

Recursive Moving Frames

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Ongoing work with Peter J. Olver

Fields Institute

December 12, 2013

Lie pseudo-groups

Lie pseudo-groups \longleftrightarrow infinite-dimensional generalization
of local Lie group actions

Given \mathcal{G} acting on M , I'm interested in the induced action on $S \subset M$

Example:

$$X = f(x)$$

$$Y = e(x, y) = f_x(x) y + g(x)$$

$$U = u + \frac{e_x}{f_x}$$

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Lie pseudo-groups in action

- symmetry of differential equations
 - Navier–Stokes, Euler, K–P, Davey–Stewartson
- equivalence transformations
 - fiber, point, contact equivalence of differential equations
- gauge transformations
 - Maxwell, Yang–Mills, conformal, string, ...
- invariant variational calculus – Noether’s second theorem (Stay tuned: Irina, Juha)
- ...

Main theme & tools

Compute

- differential invariants
- invariant differential forms
- invariant differential operators

Tools available:

- Lie's infinitesimal method
- Cartan's method (EDS)
- Equivariant moving frames
- Lie algebroids

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Why use equivariant moving frames?

- Decouples the moving frame theory from reliance on any form of frame bundle or connection
 - basic calculus
 - even an undergraduate student can do this!

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Growing number of applications

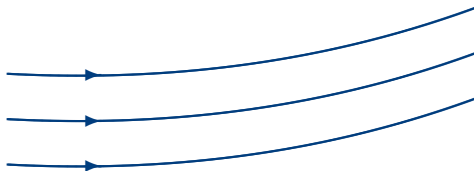
- computer vision
- group foliation
- invariant calculus of variation
- invariant geometric flows
- invariant numerical schemes
- computation of
 - Laplace invariants of differential operators
 - invariants and covariants of Killing tensors
 - invariants of Lie algebras

Moving frame algorithm

- 1 Lie (pseudo-)group action
- 2 prolonged action (freeness)
- 3 cross-section
- 4 normalization
- 5 invariantization

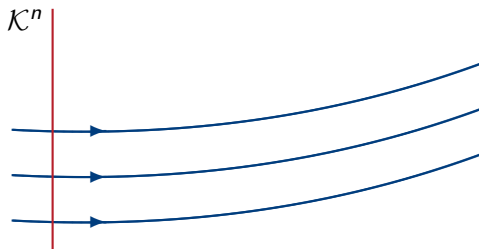
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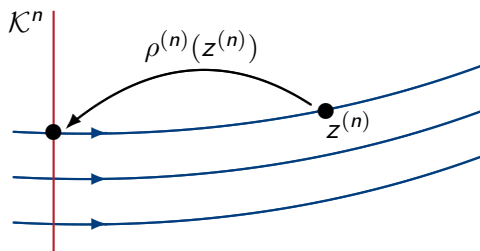
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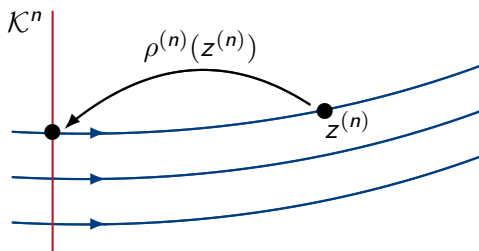
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Prolonged action: (Lifted invariants)

$$U_X = \frac{u_x}{f_x} + \frac{e_{xx} - e_x u_y}{f_x^2} - 2 \frac{f_{xx} e_x}{f_x^3}$$

$$U_Y = \frac{u_y}{f_x} + \frac{f_{xx}}{f_x^2}$$

$$U_{XY} = \frac{u_{xy}}{f_x^2} + \frac{f_{xxx} - f_{xx} u_y - e_x u_{yy}}{f_x^3} - 2 \frac{f_{xx}^2}{f_x^4}$$

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Cross-section:

$$\mathcal{K}^\infty = \{x = y = u_{x^k} = u_{y x^k} = 0, u_{yy} = 1, \quad k \geq 0\}.$$

Normalization equations:

$$X = Y = U_{X^k} = U_{Y X^k} = 0 \quad U_{YY} = 1$$

Definition: The constant lifted invariants are called **phantom invariants**

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Solving ... $0 = X = f$

$$0 = Y = e$$

$$0 = U = u + \frac{e_x}{f_x}$$

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 $\hat{\rho}:$

$$f = 0$$

$$e = 0$$

$$e_x = -u \sqrt{u_{yy}}$$

$$e_{xx} = (u u_y - u_x) \sqrt{u_{yy}}$$

$$e_{xxx} = (u u_{xy} + 2u^2 u_{yy} + 2u_x u_y - u_{xx} - 2u_y^2) \sqrt{u_{yy}}$$

$$f_{xx} = -u_y \sqrt{u_{yy}}$$

$$f_{xxx} = (u_y^2 - u_{xy} - u u_{yy}) \sqrt{u_{yy}}$$

$$f_x = \sqrt{u_{yy}}$$

Invariantization:

$$U_{XY\Upsilon} = \frac{f_x u_{xyy} - e_x u_{yyy} - 2f_{xx} u_{yy}}{f_x^4}$$

$$U_{Y\Upsilon\Upsilon} = \frac{u_{yyy}}{f_x^3}$$



$$f_x = \sqrt{u_{yy}}$$

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$$\hat{U}_{XY\Upsilon} = \frac{u_{xyy} + u u_{yyy} + 2u_y u_{yy}}{u_{yy}^{3/2}}$$

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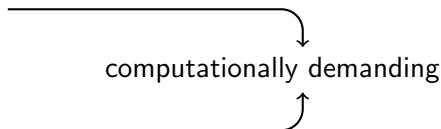
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How can steps 2 and 4 be made more effective?

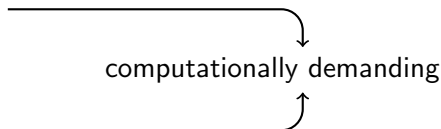
Avoid computing the prolonged action (Like Cartan!)

Recursively construct partial moving frames

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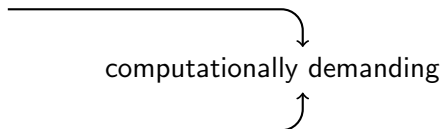
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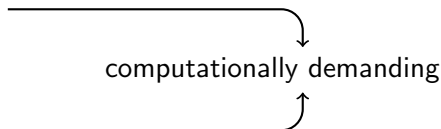
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Bundles

$z = (x, u)$ coordinates on M

J^k – submanifold jet bundle:

$$z^{(k)} : \quad \begin{array}{lll} x^1, \dots, x^p & u^1, \dots, u^q & \dots u_K^\alpha \dots \\ \text{independent} & \text{dependent} & \text{jet} \end{array}$$

\mathcal{G} – Lie pseudo-group:

$$g : \quad Z^a = \phi^a(z^b) \quad a, b = 1, \dots, m = p + q$$

$\mathcal{G}^{(k)}$ – pseudo-group jet bundle:

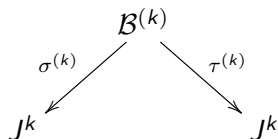
$$g^{(k)} : \quad \begin{array}{lll} z^1, \dots, z^m & Z^1, \dots, Z^m & \dots Z_B^a \dots \\ \text{source} & \text{target} & \text{jet} \end{array}$$

Lifted bundle

$\mathcal{B}^{(k)}$ – Lifted bundle:

$$z^{(k)} = (x^i \dots u_K^\alpha \dots) \quad g^{(k)} = (X_B^i \dots U_B^\alpha)$$

Groupoid structure:



$$\sigma^{(k)}(z^{(k)}, g^{(k)}) = z^{(k)}$$

$$\tau^{(k)}(z^{(k)}, g^{(k)}) = g^{(k)} \cdot z^{(k)}$$

Right multiplication:

$$R_h(z^{(k)}, g^{(k)}) = (h^{(k)} \cdot z^{(k)}, g^{(k)} \cdot (h^{(k)})^{-1})$$

Lift

Coframe on $\mathcal{B}^{(\infty)}$:

- Jet forms: $dx^i \quad du_K^\alpha \quad \left(\text{or } \theta_K^\alpha = du_K^\alpha - \sum_{k=1}^p u_{K,k}^\alpha dx^k \right)$

- Group forms: $\Upsilon_B^a = dZ_B^a - \sum_{b=1}^m Z_{B,b}^a dz^b$

Jet projection:

$$\pi_J: \Omega^*(\mathcal{B}^{(\infty)}) \rightarrow \Omega^*(\mathcal{B}^{(\infty)}) = \langle \dots dx^i \dots du_K^\alpha \dots \rangle$$

Definition: The lift of $\omega \in \Omega^*(J^\infty)$ is

$$\lambda(\omega) = \pi_J[(\tau^{(\infty)})^* \omega]$$

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Invariant coframe

Lifted jet coframe:

$$\sigma^i = \lambda(dx^i) \quad \sigma_K^\alpha = \lambda(du_K^\alpha) \quad \left(\text{or } \vartheta_K^\alpha = \lambda(\theta_K^\alpha) \right)$$

Relation:

$$\sigma_K^\alpha = \sum_{i=1}^p U_{K,i}^\alpha \sigma^i + \vartheta_K^\alpha \equiv \sum_{i=1}^p U_{K,i}^\alpha \sigma^i$$

Lifted jet frame:

$$\mathbb{D}_i = \lambda\left(\frac{\partial}{\partial x^i}\right) \quad \mathbb{D}_\alpha^K = \lambda\left(\frac{\partial}{\partial u_K^\alpha}\right)$$

defined by
$$d_J F(x, u^{(n)}, g^{(n)}) = \sum_{i=1}^p \mathbb{D}_i(F) \sigma^i + \sum_{\alpha, K} \mathbb{D}_\alpha^K(F) \sigma_K^\alpha$$

Maurer–Cartan forms:

$$\mu_B^a = \mathbb{D}_{b^1} \cdots \mathbb{D}_{b^k}(\Upsilon^a) \quad B = (b^1, \dots, b^k) \quad 1 \leq b^i \leq m$$

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Partial moving frame

Definition: A **partial moving frame** of order k is a right-invariant (local) subbundle $\hat{\mathcal{B}}^{(k)} \subset \mathcal{B}^{(k)}$. **Right-invariance**

$$R_h(\hat{\mathcal{B}}^{(k)}) \subset \hat{\mathcal{B}}^{(k)}$$

Proposition: If

$$T\mathcal{K}^k|_{z^{(k)}} \oplus \mathfrak{g}^{(k)}|_{z^{(k)}} = TJ^k|_{z^{(k)}}$$

for all $z^{(k)} \in \mathcal{K}^k$, then $\hat{\mathcal{B}}^{(k)} = (\tau^{(k)})^{-1}\mathcal{K}^k$ defines a partial moving frame of order k .

Moving frame: $\hat{\rho}^{(k)}(z^{(k)}) \in \hat{\mathcal{B}}^{(k)}$

Partial moving frame: $\hat{\rho}^{(k)}(z^{(k)}, h^{(k)}) \in \hat{\mathcal{B}}^{(k)}$

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Moving frame: $\hat{\rho}^{(k)}(z^{(k)}) \in \hat{\mathcal{B}}^{(k)}$

Partial moving frame: $\hat{\rho}^{(k)}(z^{(k)}, h^{(k)}) \in \hat{\mathcal{B}}^{(k)}$

Invariantization

Definition: Let $\hat{\rho}$ be a (partial) moving frame. The **invariantization** of $\omega \in \Omega^*(J^\infty)$ is

$$\hat{\omega} = \iota(\omega) = \hat{\rho}^*[\lambda(\omega)]$$

Notation:

$$\hat{\sigma}^i = \iota(dx^i) \quad \hat{\sigma}_K^\alpha = \iota(du_K^\alpha) \quad \hat{\mathbb{D}}_i = \iota\left(\frac{\partial}{\partial x^i}\right) \quad \hat{\mathbb{D}}_\alpha^K = \iota\left(\frac{\partial}{\partial u_K^\alpha}\right)$$

and

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Recurrence relations

$$\iota \circ d \neq d \circ \iota$$

$$\iota = \hat{\rho}^* \circ \pi_J \circ (\tau^{(\infty)})^*$$

$\mathfrak{g} = \{ \text{local vector fields tangent to pseudo-group orbits in } M \}$

$\mathfrak{g}^{(k)} = \{ \text{local vector fields tangent to pseudo-group orbits in } J^k \}$

The prolongation of

$$\mathbf{v} = \sum_{a=1}^m \zeta^a(z) \frac{\partial}{\partial z^a} = \sum_{i=1}^p \xi^i(x, u) \frac{\partial}{\partial x^i} + \sum_{\alpha=1}^q \varphi_\alpha(x, u) \frac{\partial}{\partial u^\alpha} \in \mathfrak{g}$$

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Lift of vector field jets:

$$\lambda(\zeta_B^a) = \mu_B^a$$

Also

$$X^i = \lambda(x^i) \quad U_K^\alpha = \lambda(u_K^\alpha)$$

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$$\begin{aligned} dX^i &= \sigma^i + \mu^i & dU_K^\alpha &= \sigma_K^\alpha + \psi_K^\alpha \\ & & &= \sum_{i=1}^p U_{K,i}^\alpha \sigma^i + \vartheta_K^\alpha + \psi_K^\alpha \end{aligned}$$

where $\psi_K^\alpha = \lambda(\varphi_\alpha^K)$

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Normalized recurrence relations:

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where $\hat{\psi}_K^\alpha = \hat{\rho}^*[\lambda(\varphi_\alpha^K)]$

Recursive moving frame goal

Find

$$\hat{\rho} \quad \hat{\sigma}^i \quad \hat{\sigma}_K^\alpha \quad \hat{\mathbb{D}}_i \quad \hat{\mathbb{D}}_\alpha^K \quad \hat{\mu}_B^a$$

recursively without computing

$$\sigma^i \quad \sigma_K^\alpha \quad \mathbb{D}_i \quad \mathbb{D}_\alpha^K \quad \mu_B^a$$

Rough idea:

normalize, prolong, normalize, prolong, ...

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Key:

- recurrence relations
- vanishing of (most) group forms along pseudo-group orbits
- $\hat{\mu}_B^a = \hat{\mathbb{D}}_{b^1} \cdots \hat{\mathbb{D}}_{b^k}(\hat{\mu}^a) \leftrightarrow$ Lie pseudo-group structure equations

By the way (Olver, Pohjanpelto – 2005)

Let \mathcal{G} with determining system

$$F^{(k)}(z, Z^{(k)}) = 0$$

Let

$$L^{(k)}(z, \zeta^{(k)}) = 0$$

be the infinitesimal determining system of \mathfrak{g} . Then

$$\lambda[L^{(k)}(z, \zeta^{(k)})] = L^{(k)}(Z, \mu^{(k)}) = 0$$

and the structure equations of \mathcal{G} are

$$d\sigma^a = \sum_{b=1}^a \mu_b^a \wedge \sigma^b, \quad d\mu_C^a = \sum_{b=1}^m \left[\sigma^b \wedge \mu_{C,b}^a + \sum_{\substack{C=(A,B) \\ \#B \geq 1}} \binom{C}{A} \mu_{A,b}^a \wedge \mu_B^b \right]$$

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The Maurer–Cartan structure equations

The **Maurer–Cartan structure equations** of \mathcal{G} are obtained by restricting the structure equations of \mathcal{G} to a target fiber.

Example 1: The Maurer–Cartan structure equations of

$$X = x + ay + b \quad Y = y$$

are

$$d\mu = 0 \quad d\mu_Y = 0$$

Example 2: The Maurer–Cartan structure equations of

$$X = f(x) \quad \text{or} \quad X = f(x), \quad U = \frac{u}{f'(x)}$$

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$$d\mu_n = \sum_{i=0}^n \binom{n}{i} \mu_{i+1} \wedge \mu_{n-i} \quad n \geq 0$$

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Example

Pseudo-group

$$X = f(x) \quad Y = e(x, y) = f'(x)y + g(x) \quad U = u + \frac{e_x}{f'(x)}$$

Step 1: Order 0 jet forms

$$\sigma^x = f_x dx \quad \sigma^y = e_x dx + f_x dy \quad \sigma^u = du + \left(\frac{e_{xx}}{f_x} - \frac{e_x f_{xx}}{f_x^2} \right) dx + \frac{f_{xx}}{f_x} dy$$

Order 0 normalizations

$$\mathcal{K}^0 = \{x = y = u = 0\} \quad \rightsquigarrow \quad X = Y = U = 0$$

Pseudo-group normalizations

$$f = 0 \quad e = 0 \quad e_x = -u f_x$$

Group forms

$$\Upsilon_k = df_k - f_{k+1} dx \quad \Psi_k = de_{k,0} - e_{k+1,0} dx - f_{k+1} dy$$

Normalization

$$\hat{\Upsilon} = -f_x dx \quad \hat{\Psi} = f_x(u dx - dy) \quad \hat{\Psi}_x = -d(u f_x) - e_{xx} dx - f_{xx} dy$$

$$\underline{\hat{\Upsilon}_k = 0, k \geq 1:}$$

$$f_{k+1} = D_x^k(f_x), \quad k \geq 1$$

$$\underline{\hat{\Psi} = 0:}$$

$$dy = u dx \quad \rightsquigarrow \quad \frac{dy}{dx} = u(x, y(x))$$

$$\underline{\hat{\Psi}_x = 0:}$$

$$e_{xx} = -(u_x + u u_y) f_x - 2u f_{xx}.$$

$$\underline{\hat{\Psi}_k = 0, k \geq 2:}$$

$$e_{k+1,0} = D_x(e_{k,0})$$

Normalization

$$\hat{\sigma}^x = f_x dx, \quad \hat{\sigma}^y = f_x(dy - u dx)$$

and

$$\hat{\sigma}^u = du - \left(u_x + u u_y + \frac{u f_{xx}}{f_x} \right) dx + \frac{f_{xx}}{f_x} dy \equiv \left(\frac{u_y}{f_x} + \frac{f_{xx}}{f_x^2} \right) \hat{\sigma}^y = \hat{U}_Y \hat{\sigma}^y$$

Order 1 normalization

$$\hat{U}_Y = 0 \quad \rightsquigarrow \quad f_{xx} = -u_y f_x$$

Prolongation

$$f = 0$$

$$f_{xx} = -u_y f_x$$

$$f_{xxx} = (u_y^2 - u_{xy} - u u_{yy}) f_x$$

$$\vdots$$

$$e = 0$$

$$e_x = -u f_x$$

$$e_{xx} = (u u_y - u_x) f_x$$

$$e_{xxx} = (u u_{xy} + 2u^2 u_{yy} + 2u_y u_x - u_{xx} - u u_y^2) f_x$$

$$\vdots$$

(Partial) Cross-section

We have normalized

$$f \quad f_{xx} \quad f_{xxx} \quad \dots \quad e \quad e_x \quad e_{xx} \quad \dots$$

without computing the prolonged action!

What is the (partial) cross-section \mathcal{K}^∞ producing these normalizations?

To find \mathcal{K}^∞ :

$$\hat{\rho} \Big|_{\mathcal{K}^\infty} = \mathbb{1}^{(\infty)} \Big|_{\mathcal{K}^\infty}$$

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$$f = x \quad f_x = 1 \quad f_{xx} = \dots = 0 \quad e = y \quad e_x = \dots = 0$$

into

$$\begin{array}{llll} f = 0 & f_{xx} = -u_y f_x & f_{xxx} = (u_y^2 - u_{xy} - u u_{yy}) f_x & \dots \\ e = 0 & e_x = -u f_x & e_{xx} = (u u_y - u_x) f_x & \dots \end{array}$$

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Step 2: Compute the 2nd order partially normalized prolonged action



Need the recurrence relations

For

$$X = f(x) \qquad Y = e(x, y) = f_x(x) + g(x) \qquad U = u + \frac{e_x}{f_x}$$

we have

$$\mathbf{v} = \xi(x) \frac{\partial}{\partial x} + \eta(x, y) \frac{\partial}{\partial y} + \eta_x(x, y) \frac{\partial}{\partial u}, \qquad \eta_y = \xi_x$$

Basis of Maurer–Cartan forms

$$\mu_{X^k} = \lambda(\xi_{x^k}) \qquad \nu_{X^k} = \lambda(\eta_{x^k})$$

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$$dX = \sigma^x + \mu$$

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$$dU = \sigma^u + \nu_X$$

$$dU_X = \sigma_x^u + \nu_{XX} - U_X \mu_X - U_Y \nu_X$$

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When

$$\mathcal{K}^1 = \{x = y = u_x = u_y = 0\} \quad \rightsquigarrow \quad X = Y = U = U_X = U_Y = 0$$

Recurrence relations:

$$0 = \hat{\sigma}^x + \hat{\mu}$$

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Normalized Maurer–Cartan forms:

$$\hat{\mu} = -\hat{\sigma}^x = -f_x dx \qquad \hat{\mu}_{XX} = -\hat{\sigma}_y^u \equiv -\hat{U}_{YY} \hat{\sigma}^y$$

Recurrence relations:

$$0 = \hat{\sigma}^x + \hat{\mu}$$

$$0 = \hat{\sigma}^y + \hat{\nu}$$

$$0 = \hat{\sigma}^u + \hat{\nu}_X$$

$$0 = \hat{\sigma}_x^u + \hat{\nu}_{XX}$$

$$0 = \hat{\sigma}_y^u + \hat{\mu}_{XX}$$

When

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We obtain \hat{U}_{YY} by computing $\hat{\mu}_{XX} = \hat{\mathbb{D}}_X^2(\hat{\mu}) = -\hat{\mathbb{D}}_X^2(\hat{\sigma}^x)$

Normalized operator:

$$\hat{\mathbb{D}}_X = \frac{1}{f_x} \left[\frac{\partial}{\partial x} + u \frac{\partial}{\partial y} + (u_x + u u_y) \frac{\partial}{\partial u} + (u_{xy} + u u_{yy}) \frac{\partial}{\partial u_y} \right. \\ \left. + (u_{xx} + u u_{xy}) \frac{\partial}{\partial u_x} + \cdots - f_x u_y \frac{\partial}{\partial f_x} \right]$$

Fact: $\hat{\mathbb{D}}_X$ is tangent to the pseudo-group orbits in $\hat{\mathcal{B}}^{(\infty)}$

$$\frac{dy}{dx} = u, \quad \frac{du}{dx} = u_x + u u_y, \quad \dots \quad \frac{df_x}{dx} = f_{xx} = -u_y f_x.$$

Hence

$$\hat{\mu}_X = \hat{\mathbb{D}}_X(\hat{\mu}) = -\hat{\mathbb{D}}_X(\hat{\sigma}^x) = u_y dx + \frac{1}{f_x} df_x \\ \hat{\mu}_{XX} = \hat{\mathbb{D}}_X(\hat{\mu}_X) \equiv -\frac{u_{yy}}{f_x^2} \hat{\sigma}^y \quad (\hat{U}_{XX} = 0)$$

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Since

$$-\hat{U}_{YY} \hat{\sigma}^y \equiv \hat{\mu}_{XX} = -\frac{u_{yy}}{f_x^2} \hat{\sigma}^y \quad \Rightarrow \quad \hat{U}_{YY} = \frac{u_{yy}}{f_x^2}$$

Case 1 $\Rightarrow u_{yy} = 0$:

$$\hat{U}_{X^i Y^{j+2}} = 0 \quad \rightsquigarrow \quad \text{no further normalization}$$

$$\rightsquigarrow \quad \text{partial moving frame}$$

Case 2 $\Rightarrow u_{yy} \neq 0$:

$$1 = \hat{U}_{YY} = \frac{u_{yy}}{f_x^2} \quad \Rightarrow \quad f_x = \sqrt{u_{yy}}$$

Then

$$\hat{\mu}_X = u_y dx + \frac{1}{f_x} df_x$$

\Downarrow

$$\hat{\mu}_X \equiv \left(\frac{u_{xyy} + u u_{yyy} + 2 u_y u_{yy}}{2 u_{yy}^{3/2}} \right) \hat{\sigma}^x + \frac{u_{yyy}}{2 u_{yy}^{3/2}} \hat{\sigma}^y = \frac{\hat{U}_{XYY}}{2} \hat{\sigma}^x + \frac{\hat{U}_{YYY}}{2} \hat{\sigma}^y$$

Thus

$$\hat{U}_{XYY} = \frac{u_{xyy} + u u_{yyy} + 2 u_y u_{yy}}{u_{yy}^{3/2}} \quad \hat{U}_{YYY} = \frac{u_{yyy}}{u_{yy}^{3/2}}$$

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Recursive algorithm

Data is needed:

Lie pseudo-group \mathcal{G} – Recurrence relations – Basis of group forms

Initial step:

- Compute $\sigma^a = d_J Z^a$
- Fix \mathcal{K}^0 and solve for pseudo-group parameters
- Prolonged pseudo-group normalizations (vanishing of group forms)
- Compute $\hat{\sigma}^i, \hat{\sigma}^\alpha \equiv \sum_{k=1}^p \hat{U}_k^\alpha \hat{\sigma}^k$
- Fix \mathcal{K}^1 and normalize pseudo-group \rightsquigarrow prolonged pseudo-group normalizations

Loop: $k \geq 1$

- Substitute cross-section normalizations into the order k lifted recurrence relations.
- Solve for $\hat{\sigma}_K^\alpha \leftrightarrow \#K = k$
- Use $\hat{\mu}_{B,b}^a = \hat{\mathbb{D}}_b(\hat{\mu}_B^a)$, and $\hat{U}^{(k)}$ to obtain coordinate expressions for

$$\hat{\sigma}_K^\alpha = d\hat{U}_K^\alpha - \hat{\psi}_K^\alpha \equiv \sum_{i=1}^p \hat{U}_{K,k}^\alpha \hat{\sigma}^k$$

- If possible, normalize some of the $\hat{U}_{K,k}^\alpha \rightsquigarrow$ pseudo-group normalization \rightsquigarrow prolonged pseudo-group normalization
- corresponding cross-section \mathcal{K}^{k+1}
- replace k by $k + 1$

Outcomes

- Prolonged action becomes eventually free
 - All pseudo-group parameters are normalized
 - Moving frame
- Prolonged action does not become free
 - Partial moving frame
 - Finitely many unnormalized pseudo-group jets \leftrightarrow prolonged coframe
 - Infinitely many unnormalized pseudo-group jets \leftrightarrow involutive coframe

All cases: use recurrence relations to analyze the algebra of differential invariants