus \mathbb{Z}_{>0}$.
- $\beta/\alpha \in \mathbb{Z}_{>0}$

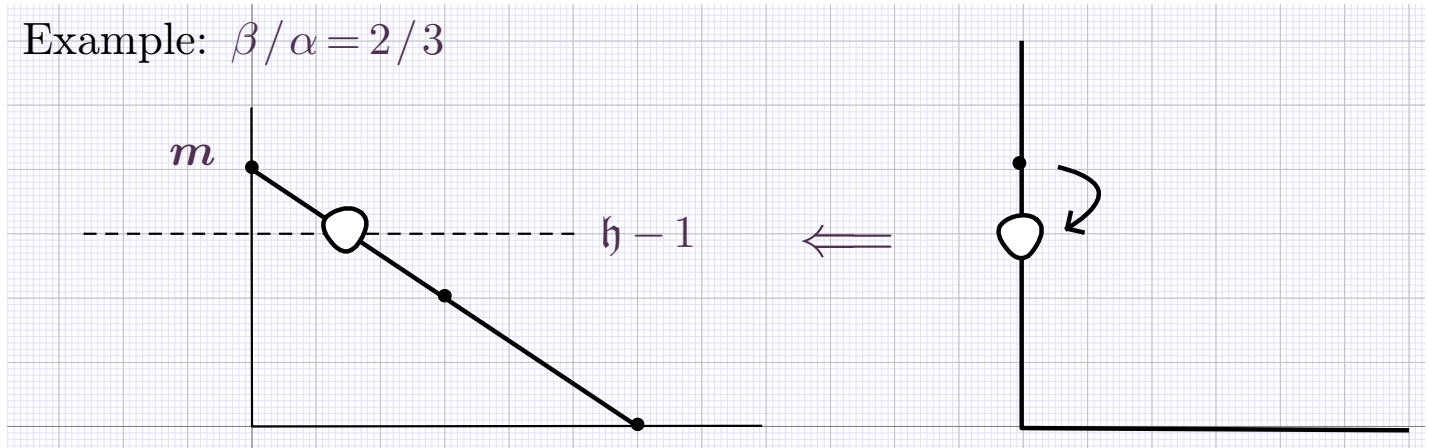
In the latter case, the above map corresponds (in the original coordinates), to the polynomial map $y \rightarrow y + \xi x^{\beta/\alpha}$ (just write $y \rightarrow x^{-\beta} y, x \rightarrow x^{1/\alpha}$).

The assumption $\tilde{\mathfrak{h}} = \mathfrak{h}$ is equivalent to say that $\text{New}_{(x,y)}(\partial)$ is edge-unstable, which contradicts the hypothesis of the Theorem.

In the former case (i.e. $\beta/\alpha \notin \mathbb{Z}$), the ϵ -initial form of ∂ has a gap at height $\mathfrak{h} - 1$.



In the former case (i.e. $\beta/\alpha \notin \mathbb{Z}$), the \mathfrak{e} -initial form of ∂ has a gap at height $\mathfrak{h} - 1$.

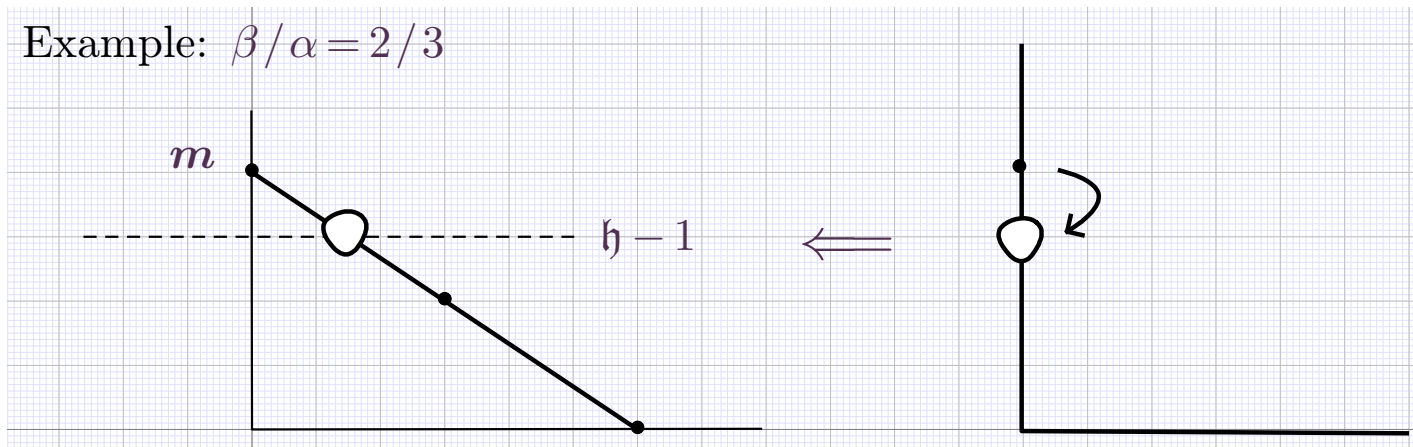


After blowing-up, followed by an arbitrary translation $y \rightarrow y + \xi$, we have

$$(y^{\mathfrak{h}}) \left(\alpha x \frac{\partial}{\partial x} + \beta y \frac{\partial}{\partial y} \right) + \text{terms in } y^{\leq \mathfrak{h}-2} \longrightarrow (y + \xi)^{\mathfrak{h}} \left(\alpha x \frac{\partial}{\partial x} + \beta (y + \xi) \frac{\partial}{\partial y} \right) + \dots$$

which gives a monomial on the support at height $\mathfrak{h} - 1$.

In the former case (i.e. $\beta/\alpha \notin \mathbb{Z}$), the \mathfrak{e} -initial form of ∂ has a gap at height $\mathfrak{h} - 1$.



After blowing-up, followed by an arbitrary translation $y \rightarrow y + \xi$, we have

$$(y^{\mathfrak{h}}) \left(\alpha x \frac{\partial}{\partial x} + \beta y \frac{\partial}{\partial y} \right) + \text{terms in } y^{\leq \mathfrak{h}-2} \longrightarrow (y + \xi)^{\mathfrak{h}} \left(\alpha x \frac{\partial}{\partial x} + \beta (y + \xi) \frac{\partial}{\partial y} \right) + \dots$$

which gives a monomial on the support at height $\mathfrak{h} - 1$.

(Abhyankar called this argument the “lazy Tschirnhausen”).

What is “behind” this argument?

What is “behind” this argument?

To simplify, let us look at the case of function germs:

What is “behind” this argument?

To simplify, let us look at the case of function germs:

$f \in \mathcal{O}_p$ is “elementary” iff f is a unit (i.e. iff $0 \in \text{New}_{(x,y)}(f)$).

What is “behind” this argument?

To simplify, let us look at the case of function germs:

$f \in \mathcal{O}_p$ is “elementary” iff f is a unit (i.e. iff $0 \in \text{New}_{(x,y)}(f)$).

Supposing that $\mathfrak{m} = (0, \mathfrak{h})$, the \mathfrak{e} -initial part of f is a (α, β) -homogeneous polynomial

$$f_{\mathfrak{e}} = cy^{\mathfrak{h}} + \sum_{\substack{\alpha i + \beta j = d \\ j \geq 1}} c_{ij} x^i y^j$$

What is “behind” this argument?

To simplify, let us look at the case of function germs:

$f \in \mathcal{O}_p$ is “elementary” iff f is a unit (i.e. iff $0 \in \text{New}_{(x,y)}(f)$).

Supposing that $\mathfrak{m} = (0, \mathfrak{h})$, the \mathfrak{e} -initial part of f is a (α, β) -homogeneous polynomial

$$f_{\mathfrak{e}} = cy^{\mathfrak{h}} + \sum_{\substack{\alpha i + \beta j = d \\ j \geq 1}} c_{ij} x^i y^j$$

(i.e. $f_{\mathfrak{e}}$ is a section a line (orbi)-bundle $\mathcal{L} \rightarrow \mathbb{P}_{(\alpha, \beta)}^1$, equal to $\mathcal{O}_{\mathbb{P}^1}(d)$ in the classical homogeneous case).

We can look at the divisor $\text{Div}(f_{\mathfrak{e}}) = \sum m_i [\xi_i]$ on $\mathbb{P}_{(\alpha, \beta)}^1$ (write $f_{\mathfrak{e}}(1, y) = \prod (y - \xi_i)^{m_i}$)

What is “behind” this argument?

To simplify, let us look at the case of function germs:

$f \in \mathcal{O}_p$ is “elementary” iff f is a unit (i.e. iff $0 \in \text{New}_{(x,y)}(f)$).

Supposing that $\mathfrak{m} = (0, \mathfrak{h})$, the \mathfrak{e} -initial part of f is a (α, β) -homogeneous polynomial

$$f_{\mathfrak{e}} = cy^{\mathfrak{h}} + \sum_{\substack{\alpha i + \beta j = d \\ j \geq 1}} c_{ij} x^i y^j$$

(i.e. $f_{\mathfrak{e}}$ is a section a line (orbi)-bundle $\mathcal{L} \rightarrow \mathbb{P}_{(\alpha,\beta)}^1$, equal to $\mathcal{O}_{\mathbb{P}^1}(d)$ in the classical homogeneous case).

We can look at the divisor $\text{Div}(f_{\mathfrak{e}}) = \sum m_i [\xi_i]$ on $\mathbb{P}_{(\alpha,\beta)}^1$ (write $f_{\mathfrak{e}}(1, y) = \prod (y - \xi_i)^{m_i}$)

The choice of \mathfrak{e} implies that $\text{Div}(f_{\mathfrak{e}}) \neq \mathfrak{h}[(1:0)]$. (i.e. the support of the divisor is not concentrated at $[(1:0)]$)

What is “behind” this argument?

To simplify, let us look at the case of function germs:

$f \in \mathcal{O}_p$ is “elementary” iff f is a unit (i.e. iff $0 \in \text{New}_{(x,y)}(f)$).

Supposing that $\mathbf{m} = (0, \mathfrak{h})$, the \mathfrak{e} -initial part of f is a (α, β) -homogeneous polynomial

$$f_{\mathfrak{e}} = cy^{\mathfrak{h}} + \sum_{\substack{\alpha i + \beta j = d \\ j \geq 1}} c_{ij} x^i y^j$$

(i.e. $f_{\mathfrak{e}}$ is a section a line (orbi)-bundle $\mathcal{L} \rightarrow \mathbb{P}_{(\alpha, \beta)}^1$, equal to $\mathcal{O}_{\mathbb{P}^1}(d)$ in the classical homogeneous case).

We can look at the divisor $\text{Div}(f_{\mathfrak{e}}) = \sum m_i [\xi_i]$ on $\mathbb{P}_{(\alpha, \beta)}^1$ (write $f_{\mathfrak{e}}(1, y) = \prod (y - \xi_i)^{m_i}$)

The choice of \mathfrak{e} implies that $\text{Div}(f_{\mathfrak{e}}) \neq \mathfrak{h}[(1:0)]$. (i.e. the support of the divisor is not concentrated at $[(1:0)]$)

$\text{New}_{(x,y)}(f)$ is **edge-unstable** iff $\text{Div}(f_{\mathfrak{e}}) = \mathfrak{h}[\xi]$ (i.e. the support of the divisor is a point $\xi \neq (1:0)$). In this case:

(1) This point is necessarily unique and,

What is “behind” this argument?

To simplify, let us look at the case of function germs:

$f \in \mathcal{O}_p$ is “elementary” iff f is a unit (i.e. iff $0 \in \text{New}_{(x,y)}(f)$).

Supposing that $\mathbf{m} = (0, \mathfrak{h})$, the \mathfrak{e} -initial part of f is a (α, β) -homogeneous polynomial

$$f_{\mathfrak{e}} = cy^{\mathfrak{h}} + \sum_{\substack{\alpha i + \beta j = d \\ j \geq 1}} c_{ij} x^i y^j$$

(i.e. $f_{\mathfrak{e}}$ is a section a line (orbi)-bundle $\mathcal{L} \rightarrow \mathbb{P}_{(\alpha,\beta)}^1$, equal to $\mathcal{O}_{\mathbb{P}^1}(d)$ in the classical homogeneous case).

We can look at the divisor $\text{Div}(f_{\mathfrak{e}}) = \sum m_i [\xi_i]$ on $\mathbb{P}_{(\alpha,\beta)}^1$ (write $f_{\mathfrak{e}}(1, y) = \prod (y - \xi_i)^{m_i}$)

The choice of \mathfrak{e} implies that $\text{Div}(f_{\mathfrak{e}}) \neq \mathfrak{h}[(1:0)]$. (i.e. the support of the divisor is not concentrated at $[(1:0)]$)

$\text{New}_{(x,y)}(f)$ is **edge-unstable** iff $\text{Div}(f_{\mathfrak{e}}) = \mathfrak{h}[\xi]$ (i.e. the support of the divisor is a point $\xi \neq (1:0)$). In this case:

(1) This point is necessarily unique and,

(2) $\beta/\alpha \notin \mathbb{Z}_{>0}$

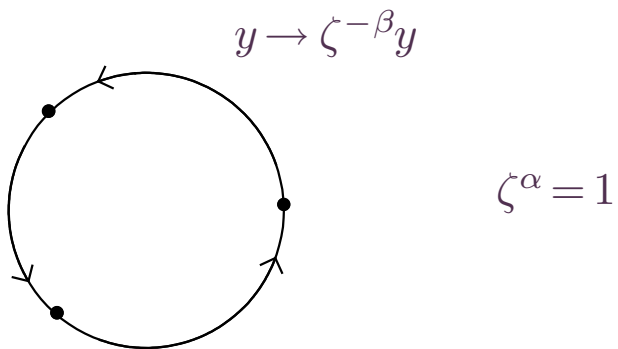
Simply because there is a $\mathbb{Z}/\alpha\mathbb{Z}$ -symmetry on the divisor.

Simply because there is a $\mathbb{Z}/\alpha\mathbb{Z}$ -symmetry on the divisor.

Symmetry breaking

Simply because there is a $\mathbb{Z}/\alpha\mathbb{Z}$ -symmetry on the divisor.

Symmetry breaking



It remains to prove that the following

It remains to prove that the following

Theorem (on edge stabilization)

(Existence) There exists adapted coordinates (x, y) such that

It remains to prove that the following

Theorem (on edge stabilization)

(Existence) There exists adapted coordinates (x, y) such that

$$\text{New}_{(x,y)}(\partial)$$

is edge stable.

It remains to prove that the following

Theorem (on edge stabilization)

(Existence) There exists adapted coordinates (x, y) such that

$$\text{New}_{(x,y)}(\partial)$$

is edge stable.

(Uniqueness of the associated filtration) Let $(x, y), (x', y')$ be coordinates such that $\text{New}_{(x,y)}(\partial)$ and $\text{New}_{(x',y')}(\partial)$ are edge stable. Then the local resolution algorithm (i.e. the local filtration of the local ring) defined through these coordinates coincide.

It remains to prove that the following

Theorem (on edge stabilization)

(Existence) There exists adapted coordinates (x, y) such that

$$\text{New}_{(x,y)}(\partial)$$

is edge stable.

(Uniqueness of the associated filtration) Let $(x, y), (x', y')$ be coordinates such that $\text{New}_{(x,y)}(\partial)$ and $\text{New}_{(x',y')}(\partial)$ are edge stable. Then the local resolution algorithm (i.e. the local filtration of the local ring) defined through these coordinates coincide.

In other words, the filtration is intrinsically determined by ∂ (and the divisor E).

It remains to prove that the following

Theorem (on edge stabilization)

(Existence) There exists adapted coordinates (x, y) such that

$$\text{New}_{(x,y)}(\partial)$$

is edge stable.

(Uniqueness of the associated filtration) Let $(x, y), (x', y')$ be coordinates such that $\text{New}_{(x,y)}(\partial)$ and $\text{New}_{(x',y')}(\partial)$ are edge stable. Then the local resolution algorithm (i.e. the local filtration of the local ring) defined through these coordinates coincide.

In other words, the filtration is intrinsically determined by ∂ (and the divisor E).

Proof: We start with an arbitrary adapted coordinate system (x, y_0) .

1) If $\text{New}_{(x,y_0)}(\partial)$ is edge-stable, we stop

2) If $\text{New}_{(x,y_0)}(\partial)$ is edge-unstable, we choose a polynomial coordinate change $(x, y_0) \rightarrow (x, y_1)$, where

$$y_1 = y_0 + \xi_0 x^{k_0}, \quad k_0 = \beta_0 / \alpha_0$$

eliminates the main edge ϵ_0 .

We now consider the new coordinates (x, y_1) and apply the same argument. I claim that this procedure eventually stops with an edge stable situation.

Indeed, assume the contrary. Then, we end-up with an infinite sequence of coordinate changes

$$y_{i+1} = y_i + \xi_i x^{k_i}, \quad i \geq 1$$

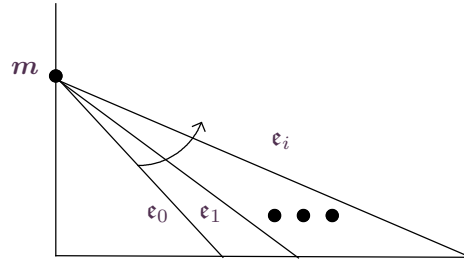
where $\{k_i = \beta_i / \alpha_i\}$ forms an strictly increasing sequence of integers, corresponding to the successive slopes of the edges \mathbf{e}_i .

We now consider the new coordinates (x, y_1) and apply the same argument. I claim that this procedure eventually stops with an edge stable situation.

Indeed, assume the contrary. Then, we end-up with an infinite sequence of coordinate changes

$$y_{i+1} = y_i + \xi_i x^{k_i}, \quad i \geq 1$$

where $\{k_i = \beta_i / \alpha_i\}$ forms an strictly increasing sequence of integers, corresponding to the successive slopes of the edges ϵ_i .

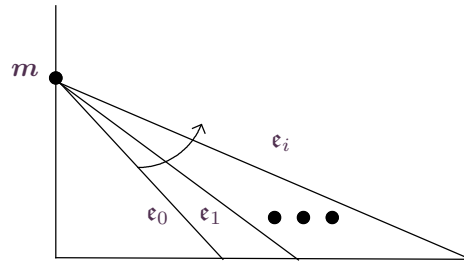


We now consider the new coordinates (x, y_1) and apply the same argument. I claim that this procedure eventually stops with an edge stable situation.

Indeed, assume the contrary. Then, we end-up with an infinite sequence of coordinate changes

$$y_{i+1} = y_i + \xi_i x^{k_i}, \quad i \geq 1$$

where $\{k_i = \beta_i / \alpha_i\}$ forms an strictly increasing sequence of integers, corresponding to the successive slopes of the edges ϵ_i .



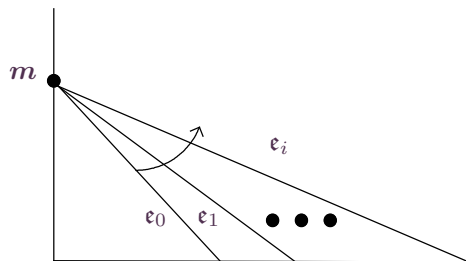
The composition of these maps converges to a formal coordinate change $\hat{y}_\infty = y_0 + \sum \xi_i x^{k_i}$

We now consider the new coordinates (x, y_1) and apply the same argument. I claim that this procedure eventually stops with an edge stable situation.

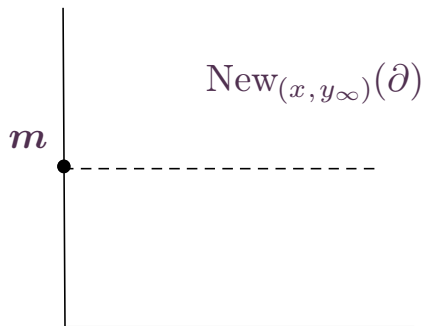
Indeed, assume the contrary. Then, we end-up with an infinite sequence of coordinate changes

$$y_{i+1} = y_i + \xi_i x^{k_i}, \quad i \geq 1$$

where $\{k_i = \beta_i / \alpha_i\}$ forms an strictly increasing sequence of integers, corresponding to the successive slopes of the edges e_i .



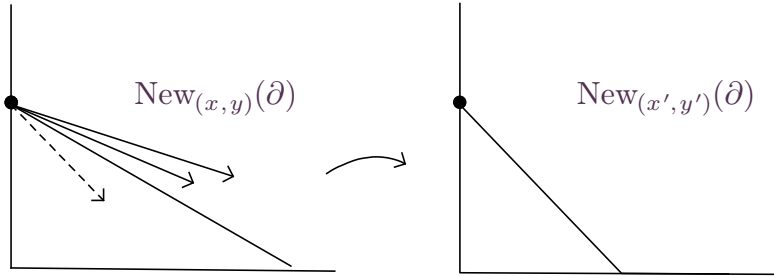
The composition of these maps converges to a formal coordinate change $\widehat{y}_\infty = y_0 + \sum \xi_i x^{k_i}$



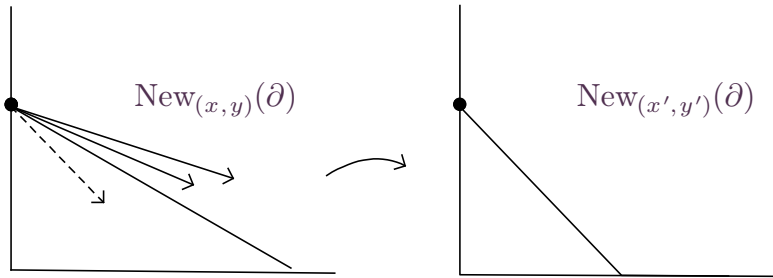
In these coordinates,

i.e. $(\widehat{y}_\infty = 0) \subset \text{Nilp}(M, \mathcal{F})$. Contradiction.

Uniqueness of the filtration. Suppose that $\text{New}_{(x,y)}(\partial)$, $\text{New}_{(x',y'')(\partial)}$ are edge stable

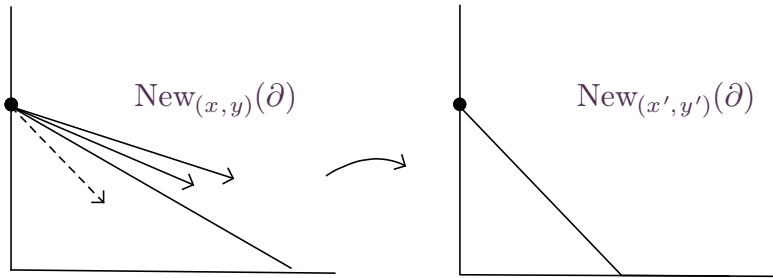


Uniqueness of the filtration. Suppose that $\text{New}_{(x,y)}(\partial)$, $\text{New}_{(x',y'')(\partial)}$ are edge stable



write $x' = x f(x, y)$, $y' = g(x, y)$. We claim that this map preserves the $\text{wt}(\mathfrak{e})$ filtration.

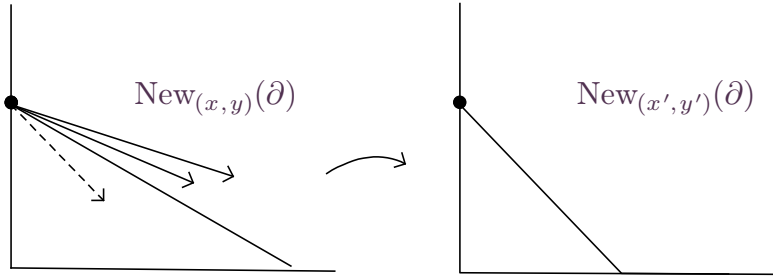
Uniqueness of the filtration. Suppose that $\text{New}_{(x,y)}(\partial)$, $\text{New}_{(x',y'')(\partial)}$ are edge stable



write $x' = x f(x, y)$, $y' = g(x, y)$. We claim that this map preserves the $\text{wt}(\mathfrak{e})$ filtration.

Let us write $g(x, y) = g_0(x) + yG(x, y)$. Then, the change of coordinates preserves the filtration if and only if

Uniqueness of the filtration. Suppose that $\text{New}_{(x,y)}(\partial)$, $\text{New}_{(x',y'')(\partial)}$ are edge stable

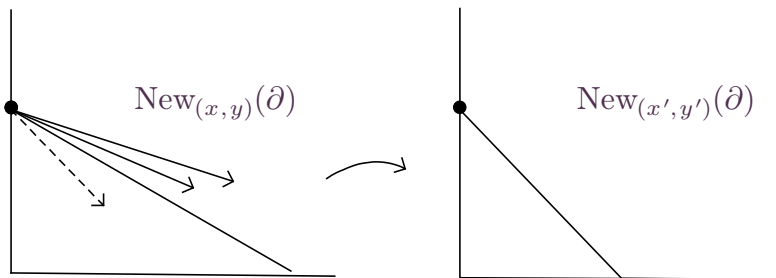


write $x' = x f(x, y)$, $y' = g(x, y)$. We claim that this map preserves the $\text{wt}(\mathfrak{e})$ filtration.

Let us write $g(x, y) = g_0(x) + yG(x, y)$. Then, the change of coordinates preserves the filtration if and only if

$$g_0(x) = O\left(x^{\frac{\beta}{\alpha}}\right)$$

Uniqueness of the filtration. Suppose that $\text{New}_{(x,y)}(\partial)$, $\text{New}_{(x',y'')}(\partial)$ are edge stable



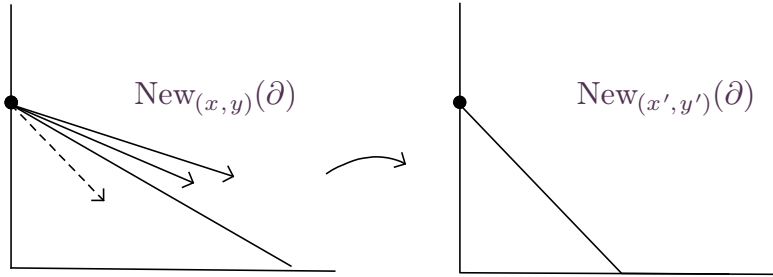
write $x' = x f(x, y)$, $y' = g(x, y)$. We claim that this map preserves the $\text{wt}(\mathfrak{e})$ filtration.

Let us write $g(x, y) = g_0(x) + yG(x, y)$. Then, the change of coordinates preserves the filtration if and only if

$$g_0(x) = O\left(x^{\frac{\beta}{\alpha}}\right)$$

Suppose that this is not the case. Then, looking at the smallest order term of g_0 , we find a polynomial change of coordinates $y_1 = y + \xi x^k$ with $\xi \neq 0$ and $k < \frac{\beta}{\alpha}$ such that

Uniqueness of the filtration. Suppose that $\text{New}_{(x,y)}(\partial)$, $\text{New}_{(x',y'')(\partial)}$ are edge stable



write $x' = x f(x, y)$, $y' = g(x, y)$. We claim that this map preserves the $\text{wt}(\mathfrak{e})$ filtration.

Let us write $g(x, y) = g_0(x) + yG(x, y)$. Then, the change of coordinates preserves the filtration if and only if

$$g_0(x) = O\left(x^{\frac{\beta}{\alpha}}\right)$$

Suppose that this is not the case. Then, looking at the smallest order term of g_0 , we find a polynomial change of coordinates $y_1 = y + \xi x^k$ with $\xi \neq 0$ and $k < \frac{\beta}{\alpha}$ such that

$$\text{New}_{(x,y_1)}(\partial)$$

is has a main edge \mathfrak{e}' of slope $k < \beta/\alpha$ (because the action of $y \rightarrow y + \xi x^k$ on $\text{New}_{(x,y)}(\partial)$ is effective).

However, $\text{New}_{(x, y_1)}(\partial)$ should also be edge-stable.

However, $\text{New}_{(x, y_1)}(\partial)$ should also be edge-stable.

(because the $(1, k)$ -initial part of ∂ with respect to (x, y_1) equals its ϵ' -initial part with respect to (x', y') , which is stable by the hypothesis).

However, $\text{New}_{(x, y_1)}(\partial)$ should also be edge-stable.

(because the $(1, k)$ -initial part of ∂ with respect to (x, y_1) equals its ϵ' -initial part with respect to (x', y') , which is stable by the hypothesis).

But this contradicts the fact that the **inverse transformation** $y = y_1 - \xi x^k$ eliminates the main edge.

Some general remarks:

Some general remarks:

1) We cannot expect to obtain a **fully convergent Tschirnhausen preparation** (or, more generally, a maximal contact hypersurface which would allow to use induction in the dimension)

Recall that, in the classical case of a germ of singular hypersurface S , this corresponds to choose a local equation of the form

$$f(\underline{x}, y) = y^h + \sum a_i(\underline{x})y^{h-i}$$

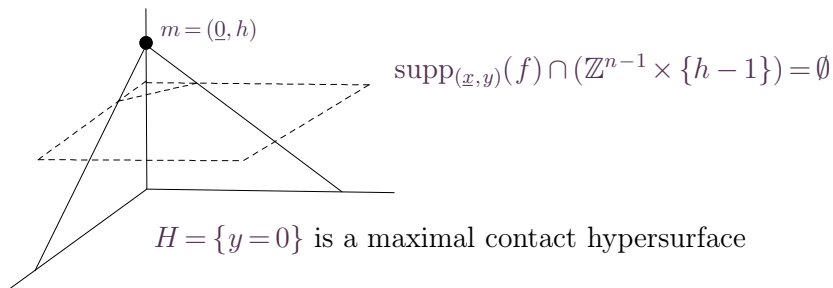
Some general remarks:

1) We cannot expect to obtain a **fully convergent Tschirnhausen preparation** (or, more generally, a maximal contact hypersurface which would allow to use induction in the dimension)

Recall that, in the classical case of a germ of singular hypersurface S , this corresponds to choose a local equation of the form

$$f(\underline{x}, y) = y^h + \sum a_i(\underline{x})y^{h-i}$$

and eliminate the term in y^{h-1} by the local change of coordinates $y \rightarrow y - \frac{1}{h}a_1$ (Tschirnhausen transformation)



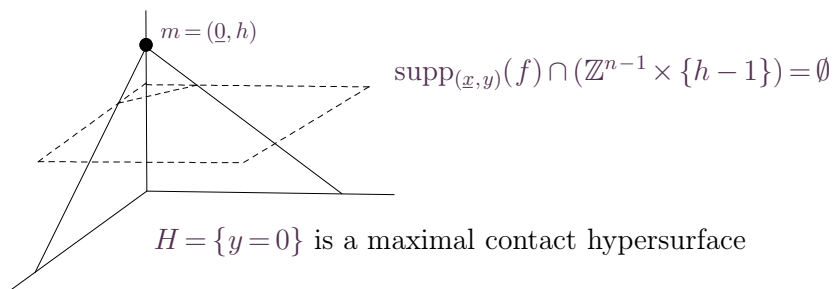
Some general remarks:

1) We cannot expect to obtain a **fully convergent Tschirnhausen preparation** (or, more generally, a maximal contact hypersurface which would allow to use induction in the dimension)

Recall that, in the classical case of a germ of singular hypersurface S , this corresponds to choose a local equation of the form

$$f(\underline{x}, y) = y^h + \sum a_i(\underline{x})y^{h-i}$$

and eliminate the term in y^{h-1} by the local change of coordinates $y \rightarrow y - \frac{1}{h}a_1$ (Tschirnhausen transformation)



As a consequence, simply because $\boxed{(\partial / \partial y)^{h-1} f = y}$, the *multiplicity h -locus* $\text{Sing}^h(f)$ is contained in the hypersurface $H = \{y = 0\}$

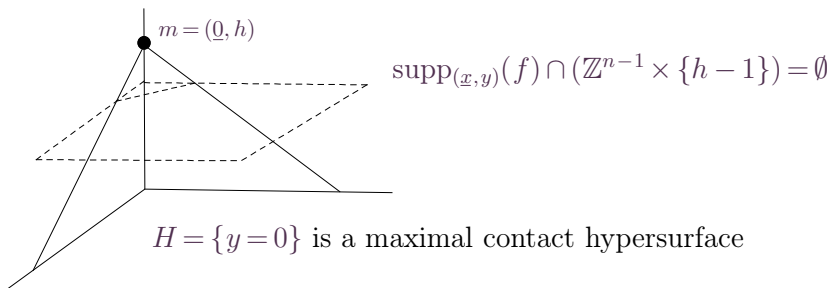
Some general remarks:

1) We cannot expect to obtain a **fully convergent Tschirnhausen preparation** (or, more generally, a maximal contact hypersurface which would allow to use induction in the dimension)

Recall that, in the classical case of a germ of singular hypersurface S , this corresponds to choose a local equation of the form

$$f(\underline{x}, y) = y^h + \sum a_i(\underline{x})y^{h-i}$$

and eliminate the term in y^{h-1} by the local change of coordinates $y \rightarrow y - \frac{1}{h}a_1$ (Tschirnhausen transformation)



As a consequence, simply because $\boxed{(\partial / \partial y)^{h-1} f = y}$, the *multiplicity h -locus* $\text{Sing}^h(f)$ is contained in the hypersurface $H = \{y = 0\}$

and this remains true for all blowings-up with center on $\text{Sing}^h(f)$.

Analogous question for vector fields, say in dim. 2:

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

The differential operator $\left(\frac{\partial}{\partial y} \right)$ acts on $\text{Der}(\mathcal{O})$ by Lie brackets.

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

The differential operator $\left(\frac{\partial}{\partial y} \right)$ acts on $\text{Der}(\mathcal{O})$ by Lie brackets.

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

The differential operator $\left(\frac{\partial}{\partial y} \right)$ acts on $\text{Der}(\mathcal{O})$ by Lie brackets.

$$\delta = (\text{ad}_{\partial/\partial y})^h \partial = \left(\left[\frac{\partial}{\partial y}, \cdot \right] \right)^h \partial = \boxed{(h+1)! by \frac{\partial}{\partial y} + h! ax \frac{\partial}{\partial x}} + (\text{terms of higher order})$$

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

The differential operator $\left(\frac{\partial}{\partial y} \right)$ acts on $\text{Der}(\mathcal{O})$ by Lie brackets.

$$\delta = (\text{ad}_{\partial/\partial y})^h \partial = \left(\left[\frac{\partial}{\partial y}, \cdot \right] \right)^h \partial = \boxed{(h+1)! by \frac{\partial}{\partial y} + h! ax \frac{\partial}{\partial x}} + (\text{terms of higher order})$$

In this situation, the analogous of a maximal contact surface should be

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

The differential operator $\left(\frac{\partial}{\partial y} \right)$ acts on $\text{Der}(\mathcal{O})$ by Lie brackets.

$$\delta = (\text{ad}_{\partial/\partial y})^h \partial = \left(\left[\frac{\partial}{\partial y}, \cdot \right] \right)^h \partial = \boxed{(h+1)! by \frac{\partial}{\partial y} + h! ax \frac{\partial}{\partial x}} + (\text{terms of higher order})$$

In this situation, the analogous of a maximal contact surface should be an *invariant curve* for δ of the form $H = \{y = f(x)\}$.

Analogous question for vector fields, say in dim. 2:

$$\partial = y^h \left(ax \frac{\partial}{\partial x} + by \frac{\partial}{\partial y} \right) + \sum y^{h-i} a(x)$$

The differential operator $\left(\frac{\partial}{\partial y} \right)$ acts on $\text{Der}(\mathcal{O})$ by Lie brackets.

$$\delta = (\text{ad}_{\partial/\partial y})^h \partial = \left(\left[\frac{\partial}{\partial y}, \cdot \right] \right)^h \partial = \boxed{(h+1)! by \frac{\partial}{\partial y} + h! ax \frac{\partial}{\partial x}} + (\text{terms of higher order})$$

In this situation, the analogous of a maximal contact surface should be an *invariant curve* for δ of the form $H = \{y = f(x)\}$.

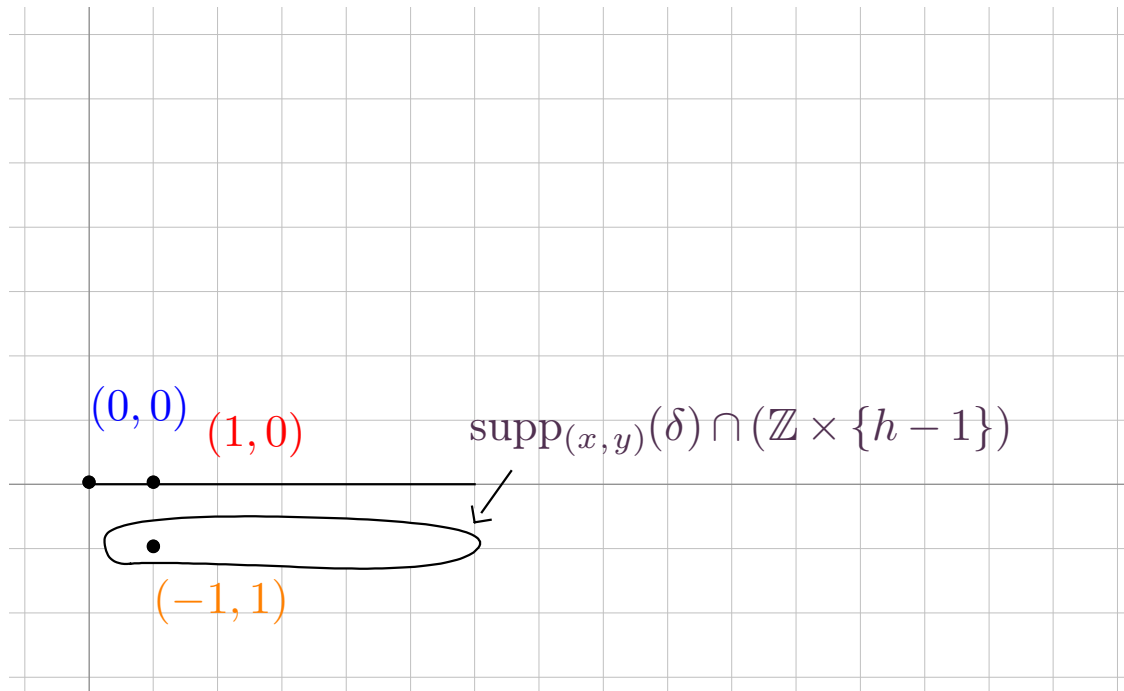
i.e. satisfying

$$\delta(y - f) \subset \langle y - f \rangle$$

Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)^r}(\partial)$ has the form

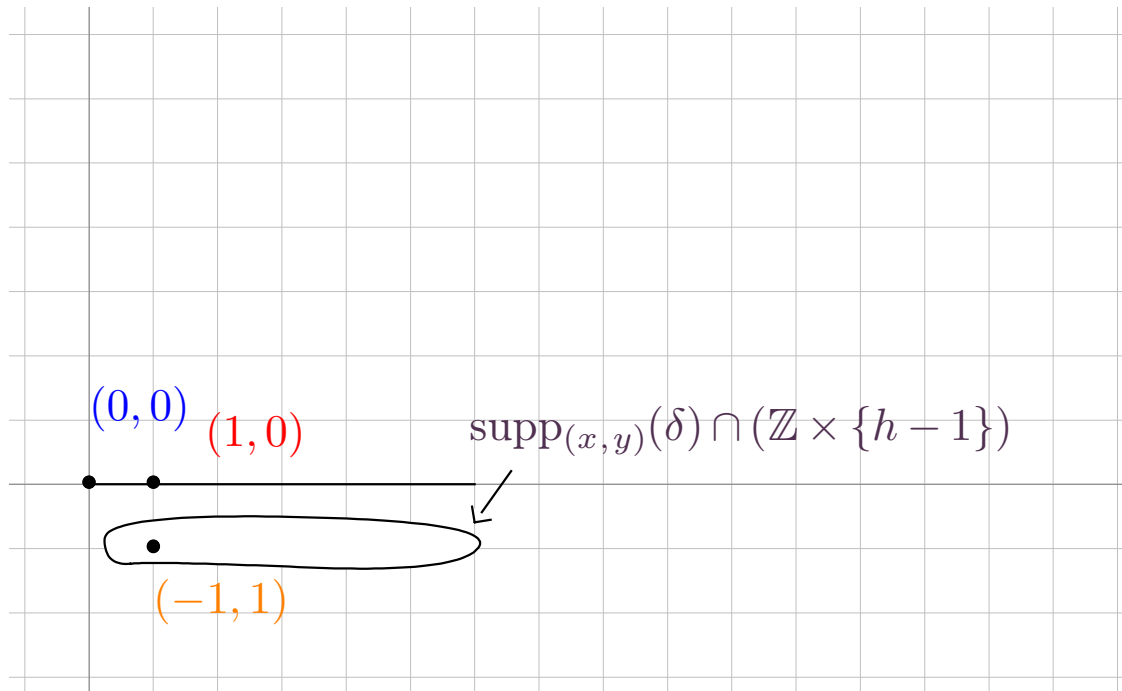
Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)r}(\partial)$ has the form

$$\delta = x^2 \frac{\partial}{\partial x} + (y - x) \frac{\partial}{\partial y}$$



Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)^r}(\partial)$ has the form

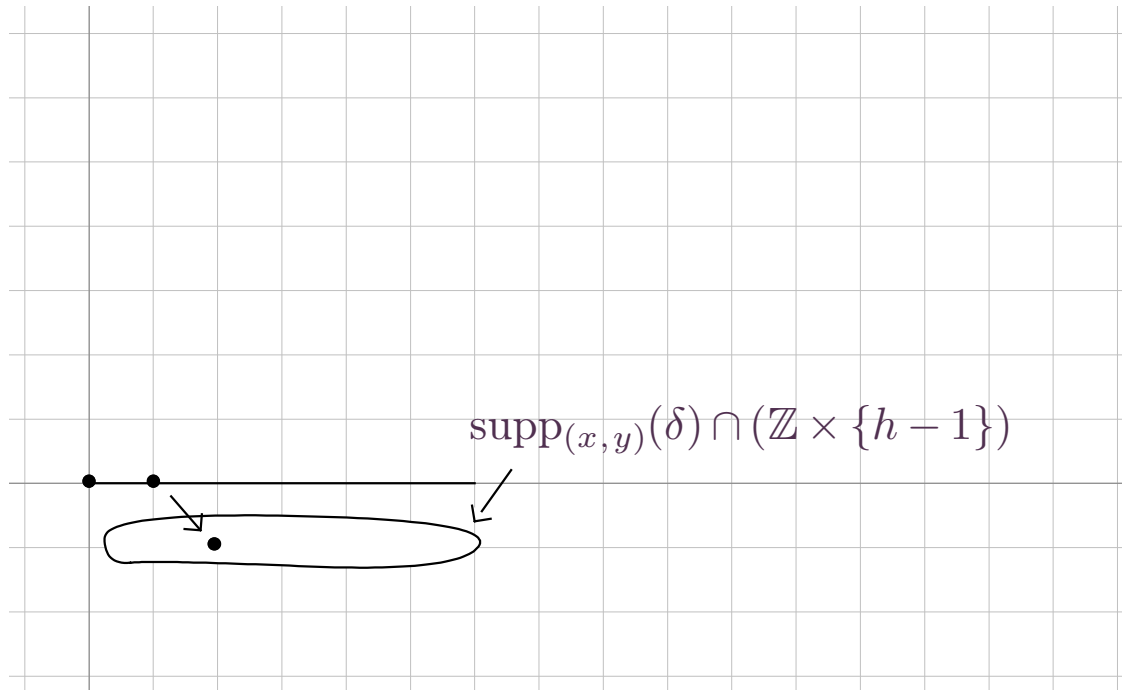
$$\delta = x^2 \frac{\partial}{\partial x} + (y - x) \frac{\partial}{\partial y}$$



$$y \rightarrow y - x$$

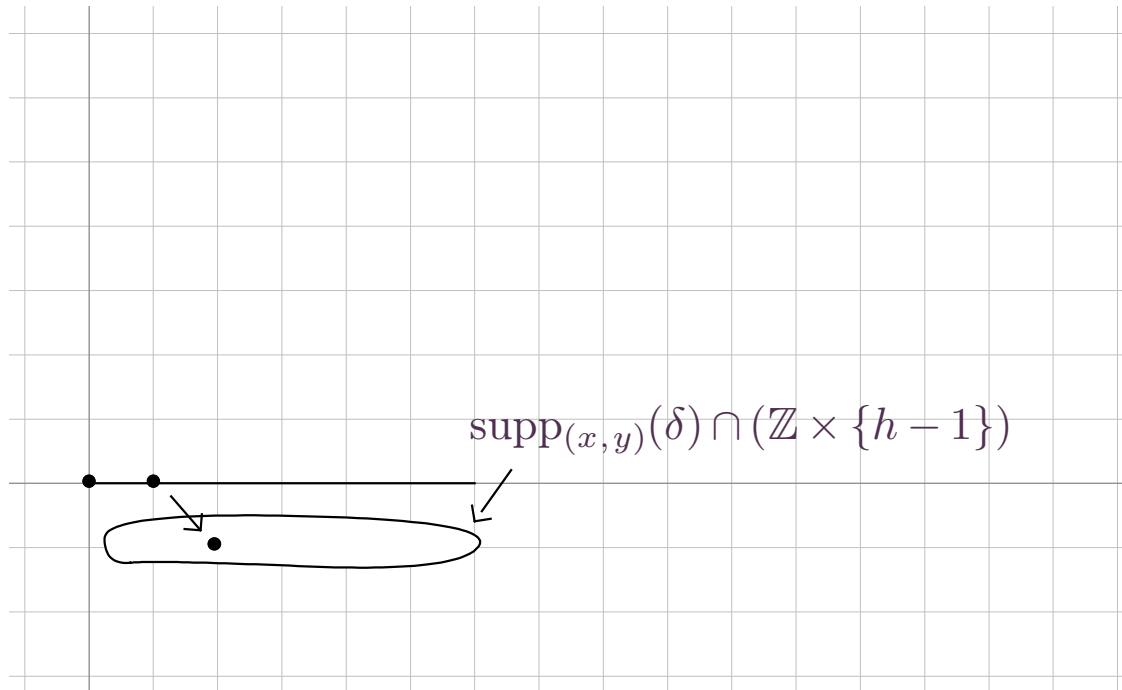
Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)r}(\partial)$ has the form

$$\delta = x^2 \frac{\partial}{\partial x} + (y - x^2) \frac{\partial}{\partial y}$$



Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)r}(\partial)$ has the form

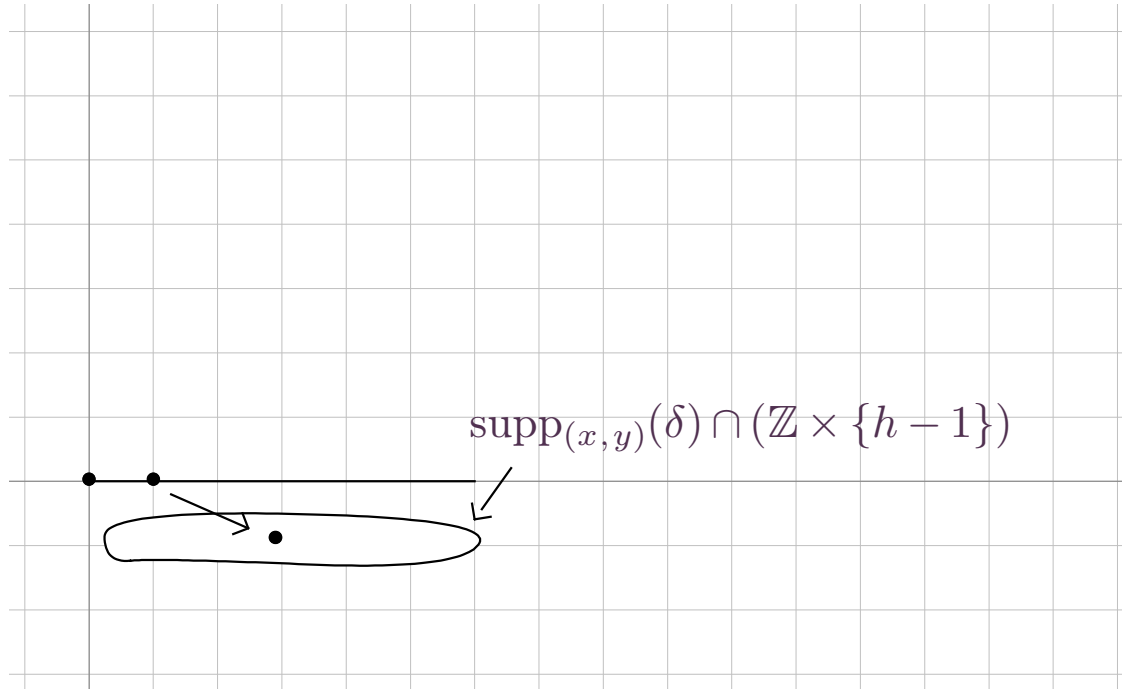
$$\delta = x^2 \frac{\partial}{\partial x} + (y - x^2) \frac{\partial}{\partial y}$$



$$y \rightarrow y - x^2$$

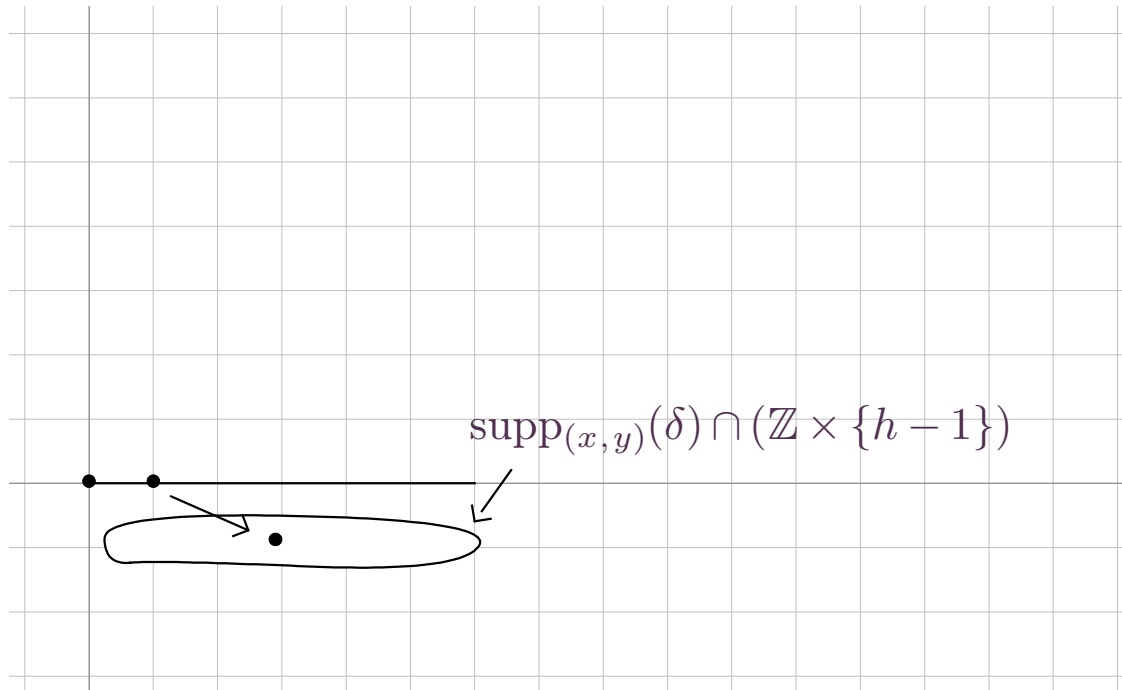
Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)^r}(\partial)$ has the form

$$\delta = x^2 \frac{\partial}{\partial x} + (y - 2x^3) \frac{\partial}{\partial y}$$



Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)^r}(\partial)$ has the form

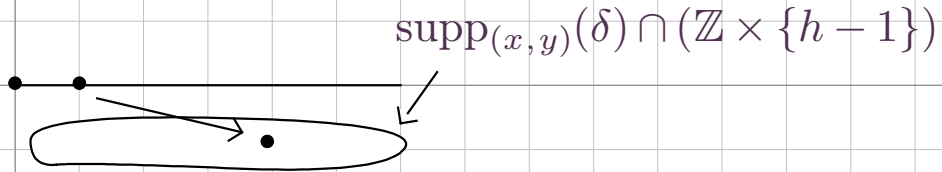
$$\delta = x^2 \frac{\partial}{\partial x} + (y - 2x^3) \frac{\partial}{\partial y}$$



$$y \rightarrow y - 2x^3$$

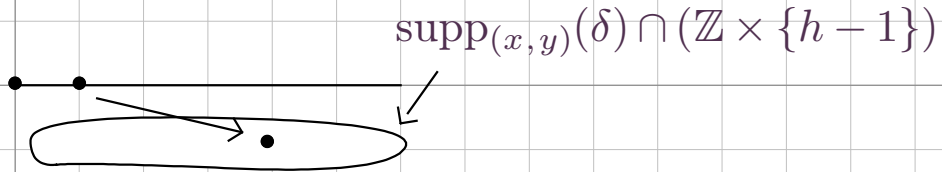
Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)^r}(\partial)$ has the form

$$\delta = x^2 \frac{\partial}{\partial x} + (y - 3x^4) \frac{\partial}{\partial y}$$



Example (Euler's equation): Assume that $\delta = \text{ad}_{(\partial/\partial y)^r}(\partial)$ has the form

$$\delta = x^2 \frac{\partial}{\partial x} + (y - 3x^4) \frac{\partial}{\partial y}$$



At the “Krull”-limit, we obtain

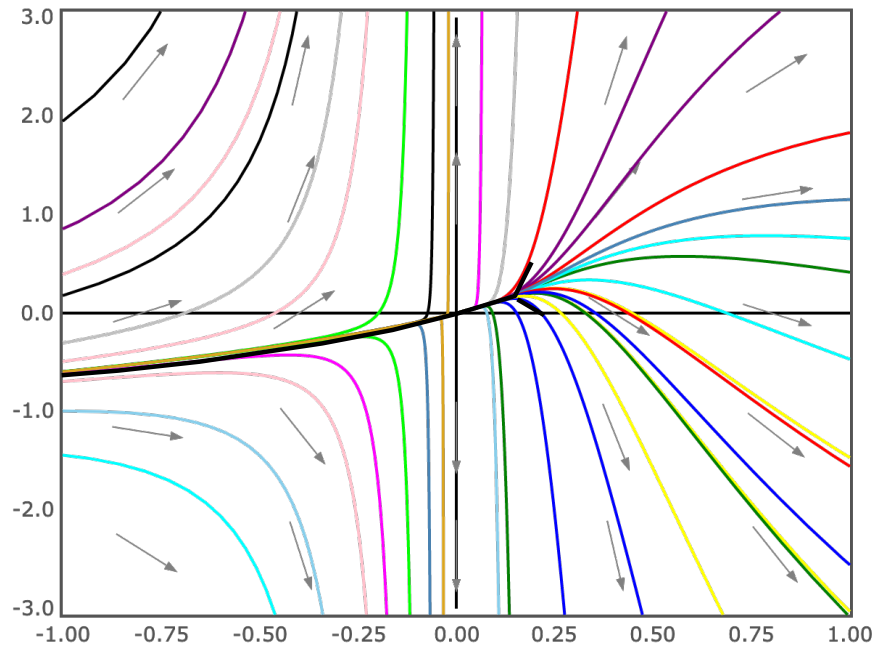
$$H = \left\{ y = \sum_{n \geq 1} (n-1)! x^n \right\}$$

which is the so-called “center manifold” of the Euler’s equation.

At the “Krull”-limit, we obtain

$$H = \left\{ y = \sum_{n \geq 1} (n-1)! x^n \right\}$$

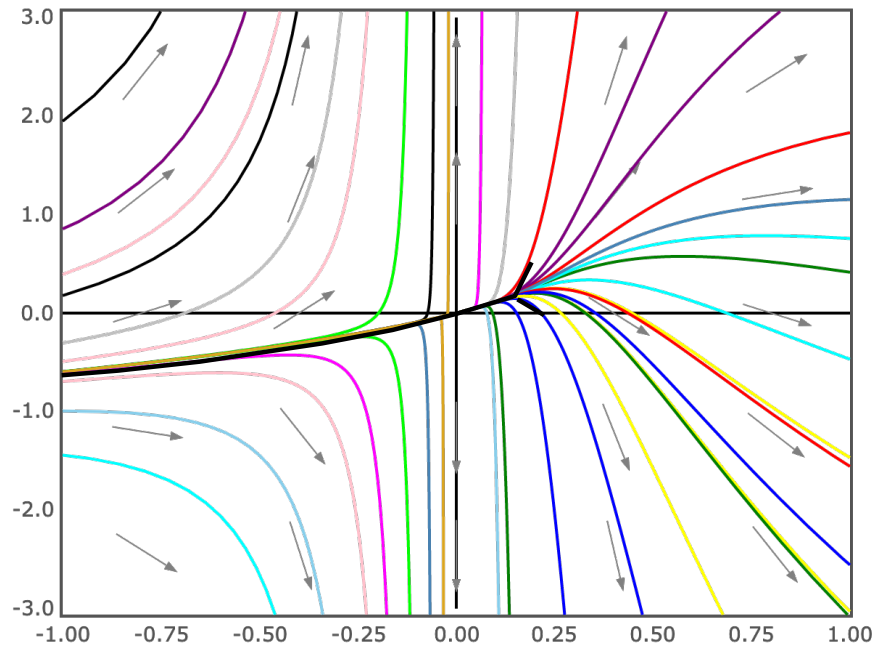
which is the so-called “center manifold” of the Euler’s equation.



At the “Krull”-limit, we obtain

$$H = \left\{ y = \sum_{n \geq 1} (n-1)! x^n \right\}$$

which is the so-called “center manifold” of the Euler’s equation.

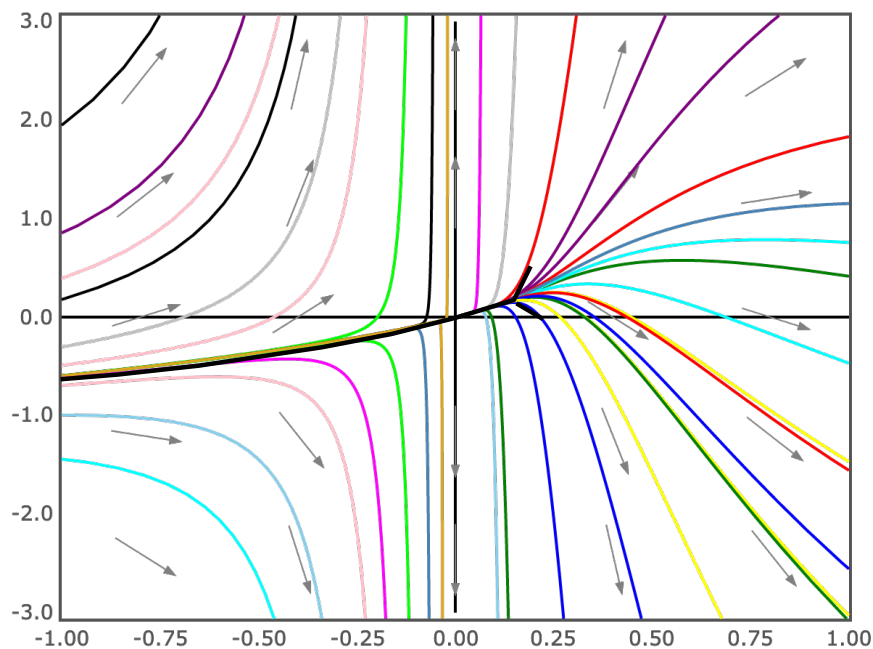


In this case, the maximal contact surface is a formal, non-convergent curve.

At the “Krull”-limit, we obtain

$$H = \left\{ y = \sum_{n \geq 1} (n-1)! x^n \right\}$$

which is the so-called “center manifold” of the Euler’s equation.



In this case, the maximal contact surface is a formal, non-convergent curve.

But which is a C^∞ -curve, lying on the pfaffian extension of \mathbb{R}_{an} .

What comes next:

What comes next:

- 1) How to generalize these ideas to eliminate the nilpotent locus for foliations in dimension three?
- 2) What to do with the final models in dimension three? (There is no such well developed theory)
- 3) Interesting particular case for the Hilbert's 16th problem: The case “2+1”.

Attainable goal: study of **one-parameter** families of planar analytic foliations.

What comes next:

- 1) How to generalize these ideas to eliminate the nilpotent locus for foliations in dimension three?
- 2) What to do with the final models in dimension three? (There is no such well developed theory)
- 3) Interesting particular case for the Hilbert's 16th problem: The case “2+1”.

Attainable goal: study of **one-parameter** families of planar analytic foliations.

- Full catalog of final cases

What comes next:

- 1) How to generalize these ideas to eliminate the nilpotent locus for foliations in dimension three?
- 2) What to do with the final models in dimension three? (There is no such well developed theory)
- 3) Interesting particular case for the Hilbert's 16th problem: The case “2+1”.

Attainable goal: study of **one-parameter** families of planar analytic foliations.

- Full catalog of final cases
- Study of normal forms

What comes next:

- 1) How to generalize these ideas to eliminate the nilpotent locus for foliations in dimension three?
- 2) What to do with the final models in dimension three? (There is no such well developed theory)
- 3) Interesting particular case for the Hilbert's 16th problem: The case “2+1”.

Attainable goal: study of **one-parameter** families of planar analytic foliations.

- Full catalog of final cases
- Study of normal forms
- Finite cyclicity conjecture for one-parameter families of planar analytic foliations.

What comes next:

- 1) How to generalize these ideas to eliminate the nilpotent locus for foliations in dimension three?
- 2) What to do with the final models in dimension three? (There is no such well developed theory)
- 3) Interesting particular case for the Hilbert's 16th problem: The case “2+1”.

Attainable goal: study of **one-parameter** families of planar analytic foliations.

- Full catalog of final cases
- Study of normal forms
- Finite cyclicity conjecture for one-parameter families of planar analytic foliations.

- 4) New ideas for dimension greater or equal than four (The Kempf's unstability approach)

Some new phenomena in for
final models in dimension three...

1) Center manifolds are not necessarily C^∞ .

1) Center manifolds are not necessarily C^∞ .

Example (van Strien 1979 - further simplified by M. Mcquillan)

1) Center manifolds are not necessarily C^∞ .

Example (van Strien 1979 - further simplified by M. Mcquillan)

a.k.a. “THE MONSTER”

1) Center manifolds are not necessarily C^∞ .

Example (van Strien 1979 - further simplified by M. Mcquillan)

a.k.a. “THE MONSTER”

$$\partial = xy \frac{\partial}{\partial y} + \left(z - \frac{y}{1-y} \right) \frac{\partial}{\partial z}$$

1) Center manifolds are not necessarily C^∞ .

Example (van Strien 1979 - further simplified by M. Mcquillan)

a.k.a. “THE MONSTER”

$$\partial = xy \frac{\partial}{\partial y} + \left(z - \frac{y}{1-y} \right) \frac{\partial}{\partial z}$$

$$C = \{z = f(x, y)\}, \quad \left(1 - xy \frac{\partial}{\partial y} \right) f = \frac{y}{1-y}$$

1) Center manifolds are not necessarily C^∞ .

Example (van Strien 1979 - further simplified by M. Mcquillan)

a.k.a. “THE MONSTER”

$$\partial = xy \frac{\partial}{\partial y} + \left(z - \frac{y}{1-y} \right) \frac{\partial}{\partial z}$$

$$C = \{z = f(x, y)\}, \quad \left(1 - xy \frac{\partial}{\partial y} \right) f = \frac{y}{1-y}$$

$$f = \sum a_k(x) y^k \implies a_k = \frac{1}{1-kx}$$

1) Center manifolds are not necessarily C^∞ .

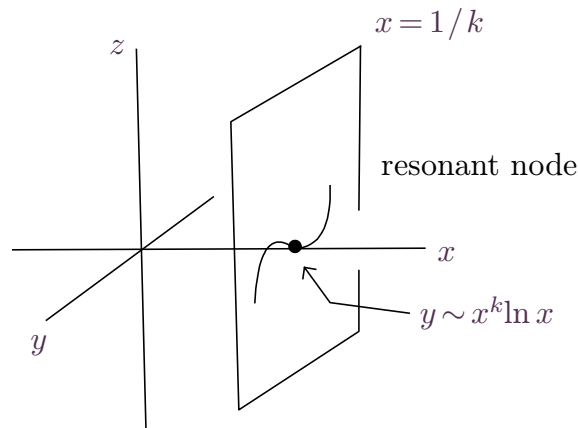
Example (van Strien 1979 - further simplified by M. Mcquillan)

a.k.a. “THE MONSTER”

$$\partial = xy \frac{\partial}{\partial y} + \left(z - \frac{y}{1-y} \right) \frac{\partial}{\partial z}$$

$$C = \{z = f(x, y)\}, \quad \left(1 - xy \frac{\partial}{\partial y} \right) f = \frac{y}{1-y}$$

$$f = \sum a_k(x) y^k \implies a_k = \frac{1}{1 - kx}$$



Example of $(2 + 1)$ foliations: Singularly perturbed van der Pol's equation

Example of (2 + 1) foliations: Singularly perturbed van der Pol's equation

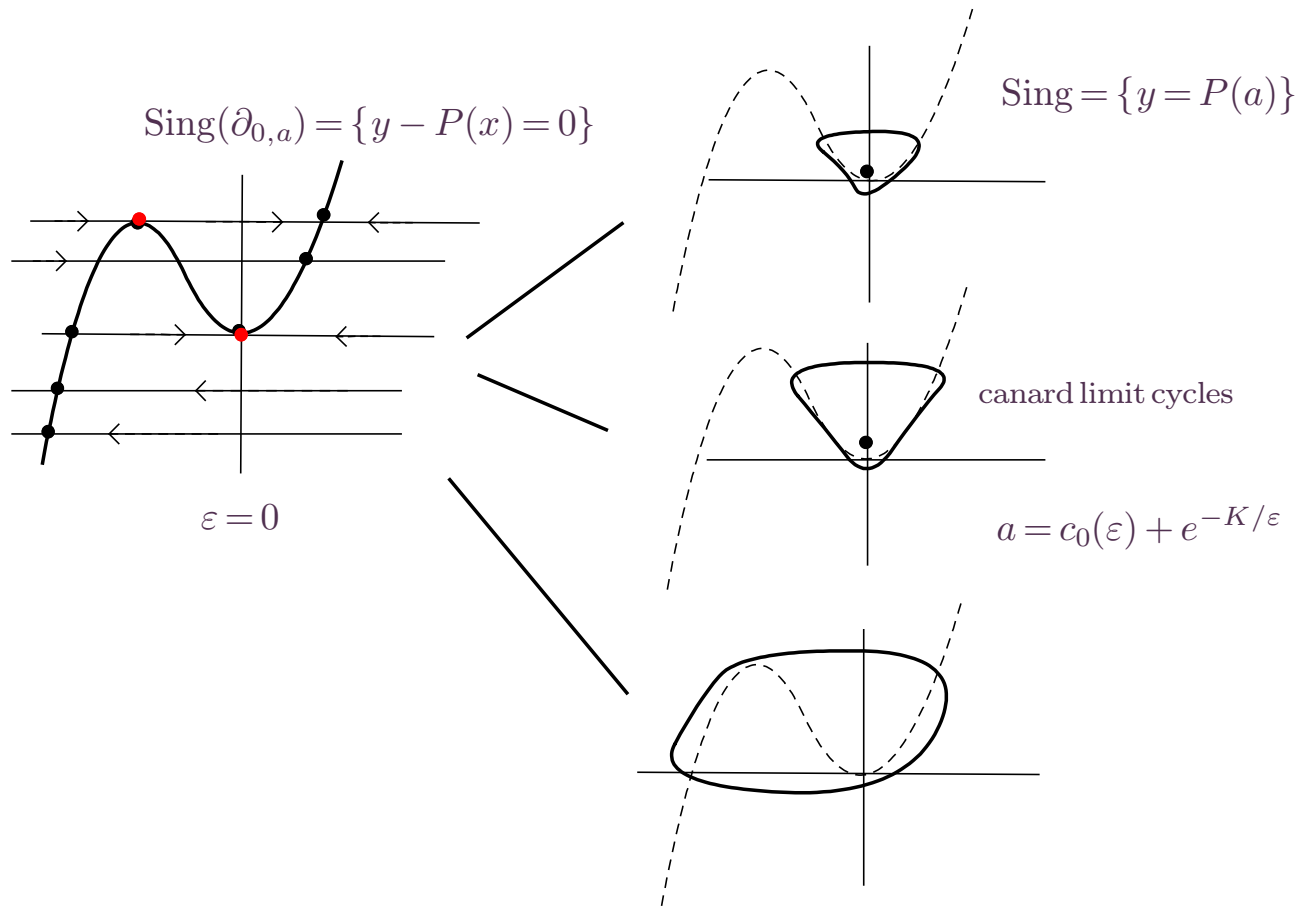
$$\partial_{\varepsilon, a} = \left(y - \frac{x^2}{2} - \frac{x^3}{3} \right) \frac{\partial}{\partial x} + \varepsilon (a - x) \frac{\partial}{\partial y}, \quad (x, y) \in \mathbb{R}^2, \varepsilon \in \mathbb{R}_{\geq 0}$$

Example of (2 + 1) foliations: Singularly perturbed van der Pol's equation

$$\partial_{\varepsilon, a} = \left(y - \frac{x^2}{2} - \frac{x^3}{3} \right) \frac{\partial}{\partial x} + \varepsilon (a - x) \frac{\partial}{\partial y}, \quad (x, y) \in \mathbb{R}^2, \varepsilon \in \mathbb{R}_{\geq 0}$$

Example of (2 + 1) foliations: Singularly perturbed van der Pol's equation

$$\partial_{\varepsilon, a} = \left(y - \frac{x^2}{2} - \frac{x^3}{3} \right) \frac{\partial}{\partial x} + \varepsilon (a - x) \frac{\partial}{\partial y}, \quad (x, y) \in \mathbb{R}^2, \varepsilon \in \mathbb{R}_{\geq 0}$$



Example of resolution (in families). We assume $a = 0$ to simplify

$$\left(y - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \varepsilon x \frac{\partial}{\partial y} = \left(x^{-1}y - \frac{x}{2} - \frac{x^2}{3}\right) \left(x \frac{\partial}{\partial x}\right) - \varepsilon x y^{-1} \left(y \frac{\partial}{\partial y}\right)$$

Is a three dimensional foliation **Tangent to the fibration:** $F = \{d\varepsilon = 0\}$

Example of resolution (in families). We assume $a = 0$ to simplify

$$\left(y - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \varepsilon x \frac{\partial}{\partial y} = \left(x^{-1}y - \frac{x}{2} - \frac{x^2}{3}\right) \left(x \frac{\partial}{\partial x}\right) - \varepsilon x y^{-1} \left(y \frac{\partial}{\partial y}\right)$$

Is a three dimensional foliation **Tangent to the fibration:** $F = \{d\varepsilon = 0\}$

Choice of weights: $-\text{wt}(x) + \text{wt}(y) = \text{wt}(x)$, $\text{wt}(\varepsilon) + \text{wt}(x) - \text{wt}(y) = \text{wt}(x)$

Example of resolution (in families). We assume $a = 0$ to simplify

$$\left(y - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \varepsilon x \frac{\partial}{\partial y} = \left(x^{-1}y - \frac{x}{2} - \frac{x^2}{3}\right) \left(x \frac{\partial}{\partial x}\right) - \varepsilon x y^{-1} \left(y \frac{\partial}{\partial y}\right)$$

Is a three dimensional foliation **Tangent to the fibration:** $F = \{d\varepsilon = 0\}$

Choice of weights: $-\text{wt}(x) + \text{wt}(y) = \text{wt}(x)$, $\text{wt}(\varepsilon) + \text{wt}(x) - \text{wt}(y) = \text{wt}(x)$

$$\text{wt}(x) = 1, \text{wt}(y) = 2, \text{wt}(\varepsilon) = 2$$

Example of resolution (in families). We assume $a = 0$ to simplify

$$\left(y - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \varepsilon x \frac{\partial}{\partial y} = \left(x^{-1}y - \frac{x}{2} - \frac{x^2}{3}\right) \left(x \frac{\partial}{\partial x}\right) - \varepsilon x y^{-1} \left(y \frac{\partial}{\partial y}\right)$$

Is a three dimensional foliation **Tangent to the fibration:** $F = \{d\varepsilon = 0\}$

Choice of weights: $-\text{wt}(x) + \text{wt}(y) = \text{wt}(x)$, $\text{wt}(\varepsilon) + \text{wt}(x) - \text{wt}(y) = \text{wt}(x)$

$$\text{wt}(x) = 1, \text{wt}(y) = 2, \text{wt}(\varepsilon) = 2$$

y - directional blowing up: $x \rightarrow yx$, $y \rightarrow y^2$, $\varepsilon \rightarrow y^2\varepsilon$

$$\left(1 - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \frac{\varepsilon x}{2} \left(y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} - 2\varepsilon \frac{\partial}{\partial \varepsilon}\right), \quad F = \{d(y^2\varepsilon) = 0\}$$

Example of resolution (in families). We assume $a = 0$ to simplify

$$\left(y - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \varepsilon x \frac{\partial}{\partial y} = \left(x^{-1}y - \frac{x}{2} - \frac{x^2}{3}\right) \left(x \frac{\partial}{\partial x}\right) - \varepsilon x y^{-1} \left(y \frac{\partial}{\partial y}\right)$$

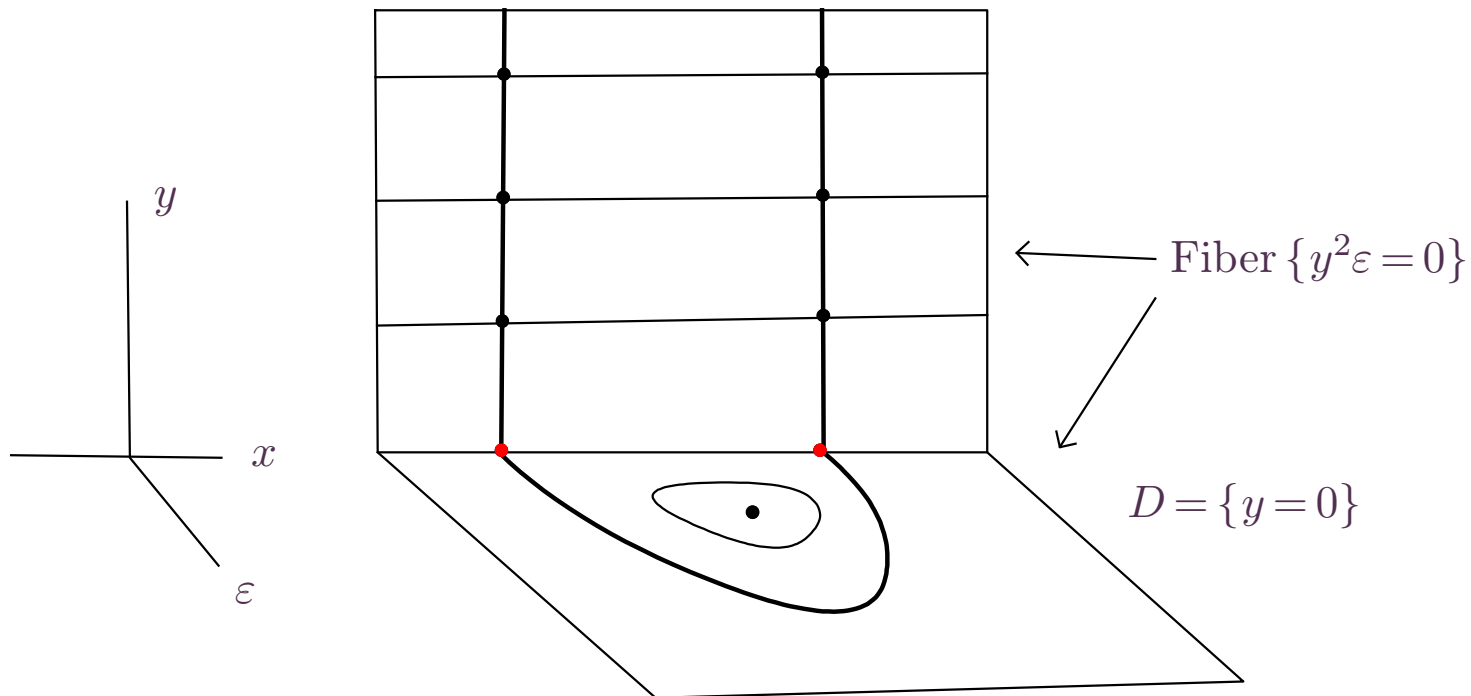
Is a three dimensional foliation **Tangent to the fibration:** $F = \{d\varepsilon = 0\}$

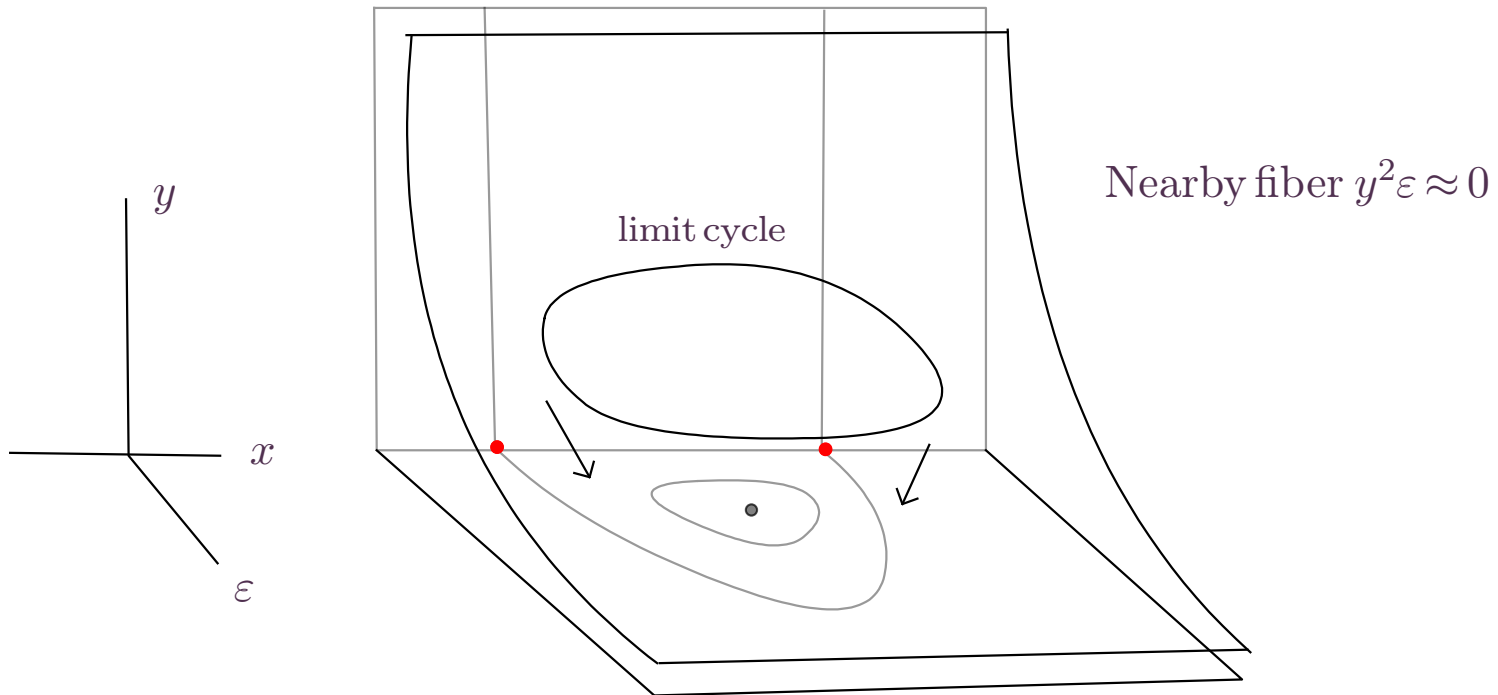
Choice of weights: $-\text{wt}(x) + \text{wt}(y) = \text{wt}(x)$, $\text{wt}(\varepsilon) + \text{wt}(x) - \text{wt}(y) = \text{wt}(x)$

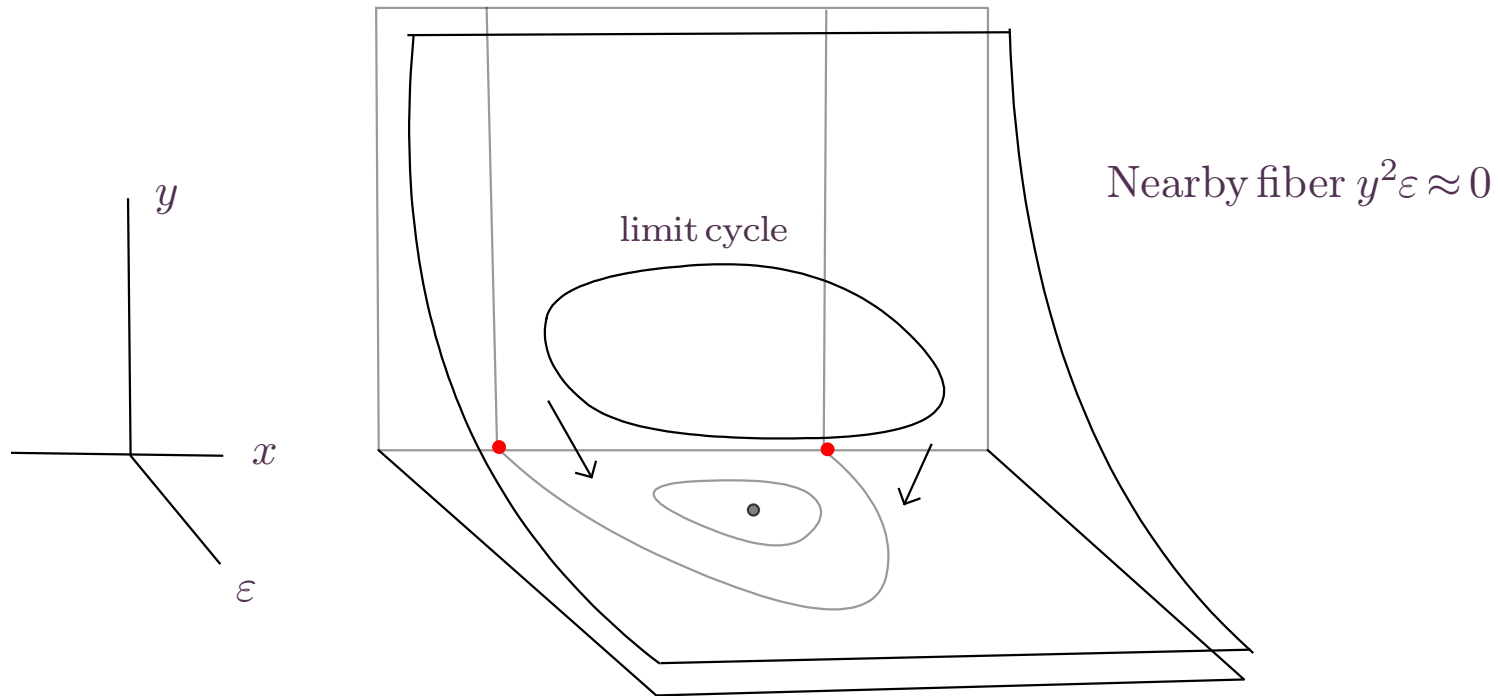
$$\text{wt}(x) = 1, \text{wt}(y) = 2, \text{wt}(\varepsilon) = 2$$

y - directional blowing up: $x \rightarrow yx$, $y \rightarrow y^2$, $\varepsilon \rightarrow y^2\varepsilon$

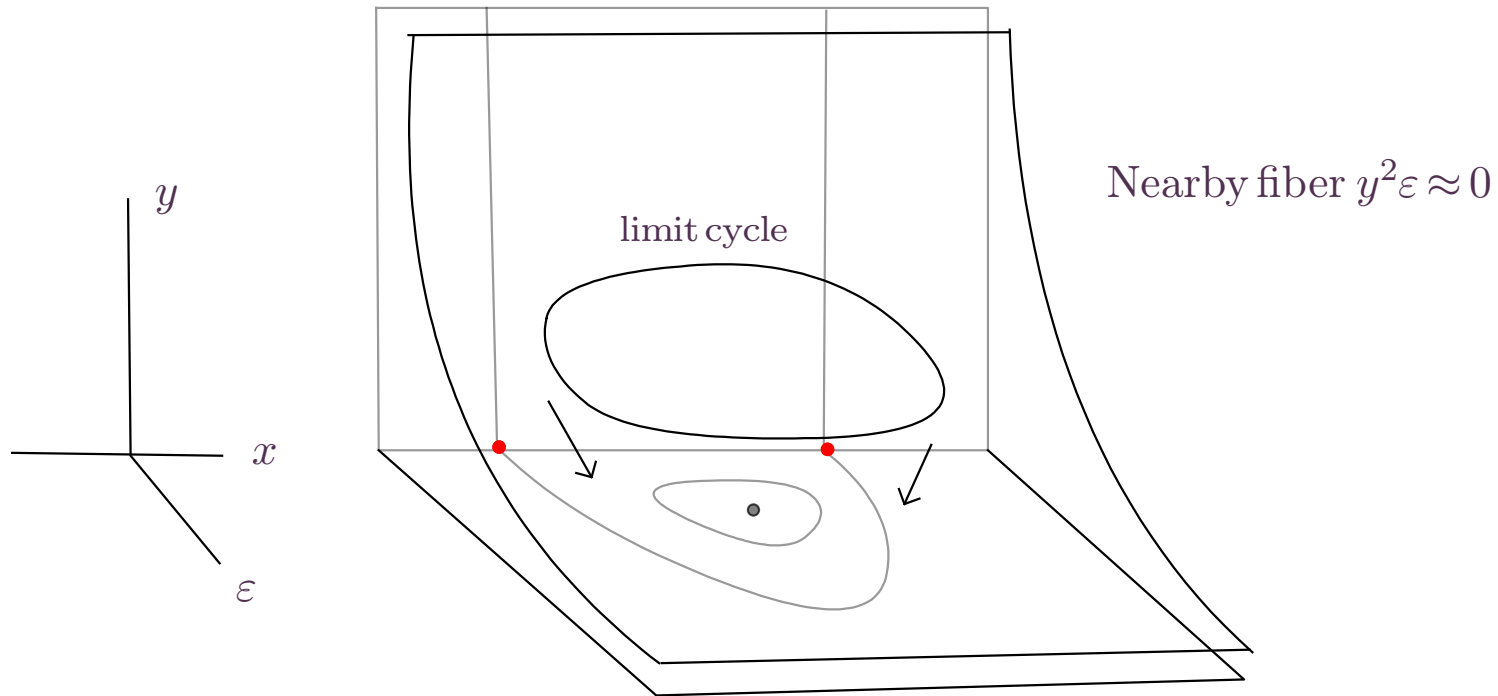
$$\left(1 - \frac{x^2}{2} - \frac{x^3}{3}\right) \frac{\partial}{\partial x} - \frac{\varepsilon x}{2} \left(y \frac{\partial}{\partial y} - x \frac{\partial}{\partial x} - 2\varepsilon \frac{\partial}{\partial \varepsilon}\right), \quad F = \{d(y^2\varepsilon) = 0\}$$







Globally, we obtain a foliation by curves on a three-dimensional manifold, now tangent to a dimension two **singular** fibration



Globally, we obtain a foliation by curves on a three-dimensional manifold, now tangent to a dimension two **singular** fibration

(c.f. a very nice recent book of Maeschaalk, Dumortier, Roussarie - *Canard cycles: from birth to transition*).

