# Constraints on marginalised DAGs. 

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## Outline

(1) Introduction
(2) Other Constraints
(3) mDAGs
(4) Finding Constraints
(5) Summary

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## Implications of Models

It is common (especially in causal settings) to hypothesise models based on DAGs:


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It is common (especially in causal settings) to hypothesise models based on DAGs:


This encodes the assumption that the joint distribution factorises as:

$$
p(A) p(T \mid A) p(S) p(C \mid S) p(B \mid S) p(E \mid T, C) p(X \mid E) p(D \mid E, B)
$$

## d-Separation

The factorisation criterion

$$
p\left(x_{V}\right)=\prod_{v \in V} p\left(x_{V} \mid x_{\mathrm{pa}_{\mathcal{G}}(v)}\right)
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is equivalent to the global Markov property:
$A$ d-separated from $B$ by $C \Longrightarrow X_{A} \Perp X_{B} \mid X_{C}[P]$.

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A \text { d-separated from } B \text { by } C \Longrightarrow X_{A} \Perp X_{B} \mid X_{C}[P] \text {. }
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In particular, all constraints on DAGs are conditional independences.

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Can only observe independences which don't involve $U$ :

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T_{1} \Perp O_{2}, T_{2} \quad T_{2} \Perp O_{1}, T_{1} .
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Is this all?

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## Example 1: Verma Graph

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If $U$ is latent, we can only observe $X_{3} \Perp X_{1} \mid X_{2}$.
But if we add an arrow $X_{1} \rightarrow X_{4}$, we still have $X_{3} \Perp X_{1} \mid X_{2}$. So can we detect that $X_{1} \nrightarrow X_{4}$ ?

## The Verma Constraint


$f\left(x_{1}, x_{2}, x_{3}, x_{4}\right)=\int f(u) f\left(x_{1}\right) f\left(x_{2} \mid x_{1}, u\right) f\left(x_{3} \mid x_{2}\right) f\left(x_{4} \mid x_{3}, u\right) d u$

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& =f\left(x_{1}\right) f\left(x_{3} \mid x_{2}\right) \int f(u) f\left(x_{2} \mid x_{1}, u\right) f\left(x_{4} \mid x_{3}, u\right) d u \\
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Note that

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\int f^{*}\left(x_{2}, x_{4} \mid x_{1}, x_{3}\right) d x_{2}=f\left(x_{4} \mid x_{3}\right)
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is independent of $x_{1}$, precisely because $X_{1} \nrightarrow X_{4}$.
This is the Verma constraint, and provides a non-parametric test for the presence of $X_{1} \rightarrow X_{4}$.

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Can we detect that $Z \nrightarrow Y$ ? Pearl (1995) showed that for discrete $Z, X$ and $Y$,

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\max _{x} \sum_{y} \max _{z} P(X=x, Y=y, \mid Z=z) \leq 1
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So, for example

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P(X=0, Y=0 \mid Z=0)+P(X=0, Y=1 \mid Z=1) \leq 1
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Inequalities for the discrete IV model can be derived using linear programs (Porta, cdd).

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However, there are inequalities (as we will see).

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This raises the following question:

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Perhaps easier:

- can we find an equivalence class of these models?
- what graphs do we need to represent these models?


## Prior Work

Conditional independences from marginalised DAGs can be captured by larger classes of graphs (ADMGs, summary graphs, MC graphs, LMGs, ...).

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Conditional independences from marginalised DAGs can be captured by larger classes of graphs (ADMGs, summary graphs, MC graphs, LMGs, ...).

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Pearl (1995) first gave inequality constraints for IV model. Bonet (2001) used linear programming to derive tight bounds.

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Hence we only need to consider latents with no parents.
Of course this is not true if we assume, e.g. latents are binary!

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## mDAGs

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ADMGs are special case where $B$ only contains subsets of size 2 .

## ADMGs are not sufficient

In general we need to distinguish between $\{1,2,3\}$ and $\{1,2\},\{1,3\}$, $\{2,3\}$.


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The model on the right is not saturated. Still true if we dichotomise.

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## Complete ‘Markov’ Property

Given an mDAG $\mathcal{G}$ and statespace $\mathfrak{X}_{V}$, want to find $\mathcal{M}\left(\mathcal{G}, \mathfrak{X}_{V}\right)$, the collection of distributions which could be generated from the mDAG.

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Then $P \in \mathcal{M}\left(\mathcal{G}, \mathfrak{X}_{V}\right)$ if there exists some product space $\mathfrak{X}_{U}$ (and $\sigma$-algebra) and some distribution $\bar{P} \in \mathcal{M}\left(\overline{\mathcal{G}}, \mathfrak{X}_{V} \times \mathfrak{X}_{U}\right)$ such that $P$ is the $V$-margin of $\bar{P}$.

## Example

Instrumental Variables mDAG $\mathcal{G}$ :


Let $\mathfrak{X}_{V}=\{0,1\}^{3}$; then Pearl (1995) shows

$$
\mathcal{M}\left(\mathcal{G}, \mathfrak{X}_{V}\right) \subseteq\left\{P \mid \max _{x} \sum_{y} \max _{z} P(x, y \mid z) \leq 1\right\}
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With linear programming one can show equality holds (Bonet, 2001).
In the general discrete case (especially for increasing statespace of $Z$ ) these inequalities are not sufficient.

## Instrumental Inequality: Alternative Interpretation



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so $Y$ behaves as if $X=0$.
Clearly $Y \Perp Z\left[f^{*}\right]$, and $f^{*}(0, y \mid z)=f(0, y \mid z)$.
So $f(0, y \mid z)$ for $y, z$ must be compatible with a distribution under which $Y \Perp Z$. This gives Pearl's instrumental inequality.

## Applying to Other Graphs

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Again no independences; in fact strictly contains IV models on $(Z, X, Y)$ and ( $Y, X, Z$ ).

But by same argument, probabilities $f(0, y, z)$, must be compatible with $Y \Perp Z$.

So e.g.

$$
(1-f(0, y, z))^{2}+(1-f(0,1-y, 1-z))^{2} \geq 1 .
$$

## Skeleton

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## Distinction by Skeleton

The instrumental inequality can be generalised for discrete graphs.
Theorem
Let $\mathcal{G}, \mathcal{G}^{\prime}$ be mDAGs and $\mathfrak{X}_{V}$ a discrete statespace. If

- $\mathcal{G}^{\prime} \subseteq \mathcal{G}$; and
- $\mathcal{G}^{\prime}$ and $\mathcal{G}$ have different skeletons,
then $\mathcal{M}\left(\mathcal{G}^{\prime}, \mathfrak{X}_{v}\right) \subsetneq \mathcal{M}\left(\mathcal{G}, \mathfrak{X}_{v}\right)$. In other words, a constraint is always induced.


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The additional constraints could be independences, Verma constraints, or inequalities (or something else!).
The proof of this result is constructive (in that it produces inequalities).

## Causal Effects

## Corollary

We can derive non-trivial inequalities for an Average Controlled Direct Effect (ACDE) between any $Z \rightarrow Y$ as long as $Z$ and $Y$ are not directly confounded.

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Unrelated confounding model, e.g.

$$
\operatorname{ACDE}(x) \leq \frac{1+P(Y=1, x, z)-P(x)}{P(x, z)}-\frac{P(Y=1, x, 1-z)}{1-P(x, z)}
$$

for each $x, z$.

## Model Equality

## Lemma

Let $\mathcal{G}^{\prime}$ and $\mathcal{G}$ be ADMGs, with $\mathcal{G}^{\prime}$ a subgraph of $\mathcal{G}$. Then $\mathcal{M}\left(\mathcal{G}^{\prime}\right) \subseteq \mathcal{M}(\mathcal{G})$

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## Theorem

Let $\mathcal{G}$ be an ADMG with an edge $a \leftrightarrow b$ such that

- $\mathrm{pa}_{\mathcal{G}}(a) \subseteq \mathrm{pa}_{\mathcal{G}}(b)$;
- $\operatorname{sp}_{\mathcal{G}}(a)=\{b\}$.

Then if $\mathcal{G}^{\prime}$ is equal to $\mathcal{G}$ except that $a \rightarrow b$ and $a \nless b$, we have $\mathcal{M}\left(\mathcal{G}^{\prime}\right)=\mathcal{M}(\mathcal{G})$.

Examples (1)


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m-separation implies $X, Z \Perp Y \ldots$

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m-separation implies $X, Z \Perp Y \ldots$ but we get precisely this without the bidirected edge anyway.

Examples (2)


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## Examples (3)



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Here we have $X \Perp W, Y$ and $Y \Perp X, Z$ as well as Bell's inequalities.

## Models on Three Observed Variables

40 unlabelled ADMGs on 3 variables ( 48 mDAGs ).

| $\Perp\{X, Y, Z\}$ | complete independence | 1 |
| :---: | :--- | ---: |
| $X \Perp Y, Z$ | joint independence | 3 |
| $X \Perp Y \mid Z$ | conditional independence | 5 |
| $X \Perp Y$ | marginal independence | 6 |
| $\operatorname{IV}(X, Y, Z)$ | instrumental variable | 3 |
| UC $(X, Y, Z)$ | unrelated confounding | 1 |
|  | unrestricted | 20 |
|  | 3-cycle | 1 |



## Larger Models

There are 1567 ADMGs over 4 variables. At least 509 are equivalent to a DAG.

After applying Theorem on equivalence, at most 671 distinct models not equivalent to DAGs.

Can reduce to 543 by splitting into districts.

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- mDAGs provide the most general necessary framework for representing DAGs under marginalisation (ADMGs are not sufficient);
- Pearl's IV bounds have a nice interpretation in terms of marginal independence;
- this interpretation leads to constructive bounds for other models;
- the absence of an edge in any mDAG can (in principle) be refuted;
- consequently causal bounds can be constructed for any unconfounded variables.


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- How tight can we get the inequalities to be?
- How powerful are the inequalities?
- What is the complete equivalence class of models?
- Are the models smooth?
- What about conditioning?


## Thank you!

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(i) any non-collider is in $C$ :

(ii) or any collider is not in $C$, nor has descendants in $C$ :



Two vertices $v$ and $w$ are d-separated given $C \subseteq V \backslash\{v, w\}$ if all paths are blocked.

## Bonet's Inequalities

Suppose $Z$ ternary and $X, Y$ binary for IV model on $Z, Y, X$. Then
$p\left(x_{0}, y_{1} \mid z_{1}\right)+p\left(x_{0}, y_{0} \mid z_{2}\right)+p\left(x_{0}, y_{1} \mid z_{0}\right)+p\left(x_{1}, y_{1} \mid z_{1}\right)+p\left(x_{1}, y_{0} \mid z_{0}\right) \leq 2$

## ADMGs are not sufficient

## Lemma

Let $\mathcal{F}, \mathcal{G}, \mathcal{H}$ be mutually independent $\sigma$-algebrae (so that $\mathcal{F} \Perp \mathcal{G} \vee \mathcal{H}$ and so on), and let $X, Y$ and $Z$ be random variables such that
(i) $X$ is $\mathcal{F} \vee \mathcal{G}$-measureable;
(ii) $Y$ is $\mathcal{G} \vee \mathcal{H}$-measureable;
(iii) $Z$ is $\mathcal{F} \vee \mathcal{H}$-measureable.

Then $P(X=Y=Z)>1-\epsilon$ implies

$$
\operatorname{Var} X<3 \epsilon
$$

