

Stochastic Perturbations and Smooth Condition Numbers

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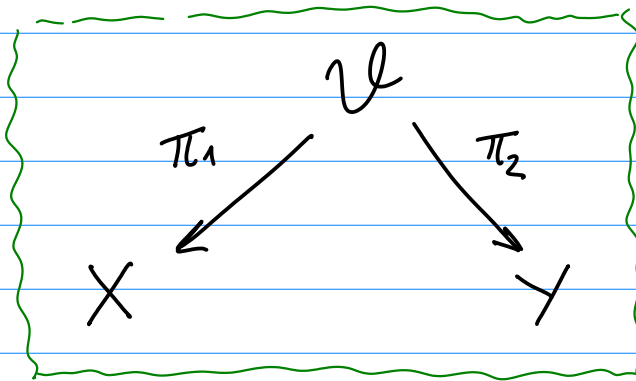
Introduction

Let X and Y be Riemannian manifolds, $\dim_{\mathbb{R}} X = m$, $\dim_{\mathbb{R}} Y = m$ associated to some computational problem, where

X is the space of inputs and Y is the space of outputs

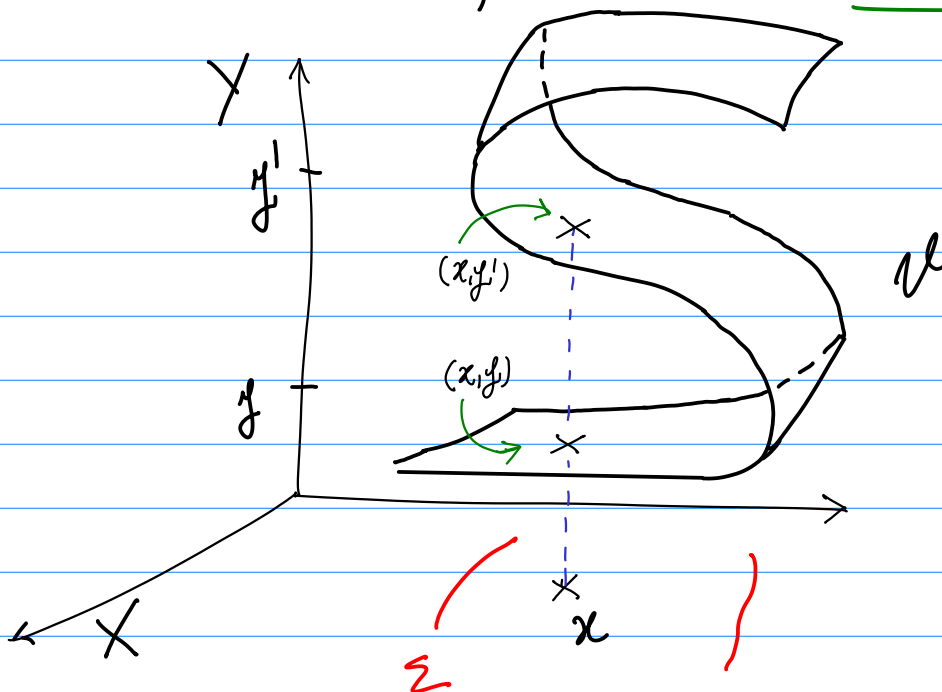
Let $\mathcal{V} := \{ (x, y) \in X \times Y : y \text{ is an output corresponding to } x \}$ be

the solution variety. Let π_1 and π_2 be the canonical projections:



$\Sigma' \subset \mathcal{V}$ is the set of critical points of π_1 , and $\Sigma := \pi_1(\Sigma')$.

Assume $\dim X = \dim \mathcal{V}$, then we have Jean-Pierre's Picture:



For each $(x, y) \in \mathcal{V} \setminus \Sigma$ there exist a smooth map G locally defined, namely

$$G := \pi_2 \circ \pi_1^{-1} \Big|_{U_x} : U_x \rightarrow U_y$$

from some neighborhoods U_x and U_y of x and y respectively.

Then $DG(x) : (T_x X, \langle \cdot, \cdot \rangle_x) \rightarrow (T_y Y, \langle \cdot, \cdot \rangle_y)$ is the condition operator at (x, y)

Def: The condition number at $(x, y) \in \mathcal{V} \setminus \Sigma$ is defined as:

$$K(x, y) := \sup_{\substack{\dot{x} \in T_x X \\ \|\dot{x}\|_x = 1}} \|DG(x)\dot{x}\|_y.$$

Remark 1: $K(x, y)$ is an upper-bound - to first-order approximation - of the worst-case sensitivity of the output error with respect to small perturbations of the input.

In many practical situations, however, there exist a discrepancy between worst case theoretical analysis and observed accuracy of algorithm.

There exist several approaches that attempt to rectify this discrepancy. Among them we find:

- average case-analysis
- smooth analysis

In many problems, the space of inputs X has a much larger dimension than the one of the space of outputs Y ($m \gg n$).

Then, infinitesimal perturbations of the input will produce drastic changes in the output only when they are performed in a few directions.

Then, a possibly different approach to analyze accuracy of algorithm is to replace "worst-case" by a certain mean over all possible directions.

(alternative already suggest by Weis, Wasilkowski, Wozniakowski, Shub for linear system solving, and more generally by Stewart for matrix perturbations).

Def: We define the p th-stochastic condition number at (x, y) as:

$$K_{st}^{[p]}(x, y) := \left[\frac{1}{\text{vol}(S_x^{m-1})} \cdot \int_{\dot{x} \in S_x^{m-1}} \|DG(x)\dot{x}\|_y^p dS_x^{m-1}(\dot{x}) \right]^{1/p}$$

($p = 1, 2, \dots$)

where $\text{vol}(S_x^{m-1}) = \frac{2\pi^{m/2}}{\Gamma(m/2)}$ is the measure of the unit sphere $S_x^{m-1} \subset \mathbb{R}^m X$.

Notation: in the case $p=2$ we simply write K_{st} .

Def: We define the Frobenius condition number as

$$K_F(x, y)^2 = \|DG(x)\|_F^2 = \sigma_1^2 + \dots + \sigma_m^2$$

where $\|\cdot\|_F$ is the Frobenius norm and $\sigma_1, \dots, \sigma_m$ are the singular values of the condition operator.

Theorem 8 $K_{st}^{[p]}(x, y) = \frac{1}{\sqrt{2}} \cdot \left[\frac{\Gamma(\frac{m}{2})}{\Gamma(\frac{m+p}{2})} \right]^{1/p} \cdot \mathbb{E}(\|\eta_{\sigma_1, \dots, \sigma_m}\|^p)^{1/p}$,

where $\eta_{\sigma_1, \dots, \sigma_m}$ is a centered Gaussian vector in \mathbb{R}^n with diagonal covariance matrix $\text{Diag}(\sigma_1, \dots, \sigma_m)$, and $\|\cdot\|$ is the Euclidean norm in \mathbb{R}^n .

In particular, for $p=2$

$$K_{st}(x, y) = \frac{K_F(x, y)}{\sqrt{m}} \quad (m = \dim X)$$

Remark: This result is most interesting when $\dim X \gg \dim Y$ ($m \gg n$), for in that case

$$K_{st}(x, y) \leq \sqrt{\frac{n}{m}} \cdot K(x, y) \ll K_F(x, y), \quad (\text{since } K_F(x, y) \leq \sqrt{n} \cdot K(x, y)).$$

Sketch of Proof: (case $p=2$)

(Gaussian standard in \mathbb{R}^m)

Step 1: $K_{st}(x, y)^2 = \frac{1}{m} \cdot \mathbb{E}(\|DG(x)\eta\|^2)$, where $\eta \sim \mathcal{N}(0, I_m)$.

Let $f: \mathbb{R}^m \rightarrow \mathbb{R}$ be $f(v) = \|DG(x)v\|^2$. Since f is homogeneous, integrating by polar coordinates we have:

$$\mathbb{E}(f(v)) \stackrel{\text{def.}}{=} \frac{1}{(2\pi)^{m/2}} \int_{\mathbb{R}^m} f(v) e^{-\frac{\|v\|^2}{2}} dv = C_m \cdot \int_{S^{m-1}} f(v) dS^{m-1}(v) = C_m \cdot K_{st}(x, y)^2.$$

Step 2: $A \in \mathcal{M}_{m \times m}$ then $\mathbb{E}(\|A\eta\|^2) = \|A\|_F^2$. ($U \in \mathcal{O}_m, V \in \mathcal{O}_m$)

Let $A = UDV$ a s.v.d. A , where $D = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_m & \\ & & & 0 \end{pmatrix}$. Using the invariance of the Gaussian distribution and the Euclidean norm under the orthogonal group, we have

$$\mathbb{E}(\|UDV\eta\|^2) = \mathbb{E}(\|UD\eta\|^2) = \mathbb{E}(\|D\eta\|^2) = \mathbb{E}(\sigma_1^2 \eta_1^2 + \dots + \sigma_m^2 \eta_m^2) = \|A\|_F^2.$$

Remark: When X and Y are (finite dimensional) linear vector spaces, instead of considering the (absolute) condition number one can take the relative condition number defined as

$$K_{\text{rel}}(x,y) = \frac{\|x\|_X}{\|y\|_Y} \cdot K(x,y), \quad x \neq 0, y \neq 0.$$

Theorem remains true if one exchange the condition number by the relative condition number.

Some Examples

Systems of Linear Equations: solve for $y \in \mathbb{R}^n$, $Ay = b$.

Let $X = M_n(\mathbb{R})$ with the Frobenius inner product, and $Y = \mathbb{R}^n$ with the Euclidean inner product. In this case $\Sigma = \{A \in M_n(\mathbb{R}) : \det A = 0\}$. The input-output map $G: M_n \setminus \Sigma \rightarrow \mathbb{R}^n$ is given by

$$G(A) = A^{-1}b (=y)$$

Implicit differentiation yields $DG(A)A = -A^{-1}AA^{-1}b = -A^{-1}Ay$.

Then:

$$K(A) = \|A^{-1}\| \cdot \|y\| \quad \text{and} \quad K_F(A) = \|A^{-1}\|_F \cdot \|y\|.$$

From where we conclude:

$$K_{\text{st}}(A) = \frac{\|A^{-1}\|_F \cdot \|y\|}{n} \leq \frac{K(A)}{\sqrt{n}}.$$

Notice that $K_{\text{rel}}(A) = \|A\| \cdot \|A^{-1}\|$.

Edelman proved that

$$\mathbb{E}(\log K_{\text{rel}}(A)) = \log n + c + o(1)$$

for $c \approx 1.537$,

where A is a random matrix whose elements are i.i.d standard normal.

Then from Theorem we have:

$$\mathbb{E}(\log K_{\text{rel}_{\text{st}}}(A)) \leq \frac{1}{2} \log n + c + o(1)$$

Finding Roots Problem: solve for $\zeta \in \mathbb{P}(\mathbb{C}^{n+1})$, $f(\zeta) = 0$, where $f \in \mathbb{P}(\mathcal{A}(d))$.

Let $(\mathcal{A}(d), \langle \cdot, \cdot \rangle, \lambda_W)$ be the space of systems $f: \mathbb{C}^{n+1} \rightarrow \mathbb{C}^n$, $f = (f_1, \dots, f_m)$ where f_i is a homogeneous polynomial of degree d_i , with the Weyl structure (see Blum-Cucker-Shub-Smale).

Let $X = \mathbb{P}(\mathcal{A}(d))$ and $Y = \mathbb{P}(\mathbb{C}^{n+1})$ with the canonical Hermitian product $\langle \cdot, \cdot \rangle_{\text{Herm}}$, the solution variety is given by:

$$\mathcal{V} = \left\{ (f, \zeta) \in \mathbb{P}(\mathcal{A}(d)) \times \mathbb{P}(\mathbb{C}^{n+1}) : f(\zeta) = 0 \right\}.$$

We denote by $N = \sum_{i=1}^m \binom{d_i+n}{n} - 1$ the complex dimension of X . We may think of $2N$ as the size of the input. For $(f, \zeta) \in \mathcal{V} \setminus \Sigma'$ we have

$$D_G(f)\dot{f} = - \left(Df(\zeta)|_{\zeta^\perp} \right)^{-1} \dot{f}(\zeta) \quad \text{then} \quad K_W(f, \zeta) = \| Df(\zeta)|_{\zeta^\perp}^{-1} \|$$

where some norm $\|\cdot\|$ affine representatives of f and ζ have been chosen.

Associated with K we consider
$$K_W(f)^2 := \frac{1}{D} \sum_{\{\zeta: f(\zeta)=0\}} K_W(f, \zeta)^2, \quad (*)$$

where $D = d_1 \cdots d_m$ is the number of roots of $f \in \mathbb{P}(\mathcal{A}(d)) \setminus \Sigma$.

The expected value of K_W^2 with respect to the Weyl distribution is an essential ingredient in the complexity analysis of path-following methods (see Shub-Smale, Betram-Pardo, Bürgisser-Cucker).

Beltrán-Pardo proved that

$$\mathbb{E}(K_W(f)^2) \leq 8m \cdot N$$

The relation between Kst and complexity is not clear yet.

However is interesting to study the expected value of the Kst-analogous of $(*)$, namely
$$K_{st,W}(f)^2 = \frac{1}{D} \sum_{\{\zeta: f(\zeta)=0\}} K_{st,W}(f, \zeta)^2.$$

Then from Theorem: $K_{st,W}(f, \zeta) \leq \frac{K_W(f, \zeta)}{\sqrt{N/m}}$ and

$$\mathbb{E}(K_{st,W}(f)^2) \leq 8m^2$$

Notice that the last bound depends on the number of unknowns n , and NOT! on the size of the input $N \gg m$.