Enrico Valdinoci

University of Western Australia

2020 Fields Medal Symposium

The stickiness property of nonlocal minima surfaces

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Nonlocal minimal surfaces

Energy functional dealing with "pointwise interactions" between a given set and its complement

Main idea: the "surface tension" is the byproduct of long-range interactions

Implications: nonlocal phase transitions and nonlocal capillarity theories

New effects due to the long-range interactions

Contributions from "far-away" can have a significant influence on the local structures of these new objects

STEKINESS Differently from classical minimal surfaces, the nonlocal minimal surfaces have the strong tendency to "stick at the boundary"

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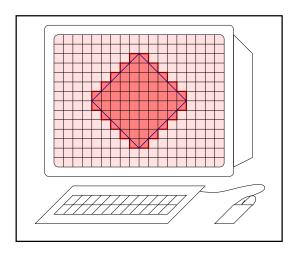
Given $s \in (0,1)$ and a bounded open set $\Omega \subset \mathbb{R}^n$ with $C^{1,\gamma}$ -boundary, the *s*-perimeter of a (measurable) set $E \subseteq \mathbb{R}^n$ in Ω is defined as

$$\begin{split} \operatorname{Per}_s(E;\Omega) &:= L(E \cap \Omega, (\mathcal{C}E) \cap \Omega) \\ &+ L(E \cap \Omega, (\mathcal{C}E) \cap (\mathcal{C}\Omega)) + L(E \cap (\mathcal{C}\Omega), (\mathcal{C}E) \cap \Omega), \end{split}$$

where $CE = \mathbb{R}^n \setminus E$ denotes the complement of E, and L(A, B) denotes the following nonlocal interaction term

$$L(A,B) := \int_A \int_B \frac{1}{|x-y|^{n+s}} dx dy \qquad \forall A,B \subseteq \mathbb{R}^n,$$

This notion of *s*-perimeter and the corresponding minimization problem were introduced in [Caffarelli-Roquejoffre-Savin, 2010].



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Boundary behavior of nonlocal minimal surfaces

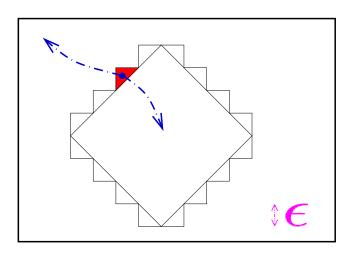
Side 1.

Perimeter 4.

Approximate Perimeter $4\sqrt{2}$.

Error $4(\sqrt{2}-1)$.





Error in each pixel $O(\epsilon^{2-s})$. Number of pixels $O(\epsilon^{-1})$ Error $O(\epsilon^{1-s})$. The stickiness property of nonlocal minima surfaces

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- 1) Existence theorem:
 - there exists E s-minimizer for Per_s in Ω with $E \setminus \Omega = E_0 \setminus \Omega$.
- 2) Maximum principle: E s-minimizer and $(\partial E) \setminus \Omega \subset \{|x_n| \le a\} \Rightarrow \partial E \subset \{|x_n| \le a\}.$
- 3) If ∂E is an hyperplane, then E is s-minimizer.
- 4) If *E* is *s*-minimizer in B_1 , then ∂E is $C^{1,\alpha}$ in $B_{1/2}$ except in a closed set Σ , with Hausdorff dimension less or equal than n-2.
- 5) If *E* is s-minimizer and $0 \in \partial E$, then

$$\int_{\mathbb{R}^n} \frac{\chi_E(y) - \chi_{E^c}(y)}{|y|^{n+s}} dy = 0.$$



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Regularity in dimension 2

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[Savin-Valdinoci, 2013]:

Regularity of cones in dimension 2.

If *E* is *s*-minimizer in B_1 , then ∂E is $C^{1,\alpha}$ in $B_{1/2}$ except in a closed set Σ , with Hausdorff dimension less or equal than n-3

Regularity in dimension 2

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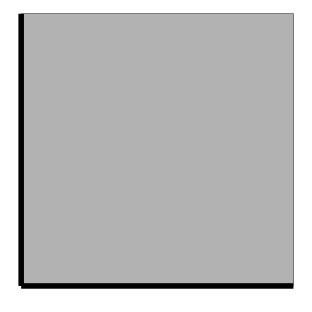
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Boundary behavior of nonlocal minimal surfaces

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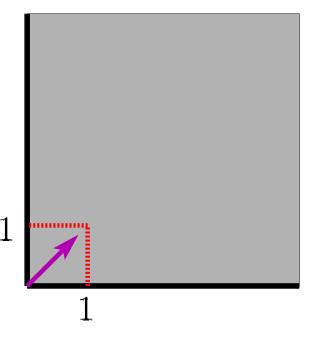
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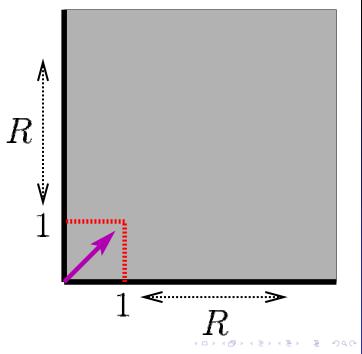


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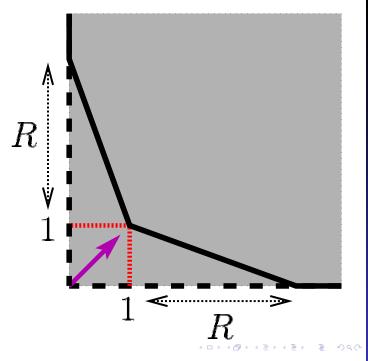
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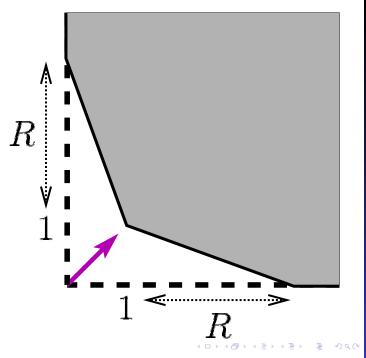
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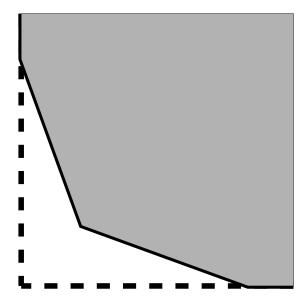
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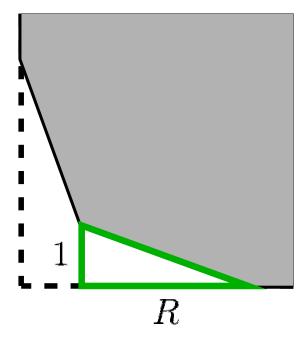
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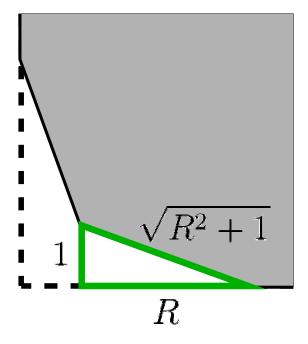
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Regularity for graphs in dimension 3

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Boundary behavior of nonlocal minimal surfaces

[Figalli-Valdinoci, 2013]:

Bernstein-type result:

- ▶ *E* is *s*-minimal in \mathbb{R}^{n+1} and ∂E is a global graph,
- \triangleright s-minimal surfaces are smooth in \mathbb{R}^n
- $\Rightarrow \partial E$ is hyperplane.

Regularity of minimal graph in dimension 3

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Regularity of minimal graph in dimension 3.

[Bourgain-Brezis-Mironescu, 2001], [Dávila, 2002], [Ponce, 2004], [Caffarelli-Valdinoci, 2011], [Ambrosio-De Philippis-Martinazzi, 2011], [Lombardini, 2018]:

$$(1-s)\operatorname{Per}_s \to \operatorname{Per}, \quad \text{as } s \nearrow 1$$

(up to normalizing multiplicative constants).

 $\downarrow \downarrow$

[Caffarelli-Valdinoci, 2013]: s close to 1: nonlocal minimal surfaces are as regular as classical minimal surfaces.

(If E is s-minimizer in B_1 , then ∂E is $C^{1,\alpha}$ in $B_{1/2}$ except in a closed set Σ , with Hausdorff dimension less or equal than (n-8).)

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[Maz'ya-Shaposhnikova, 2002] and

[Dipierro-Figalli-Palatucci-Valdinoci, 2013]:

If there exists the limit

$$\alpha(E) := \lim_{s \searrow 0} s \int_{E \cap (\mathcal{C}B_1)} \frac{1}{|y|^{n+s}} \, dy,$$

then

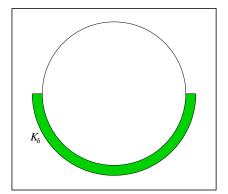
$$\lim_{s \searrow 0} s \operatorname{Per}_{s}(E, \Omega) = \left(\omega_{n-1} - \alpha(E)\right) \frac{|E \cap \Omega|}{\omega_{n-1}} + \alpha(E) \frac{|\Omega \setminus E|}{\omega_{n-1}}.$$

Stickiness to half-balls

For any $\delta > 0$,

$$K_{\delta}:=\left(B_{1+\delta}\setminus B_{1}\right)\cap\{x_{n}<0\}.$$

We define E_{δ} to be the set minimizing the *s*-perimeter among all the sets E such that $E \setminus B_1 = K_{\delta}$.



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Stickiness to half-balls

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Boundary behavior of nonlocal minimal surfaces

There exists $\delta_o > 0$ such that for any $\delta \in (0, \delta_o]$ we have that

$$E_{\delta}=K_{\delta}$$
.

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Boundary behavior of nonlocal minimal surfaces

Given a large M > 1 we consider the s-minimal set E_M in $(-1,1) \times \mathbb{R}$ with datum outside $(-1,1) \times \mathbb{R}$ given by the jump $J_M := J_M^- \cup J_M^+$, where

$$J_M^-:=(-\infty,-1]\times(-\infty,-M)$$
 and
$$J_M^+:=[1,+\infty)\times(-\infty,M).$$

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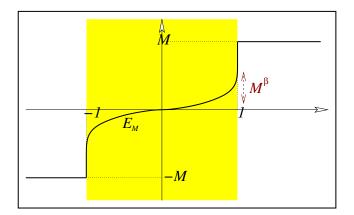
Boundary behavior of nonlocal minimal surfaces

There exist $M_o > 0$ and $C_o \ge C'_o > 0$, depending on s, such that if $M \ge M_o$ then

$$[-1,1) imes [C_o M^{rac{1+s}{2+s}}, M] \subseteq E_M^c$$
 and $(-1,1] imes [-M, -C_o M^{rac{1+s}{2+s}}] \subseteq E_M.$

Also, the exponent $\beta := \frac{1+s}{2+s}$ above is optimal.

Stickiness to the sides of a box



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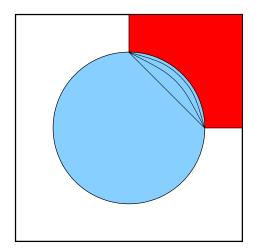
We consider a sector in \mathbb{R}^2 outside B_1 , i.e.

$$\Sigma := \{(x, y) \in \mathbb{R}^2 \setminus B_1 \text{ s.t. } x > 0 \text{ and } y > 0\}.$$

Let E_s be the *s*-minimizer of the *s*-perimeter among all the sets E such that $E \setminus B_1 = \Sigma$.

Then, there exists $s_o > 0$ such that for any $s \in (0, s_o]$ we have that $E_s = \Sigma$.

Stickiness as $s \to 0^+$



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Fix $\epsilon_0 > 0$ arbitrarily small. Then, there exists $\delta_0 > 0$, possibly depending on ϵ_0 , such that for any $\delta \in (0, \delta_0]$ the following statement holds true.

Assume that $F \supset H \cup F_- \cup F_+$, where

$$H := \mathbb{R} \times (-\infty, 0),$$

$$F_{-} := (-3, -2) \times [0, \delta)$$

and

$$F_+ := (2,3) \times [0,\delta).$$

Let *E* be the *s*-minimal set in $(-1,1) \times \mathbb{R}$ among all the sets that coincide with *F* outside $(-1,1) \times \mathbb{R}$.

Then

$$E \supseteq (-1,1) \times (-\infty, \delta^{\frac{2+\epsilon_0}{1-s}}].$$

Instability of the flat fractional minimal surfaces

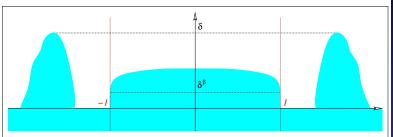
The stickiness property of nonlocal minima surfaces

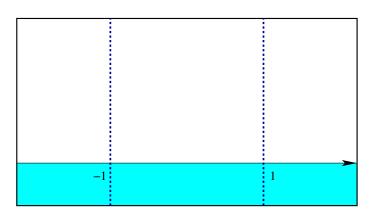
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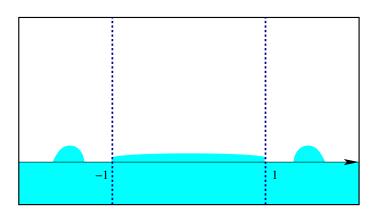




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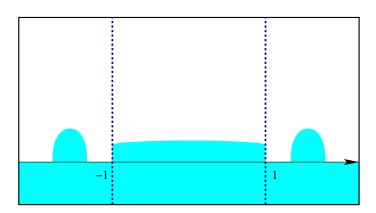
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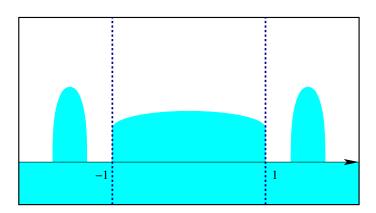


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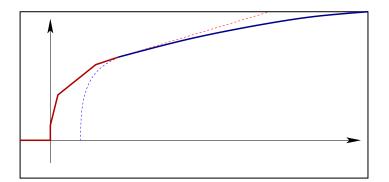
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A useful barrier



The stickiness property of nonlocal minima surfaces

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The usual suspects

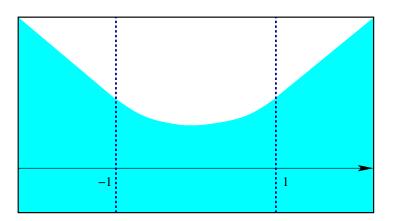


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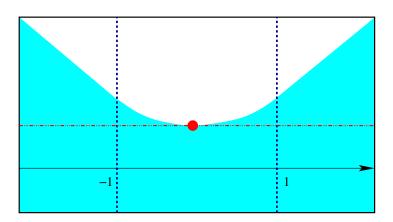
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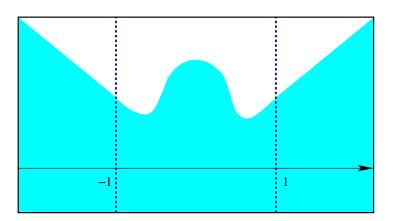
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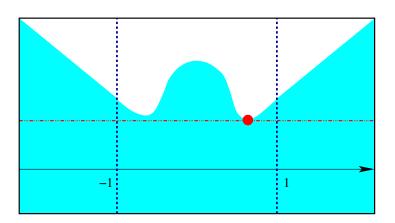
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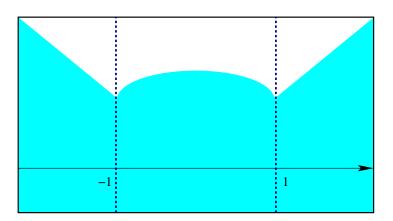
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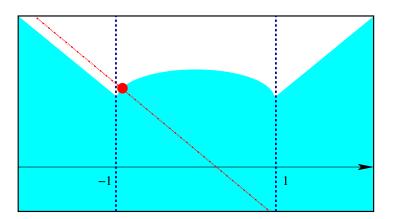
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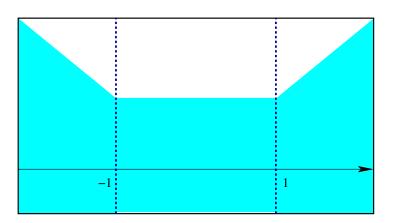
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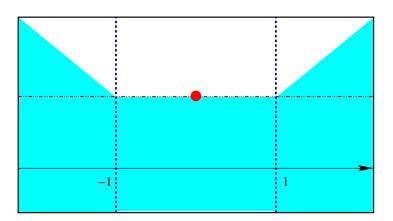
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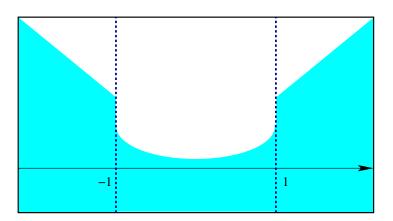
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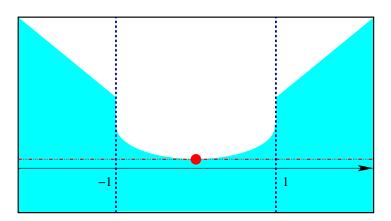
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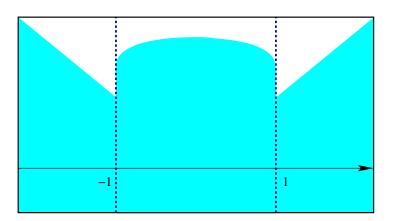
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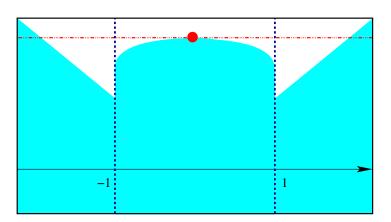
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The leading role of infinity [Bucur-Lombardini-Valdinoci, 2019]

The stickiness property of nonlocal minimal surfaces

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of nonlocal minimal surfaces

Let $\Omega \subset \mathbb{R}^n$ be bounded, connected and smooth. Let $E_0 \subset \mathbb{R}^n$ be such that

 $B_r(x_0)\setminus\Omega\subset E_0$

$$B_r(x_0) \setminus \Omega \subset E_0$$

for some $x_0 \in \partial \Omega$ and r > 0, and

$$\alpha(E_0) < \alpha(\text{halfplane}).$$

Then, there exists $s_0 \in (0, 1)$ such that if $s \in (0, s_0)$ and E is the nonlocal minimal set in Ω with external datum E_0 , we have

$$E \cap \Omega = \emptyset$$
.



Boundary behavior of nonlocal minimal surfaces

Let $\Omega \subset \mathbb{R}^n$ be bounded, connected and smooth.

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- 1. How regular are the nonlocal minimal surfaces *coming from inside the domain*?
- 2. Is the Euler-Lagrange equation satisfied up to the boundary?
- 3. How *typical* is the stickiness phenomenon?

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- 1. How regular are the nonlocal minimal surfaces *coming from inside the domain*?
- 2. Is the Euler-Lagrange equation satisfied up to the boundary?
- 3. How *typical* is the stickiness phenomenon?

Consider a nonlocal minimal graph in (0, 1), with a smooth external graph u_0 .

There is a dichotomy:

▶ either

$$\lim_{x \to 0} u_0(x) \neq \lim_{x \to 0} u(x)$$

and

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Consider a nonlocal minimal graph in (0, 1), with a smooth external graph u_0 .

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This dichotomy is a purely nonlinear effect, since the boundary behavior of linear equation is of Hölder type [Serra-Ros Oton].

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Stickiness + dichotomy = butterfly effect

An arbitrarily small perturbation of the flat data produce a boundary discontinuity, which entails an infinite derivative at the boundary.

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Boundary behavior of nonlocal minimal surfaces

As a curve, the nonlocal minimal graph turns out to be always $C^{1,\frac{1+s}{2}}$:

it is either the graph of a $C^{1,\frac{1+s}{2}}$ -function (when it is continuous at the boundary!), or it is discontinuous and sticks vertically detaching in a $C^{1,\frac{1+s}{2}}$ fashion [De Silva-Savin] (then the inverse function is a $C^{1,\frac{1+s}{2}}$ function).

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The nonlocal mean curvature can be written in the form

$$\int_{-\infty}^{+\infty} F\left(\frac{u(x+y)-u(x)}{|y|}\right) \frac{dy}{|y|^{1+s}}.$$

And this is a " $C^{1,s}$ operator".

But $\frac{1+s}{2} > s$, therefore we can "pass the equation to the limit"...

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If u is a nonlocal minimal graph in (0, 1) with smooth datum outside, then

$$\int_{-\infty}^{+\infty} F\left(\frac{u(x+y) - u(x)}{|y|}\right) \frac{dy}{|y|^{1+s}} = 0$$

for all $x \in [0, 1]$.

With this, we can take any configuration, add an arbitrarily small bump and use the unperturbed configuration as a barrier.

At touching points the additional bump produces an extra-mass violating the Euler-Lagrange equation.

Notice that now also touching at the boundary can be taken into account!

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Let $u^{(t)}$ be the nonlocal minimal graph in (0,1) with external datum

$$u_0^{(t)} := u_0 + t\varphi.$$

Suppose that

$$\lim_{x \nearrow 0} u_0(x) = \lim_{x \searrow 0} u(x).$$

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Boundary behavior of nonlocal minimal surfaces

Think about the usual suspects (discontinuous, Lispchitz, Hölder, smooth).

Blow-up

The "worst" cases to understand are the Hölder and the smooth (the Lispchitz produces non-minimal corners).

The smooth case produces flat objects: use a boundary improvement of flatness (combined with a boundary monotonicity formula) to deduce smoothness of the initial minimizer (for this, use new barrier to go beyond the linear theory!).



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Thank you very much for your attention!



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