

Homothetic packings of centrally symmetric convex bodies

Sean Dewar

Fields Institute/RICAM

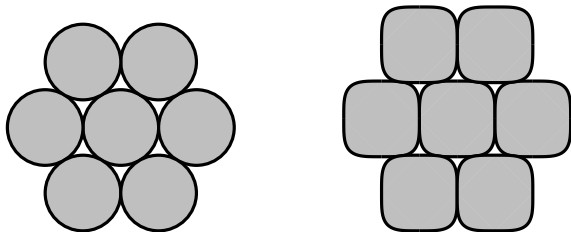
April 12th, 2021

Contact: sean.dewar@ricam.oeaw.ac.at

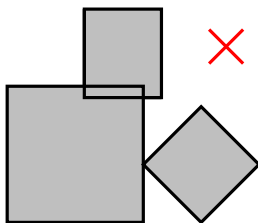
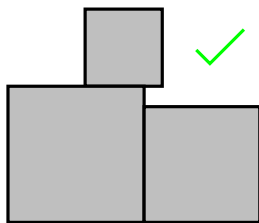
Acknowledgement: Supported by the Fields Institute for Research in Mathematical Sciences and the Austrian Science Fund (P31888).

Centrally symmetric convex body packings

- **Convex body** $C \subset \mathbb{R}^d$: a compact convex set with non-empty interior.
- **Centrally symmetric (c.s.) convex body** $C \subset \mathbb{R}^d$: a convex body where $x \in C \Leftrightarrow -x \in C$.
- **Homothetic packing of C** (or **C -packing for short**): a packing (i.e. no interior overlaps) of sets of the form $rC + x$ for some $r > 0$, $x \in \mathbb{R}^d$.



More examples



Contact graphs

Every C -packing $P = \{r_v C + p_v : v \in V\}$ is uniquely determined by the pair $p : V \rightarrow \mathbb{R}^d$ and $r : V \rightarrow \mathbb{R}_{>0}$.

Contact graphs

Every C -packing $P = \{r_v C + p_v : v \in V\}$ is uniquely determined by the pair $p : V \rightarrow \mathbb{R}^d$ and $r : V \rightarrow \mathbb{R}_{>0}$.

Contact graph of P : the graph $G = (V, E)$, where $vw \in E$ if and only if $v \neq w$ and $(r_v C + p_v) \cap (r_w C + p_w) \neq \emptyset$.

Contact graphs

Every C -packing $P = \{r_v C + p_v : v \in V\}$ is uniquely determined by the pair $p : V \rightarrow \mathbb{R}^d$ and $r : V \rightarrow \mathbb{R}_{>0}$.

Contact graph of P : the graph $G = (V, E)$, where $vw \in E$ if and only if $v \neq w$ and $(r_v C + p_v) \cap (r_w C + p_w) \neq \emptyset$.

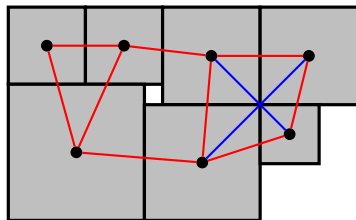
Any C -packing can be denoted by the triple $P = (G, p, r)$.

Contact graphs

Every C -packing $P = \{r_v C + p_v : v \in V\}$ is uniquely determined by the pair $p : V \rightarrow \mathbb{R}^d$ and $r : V \rightarrow \mathbb{R}_{>0}$.

Contact graph of P : the graph $G = (V, E)$, where $vw \in E$ if and only if $v \neq w$ and $(r_v C + p_v) \cap (r_w C + p_w) \neq \emptyset$.

Any C -packing can be denoted by the triple $P = (G, p, r)$.

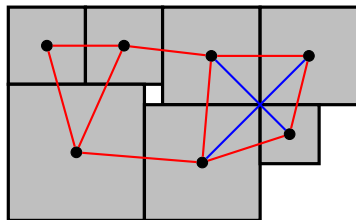


Contact graphs

Every C -packing $P = \{r_v C + p_v : v \in V\}$ is uniquely determined by the pair $p : V \rightarrow \mathbb{R}^d$ and $r : V \rightarrow \mathbb{R}_{>0}$.

Contact graph of P : the graph $G = (V, E)$, where $vw \in E$ if and only if $v \neq w$ and $(r_v C + p_v) \cap (r_w C + p_w) \neq \emptyset$.

Any C -packing can be denoted by the triple $P = (G, p, r)$.



For homothetic c.s. convex bodies, the induced embedding of the contact graph is always planar if C is not a parallelogram (Danzer-Grünbaum, 1962).

Known results

Strictly convex: The boundary does not contain any line intervals with positive length.

Smooth: Every point of the boundary has at most one tangent hyperplane.

Known results

Strictly convex: The boundary does not contain any line intervals with positive length.

Smooth: Every point of the boundary has at most one tangent hyperplane.

Theorem (Schramm, 1990)

Let C be a smooth convex body in the plane and G a planar graph. Then there exists a C -packing with contact graph G .

Known results

Strictly convex: The boundary does not contain any line intervals with positive length.

Smooth: Every point of the boundary has at most one tangent hyperplane.

Theorem (Schramm, 1990)

Let C be a smooth convex body in the plane and G a planar graph. Then there exists a C -packing with contact graph G .

It is worth noting that central symmetry is not required for Schramm's result.

Known results

Strictly convex: The boundary does not contain any line intervals with positive length.

Smooth: Every point of the boundary has at most one tangent hyperplane.

Theorem (Schramm, 1990)

Let C be a smooth convex body in the plane and G a planar graph. Then there exists a C -packing with contact graph G .

It is worth noting that central symmetry is not required for Schramm's result.

Result is not true if we drop smooth; for example, we cannot realise some planar graphs with separating triangles as square packings.

Known results

Strictly convex: The boundary does not contain any line intervals with positive length.

Smooth: Every point of the boundary has at most one tangent hyperplane.

Theorem (Schramm, 1990)

Let C be a smooth convex body in the plane and G a planar graph. Then there exists a C -packing with contact graph G .

It is worth noting that central symmetry is not required for Schramm's result.

Result is not true if we drop smooth; for example, we cannot realise some planar graphs with separating triangles as square packings.

If C is also strictly convex and G is a triangulation of a sphere, then this C -packing will be unique up to the choice of position for the bounding triangle (Schramm 1991).

Disc packings

Generic set: A finite set of real numbers that are algebraically independent over the rational numbers.

$(2, k)$ -sparse graph ($k \in \{2, 3\}$): A graph G where for each subgraph $G' = (V', E')$ with $|E'| \geq 1$ we have $|E'| \leq 2|V'| - k$.

Disc packings

Generic set: A finite set of real numbers that are algebraically independent over the rational numbers.

$(2, k)$ -sparse graph ($k \in \{2, 3\}$): A graph G where for each subgraph $G' = (V', E')$ with $|V'| \geq 1$ we have $|E'| \leq 2|V'| - k$.

Theorem (Connelly, Gortler, Theran 2019)

Let \mathbb{D} be the unit disc in the plane and $P = (G, p, r)$ be a \mathbb{D} -packing. If the set of radii $\{r_v : v \in V\}$ is generic, then the contact graph of P will be a $(2, 3)$ -sparse planar graph.

Disc packings

Generic set: A finite set of real numbers that are algebraically independent over the rational numbers.

$(2, k)$ -sparse graph ($k \in \{2, 3\}$): A graph G where for each subgraph $G' = (V', E')$ with $|E'| \geq 1$ we have $|E'| \leq 2|V'| - k$.

Theorem (Connelly, Gortler, Theran 2019)

Let \mathbb{D} be the unit disc in the plane and $P = (G, p, r)$ be a \mathbb{D} -packing. If the set of radii $\{r_v : v \in V\}$ is generic, then the contact graph of P will be a $(2, 3)$ -sparse planar graph.

In layman's terms:

- I give you n circular coins C_1, \dots, C_n where the radii are chosen **randomly**.

Disc packings

Generic set: A finite set of real numbers that are algebraically independent over the rational numbers.

$(2, k)$ -sparse graph ($k \in \{2, 3\}$): A graph G where for each subgraph $G' = (V', E')$ with $|E'| \geq 1$ we have $|E'| \leq 2|V'| - k$.

Theorem (Connelly, Gortler, Theran 2019)

Let \mathbb{D} be the unit disc in the plane and $P = (G, p, r)$ be a \mathbb{D} -packing. If the set of radii $\{r_v : v \in V\}$ is generic, then the contact graph of P will be a $(2, 3)$ -sparse planar graph.

In layman's terms:

- I give you n circular coins C_1, \dots, C_n where the radii are chosen **randomly**.
- You slide the coins around the table however you like.

Disc packings

Generic set: A finite set of real numbers that are algebraically independent over the rational numbers.

$(2, k)$ -sparse graph ($k \in \{2, 3\}$): A graph G where for each subgraph $G' = (V', E')$ with $|E'| \geq 1$ we have $|E'| \leq 2|V'| - k$.

Theorem (Connelly, Gortler, Theran 2019)

Let \mathbb{D} be the unit disc in the plane and $P = (G, p, r)$ be a \mathbb{D} -packing. If the set of radii $\{r_v : v \in V\}$ is generic, then the contact graph of P will be a $(2, 3)$ -sparse planar graph.

In layman's terms:

- I give you n circular coins C_1, \dots, C_n where the radii are chosen **randomly**.
- You slide the coins around the table however you like.

Outcome: The n coins will now have at most $2n - 3$ contacts between them.

Generalising the previous result

Theorem (D– 2020+)

Let $C \subset \mathbb{R}^2$ be a strictly convex and smooth c.s. convex body. Then for almost all $r \in \mathbb{R}_{>0}^{|V|}$, any C -packing with radii r will have a planar $(2, 2)$ -sparse contact graph.

Generalising the previous result

Theorem (D- 2020+)

Let $C \subset \mathbb{R}^2$ be a strictly convex and smooth c.s. convex body. Then for almost all $r \in \mathbb{R}_{>0}^{|V|}$, any C -packing with radii r will have a planar $(2, 2)$ -sparse contact graph.

In layman's terms:

- You describe **any** c.s. symmetric convex body $C \subset \mathbb{R}^2$ to me that has no corners and no flat edges.

Generalising the previous result

Theorem (D- 2020+)

Let $C \subset \mathbb{R}^2$ be a strictly convex and smooth c.s. convex body. Then for almost all $r \in \mathbb{R}_{>0}^{|V|}$, any C -packing with radii r will have a planar $(2, 2)$ -sparse contact graph.

In layman's terms:

- You describe **any** c.s. symmetric convex body $C \subset \mathbb{R}^2$ to me that has no corners and no flat edges.
- I **randomly** choose positive scalars r_1, \dots, r_n .

Generalising the previous result

Theorem (D– 2020+)

Let $C \subset \mathbb{R}^2$ be a strictly convex and smooth c.s. convex body. Then for almost all $r \in \mathbb{R}_{>0}^{|V|}$, any C -packing with radii r will have a planar $(2, 2)$ -sparse contact graph.

In layman's terms:

- You describe **any** c.s. symmetric convex body $C \subset \mathbb{R}^2$ to me that has no corners and no flat edges.
- I **randomly** choose positive scalars r_1, \dots, r_n .
- I now give you n coins C_1, \dots, C_n where each coin C_i is a scaling of C by r_i .

Generalising the previous result

Theorem (D– 2020+)

Let $C \subset \mathbb{R}^2$ be a strictly convex and smooth c.s. convex body. Then for almost all $r \in \mathbb{R}_{>0}^{|V|}$, any C -packing with radii r will have a planar $(2, 2)$ -sparse contact graph.

In layman's terms:

- You describe **any** c.s. symmetric convex body $C \subset \mathbb{R}^2$ to me that has no corners and no flat edges.
- I **randomly** choose positive scalars r_1, \dots, r_n .
- I now give you n coins C_1, \dots, C_n where each coin C_i is a scaling of C by r_i .
- With the restriction that the coins have the same orientation, you slide the coins around the table however you like.

Generalising the previous result

Theorem (D– 2020+)

Let $C \subset \mathbb{R}^2$ be a strictly convex and smooth c.s. convex body. Then for almost all $r \in \mathbb{R}_{>0}^{|V|}$, any C -packing with radii r will have a planar $(2, 2)$ -sparse contact graph.

In layman's terms:

- You describe **any** c.s. symmetric convex body $C \subset \mathbb{R}^2$ to me that has no corners and no flat edges.
- I **randomly** choose positive scalars r_1, \dots, r_n .
- I now give you n coins C_1, \dots, C_n where each coin C_i is a scaling of C by r_i .
- With the restriction that the coins have the same orientation, you slide the coins around the table however you like.

Outcome: The n coins will now have at most $2n - 2$ contacts between them.

What about the converse?

Conjecture

For every $(2, 3)$ -sparse planar graph $G = ([n], E)$, there exists a \mathbb{D} -packing of n discs with generic radii where the contact graph is G .

What about the converse?

Conjecture

For every $(2, 3)$ -sparse planar graph $G = ([n], E)$, there exists a \mathbb{D} -packing of n discs with generic radii where the contact graph is G .

Known to be true for all partial 2-trees (= 2-flattenable graphs).

What about the converse?

Conjecture

For every $(2, 3)$ -sparse planar graph $G = ([n], E)$, there exists a \mathbb{D} -packing of n discs with generic radii where the contact graph is G .

Known to be true for all partial 2-trees (= 2-flattenable graphs).

Theorem (D- 2020+)

There exists a comeagre subset \mathcal{G} of the c.s. convex bodies in the plane** where for each $C \in \mathcal{G}$ the following are equivalent:*

- (i) $G = (V, E)$ is a $(2, 2)$ -sparse planar graph.*
- (ii) There is a set $R \subset \mathbb{R}_{>0}^{|V|}$ with positive measure where for every $r \in R$ there exists $p \in \mathbb{R}^{2|V|}$ so that (G, p, r) is a C -packing.*

*A countable intersection of open dense sets. The ambient space is a Baire space if and only if every comeagre subset is also dense.

**The topology is generated by the Hausdorff distance. The set is locally compact, and hence is a Baire space by the Baire category theorem.

In layman's terms...

For any given $C \in \mathcal{G}$, we do the following:

In layman's terms...

For any given $C \in \mathcal{G}$, we do the following:

- You describe **any** $(2, 2)$ -sparse planar graph $G = ([n], E)$.

In layman's terms...

For any given $C \in \mathcal{G}$, we do the following:

- You describe **any** $(2, 2)$ -sparse planar graph $G = ([n], E)$.
- I **randomly** choose positive scalars r_1, \dots, r_n .

In layman's terms...

For any given $C \in \mathcal{G}$, we do the following:

- You describe **any** $(2, 2)$ -sparse planar graph $G = ([n], E)$.
- I **randomly** choose positive scalars r_1, \dots, r_n .
- I now give you n coins C_1, \dots, C_n where each coin C_i is a scaling of C by r_i .

In layman's terms...

For any given $C \in \mathcal{G}$, we do the following:

- You describe **any** $(2, 2)$ -sparse planar graph $G = ([n], E)$.
- I **randomly** choose positive scalars r_1, \dots, r_n .
- I now give you n coins C_1, \dots, C_n where each coin C_i is a scaling of C by r_i .

Outcome: With respect to our choice of radii, there is a positive probability that you can arrange the n coins (without altering their orientations) so that their contact graph is G .

Open questions

- When can we drop the strict convexity and smoothness requirements in the first result?

Open questions

- When can we drop the strict convexity and smoothness requirements in the first result?
- Can we drop the requirement of central symmetry and/or allow multiple convex bodies in any of the results?

Open questions

- When can we drop the strict convexity and smoothness requirements in the first result?
- Can we drop the requirement of central symmetry and/or allow multiple convex bodies in any of the results?
 - Preliminary results suggest that this is possible so long as the boundaries of the convex bodies have positive curvature.

Open questions

- When can we drop the strict convexity and smoothness requirements in the first result?
- Can we drop the requirement of central symmetry and/or allow multiple convex bodies in any of the results?
 - Preliminary results suggest that this is possible so long as the boundaries of the convex bodies have positive curvature.
- Can similar methods be applied to packings where homotheticity is not required? I.e., you can rotate the coins as you slide them around.

Open questions

- When can we drop the strict convexity and smoothness requirements in the first result?
- Can we drop the requirement of central symmetry and/or allow multiple convex bodies in any of the results?
 - Preliminary results suggest that this is possible so long as the boundaries of the convex bodies have positive curvature.
- Can similar methods be applied to packings where homotheticity is not required? I.e., you can rotate the coins as you slide them around.
- What can we say about packings in higher dimensions?

References

R. Connelly, S. Gortler, L. Theran, *Rigidity of sticky disks*, Proceedings of the Royal Society A, 475(2222) (2019).

L. Danzer, B. Grünbaum, *Über zwei Probleme bezüglich konvexer Körper von P. Erdős und von V. L. Klee*, Math. Z, 79 (1962), pp. 95–99.

O. Schramm, *Packing two-dimensional bodies with prescribed combinatorics and applications to the construction of conformal and quasiconformal mappings*, Ph.D. thesis, Princeton, (1990).

O. Schramm, *Existence and uniqueness of packings with specified combinatorics*, Israel J. Math., 73 (1991), pp. 321–341.