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Optimal hedging in discrete and continuous time

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Goal: Find an optimal investing strategy for a portfolio

- Target: Payoff at maturity
- Investment strategy for the portfolio (optimal with respect to a measure of risk)
- Realtime implementation

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Hedging is very important in finance as a tool for

- Option pricing
- Replication of hedge funds
- Risk management

Description of the problem

- S_k : Value of the d underlying assets at period k (assumed square integrable).
- $\mathbb{F} = \{\mathcal{F}_k, k = 0, \dots, n\}$: Filtration. S is \mathbb{F} -adapted.
- $\Delta_k = \beta_k S_k - \beta_{k-1} S_{k-1}$, where the discounting factors β_k are predictable, i.e. β_k is \mathcal{F}_{k-1} -measurable for $k = 1, \dots, n$.
- C : Payoff at period n .

Aim: Find an initial investment amount V_0 and a predictable investment strategy $\vec{\phi} = (\phi_k)_{k=1}^n$ that minimize the expected quadratic hedging error $E \left[\left\{ G \left(V_0, \vec{\phi} \right) \right\}^2 \right]$, where

$$G = G \left(V_0, \vec{\phi} \right) = \beta_n C - V_n,$$

and the discounted value of the portfolio at period k is

$$V_k = V_0 + \sum_{j=1}^k \phi_j^\top \Delta_j, \quad k = 0, \dots, n.$$

Optimal hedging strategy

Set $P_{n+1} = 1$, and for $k = n, \dots, 1$, define

$$A_k = E\left(\Delta_k \Delta_k^\top P_{k+1} | \mathcal{F}_{k-1}\right),$$

$$b_k = A_k^{-1} E\left(\Delta_k P_{k+1} | \mathcal{F}_{k-1}\right),$$

$$\alpha_k = A_k^{-1} E\left(\beta_n C \Delta_k P_{k+1} | \mathcal{F}_{k-1}\right),$$

$$P_k = \prod_{j=k}^n \left(1 - b_j^\top \Delta_j\right).$$

Theorem

Suppose that $E(P_k | \mathcal{F}_{k-1}) \neq 0$ P -a.s., for $k = 1, \dots, n$.

Then the solution $(V_0, \vec{\phi})$ of the minimization problem is $V_0 = E(\beta_n C P_1) / E(P_1)$, and

$$\phi_k = \alpha_k - V_{k-1} b_k, \quad k = 1, \dots, n.$$

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C_k : optimal investment at period k so that the value of the portfolio at period n is as close as possible to C , in terms of mean square error.

$$\Rightarrow \beta_k C_k = \frac{E(\beta_n C P_{k+1} | \mathcal{F}_k)}{E(P_{k+1} | \mathcal{F}_k)}, \quad k = 0, \dots, n.$$

Minimal martingale measure \hat{P} :

$$\left. \frac{d\hat{P}}{dP} \right|_{\mathcal{F}_k} = \prod_{j=1}^k \frac{E(P_j | \mathcal{F}_j)}{E(P_j | \mathcal{F}_{j-1})}$$

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If the price process S is Markovian and $C_n = C_n(S_n)$, then $C_k = C_k(S_k)$, $\alpha_k = \alpha_k(S_{k-1})$, and $b_k = b_k(S_{k-1})$. It follows that all these functions can be approximated using the methodology developed in Papageorgiou et al. (2008).

Another interesting case encountered in practice is when S_k is not a Markov process but (S_k, h_k) is Markov, even if h_k is not observable, as in GARCH models or Hidden Markov models (HMM for short).

If $C_n = C_n(S_n)$, then $C_k = C_k(S_k, h_k)$, $\alpha_k = \alpha_k(S_{k-1}, h_{k-1})$, and $b_k = b_k(S_{k-1}, h_{k-1})$. Again, all these functions can be approximated using the methodology developed in Remillard et al. (2010). Implementation of the hedging strategy then requires prediction of h_t given S_0, \dots, S_t , which is a filtering problem.

Lévy processes

Examples

- Brownian motion
- Poisson process
- Jump-diffusion (Merton, 1976):

$$L_t = \mu t + \sigma B_t + \sum_{j=1}^{N_t} \zeta_j.$$

More generally a Lévy process L is a process with independent stationary increments, i.e.,

$$L_h, L_{2h} - L_h, \dots, L_{nh} - L_{(n-1)h}$$

are all independent and have the same distribution.

The only continuous Lévy processes are Brownian motions with drifts: $\mu t + \sigma B_t$.

In the following, we consider Lévy processes with exponential moments.

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For the rest of the presentation, we only consider one dimensional processes. The multivariate case is treated in the paper.

A Lévy process L can be characterized by three parameters (μ, a, ν) such that for all $|\theta| \leq 2$,

$$E\left(e^{\theta L_t}\right) = e^{t\Psi_{\mu,a,\nu}(\theta)},$$

where

$$\Psi(\theta) = \theta\mu + \frac{1}{2}\theta^2 a + \int_{\mathbb{R}\setminus\{0\}} \left(e^{y\theta} - 1 - \theta y\right) \nu(dy).$$

Here $\mu \in \mathbb{R}$, $a > 0$ and ν is a Lévy measure. In particular, $E(L_t) = t\mu$, $\text{Var}(L) = t(a + a_\nu)$, where $a_\nu = \int_{\mathbb{R}\setminus\{0\}} y^2 \nu(dy)$.

Generator

Often financial models are described in terms of a stochastic differential equation.

Black-Scholes-Merton:

$$dS_t = \mu S_t dt + \sigma S_t dW_t$$

A more practical approach is to describe the law of the process L through its infinitesimal generator \mathcal{L} : For all “nice” functions f ,

$$f(x_t) - \int_0^t \mathcal{L}f(x_u) du$$

is a martingale. For a Lévy process with parameters (μ, a, ν) ,

$$\begin{aligned} \mathcal{L}f(x) &= \mu f'(x) + \frac{a}{2} f''(x) \\ &+ \int_{\mathbb{R} \setminus \{0\}} \{f(x+y) - f(x) - yf'(x)\} \nu(dy). \end{aligned}$$

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- Brownian motion: $\mathcal{L}f(x) = \frac{1}{2}f''(x)$.
- Poisson process with intensity λ :

$$\mathcal{L}f(x) = \lambda\{f(x+1) - f(x)\}, \quad x = 0, 1, \dots$$

- Jump-diffusion:

$$\mathcal{L}f(x) = \mu f'(x) + \frac{\sigma^2}{2} f''(x) + \lambda \int \{f(x+y) - f(x)\} g(y) dy,$$

if the size of the jumps ζ_j have density g .

Regime-switching geometric Lévy processes

Given a regime-switching Lévy process L , process S , hereafter called a regime-switching geometric Lévy process,

$$S_t = se^{L_t}$$

is the associated regime-switching geometric Lévy process, i.e., (S, τ) is a Markov process with generator \mathcal{L}

$$\mathcal{L}f(s, i) = \mathcal{L}_i f(s, i) + \sum_{j=1}^l \Lambda_{ij} f(s, j),$$

where for each $i = 1, \dots, l$, \mathcal{L}_i is the generator of the geometric Lévy process $S_{i,t} = se^{L_{i,t}}$, and

$$\begin{aligned} \mathcal{L}_i f(s) &= s\psi(i)f'(s) + s^2 \frac{a(i)}{2} f''(s) \\ &\quad + \int_{\mathbb{R} \setminus \{0\}} [f\{s(1+y)\} - f(s) - ysf'(s)] \tilde{\nu}_i(dy), \end{aligned}$$

Set

$$(\Lambda_t)_{ij} = \Lambda_{ij}\gamma(t,j)/\gamma(t,i), \quad i \neq j,$$

$$(\Lambda_t)_{ii} = -\sum_{j \neq i} (\Lambda_t)_{ij},$$

where

$$\frac{d}{dt}\gamma(t,i) = -\ell(i)\gamma(t,i) + \sum_{j=1}^l \Lambda_{ij}\gamma(t,j), \quad \gamma(0,i) = 1,$$

$i = 1, \dots, l$.

Λ_t is the generator of a time non homogeneous Markov chain $\tilde{\tau}$.

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Let C is the unique solution of

$$\partial_t C_t(s, i) + \mathcal{H}_{T-t} C_t(s, i) = rC_t(s, i), \quad C_T(s, i) = \Phi(s),$$

where

$$\begin{aligned} \mathcal{H}_t f(s, i) = & rsf'(s, i) + \frac{a(i)}{2} s^2 f''(s, i) + \sum_{j=1}^I (\Lambda_t)_{ij} f(s, j) \\ & + \int \{1 - \rho(i)y\} [f\{s(1+y)\} - f(s) - ysf'(s)] \tilde{\nu}_i(dy). \end{aligned}$$

Set

$$\alpha(t, s, i) = \partial_s C_t(s, i) + \frac{1}{s\Delta(i)} \{C_t(s, i)m(i) + \mathcal{K}_i C_t(s, i)\},$$

where $\mathcal{K}_i f(s) = \int y [f\{s(1+y)\} - f(s) - ysf'(s)] \tilde{\nu}_i(dy)$.

Solution for regime-switching geometric Lévy processes

Explicit representation of the “Minimal Martingale Measure”.

Theorem

The optimal solution of the hedging problem for a regime-switching geometric Lévy process is given by ϕ , and the actualized value of the associated portfolio is V ,

where V satisfies the stochastic differential equation

$$V_t = C(0, s, i) + \int_0^t \alpha(u-, S_{u-}, \tau_{u-}) dX_u - \int_0^t V_{u-} dM_u$$

and $\phi_t = \alpha(t, S_{t-}, \tau_{t-}) - V_{t-} \frac{\rho(\tau_{t-})}{X_{t-}}$, with C and α defined below.

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One can write

$$C_t(S_t, \tau_t) = E \{ \Phi(S_T) Z_T | \mathcal{F}_t \} / \gamma_{T-t}(\tau_t),$$

where $M_t = \int_0^t \frac{\rho(\tau_{u-})}{X_{u-}} dX_u$ and $Z = \mathcal{E} \{ -M \}$.

If Z is positive, then $\frac{d\hat{P}_i}{dP_i} = Z_T / \gamma(T, i)$ defines a change of measure under which X is a martingale.

For example, for the regime-switching geometric Brownian motion, S is continuous so Z is positive, being an exponential.

If Z is not positive, then the “price” $C_t(s, i)$ does not correspond to an expectation under an equivalent martingale measure.

Regime-switching Brownian motion

For that model $\nu_i \equiv 0$ and $\mathbb{A} = a$, S is continuous, and its generator is

$$\mathcal{L}f(s, i) = \psi(i)sf'(s, i) + \frac{a(i)}{2}s^2f''(s, i) + \sum_{j=1}^I \Lambda_{ij}f(s, j).$$

It follows that

$$\mathcal{H}_t f(s, i) = rsf'(s, i) + \frac{a(i)}{2}s^2f''(s, i) + \sum_{j=1}^I (\Lambda_t)_{ij}f(s, j)$$

is the generator of a time non homogeneous Markov process $(\tilde{S}, \tilde{\tau})$, where the Markov chain $\tilde{\tau}$ has generator (Λ_t) , so

$$C_t(s, i) = e^{-r(T-t)} E \left\{ \Phi(\tilde{S}_T) | \tilde{S}_t = s, \tilde{\tau}_t = i \right\}.$$

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Next,

$$\alpha(t, s, i) = \partial_s C_t(s, i) + C_t(s, i)\rho(i)/s, \quad i = 1, \dots, l.$$

Using the “pathwise method” in Broadie and Glasserman (1996), one can use simulations to obtain an unbiased estimate of α_t .

In fact if Φ is differentiable almost everywhere, then

$$\partial_s C_t(s, i) = \frac{1}{s} e^{-r(T-t)} E \left\{ \tilde{S}_T \Phi'(\tilde{S}_T) \mid \tilde{S}_t = s, \tilde{\tau}_t = i \right\},$$

so α_t can be written as an expectation of a function of \tilde{S}_T .
Finally,

$$\phi_t = \partial_s C_t(S_t, \tau_{t-}) + \left\{ C_t(S_t, \tau_{t-}) - e^{rt} V_{t-} \right\} \frac{\rho(\tau_{t-})}{S_t}.$$

In particular, $\phi_0 = \partial_s C_0(S_0, \tau_0)$. It follows that ϕ_t can be estimated by Monte-Carlo methods.

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For the Black-Scholes-Merton model, there is perfect hedging, i.e., $V_t = e^{-rt} C_t(S_t)$, so $\phi_t = \partial_S C_t(S_t)$.

It follows that the optimal hedging is delta-hedging only when there is no hedging error.

The formula

$$\phi_t = \partial_S C_t(S_t, \tau_{t-}) + \{ C_t(S_t, \tau_{t-}) - e^{rt} V_{t-} \} \frac{\rho(\tau_{t-})}{S_t}$$

allows for a “correction”, using the hedging error

$$G_t = C_t(S_t, \tau_{t-}) - e^{rt} V_{t-}.$$

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It can be shown that the discrete time regime-switching models can be approximated by their continuous time counterpart. Here we state some conditions under which the HMM model “converges ” in some sense to a regime-switching geometric Lévy process.

More direct approach than in Prigent (2003).

Under slightly the same conditions, the “option prices” and the optimal strategy under a HMM model also converge in some sense to the optimal strategy of the regime-switching geometric Lévy process.

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Suppose now that for each n , one has a HMM model $(S_k^{(n)}, \tau_k^{(n)})$, where $\beta_k^{(n)} = e^{-rT_k/n}$. Define $S^{(n)}(t) = S_{[nt/T]}^{(n)}$.

From now on, when talking of convergence in law, denoted by \rightsquigarrow , we mean convergence in law in the space in the space of càdlàg functions over $[0, T]$ with the Skorohod topology.

For simplicity, let \mathbb{E}_i denote expectation under the law of $\xi_1^{(n)}$ given $\tau_1^{(n)} = i$ and recall the following notations:

$$\mathbb{E}_i \left(\xi_1^{(n)} \right) = \mu^{(n)}(i) \text{ and } \mathbb{E}_i \left\{ \left(\xi_1^{(n)} \right)^2 \right\} = B^{(n)}(i), \quad i = 1, \dots, l.$$

Further let $C_2(\mathbb{R}^d)$ be the set of continuous functions f on \mathbb{R}^d so that $f(y) = O(|y|^2)$ and $f(y)/|y|^2 \rightarrow 0$ as $y \rightarrow 0$.

Theorem

Suppose that $\lim_{n \rightarrow \infty} n(Q^{(n)} - I) \rightarrow \Lambda T$. Assume also that for any $i = 1, \dots, l$, the following conditions are satisfied, as $n \rightarrow \infty$: $n\mu^{(n)}(i) \rightarrow Tm(i)$, $nB^{(n)}(i) \rightarrow T\mathbb{A}(i)$, and for all $f \in C_2(\mathbb{R}^d)$, $n\mathbb{E}_i \left\{ f \left(\xi_1^{(n)} \right) \right\} \rightarrow T \int f(y) \tilde{\nu}_i(dy)$.

Then $(S^{(n)}, \tau^{(n)}) \rightsquigarrow (S, \tau)$ with generator

$$\mathcal{L}f(s, i) = \mathcal{L}_i f(s, i) + \sum_{j=1}^l \Lambda_{ij} f(s, j),$$

where for each $i = 1, \dots, l$,

$$\begin{aligned} \mathcal{L}_i f(s) &= s\psi(i)f'(s) + s^2 \frac{a(i)}{2} f''(s) \\ &\quad + \int_{\mathbb{R} \setminus \{0\}} [f\{s(1+y)\} - f(s) - ysf'(s)] \tilde{\nu}_i(dy), \end{aligned}$$

is the generator of a geometric Lévy process.

Example

Consider a regime-switching geometric Gaussian random walk with

$$\xi_k^{(n)} = e^{R_k^{(n)} - rT/n} - 1,$$

where under \mathbb{P}_i , $R_k^{(n)}$ is Gaussian with mean $\left\{ \psi(i) - \frac{a(i)}{2} \right\} T/n$ and variance $a(i)T/n$.

It is easy to check that the conditions of the previous theorem are met with $\psi(i)$, $\mathbb{A}(i) = a(i)$ and $\nu_i \equiv 0$.

In other words, the limiting process is a regime-switching geometric Brownian.

Continuous time limit of the optimal hedging strategy

Suppose that the assumptions of the previous theorem are met.

Theorem

Suppose that $\Phi(s) = O(|s|^p)$, Φ is almost everywhere differentiable with derivative $\Phi'(s) = O(|s|^{p-1})$ and $E \left\{ (\zeta^{(n)})^k \right\} = 1 + \theta_k/n + o(1/n)$, $k = 1, \dots, 2p + 2$. Then

$$\left(S^{(n)}, \tau^{(n)}, C^{(n)}, \alpha^{(n)}, V^{(n)}, \phi^{(n)} \right) \rightsquigarrow (S, \tau, C, \alpha, V, \phi).$$

For regime-switching geometric Gaussian random walk, the condition hold for call and put options with $p = 1$.

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Example comes from Remillard et al. (2010) where the authors analyzed the daily log-returns of the S&P 500 from January 1st 2007 to December 31st 2008.

They concluded that a regime-switching geometric Gaussian random walk with 4 regimes was the best fit for that data set.

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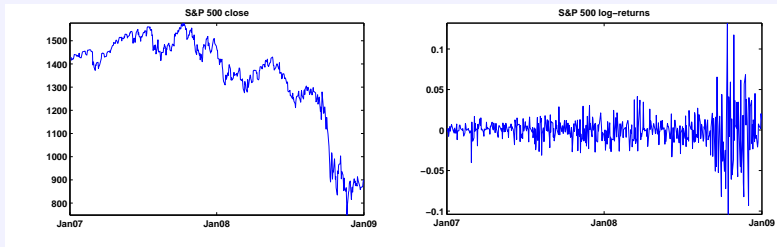


Figure: S&P 500 over the period 01/01/2007 to 12/31/2008.

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Table: Parameter estimations of the daily log-returns using 4 regimes.

Regime	Mean	Variance	stat. distr.	Prob. of next regime
1	-0.00500	0.002221	0.133	0.0084
2	-0.00134	0.000191	0.517	0.9850
3	0.00131	0.000126	0.113	4.2798e-006
4	0.00119	0.000014	0.237	0.0064

Table: Transition matrix Q for 4 regimes.

Regime	1	2	3	4
1	0.9842	0.0158	0	0
2	0.0043	0.9744	0	0.0213
3	0	0	0	1
4	0	0.0542	0.4754	0.4704

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To find the associated parameters in continuous time (measured in years), one can multiply the mean and variance by 250 and set $\Lambda = 250(Q - I)$.

Our aim is to price, using a regime-switching geometric Brownian motion, at-the-money call and put options with a maturity of 0.12 years (30 days), using an annual rate of 3% and a starting price of the underlying asset of 100.

Parameters for the regime-switching geometric Brownian motion

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Table: Parameters for the continuous time case.

Regime	ψ	A	ρ	ℓ
1	-0.9724	0.5553	-1.8053	1.8096
2	-0.3111	0.0478	-7.1440	2.4370
3	0.3433	0.0315	9.9444	3.1151
4	0.2993	0.0035	76.9286	20.7130

Table: Generator Λ .

Regime	1	2	3	4
1	-3.9500	3.9500	0	0
2	1.0750	-6.4000	0	5.3250
3	0	0	-250.0000	250.0000
4	0	13.5500	118.8500	-132.4000

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The next table contains prices of at-the-money call and put options, together with the value of $\phi_0 = \partial_s C_0(s, i)$, obtained by using 1,000,000 repetitions and antithetic variables.

Using previous results, one predicts that the next regime will be regime 2, having probability .98.

Because one can evaluate C_t and ϕ_t for any t , one could do as proposed in Remillard et al. (2010) and compare the optimal discrete hedging with the discretized version, i.e., by considering $\phi_{T_k/n}$ for $k = 1, \dots, n$, as in the discretized version of the Black-Scholes model, using filtering to predict the regimes using information available previously.

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95% confidence intervals for the price of at-the-money calls and puts, together with initial investments, using 1,000,000 simulations.

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Regime	Call	
	Price	ϕ_0
1	9.3103 ± 0.0182	0.5524 ± 0.0004
2	3.5034 ± 0.0069	0.5356 ± 0.0001
3	2.6398 ± 0.0049	0.5380 ± 0.0002
4	2.6469 ± 0.0049	0.5384 ± 0.0002

Regime	Put	
	Price	ϕ_0
1	8.9549 ± 0.0110	-0.4475 ± 0.0003
2	3.1435 ± 0.0055	-0.4644 ± 0.0001
3	2.2803 ± 0.0041	-0.4620 ± 0.0002
4	2.2874 ± 0.0042	-0.4616 ± 0.0002

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