## Spherical Designs and Approximate Spherical Designs

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(Approximate) Spherical Designs

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## Definition - Spherical *t*-design

- Unit sphere  $\mathbb{S}^2 := \left\{ \mathbf{x} \in \mathbb{R}^3 : |\mathbf{x}| = 1 \right\}$
- Standard Euclidean inner product  $\mathbf{x} \cdot \mathbf{y}$  in  $\mathbb{R}^3$ :  $|\mathbf{x}|^2 = \mathbf{x} \cdot \mathbf{x}$

• 
$$\omega_2 = |\mathbb{S}^2| = \int_{\mathbb{S}^2} d\omega(\mathbf{x}) = 4\pi$$

• Set 
$$\mathcal{X}_N = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \subset \mathbb{S}^2$$

- Space P<sub>t</sub> ≡ P<sub>t</sub> (S<sup>2</sup>) of spherical polynomials of degree at most t
   dim(P<sub>t</sub>) = (t + 1)<sup>2</sup>
- Spherical *t*-design is a set  $\mathcal{X}_N$  of N points such that

$$\frac{1}{N}\sum_{j=1}^{N}p(\mathbf{x}_j) = \frac{1}{4\pi}\int_{\mathbb{S}^2}p(\mathbf{x})d\omega(\mathbf{x}) \qquad \forall p \in \mathbb{P}_t,$$
(1)

•  $\mathcal{X}_N$  equal weight N point quadrature rule with degree of precision t

# Spherical designs – Number of points

• Delsarte, Goethals and Seidel (1977) [10]

• For  $\mathbb{S}^2$ 

$$N \ge N_0(t) := \begin{cases} rac{(t+1)(t+3)}{4} & \text{if } t \text{ odd,} \\ rac{(t+2)^2}{4} & \text{if } t \text{ even.} \end{cases}$$

- Bannai and Damerell (1979, 1980) [4, 5]
  - Tight spherical *t*-designs if achieve lower bounds
  - $\bullet\,$  Cannot exist on  $\mathbb{S}^2$  except for t=1,2,3,5
- Seymour and Zaslavsky (1984) [16]: Spherical t designs exist for N sufficiently large
- Bannai and Bannai (2009) [3] Survey on spherical designs and algebraic combinatorics on spheres
- Bondarenko, Radchenko and Viazovska (2010) [6] spherical t-designs on  $\mathbb{S}^d$  exist for  $N\geq c_dt^d$

(2)

## Existence Results for $\mathbb{S}^2$

- Bajnok (1991) [2] construction with  $N = O(t^3)$ 
  - n points  $z_1, \ldots, z_n$ , t-design on [-1, 1]
  - Regular m-gon at latitudes  $z_j$
  - N = mn point t-design if  $m \ge t+1$
- Korevaar and Meyers (1993) [14] Faraday Cage

• 
$$N = O(t^3)$$

- Both depend on t-designs for interval [-1,1]
  - Set of n points  $z_j \in [-1, 1]$ :

$$\frac{2}{n}\sum_{j=1}^{n}p(z_{j}) = \int_{-1}^{1}p(z)dz \quad \forall p \in \mathbb{P}_{t}([-1,1])$$

- Equal weights  $\implies n = O(t^2)$  points
- Survey Gautschi [11]
- Tensor product constructions based on 1-D existence result

#### Conjectures

### Evidence for $\mathbb{S}^2$

- Hardin and Sloane (1996) [13]
  - Summary of known results for  $\mathbb{S}^2$
  - Conjecture

$$N = \frac{t^2}{2} \left( 1 + o(1) \right)$$

• 
$$N = (t+1)^2 = \dim \left( \mathbb{P}_t(\mathbb{S}^2) \right)$$

- Start from extremal (maximum determinant) points Sloan, Womersley (2004) [17]
- Under-determined system of equations
- Use interval methods to verify a nearby solution
  - Chen and Womersley (2006) [8]
  - Chen, Frommer, Lang (2009) [7]
  - An, Chen, Sloan, Womersley (2010) [1]

#### Spherical designs – nonlinear equations

Delsarte, Goethals and Seidel (1977) [10]

 $\mathcal{X}_N = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \subset \mathbb{S}^2$  is a spherical t-design if and only if

$$r_{\ell,k}(\mathcal{X}_N) := \sum_{j=1}^N Y_{\ell,k}(\mathbf{x}_j) = 0$$
(3)

for  $k = 1, \ldots, 2\ell + 1$ ,  $\ell = 1, \ldots, t$ .

- Spherical harmonics  $\{Y_{\ell,k}: k = 1, \dots, 2\ell + 1, \ell = 0, 1, \dots, t\}$ 
  - Orthonormal basis for  $\mathbb{P}_t(\mathbb{S}^2)$
  - $Y_{\ell,k}$  a spherical harmonic of degree  $\ell$
- Constant ( $\ell = 0$ ) polynomial  $Y_{0,1} = 1/\sqrt{4\pi}$  not included in (3)
- $\bullet\,$  Integral of all spherical harmonics of degree  $\ell\geq 1$  is zero

## Polynomials with positive Legendre coefficients

• Polynomial  $\psi_t \in \mathbb{P}_t[-1,1]$  with positive Legendre coefficients

$$\psi_t(z) := \sum_{\ell=1}^t a_{t,\ell} P_\ell(z),$$

$$a_{t,\ell} > 0 \quad \text{for} \quad \ell = 1, \dots, t.$$
(5)

- Legendre polynomial  $P_{\ell}(z)$  for  $z \in [-1,1]$ •  $\int_{-1}^{1} \psi_t(z) dz = 0$
- Variational form

$$A_{t,N,\psi}(\mathcal{X}_N) := \frac{1}{N^2} \sum_{i=1}^N \sum_{j=1}^N \psi_t(\mathbf{x}_i \cdot \mathbf{x}_j)$$

#### Spherical designs – variational characterizations

$$t \ge 1$$
,  $\mathcal{X}_N = \{\mathbf{x}_1, \dots, \mathbf{x}_N\} \subset \mathbb{S}^2$ ,  $\psi_t$  as in (4), (5). Then  
$$0 \le A_{t,N,\psi}(\mathcal{X}_N) \le \sum_{\ell=1}^t a_{t,\ell} = \psi_t(1)$$

$$\overline{A}_{t,N,\psi} := \frac{1}{(\omega_2)^N} \int_{\mathbb{S}^2} \cdots \int_{\mathbb{S}^2} A_{t,N,\psi}(\mathbf{x}_1, \dots, \mathbf{x}_N) d\omega(\mathbf{x}_1) \cdots d\omega(\mathbf{x}_N) = \frac{\psi_t(1)}{N}.$$
  
$$\mathcal{X}_N \text{ is a spherical design if and only if}$$

$$A_{t,N,\psi}(\mathcal{X}_N) = 0.$$

Weighted sum of squares, strictly positive coefficients

$$A_{t,N,\psi}(\mathcal{X}_N) = \frac{4\pi}{N^2} \sum_{\ell=1}^t \frac{a_{t,\ell}}{2\ell+1} \sum_{k=1}^{2\ell+1} \left( r_{\ell,k}(\mathcal{X}_N) \right)^2$$
(6)

•  $A_{t,N,\psi}(\mathcal{X}_N) = 0 \iff \mathcal{X}_N$  spherical *t*-design • Global min  $A_{t,N,\psi}(\mathcal{X}_N) > 0 \Longrightarrow$  no spherical *t*-design with N points

### Specific cases

• Grabner and Tichy (1993) [12]

$$\psi_t(z) = z^t + z^{t-1} - a_{t,0} \tag{7}$$

$$a_{t,0} = \begin{cases} \frac{1}{t} & t \text{ odd,} \\ \frac{1}{t+1} & t \text{ even.} \end{cases}$$

• Cohn and Kumar (2007) [9]

$$\psi_t(z) = (1+z)^t - \frac{2^t}{t+1}.$$
 (8)

• Sloan and Womersley (2009) [18]

$$\psi_t(z) = \frac{1}{4\pi} P_t^{(1,0)}(z) - 1 = \sum_{\ell=1}^t (2\ell + 1) P_\ell(z) \tag{9}$$

•  $P_t^{(1,0)}$  Jacobi polynomial

# Evaluating $A_{t,N,\psi}(\mathcal{X}_N)$

- Matrix  $\Psi$ :  $\Psi_{ij} = \psi_t(\mathbf{x}_i \cdot \mathbf{x}_j), \quad i, j = 1, \dots, N$
- Spherical harmonic basis matrix  $\mathbf{Y}$  of size  $(t+1)^2 1$  by N:

$$\mathbf{Y} = [Y_{\ell,k}(\mathbf{x}_j)], \qquad \ell = 1, \dots, t, \ k = 1, \dots, 2\ell + 1; \quad j = 1, \dots, N,$$

• Spherical *t*-design  $\iff (t+1)^2 - 1$  equations (3)

$$\mathbf{r}:=\mathbf{Y}\mathbf{e}=\mathbf{0},$$

• Diagonal matrix  $\mathbf D$  of weights from (6)

$$\Psi = (4\pi) \mathbf{Y}^T \mathbf{D} \mathbf{Y}$$
$$\mathbf{D} = \operatorname{diag} \left( \frac{a_{t,\ell}}{2\ell + 1}, k = 1, \dots, 2\ell + 1, \ell = 1, \dots, t \right)$$

- Any symmetric positive definite D possible
- Minimize

$$A_{t,N,\psi}(\mathcal{X}_N) = \frac{1}{N^2} \mathbf{e}^T \mathbf{\Psi} \mathbf{e} = \frac{4\pi}{N^2} \mathbf{e}^T \mathbf{Y}^T \mathbf{D} \mathbf{Y} \mathbf{e} = \frac{4\pi}{N^2} \mathbf{r}^T \mathbf{D} \mathbf{r}$$

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# Evaluating $A_{t,N,\psi}(\mathcal{X}_N)$ using $\Psi$

• N by N matrix 
$$\Psi_{ij} = \psi_t(\mathbf{x}_i \cdot \mathbf{x}_j)$$

- Constant diagonal elements  $\psi_t(1) = \sum_{\ell=1}^t a_{t,\ell}$
- Matrix  $\Psi$  for  $a_{t,\ell} = 2\ell + 1 \iff \mathbf{D} = \mathbf{I}$



- Advantages: simple, (trivially) parallel
- Issue: cancelation errors in summing off diagonal elements

#### Standard results

- System of equations  $\mathbf{r}(x) = \mathbf{0}$ ,  $\mathbf{r}: \mathbb{R}^n \to \mathbb{R}^m$
- n variables, m equations
  - Under-determined m < n
  - Well-determined m = n
  - Over-determined m > n
- Sum of squares  $f(x) = \mathbf{r}^T(x)\mathbf{r}(x) = \sum_{j=1}^m r_j(x)^2$ 
  - $f(x) \ge 0$  for all x,  $f(x^*) = 0 \iff \mathbf{r}(x^*) = \mathbf{0}$
  - $x^*$  global minimizer  $f(x^*) > 0 \iff$  no solution exists
  - $x^*$  local minimizer  $f(x^*) > 0 \Longrightarrow ?$
- Derivatives
  - Jacobian  $J \in \mathbb{R}^{m \times n}$ :  $J_{ij}(x) = \frac{\partial r_i(x)}{\partial x_j}$ ,  $i = 1, \dots, m, j = 1, \dots, n$
  - Gradient  $\nabla f(x) = 2J^T \mathbf{r} \in \mathbb{R}^n$
  - Hessian  $\nabla^2 f(x) = 2J^T J + 2\sum_{i=1}^m r_i \nabla^2 r_i \in \mathbb{R}^{n \times n}$
- Newton's method: Correction  $\mathbf{d} : J\mathbf{d} + \mathbf{r} \approx \mathbf{0}$ 
  - $x^*: \mathbf{r}(x^*) = \mathbf{0}, J^*$  full rank  $\Longrightarrow$  quadratic convergence if start sufficiently close

#### Examples

## Degrees of freedom

- Spherical parametrization, normalization  $\implies n = 2N 3$  variables
- $m = \dim(\mathbb{P}_t) 1 = (t+1)^2 1$  equations
- Threshold  $n > m \Longrightarrow$

$$N \ge N_1(t) := \left[ (t+1)^2 \right] / 2 + 1$$

• Sum of squares for t = 19, varying N ( $N_1(19) = 201$ )



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## Example: t = 32, $N = N_1(32) = 546$

- m = 1088, n = 1089, under-determined
- Iterations:  $f \rightarrow 4.8 \times 10^{-6}$ ,  $\sigma_m = 1.16 \times 10^{-4}$ ,  $\kappa = 2.3 \times 10^{6}$



- Local minimum, but close to zero
- Jacobian at solution nearly singular
- $\bullet\,$  Other starting points give a global minimizer with f=0

#### Spherical designs - numerical results

- Aim: Use  $N = N_1(t)$ ,  $\Longrightarrow n = m, t \text{ odd}$ , n = m + 1, t even
- Rounding error limits achievable accuracy in A<sub>t,N</sub>
- Both  $A_{t,N,\psi}(\mathcal{X}_N)$ ,  $\mathbf{r}^T \mathbf{r}$  order of rounding error  $\Longrightarrow$  what confidence?
- $t = 100 \implies N_1(t) = 5102, m = 10200, n = 10201$



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### Condition numbers

• Condition numbers of Jacobian  $J(\hat{x})$ 



## Mesh norm and Separation

• Mesh norm (covering radius)

$$h_{\mathcal{X}_N} = \max_{\mathbf{x} \in \mathbb{S}^2} \min_{j=1,\dots,N} \ \mathsf{dist} \left(\mathbf{x}, \mathbf{x}_j\right) \geq \frac{c_{\mathsf{COV}}}{\sqrt{N}}$$

- Stationary point of  $A_{t,N,\psi}(\mathcal{X}_N)$  with  $h_X < 1/(t+1)$  $\implies A_{t,N,\psi}(\mathcal{X}_N) = 0$
- But  $h_X < 1/(t+1) \Longrightarrow N > c(t+1)^2$  where c > 4
- Yudin [19] Mesh norm h given by largest zero  $z_t = \cos(h)$  of  $P^{(1,0)}(z)$
- Reimer [15] extended to any positive weight cubature rule with degree of precision t
- Separation (twice packing radius)

$$\delta_{\mathcal{X}_{N}} = \min_{i \neq j} \mathsf{dist}\left(\left(,\mathbf{x}\right)_{i},\mathbf{x}_{j}\right) \leq \frac{c_{\mathsf{pack}}}{\sqrt{N}}$$

- Union of two spherical *t*-designs is a spherical *t*-design
- $\mathcal{X}_N \cup Q\mathcal{X}_N$  is 2N point spherical t-design with arbitrary separation

#### Mesh ratio



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### Symmetric designs

• 
$$N$$
 even,  $\mathbf{x} \in \mathcal{X}_N \iff -\mathbf{x} \in \mathcal{X}_N$ 

- Equal weights,  $\ell$  odd  $\Longrightarrow Y_{\ell,k}$  integrated exactly
- Constraints from even degrees  $\leq t$ , t odd

$$m = \sum_{k=1}^{(t-1)/2} 2(2k) + 1 = \frac{(t-1)(t+2)}{2}$$

- N = 2K points  $\Longrightarrow 2K 3 = N 3$  degrees of freedom
- Degrees of freedom ≥ number of equations ⇒

$$N \ge N_2(t) := 2\left\lceil \frac{(t-1)(t+2)+6}{4} \right\rceil \ge \frac{(t-1)(t+2)}{2} + 3$$

- Slightly less than  $N_1(t)$
- Roughly half storage for Jacobian and time

#### Extended precision - Spherical designs



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#### Extended precision - Symmetric spherical designs



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#### Extended precision - Refinement

- Refine with Gauss-Newton steps in Quad precision
- Store as 16 digit or 32 digit files



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## Well-conditioned spherical designs

- When N is larger, eg  $N > N_1(t)$ ,  $N \ge (t+1)^2$
- Use degrees of freedom to optimize other criteria
- Optimization problem

$$\max_{\substack{\mathcal{X}_N \subset \mathbb{S}^2 \\ \text{Subject to}}} \prod_{j=1}^{\min(N,(t+1)^2)} \sigma_j(\mathbf{Y}_t(\mathcal{X}_N))$$

- Spherical harmonic basis matrix  $\mathbf{Y}_t = \begin{bmatrix} \frac{1}{4\pi} \mathbf{e}^T \\ \mathbf{Y} \end{bmatrix}$ ,  $(t+1)^2$  by N
- Singular values

$$\sum_{j=1}^{\min(N,(t+1)^2)} \sigma_j^2(\mathbf{Y}_t(\mathcal{X}_N)) = \frac{N(t+1)^2}{4\pi}.$$

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#### Example with one degree of freedom

- Degree  $t = 22 \Longrightarrow m = 528$  equations
- Number of points  $N = 266 \Longrightarrow n = 529$  variables
- One degree of freedom
- Continuation to follow spherical design constraint



#### Worst case error

Cubature rule: nodes  $\mathcal{X}_N = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ , weights  $w_1, \dots, w_N$ 

$$Q_N(f) := \sum_{j=1}^N w_j f(\mathbf{x}_j)$$

Approximate integral

$$I(f) := \int_{\mathbb{S}^d} f(\mathbf{x}) d\omega(\mathbf{x})$$

Sobolev space  $\mathbb{H}^s=\mathbb{H}^s(\mathbb{S}^d)$  of functions, norm  $\|f\|_{\mathbb{H}^s},\,s>d/2$  Worst case cubature error

$$\mathsf{wce}(Q_N, \mathbb{H}^s) := \sup_{\|f\|_{\mathbb{H}^s} \le 1} |I(f) - Q_N(f)|$$

Positive weight rule with degree of precision  $\boldsymbol{t}$ 

$$c(d,s) \ N^{-s/d} \le \mathsf{wce}(Q_N,\mathbb{H}^s) \le C(d,s) \ t^{-s}$$

Same order if  $N = O(t^d)$ 

## Approximate spherical designs

Sequence of N = N(t) point configurations. As  $t \to \infty$  $\sup_{\|f\|_{\mathbb{H}^s} \le 1} \left| I(f) - \frac{|\mathbb{S}^d|}{N} \sum_{j=1}^N f(\mathbf{x}_j) \right| = O\left(\frac{1}{t^s}\right)$ 

Key: For s>d/2 Sobolev space  $\mathbb{H}^s_{\mathbf{a}}$  with reproducing kernel

$$K(\mathbf{a}; \mathbf{x}, \mathbf{y}) = \sum_{\ell=1}^{\infty} a_{\ell}^{(s)} Z(d, \ell) P_{\ell}^{(d)}(\mathbf{x} \cdot \mathbf{y})$$

•  $a_{\ell}^{(s)}$  define inner product in  $\mathbb{H}_{\mathbf{a}}^{s}$ • For  $d \geq 2$ 

Approximate spherical designs

$$\frac{1}{N^2} \sum_{i=1}^{N} \sum_{j=1}^{N} K_t(\mathbf{a}, \mathbf{x}_i, \mathbf{x}_j) - a_0^{(s)} = O\left(t^{-2s}\right)$$

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#### Spherical design functions



## Worst case error for s = 3/2

For 
$$d=2$$
,  $s=(d+1)/2=3/2$ : choose  $\mathbf{a}^{(s)}$  to get

- Cui and Freeden generalized discrepancy
- Sums of distances.



#### Conclusions

#### Conclusions

- Good points:  $\mathbb{S}^2$ 
  - Numerical spherical *t*-designs for  $t = 1, \dots, 140$
  - Equal weight cubature rule, degree of precision t with  $N=(t+1)^2/2+{\cal O}(1)$  points
  - Symmetric equal weight cubature rule, degree of precision t with N=(t-1)(t+2)/2+O(1) points for  $t=1,\ldots,181$
  - Good geometric properties: mesh norm, separation
  - Larger N: Use degrees of freedom to satisfy other criteria
  - Approximate designs: more flexibility
- Issues
  - Rounding errors in evaluating criteria, speed of extended precision
  - Convergence difficulties with close to singular Jacobians
  - No proof of nearby exact spherical designs when  $N < (t+1)^2$
  - No proof of existence for all t
  - There exist t-designs with  $N < N_1(t)$ ; special symmetries
  - Calculation by optimization for each  $t, \ N$
  - Point sets  $\mathcal{X}_N$  not nested

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