

# Persistent homotopy theory

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# Basic setup

$X$  finite,  $X \subset Z$ ,  $Z$  a metric space.

- $P_s(X)$  = poset of subsets  $\sigma \subset X$  such that  $d(x, y) \leq s$  for all  $x, y \in \sigma$ .

$P_s(X)$  is the poset of non-degenerate simplices of the Vietoris-Rips complex  $V_s(X)$ .  $BP_s(X)$  is **barycentric subdivision** of  $V_s(X)$ .

We have poset inclusions

$$\sigma : P_s(X) \subset P_t(X), \quad s \leq t,$$

$P_0(X) = X$ , and  $P_t(X) = \mathcal{P}(X)$  (all subsets of  $X$ ) for  $t$  suff large.

- $k \geq 0$ :  $P_{s,k}(X) \subset P_s(X)$  subposet of simplices  $\sigma$  such that each element  $x \in \sigma$  has at least  $k$  neighbours  $y$  such that  $d(x, y) \leq s$ .

$P_{s,k}(X)$  is the poset of non-degenerate simplices of the degree Rips complex  $L_{s,k}(X)$ , again the **barycentric subdivision**.

## Theorem 1 (Rips stability).

Suppose  $X \subset Y$  in  $D(Z)$  such that  $d_H(X, Y) < r$ . There is a homotopy commutative diagram (homotopy interleaving)

$$\begin{array}{ccc} P_s(X) & \xrightarrow{\sigma} & P_{s+2r}(X) \\ i \downarrow & \nearrow \theta & \downarrow i \\ P_s(Y) & \xrightarrow{\sigma} & P_{s+2r}(Y) \end{array}$$

## Theorem 2.

Suppose  $X \subset Y$  in  $D(Z)$  such that  $d_H(X_{dis}^{k+1}, Y_{dis}^{k+1}) < r$ . There is a homotopy commutative diagram

$$\begin{array}{ccc} P_{s,k}(X) & \xrightarrow{\sigma} & P_{s+2r,k}(X) \\ i \downarrow & \nearrow \theta & \downarrow i \\ P_{s,k}(Y) & \xrightarrow{\sigma} & P_{s+2r,k}(Y) \end{array}$$

# Controlled equivalences

**NB:**  $V_*(X) := BP_*(X)$  henceforth.

Suppose that  $X \subset Y$  in  $D(Z)$  and we have a homotopy interleaving

$$\begin{array}{ccc} V_s(X) & \xrightarrow{\sigma} & V_{s+2r}(X) \\ i \downarrow & \nearrow \theta & \downarrow i \\ V_s(Y) & \xrightarrow{\sigma} & V_{s+2r}(Y) \end{array}$$

- 1)  $i : \pi_0 V_*(X) \rightarrow \pi_0 V_*(Y)$  is a  **$2r$ -monomorphism**: if  $i([x]) = i([y])$  in  $\pi_0 V_s(Y)$  then  $\sigma[x] = \sigma[y]$  in  $\pi_0 V_{s+2r}(X)$
- 2)  $i : \pi_0 V_*(X) \rightarrow \pi_0 V_*(Y)$  is a  **$2r$ -epimorphism**: given  $[y] \in \pi_0 V_s(Y)$ ,  $\sigma[y] = i[x]$  for some  $[x] \in \pi_0 V_{s+2r}(X)$ .
- 3) All  $i : \pi_n(V_*(X), x) \rightarrow \pi_n(V_*(Y), i(x))$  are  **$2r$ -isomorphisms**.

The map  $i : V_*(X) \rightarrow V_*(Y)$  is a  **$2r$ -equivalence** of systems.

A system of spaces is a functor  $X : [0, \infty) \rightarrow \mathbf{sSet}$ , aka. a diagram of simplicial sets with index category  $[0, \infty)$ .

A map of systems  $X \rightarrow Y$  is a natural transformation of functors defined on  $[0, \infty)$ .

## Examples

1) The functor  $V_*(X)$ ,  $s \mapsto V_s(X) = BP_s(X)$  is a system of spaces, for a data set  $X \subset Z$ .

2) If  $X \subset Y \subset Z$  are data sets, the induced maps  $P_s(X) \rightarrow P_s(Y)$ ,  $V_s(X) \rightarrow V_s(Y)$  define maps of systems  $P_*(X) \rightarrow P_*(Y)$  (posets) and  $V_*(X) \rightarrow V_*(Y)$  (spaces).

# Homotopy types

There are many ways to discuss homotopy types of systems. The oldest is the **projective structure** (Bousfield-Kan, 1972):

A map  $f : X \rightarrow Y$  is a **weak equivalence** (resp. **fibration**) if each map  $X_s \rightarrow Y_s$  is a weak equiv. (resp. fibration) of simplicial sets.

A map  $A \rightarrow B$  is a **projective cofibration** if it has the left lifting property with respect all maps which are trivial fibrations.

## Lemma 3.

*Suppose that  $X \subset Y \subset Z$  are data sets. Then  $V_*(X) \rightarrow V_*(Y)$  is a projective cofibration.*

The map  $V_*(X) \rightarrow V_*(Y)$  is also a sectionwise cofibration, i.e. all maps  $V_s(X) \rightarrow V_s(Y)$  are monomorphisms.

Suppose that  $f : X \rightarrow Y$  is a map of systems. Say that  $f$  is an  **$r$ -equivalence** if

- 1) the map  $f : \pi_0(X) \rightarrow \pi_0(Y)$  is an  $r$ -isomorphism of systems of sets
- 2) the maps  $f : \pi_k(X_s, x) \rightarrow \pi_k(Y_s, f(x))$  are  $r$ -isomorphisms of systems of groups, for all  $s \geq 0$ ,  $x \in X_s$ ,  $k \geq 1$ .

**Observation:** Suppose given a diagram of systems

$$\begin{array}{ccc} X_1 & \xrightarrow{f_1} & Y_1 \\ \text{sect} \simeq \downarrow & & \downarrow \simeq \text{sect} \\ X_2 & \xrightarrow{f_2} & Y_2 \end{array}$$

Then  $f_1$  is an  $r$ -equivalence iff  $f_2$  is an  $r$ -equivalence.

**Examples:** Stability results. A sectionwise equivalence is a 0-equivalence.

A **controlled equivalence** is a map which is an  $r$ -equivalence for some  $r \geq 0$ .

## Lemma 4.

*Suppose given a commutative triangle*

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ & \searrow h & \downarrow g \\ & & Z \end{array}$$

*If one of the maps is an  $r$ -equivalence, a second is an  $s$ -equivalence, then the third map is a  $(r + s)$ -equivalence.*

## Proof.

Set theory. □



## Lemma 5.

Suppose that  $p : X \rightarrow Y$  is a sectionwise fibration of systems of Kan complexes and that  $p$  is an  $r$ -equivalence. Then each lifting problem

$$\begin{array}{ccccc}
 \partial\Delta^n & \xrightarrow{\alpha} & X_s & \xrightarrow{\sigma} & X_{s+2r} \\
 \downarrow & & \downarrow & \nearrow \theta & \downarrow p \\
 \Delta^n & \xrightarrow{\beta} & Y_s & \xrightarrow{\sigma} & Y_{s+2r}
 \end{array}$$

can be solved **up to shift**  $2r$ .

## Lemma 6.

Suppose that  $p : X \rightarrow Y$  is a sectionwise fibration of systems of Kan complexes, and that all lifting problems

$$\begin{array}{ccccc}
 \partial\Delta^n & \longrightarrow & X_s & \xrightarrow{\sigma} & X_{s+r} \\
 \downarrow & & \theta \downarrow & \nearrow & \downarrow p \\
 \Delta^n & \longrightarrow & Y_s & \xrightarrow{\sigma} & Y_{s+r}
 \end{array}$$

have solutions up to shift  $r$ . Then  $p : X \rightarrow Y$  is an  $r$ -equivalence.

## Proof.

If  $p_*([\alpha]) = 0$  for  $[\alpha] \in \pi_{n-1}(X_s, *)$ , then there is a diagram on the left above. The existence of  $\theta$  gives  $\sigma_*([\alpha]) = 0$  in  $\pi_{n-1}(X_{s+r}, *)$ .



## Corollary 7.

Suppose given a pullback diagram

$$\begin{array}{ccc} X' & \longrightarrow & X \\ p' \downarrow & & \downarrow p \\ Y' & \longrightarrow & Y \end{array}$$

where  $p$  is a sectionwise fibration and an  $r$ -equivalence.

Then the map  $p'$  is a sectionwise fibration and a  $2r$ -equivalence.

## Theorem 8.

Suppose that  $i : A \rightarrow B$  is a sectionwise cofibration and an  $r$ -equivalence, and suppose given a pushout

$$\begin{array}{ccc} A & \rightarrow & C \\ i \downarrow & & \downarrow i_* \\ B & \rightarrow & D \end{array}$$

Then  $i_*$  is a sectionwise cofibration and a  $2r$ -equivalence.

**Sketch (Whitehead theorem):** There is a  $2r$ -interleaving

$$\begin{array}{ccc} A_s & \xrightarrow{\simeq} & FA_{s+2r} \\ \downarrow & \nearrow & \downarrow \\ B_s & \xrightarrow{\simeq} & FB_{s+2r} \end{array}$$

for a sectionwise fibrant model of  $i$ . The class of cofibrations admitting  $2r$ -interleavings is closed under pushout.

# Category of cofibrations I

**(A')**: Suppose given a commutative diagram

$$\begin{array}{ccc} A & \longrightarrow & C \\ & \searrow & \nearrow \\ & B & \end{array}$$

If one of the maps is an  $r$ -equivalence, another is an  $s$ -equivalence, then the third is an  $(r + s)$ -equivalence.

**(B)**: The composite of two cofibrations is a cofibration. Any isomorphism is a cofibration.

**(C')**: Cofibrations are closed under pushout. Given a pushout

$$\begin{array}{ccc} A & \longrightarrow & C \\ i \downarrow & & \downarrow i_* \\ B & \longrightarrow & D \end{array}$$

with  $i$  a cofibration and  $r$ -equivalence, then  $i_*$  is a cofibration and a  $2r$ -equivalence.

# Category of cofibrations II

(D): For any object  $A$  there is at least one cylinder object  $A \otimes \Delta^1$ .

(E): All objects are cofibrant.

This is an adjusted list of axioms for a category of cofibrations structure — works for projective or sectionwise cofibrations.

There are standard formal (adjusted) outcomes:

## Lemma 9 (left properness).

*Suppose given a pushout*

$$\begin{array}{ccc} A & \xrightarrow{u} & C \\ i \downarrow & & \downarrow \\ B & \xrightarrow{u_*} & D \end{array}$$

*where  $i$  is a cofibration and  $u$  is an  $r$ -equivalence. Then  $u_*$  is a  $2r$ -equivalence.*

There is also a **patching lemma**.

## Example

Suppose given data sets  $X \subset Y$ ,  $X \subset W$  in a metric space  $Z$  such that  $d_H(X, Y) < r$ . Then  $d_H(W, W \cup Y) < r$ .




Here's a picture:

$$\begin{array}{ccc} V_*(X) & \xrightarrow{2r} & V_*(Y) \\ \downarrow & & \downarrow \\ V_*(W) & \xrightarrow{2r} & V_*(W \cup Y) \end{array}$$

$V_*(W) \rightarrow V_*(W) \cup V_*(Y)$  is a  $4r$ -equivalence.

The map  $V_*(W) \cup V_*(Y) \rightarrow V_*(W \cup Y)$  (“mapper”  $\rightarrow$  “reality”) is not an isomorphism, but it is a  $6r$ -equivalence.

- This is an excision statement for the Vietoris-Rips functor.
- The  $6r$  bound is probably too coarse.

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