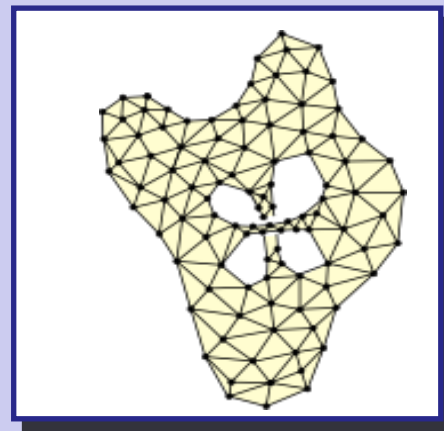
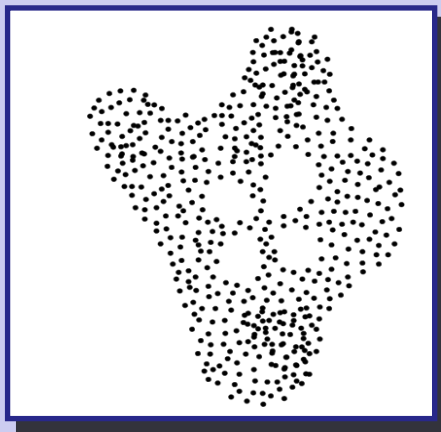
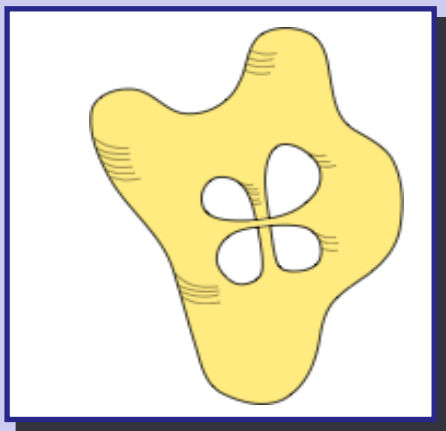


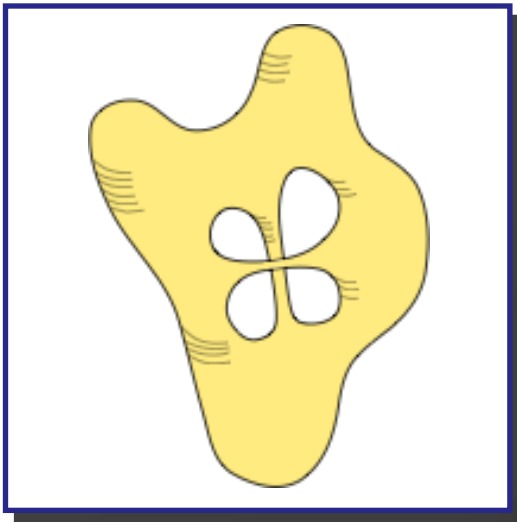
Vietoris-Rips complexes also provide topologically correct reconstructions of sampled shapes

Dominique Attali, Andre Lieutier and David Salinas



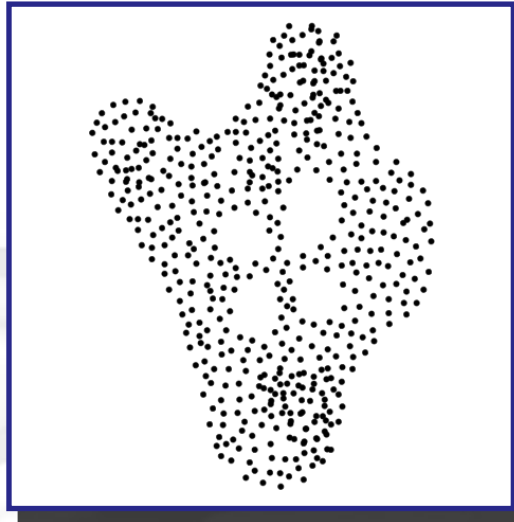
Shape Reconstruction

UNKNOWN



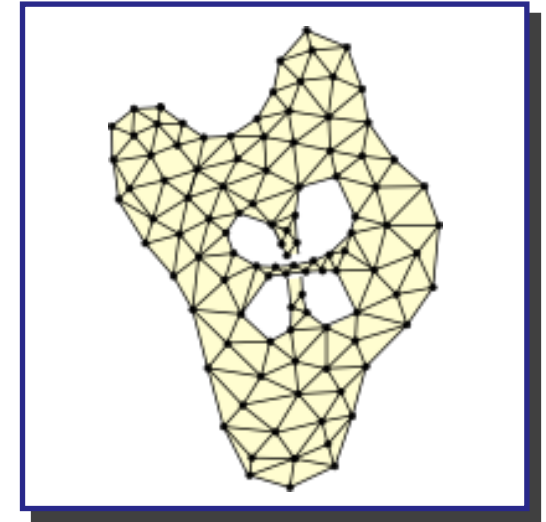
Shape

INPUT



Sample

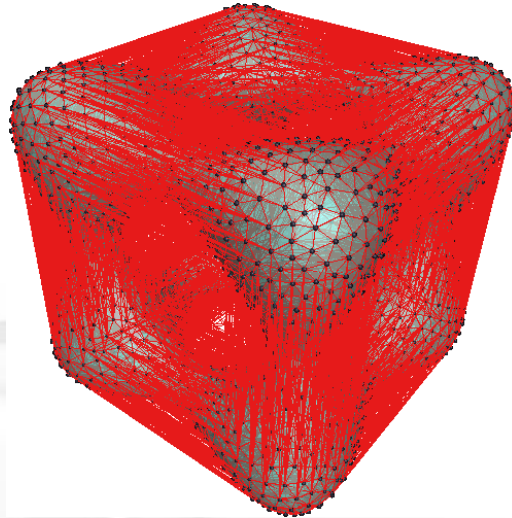
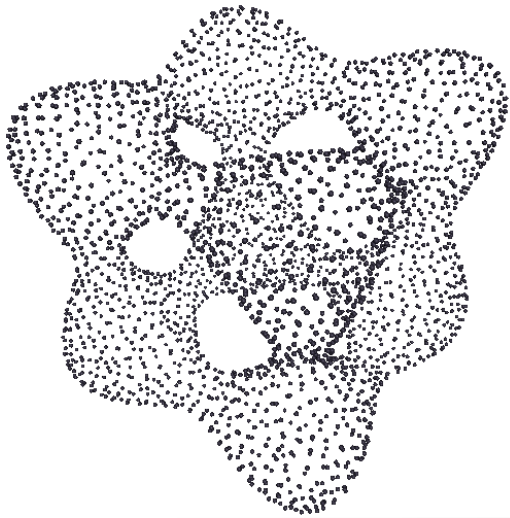
OUTPUT



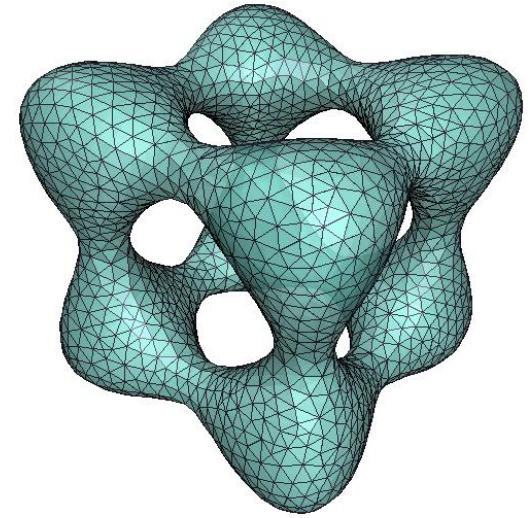
Approximation
of the shape

- geometrically accurate
- topologically correct

Algorithms in 3D



Delaunay triangulation

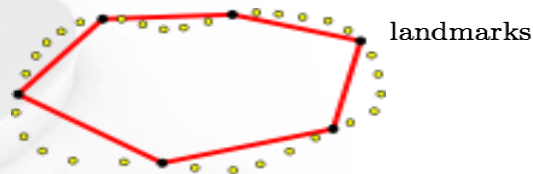


select a subset of the Delaunay triangulation

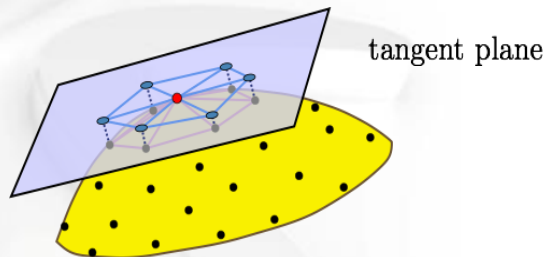
Algorithms in High Dimensions

How can we reconstruct without having to build the whole Delaunay triangulation ?

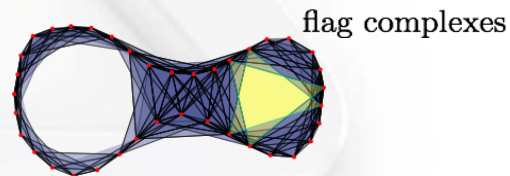
- ✱ weak Delaunay triangulation
[de Silva 2008]



- ✱ tangential Delaunay complexes
[Boissonnat & Ghosh 2010]

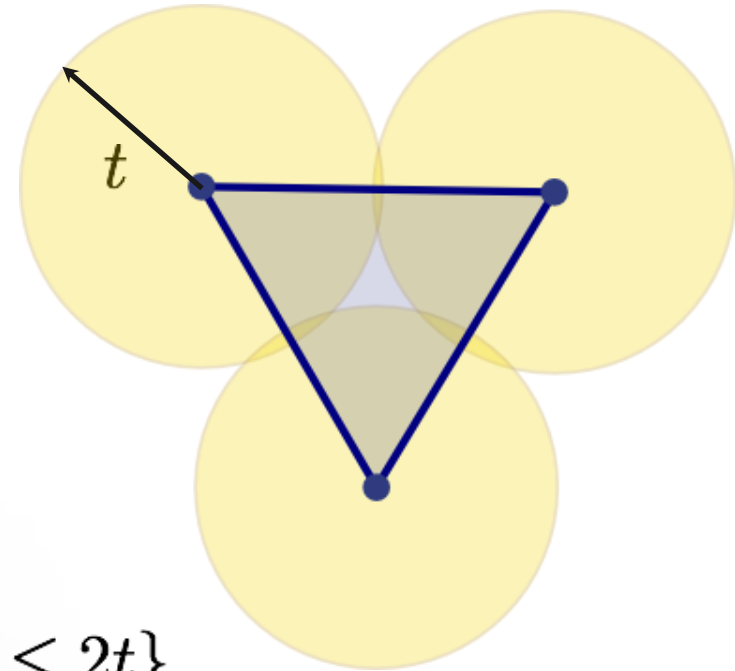
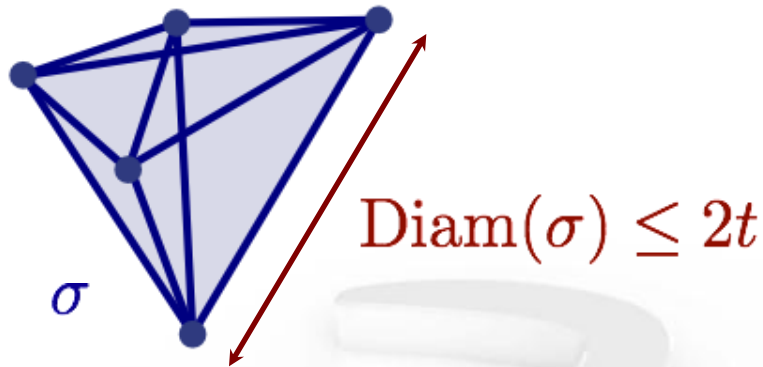


- ✱ Rips complexes
[Attali, Lieutier & Salinas 2011]



Rips Complex (or Vietoris-Rips complex)

P finite set of points



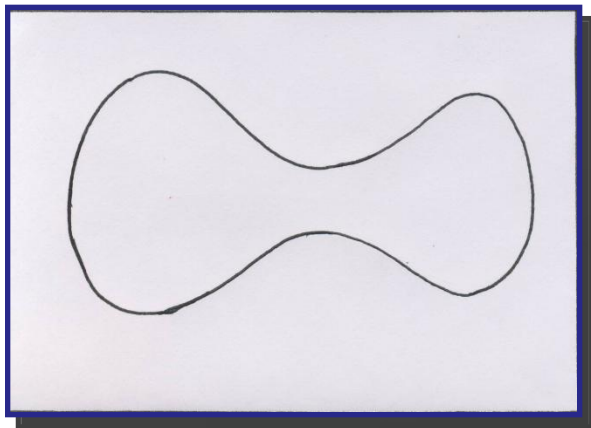
$$\mathcal{R}(P, t) = \{\sigma \mid \emptyset \neq \sigma \subset P, \text{Diam}(\sigma) \leq 2t\}$$

Rips complexes are **flag** (or **clique**) **complexes**, they can therefore be represented by their 1-skeleton, which is a **graph**:

This allows a **parcimonious** representation even in high ambient dimension

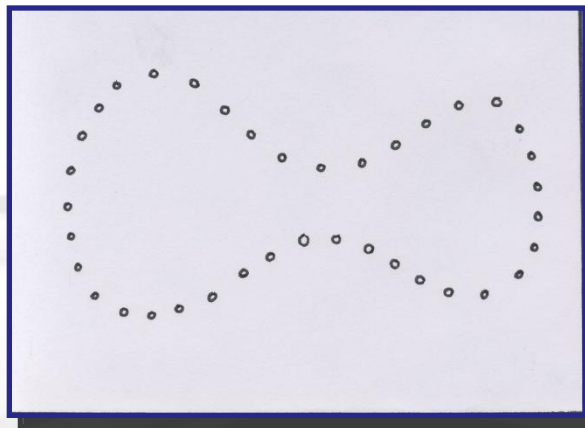
A Simple Algorithm

UNKNOWN



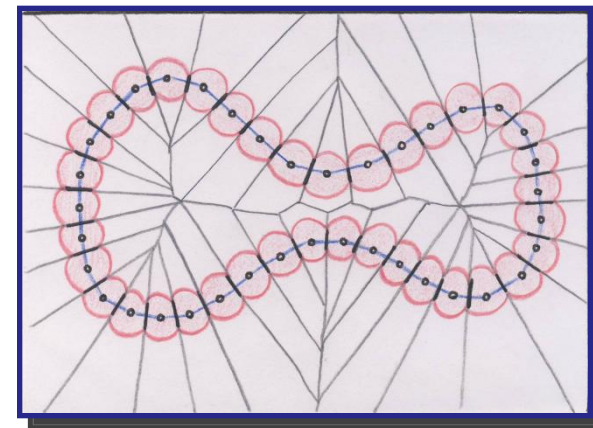
Shape

INPUT



Sample

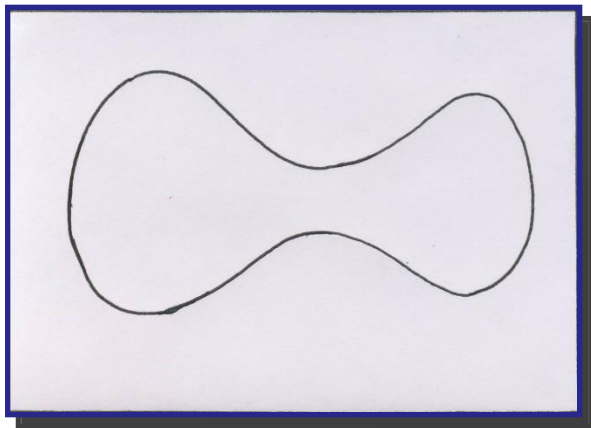
OUTPUT



α -offset = union of balls
with radius α centered
on the sample

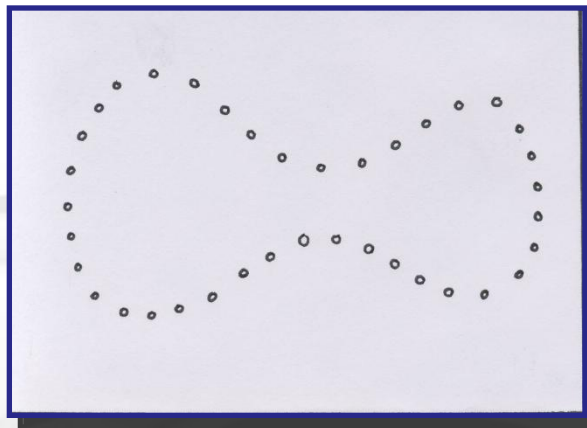
A Simple Algorithm

UNKNOWN



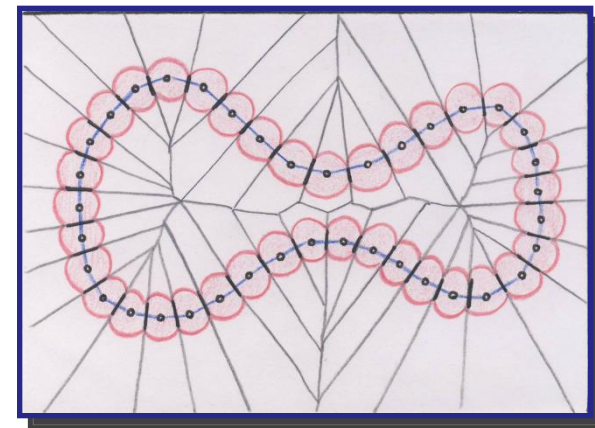
Shape

INPUT



Sample

OUTPUT



From Nerve Theorem:

α -offset

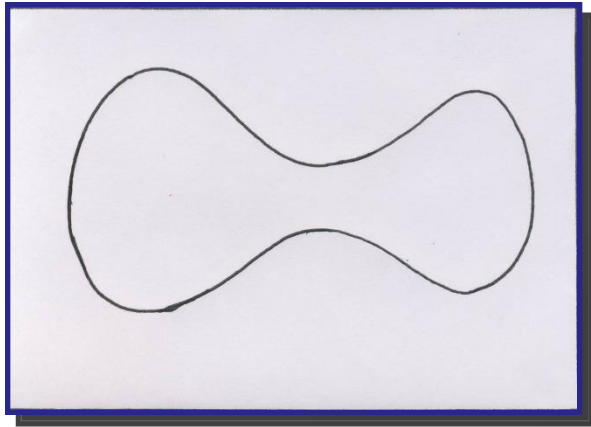
\simeq

α -complex

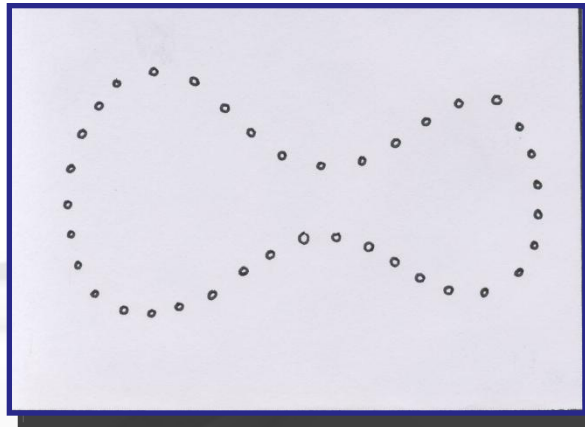


A Simple Algorithm

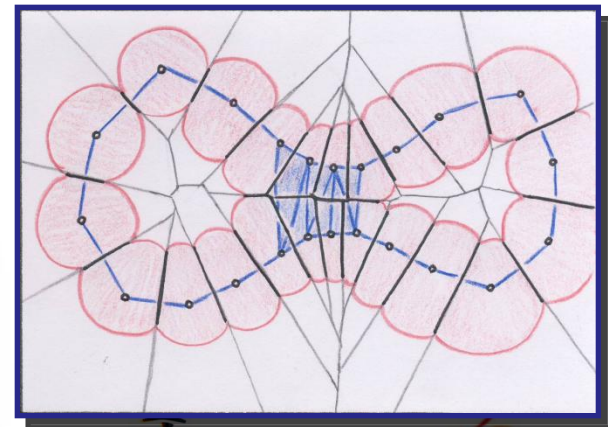
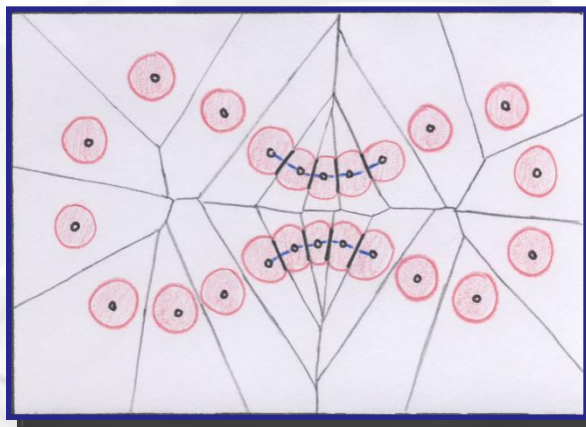
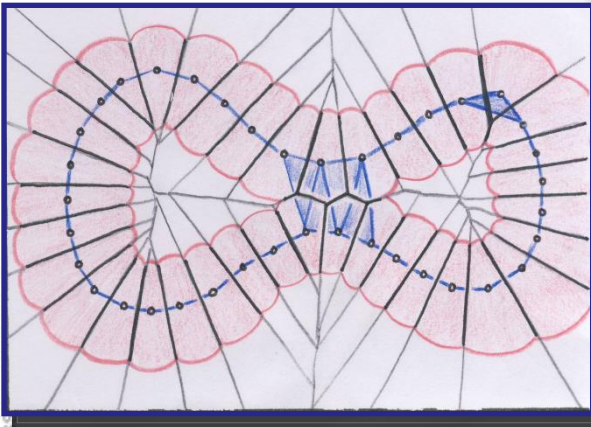
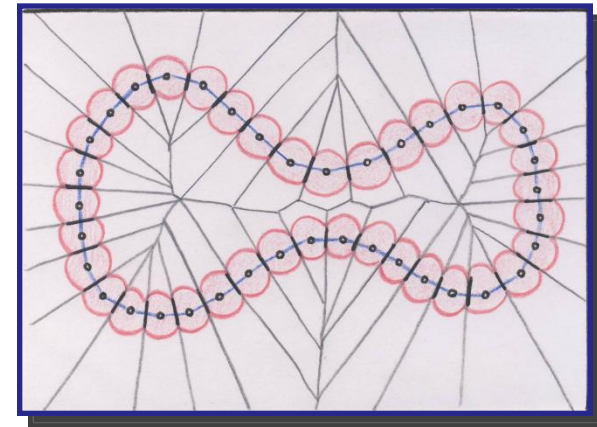
Shape

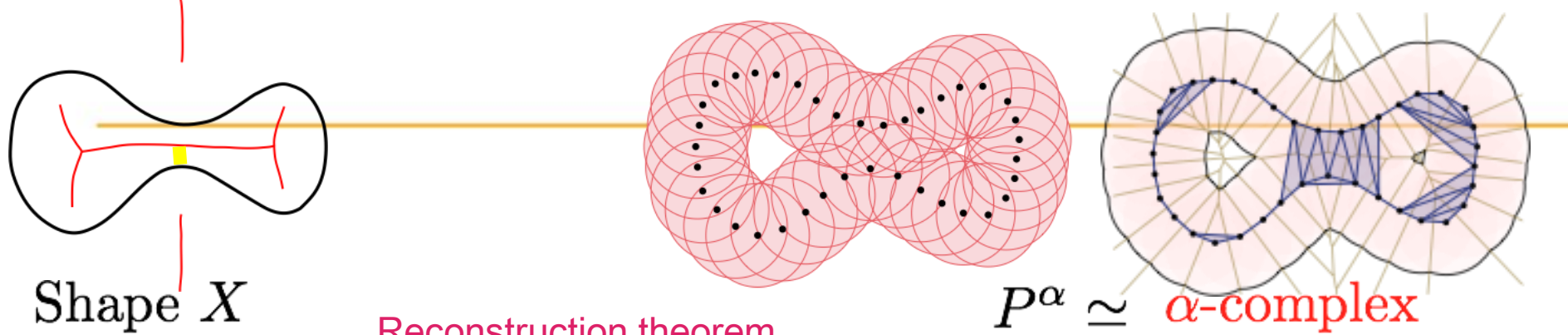


Sample



OUTPUT





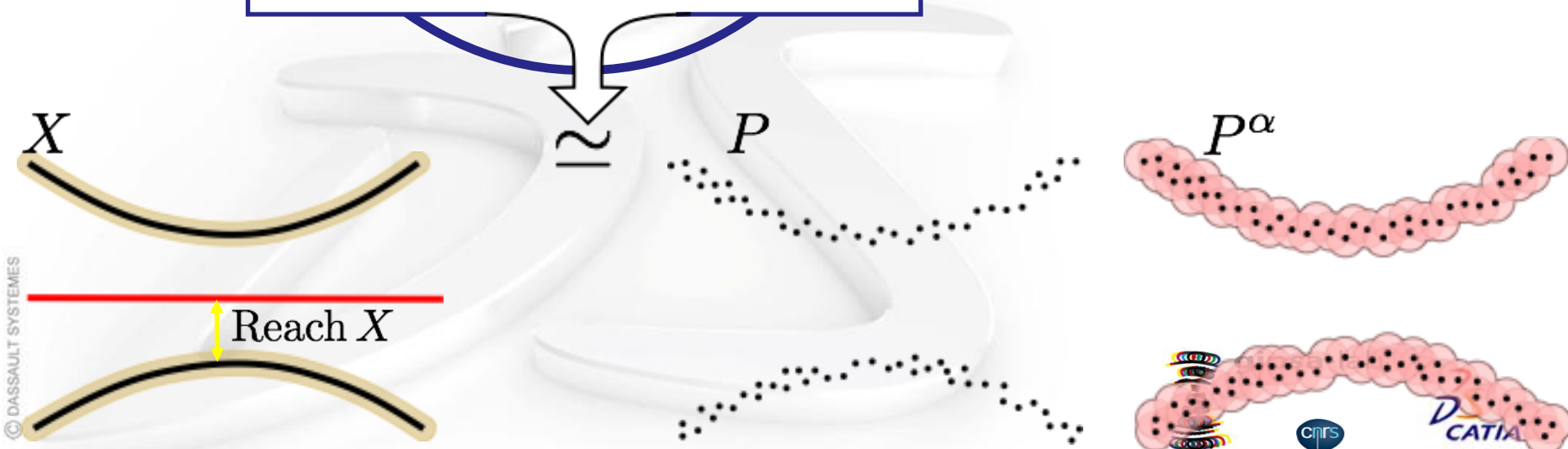
Sampling conditions

[Niyogi Smale Weinberger 2004]

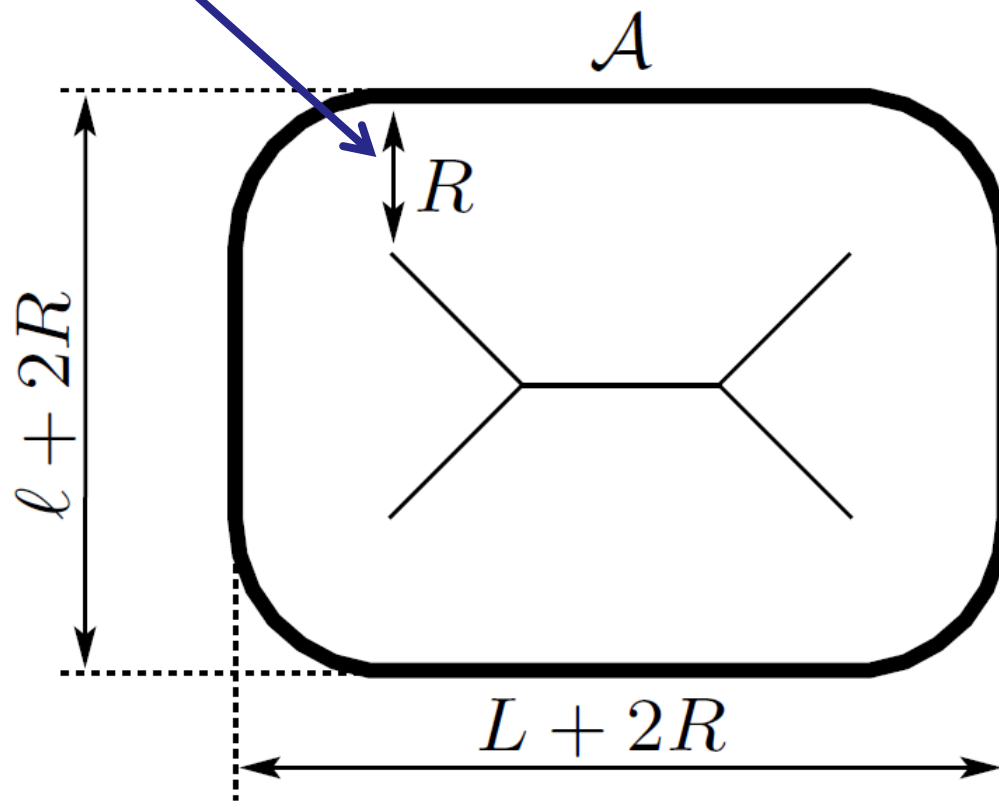
$$d_H(X, P) \leq (3 - \sqrt{8}) \text{Reach}(X)$$

$$\alpha = (2 + \sqrt{2})d_H(X, P)$$

Similar result:
Chazal Lieutier 2006

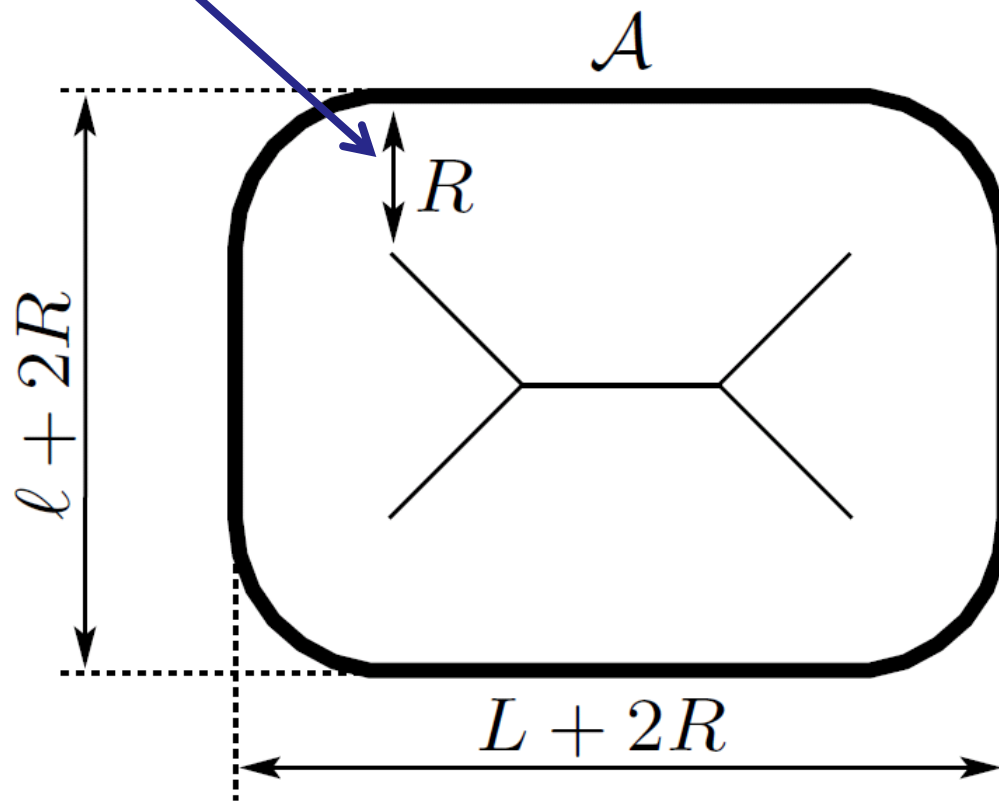


Reach(\mathcal{A})

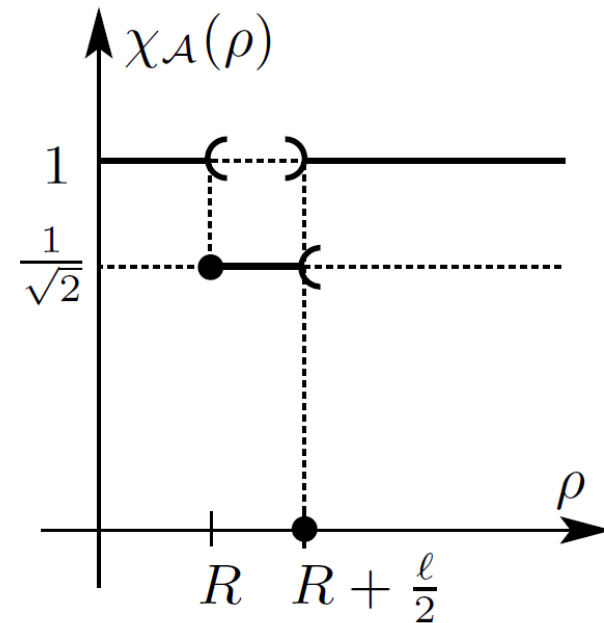
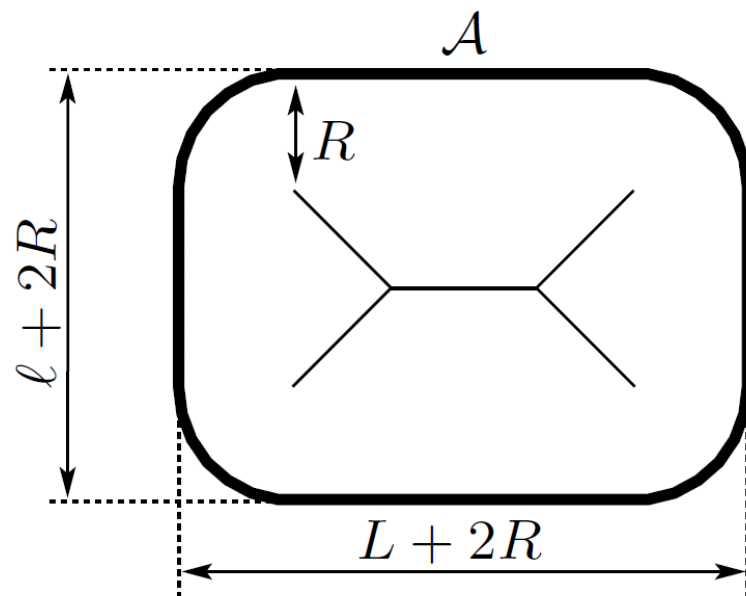


Reach(\mathcal{A})

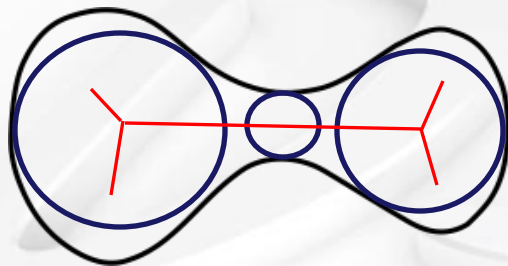
But reach vanishes on non smooth objects



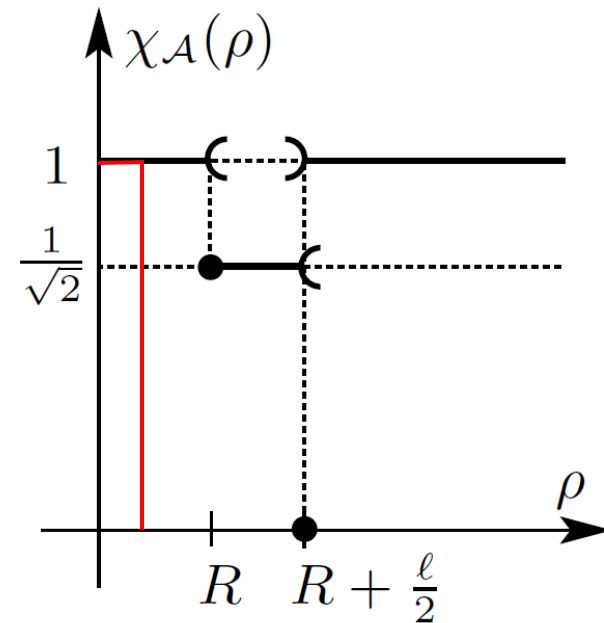
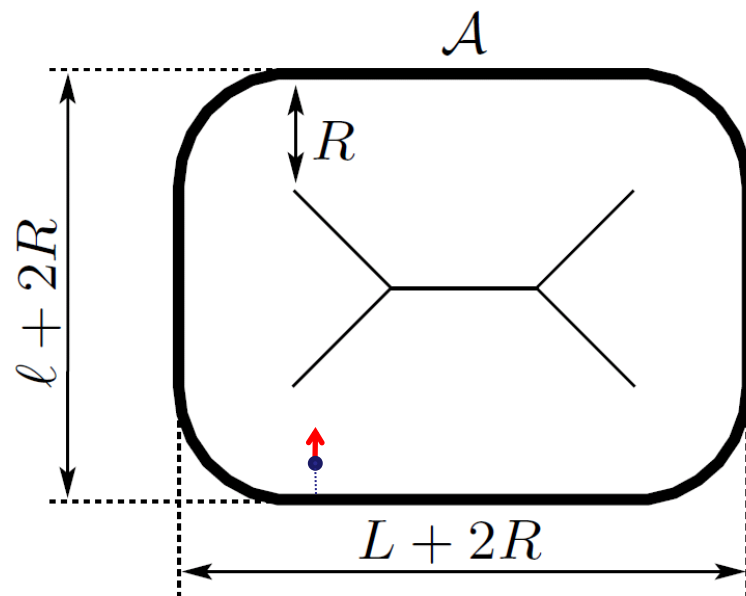
Beyond the reach : WFS and μ -reach



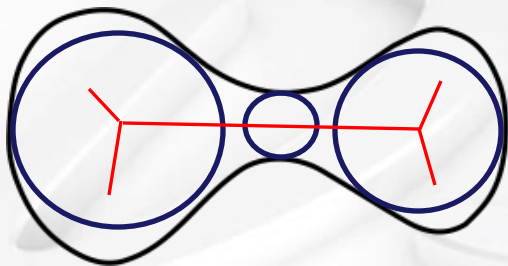
Critical function



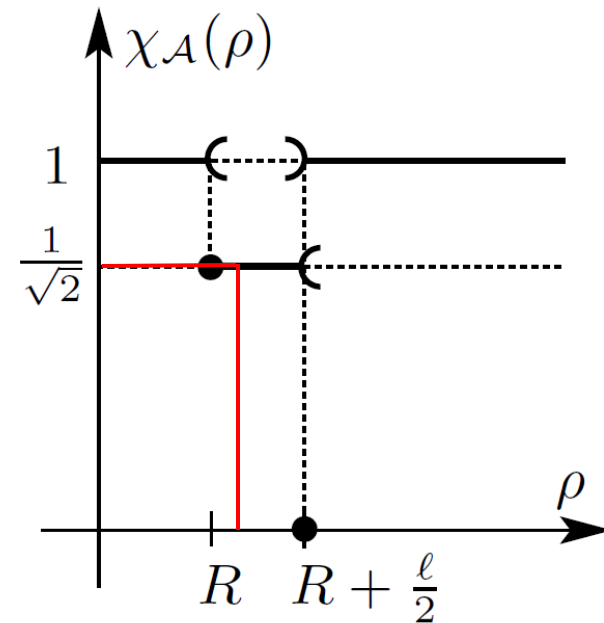
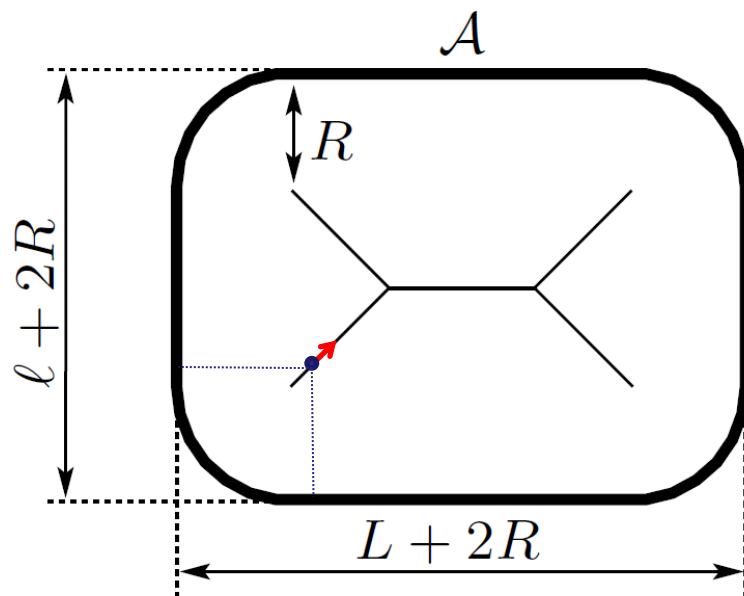
Beyond the reach : WFS and μ -reach



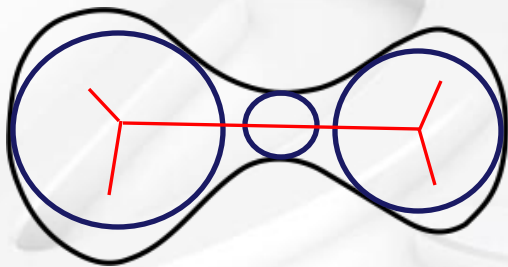
Critical function



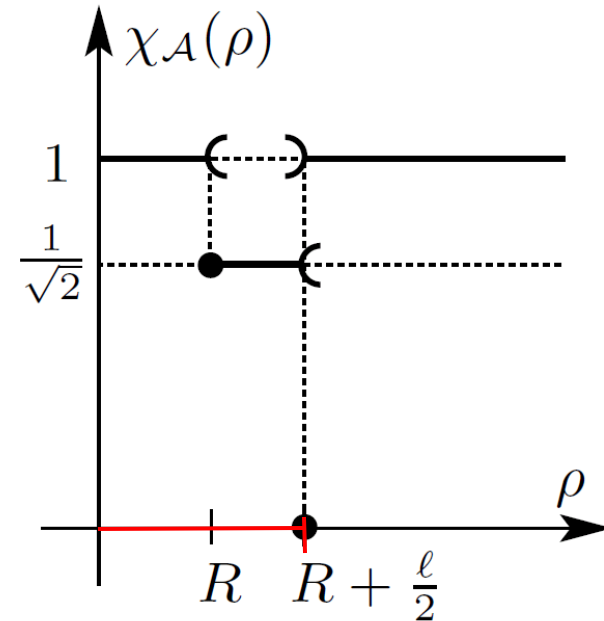
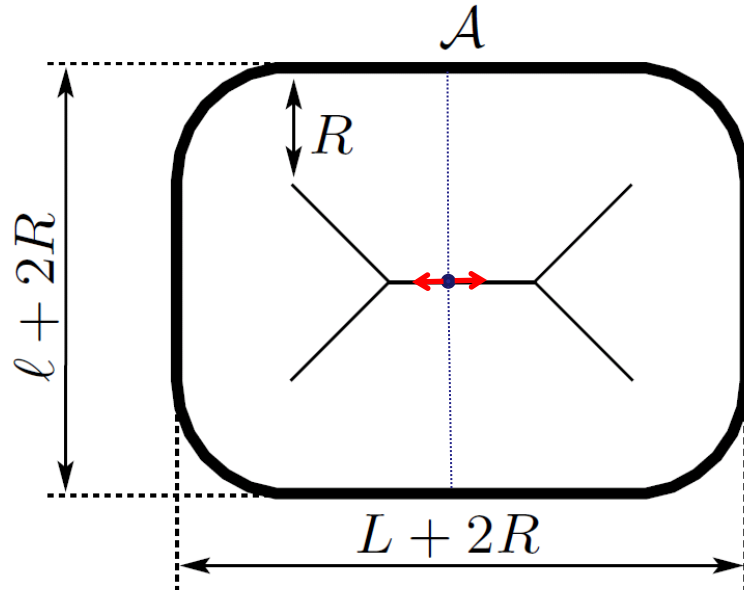
Beyond the reach : WFS and μ -reach



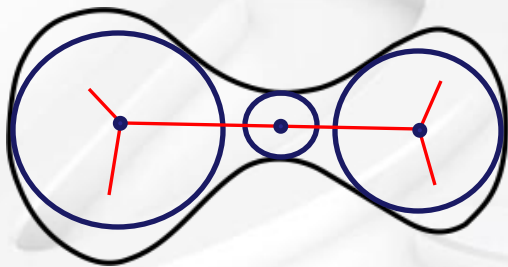
Critical function



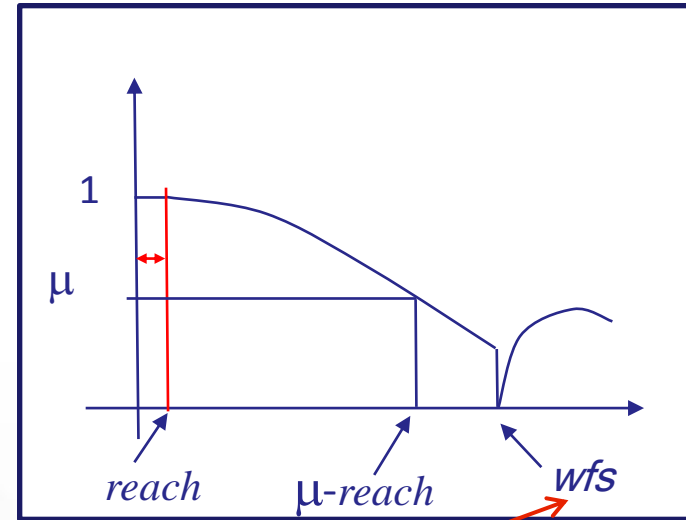
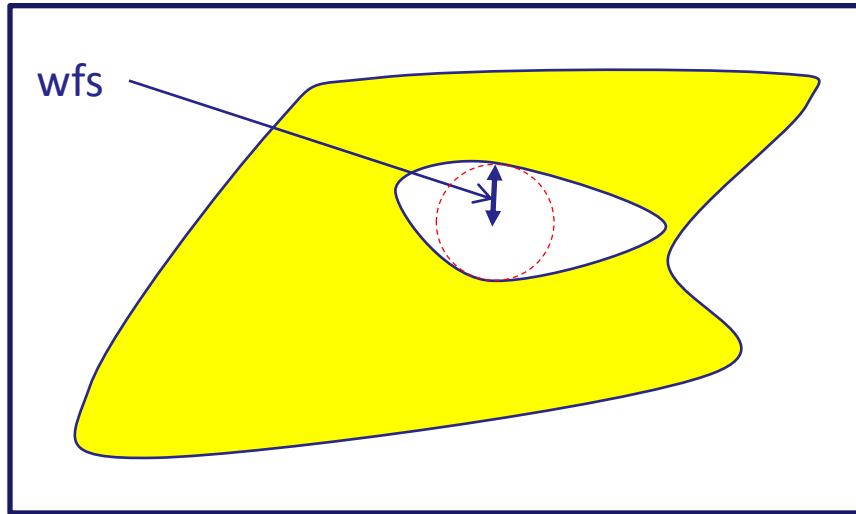
Beyond the reach : WFS and μ -reach



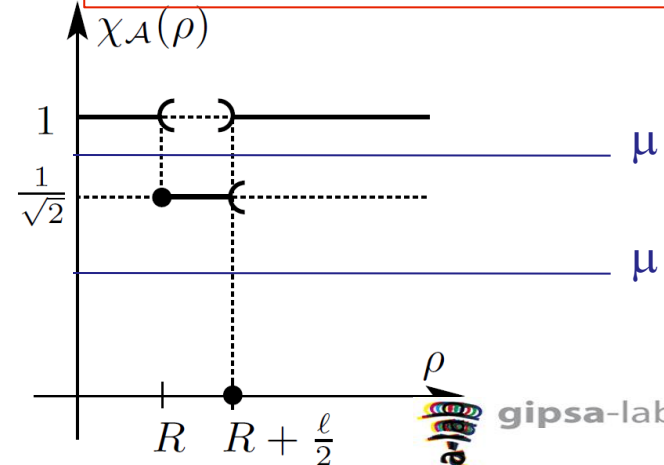
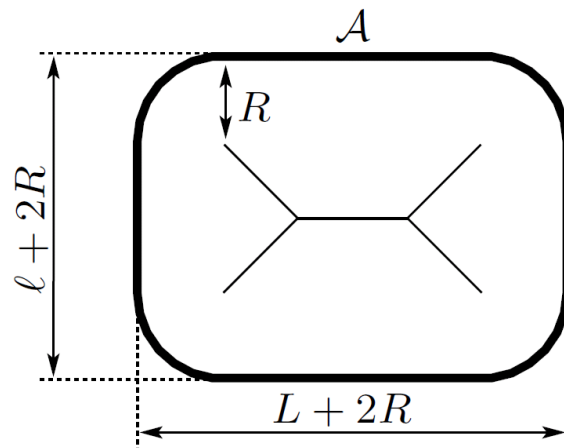
Critical function



Beyond the reach : WFS and μ -reach



First critical value of distance function



gipsa-lab



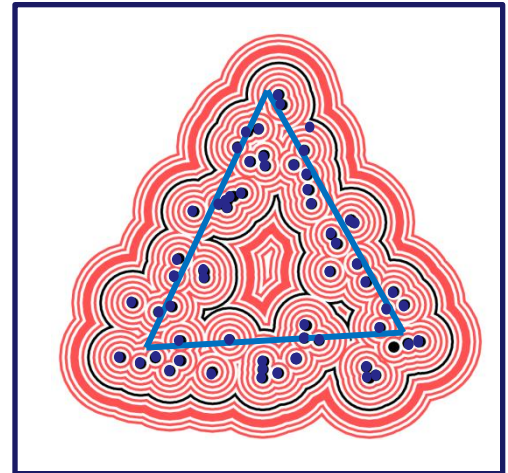
Previous best known result for faithful reconstruction of set with positive m-reach

(Chazal, Cohen-Steiner, Lieutier 2006)

Theorem 2. Let \mathcal{A} and \mathcal{S} be compact subsets of \mathbb{R}^n and a real number $\alpha > 0$ such that

$$d_H(\mathcal{S}, \mathcal{A}) < \alpha < \frac{\mu^2}{5\mu^2 + 12} r_\mu(\mathcal{A}) \quad (2)$$

Then $\mathcal{S}_{\frac{4\alpha}{\mu^2}}$ is a faithful reconstruction of \mathcal{A} .

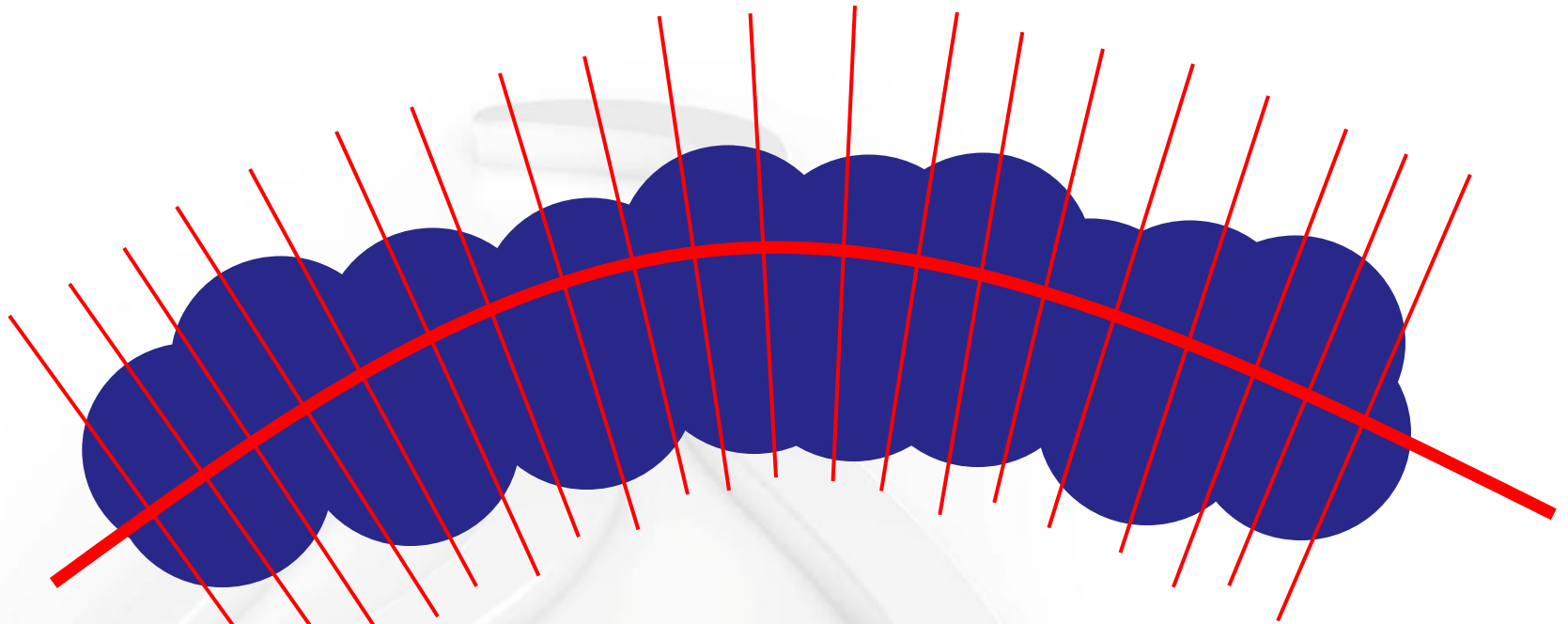


Under the conditions of the theorem, a simple offset of the sample is a faithful reconstruction

Proofs technics

Proof for Cech / α -complexes for **positive reach** (i.e. smooth) case (NSW04, CL06) relies upon :

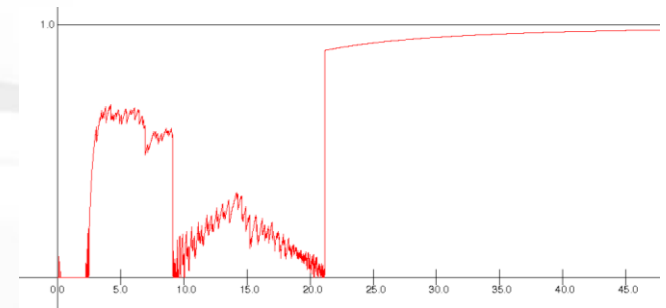
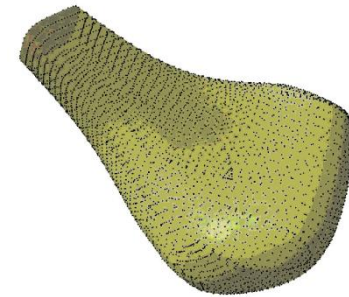
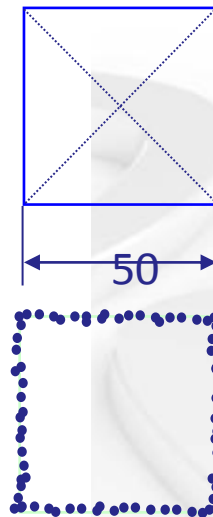
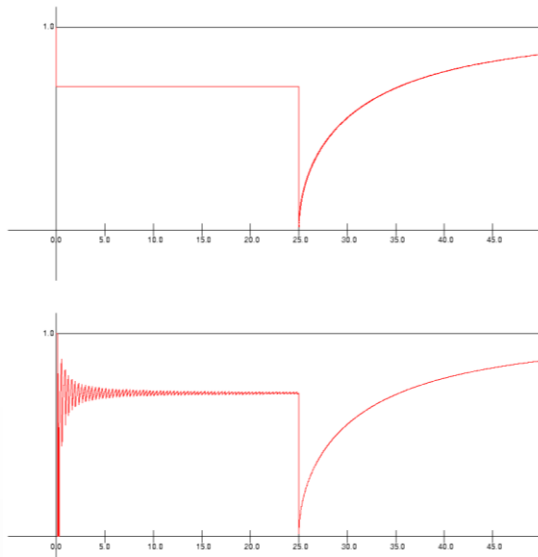
Transversality of normal fibers to union of balls boundary



Proofs technics

Proof for previous result (C.C.-S.L. 06) Cech / α -complexes for positive μ -reach case (non smooth) relies upon:

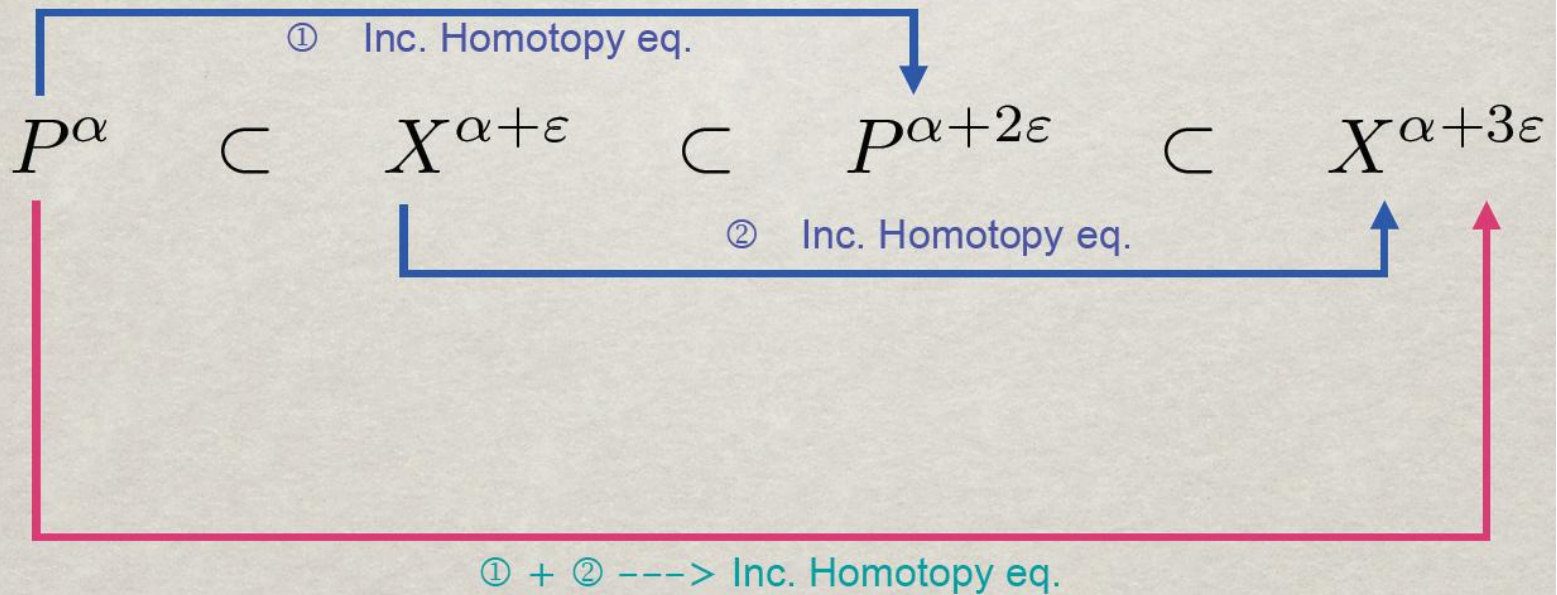
Hausdorff stability of critical function



Proofs technics

$$d_H(X, P) \leq \varepsilon$$

By Hausdorff stability of critical function

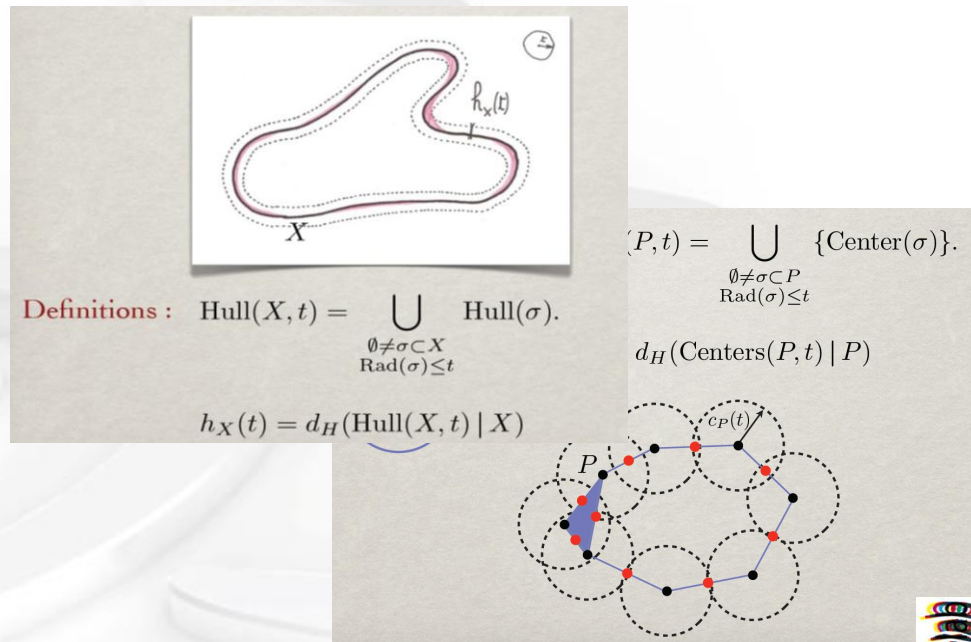


Proofs technics

New Proof Technics (socg 2011) that both:

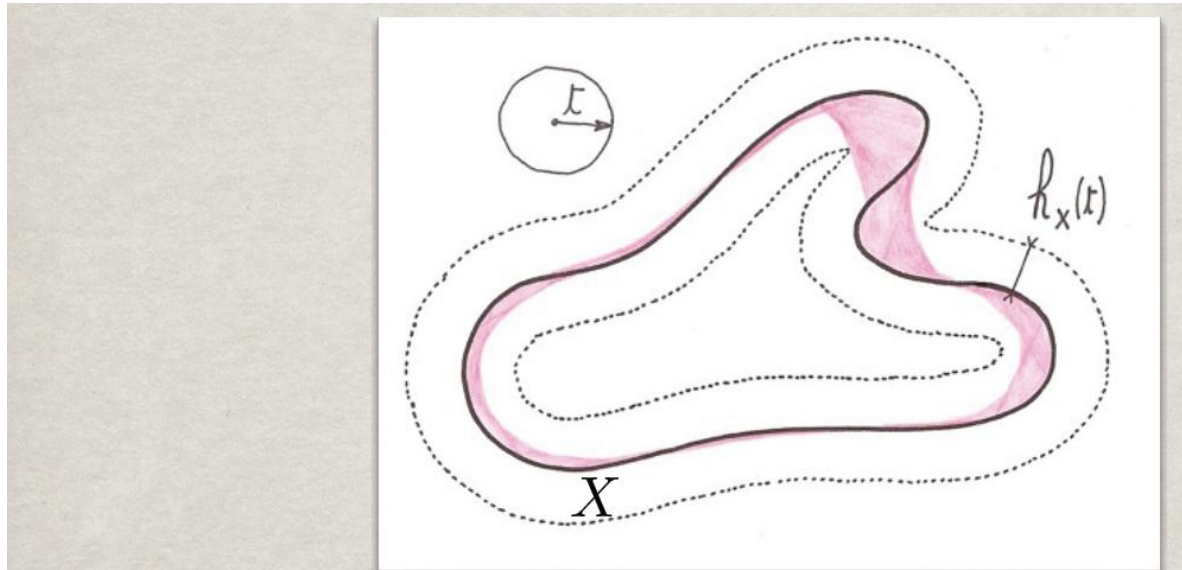
- **improves** over **previous result (C.C.-S.L. 06)** Cech / α -complexes for **positive μ -reach case** (i.e. non smooth case)
- **Extends** reconstruction theorem to **Rips complex**

Relies upon the new notion of **convexity defect functions** :



Convexity defects function

h_X : (convex Hull) convexity defect function



Definitions :
$$\text{Hull}(X, t) = \bigcup_{\substack{\emptyset \neq \sigma \subset X \\ \text{Rad}(\sigma) \leq t}} \text{Hull}(\sigma).$$

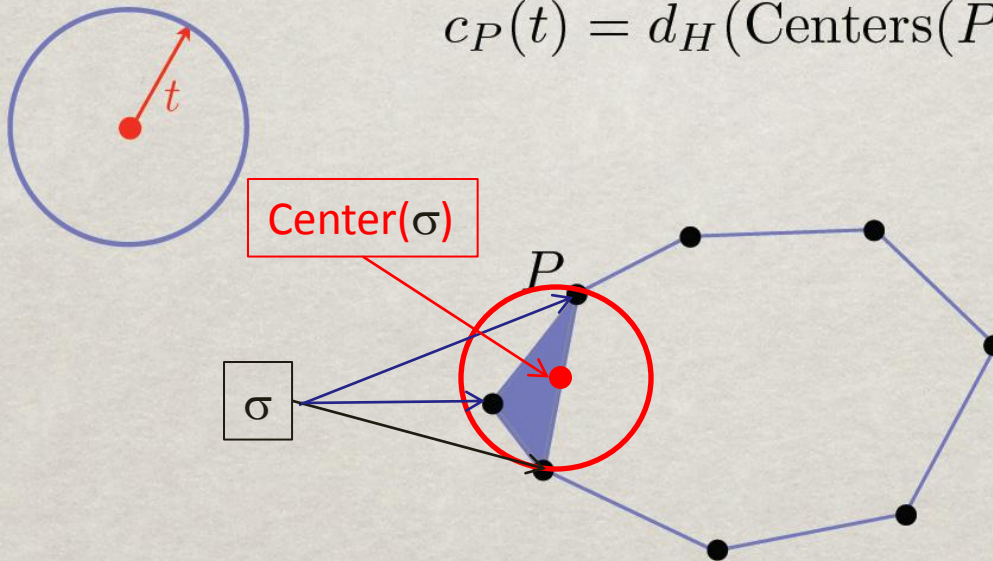
$$h_X(t) = d_H(\text{Hull}(X, t) \mid X)$$

Convexity defects function

C_P : (Center) convexity defect function

Definitions: $\text{Centers}(P, t) = \bigcup_{\substack{\emptyset \neq \sigma \subset P \\ \text{Rad}(\sigma) \leq t}} \{\text{Center}(\sigma)\}.$

$$c_P(t) = d_H(\text{Centers}(P, t) \mid P)$$



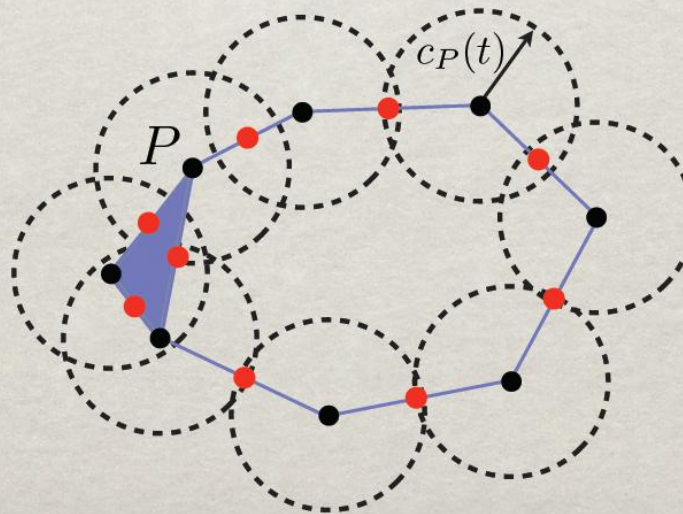
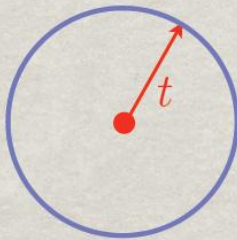
Convexity defects function

C_P : (Center) convexity defect function

Definitions:

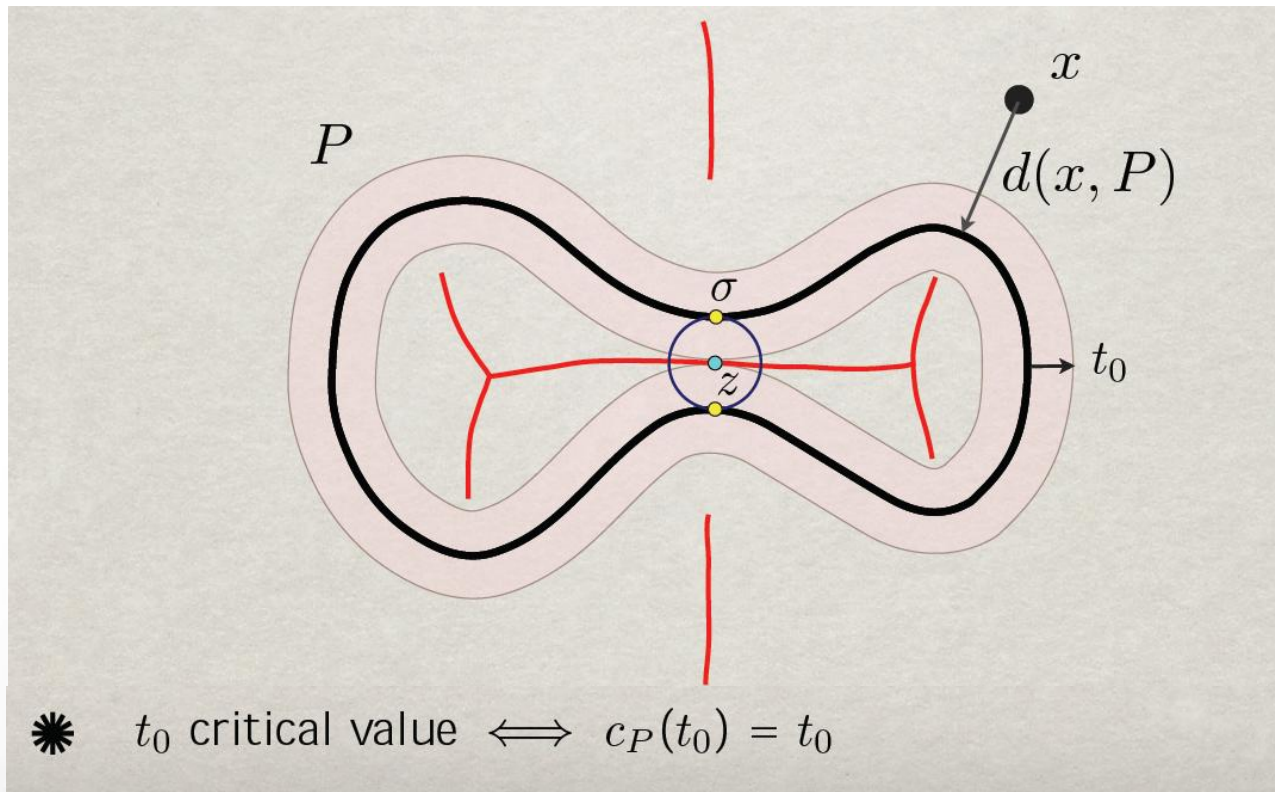
$$\text{Centers}(P, t) = \bigcup_{\substack{\emptyset \neq \sigma \subset P \\ \text{Rad}(\sigma) \leq t}} \{\text{Center}(\sigma)\}.$$

$$c_P(t) = d_H(\text{Centers}(P, t) \mid P)$$



Convexity defects function

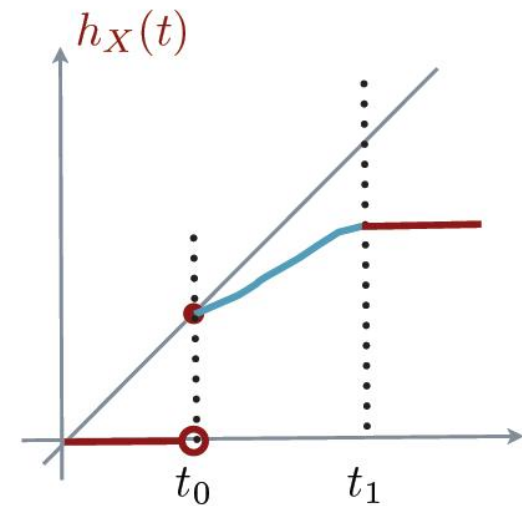
h_x : (convex Hull) convexity defect function



Convexity defects function

Properties:

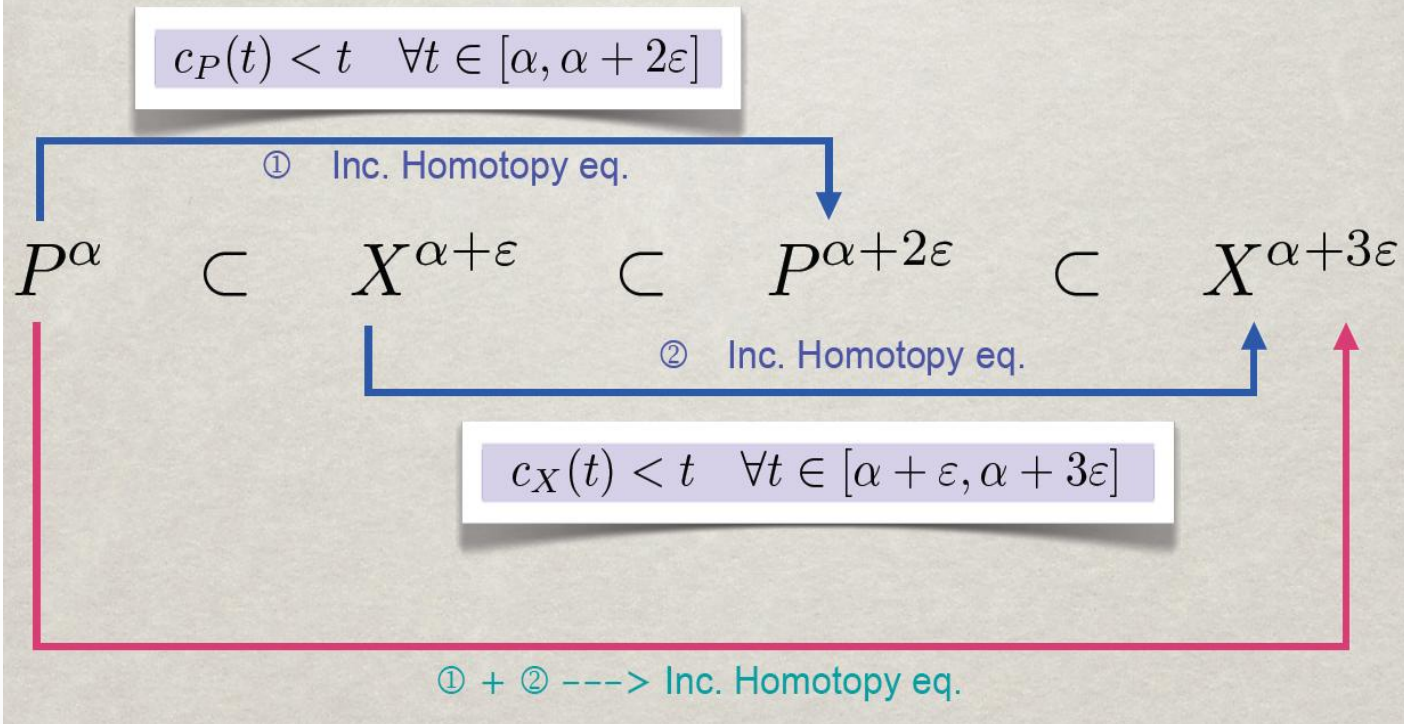
- * If X compact, then
 X convex $\iff h_X = 0$
- * h_X non decreasing
- * $c_X(t) \leq h_X(t) \leq t$
- * $h_X(t) = t$ iff t critical value of $d(\cdot, X)$
- * $d_H(X, P) \leq \varepsilon \Rightarrow h_P(t) \leq h_X(t + \varepsilon) + 2\varepsilon$



Hausdorff stability of defects of convexity

Convexity defects function

$$d_H(X, P) \leq \varepsilon$$



Convexity defects function

$$d_H(X, P) \leq \varepsilon$$

$$h_P \quad \cancel{c_P(t) < t} \quad \forall t \in [\alpha, \alpha + 2\varepsilon]$$

① Inc. Homotopy eq.

$$P^\alpha \subset X^{\alpha+\varepsilon} \subset P^{\alpha+2\varepsilon} \subset X^{\alpha+3\varepsilon}$$

② Inc. Homotopy eq.

$$h_X \quad \cancel{c_X(t) < t} \quad \forall t \in [\alpha + \varepsilon, \alpha + 3\varepsilon]$$

① + ② ----> Inc. Homotopy eq.

$$h_X(t) < t - 3\varepsilon \quad \forall t \in [\alpha + \varepsilon, \alpha + 3\varepsilon]$$

Large μ -reach

=> small convexity defect functions

LEMMA 6. Consider two real numbers $\mu \in (0, 1]$ and $R \geq 0$. Let $X \subset \mathbb{R}^n$ be a compact set such that $\chi_X(t) \geq \mu$ for all $t \in (0, R)$. Then, for all $0 \leq t \leq R$, one has:

$$h_X(t) \leq \frac{1 + \mu(1 - \mu) - \sqrt{1 - \mu(2 - \mu) \left(\frac{t}{R}\right)^2}}{\mu(2 - \mu)} R.$$

Small convexity defect functions

=> Large critical function and therefore large μ -reach

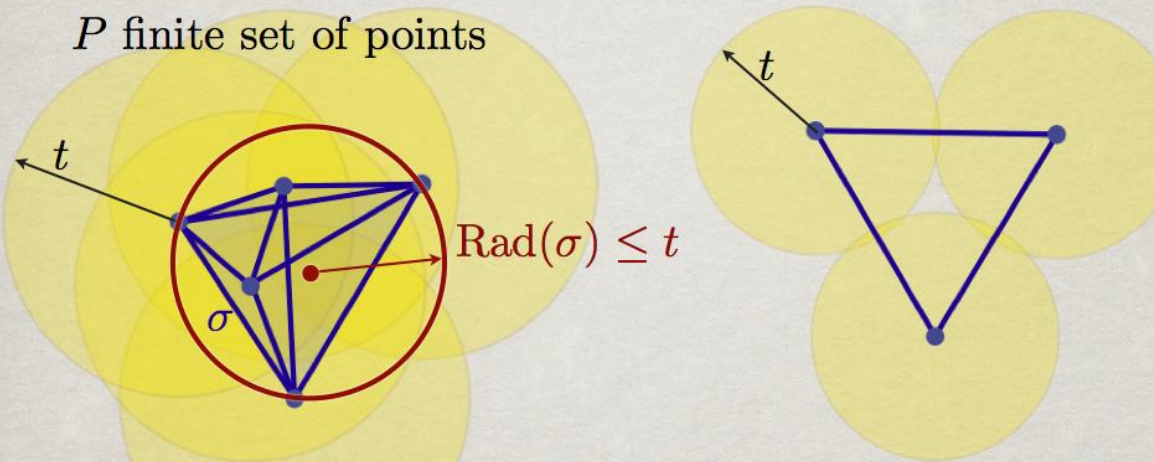
LEMMA 5. For all compact set $X \subset \mathbb{R}^n$, all $0 \leq \mu \leq 1$ and all $t \geq 0$, the following implication holds:

$$c_X(t) < (1 - \mu)t \implies \chi_X(t) > \mu.$$

Union of balls $\approx \alpha$ -complex \approx Cech complex

CECH COMPLEX

P finite set of points



$\text{Rad}(\sigma) \leq t$

$\text{Rad}(\sigma)$ = radius of smallest enclosing ball

$\mathcal{C}(P, t) = \{\sigma \mid \emptyset \neq \sigma \subset P, \text{Rad}(\sigma) \leq t\}.$

$\mathcal{C}(P, t) = \text{Nerve} \{B(p, t) \mid p \in P\}$

$|\mathcal{C}(P, t)|$ homotopy equivalent to $\bigcup B(p, t) = P^t$

Convexity defects function

Small defect of convexity

=> Rips complexes **collapses** on Čech complexes

Theorem 1. Let $P \subset \mathbb{R}^d$ be a finite set of points in general position. If

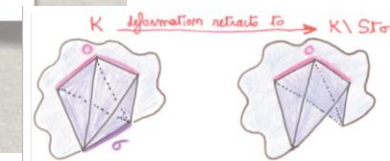
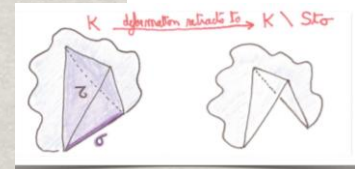
$$c_P(\sqrt{2}\alpha) < 2\alpha - \sqrt{2}\alpha$$

there exists a sequence of collapses from the Rips complex $\mathcal{R}(P, \alpha)$ to the Čech complex $\mathcal{C}(P, \alpha)$.

Proof. (1) sequence of (classical) collapses

$$\mathcal{C}(P, \alpha) \subset \mathcal{R}(P, \alpha) \subset \mathcal{C}(P, \sqrt{2}\alpha)$$

(2) sequence of (extended) collapses



Cech / Rips

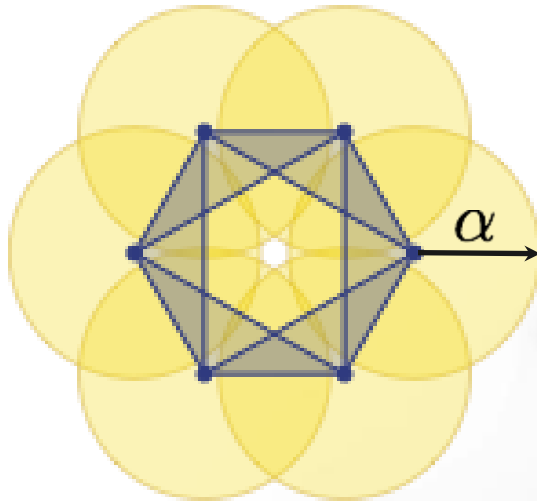
$\mathcal{C}(P, \alpha)$

\subset

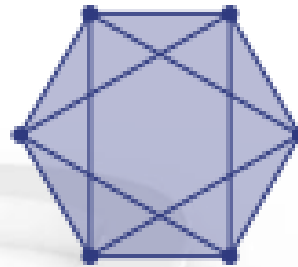
$\mathcal{R}(P, \alpha)$

\subset

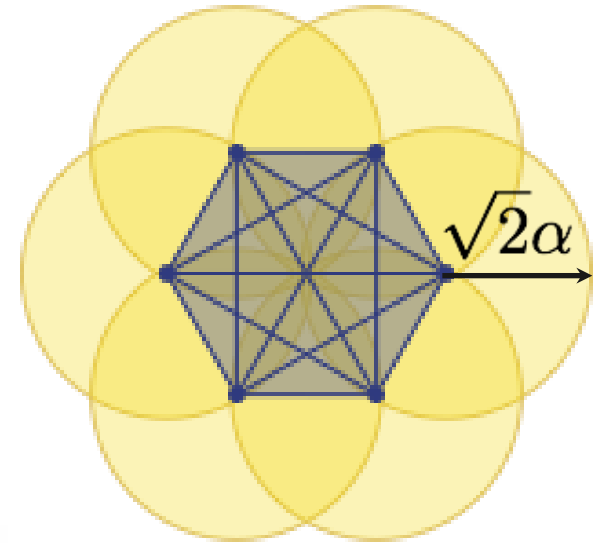
$\mathcal{C}(P, \sqrt{2}\alpha)$



\simeq circle

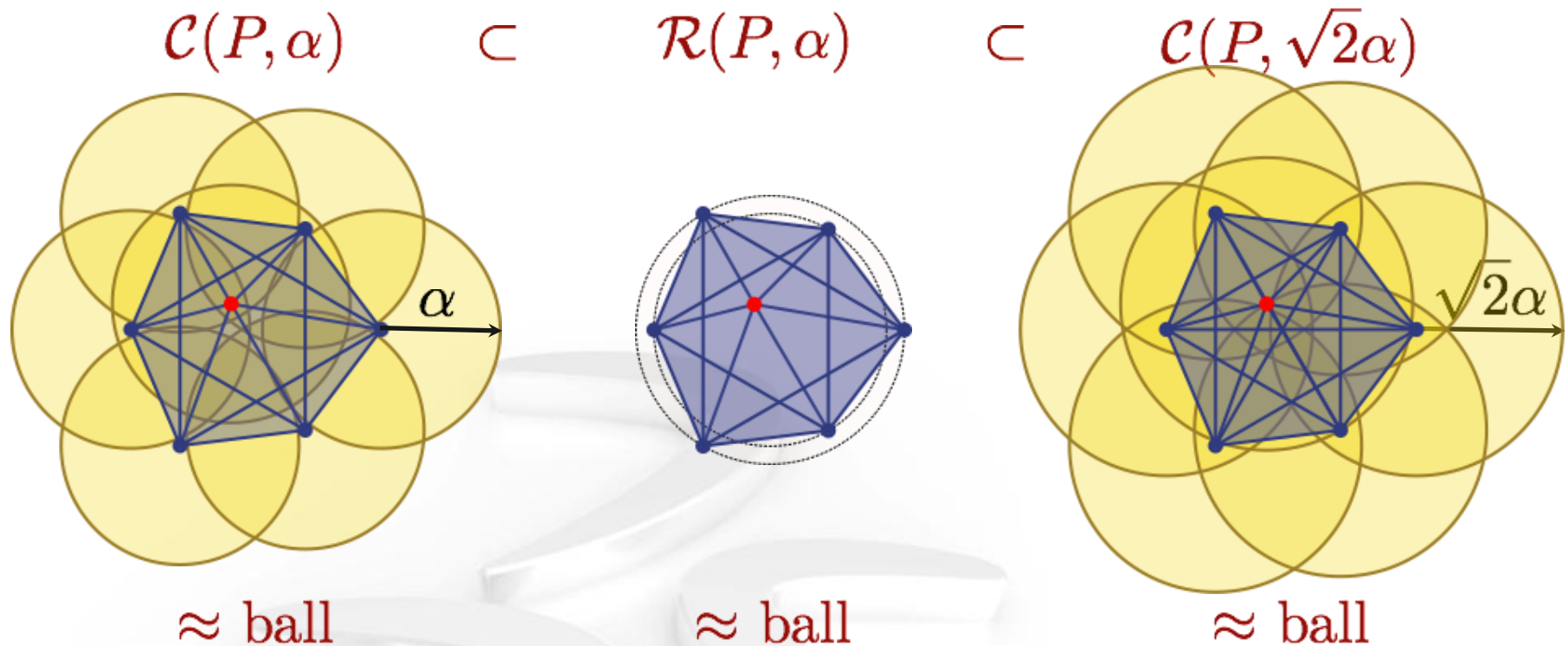


\approx sphere



\approx ball

Cech / Rips

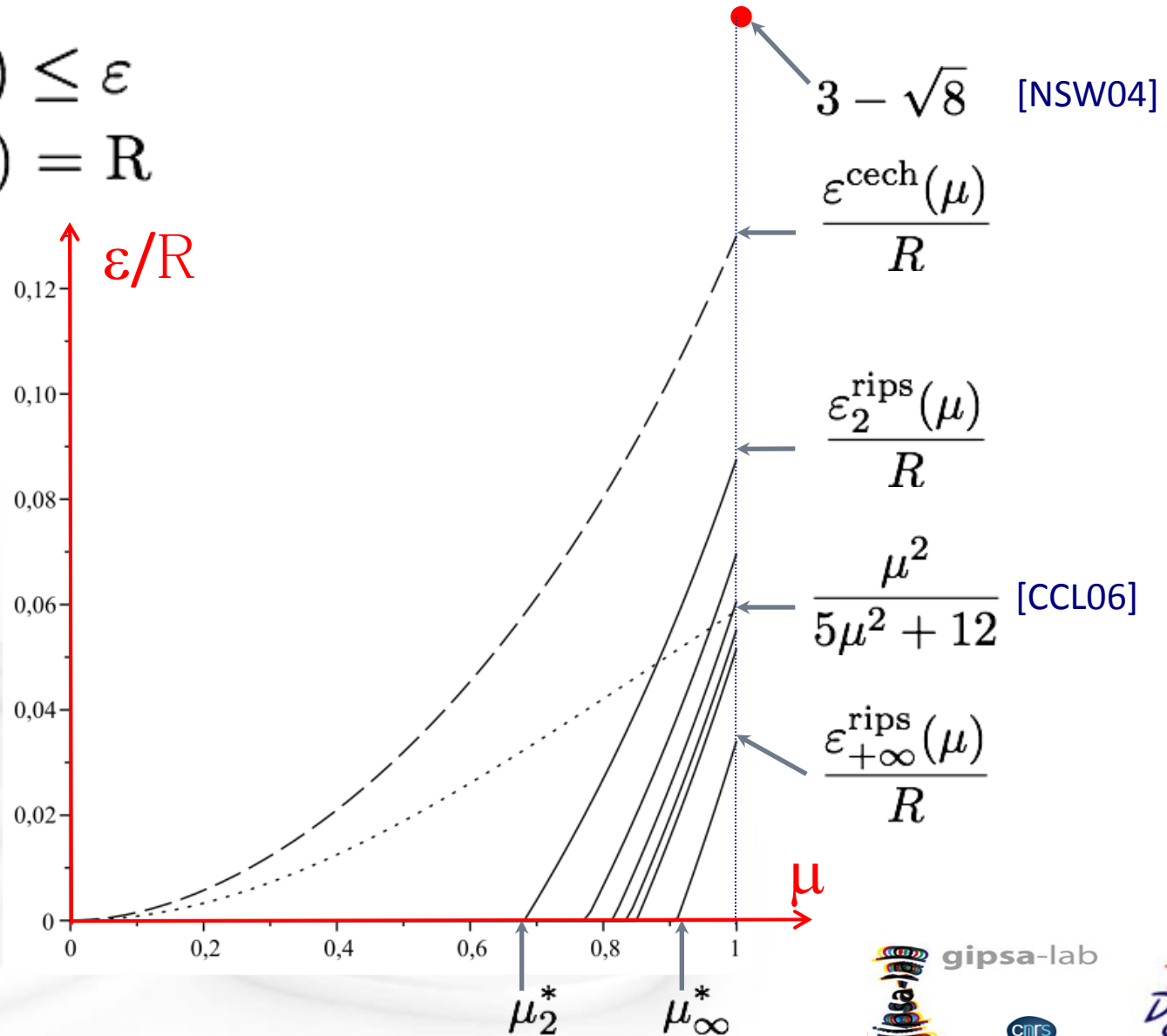


Had there been a point close to the center, it would have destroyed spurious cycles appearing in the Rips, without changing the Cech.

Sampling conditions for Cech and Rips

$$d_H(X, P) \leq \varepsilon$$

$$\mu\text{-reach}(X) = R$$



Questions ?



Questions ?

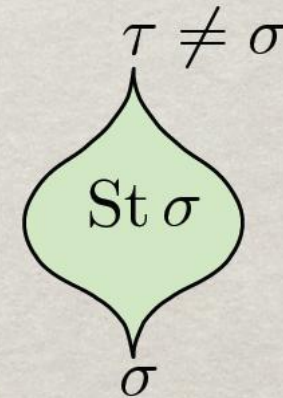
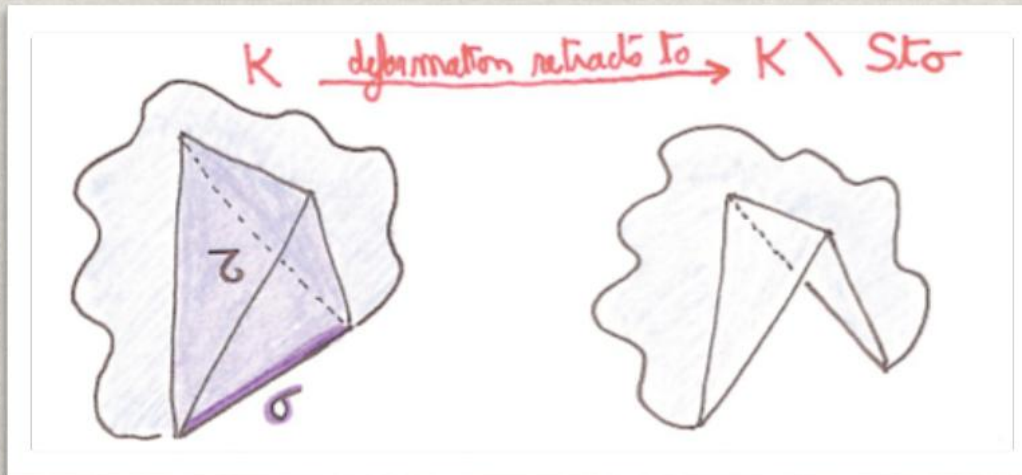


CLASSICAL COLLAPSES

$\text{St}_K(\sigma) = \text{set of cofaces of } \sigma$

K deformation retracts to $K \setminus \text{St}_K(\sigma)$

provided that $\text{St}_K(\sigma)$ has a **unique** maximal simplex $\tau \neq \sigma$

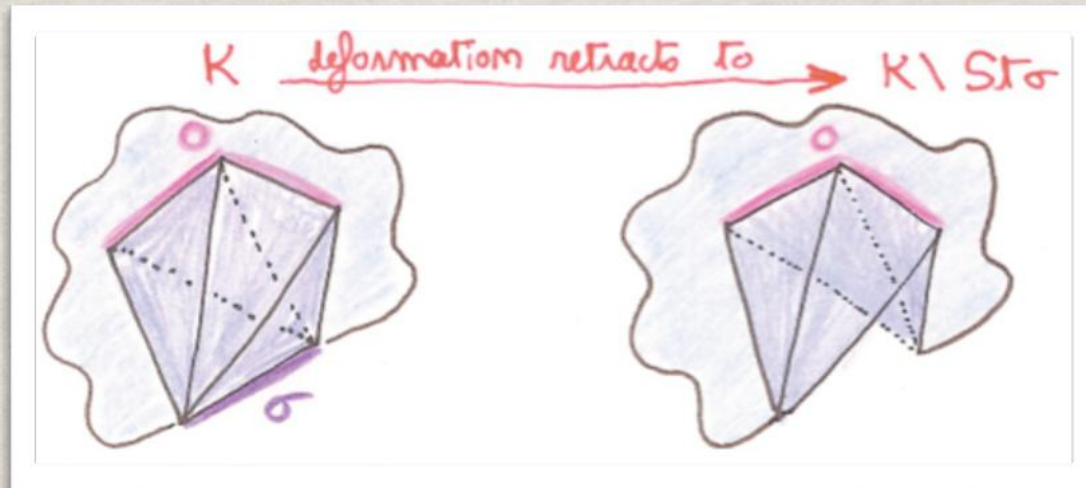


EXTENDED COLLAPSES

$\text{St}_K(\sigma) = \text{set of cofaces of } \sigma$

K deformation retracts to $K \setminus \text{St}_K(\sigma)$

provided that link of σ is a cone

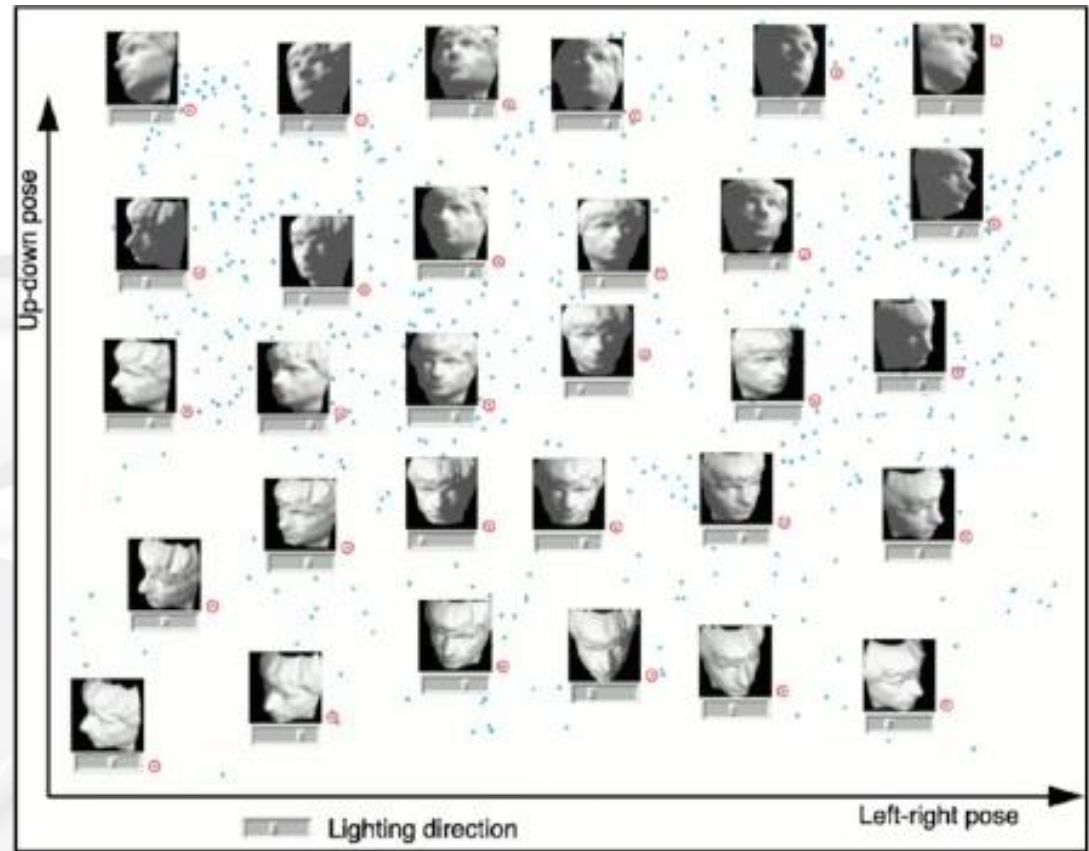


Shape Reconstruction (or manifold learning)

INPUT



OUTPUT

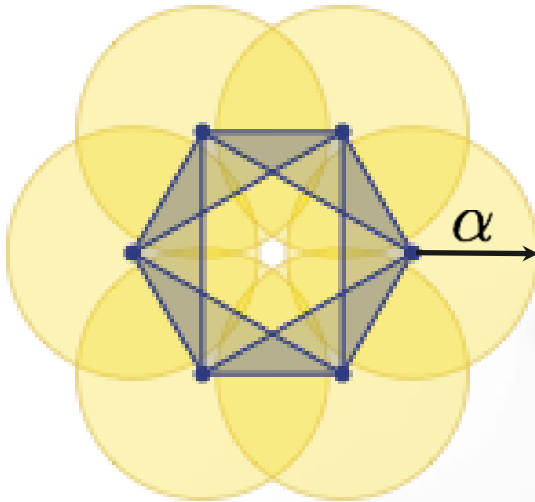


Unordered sequence
of images varying
in pose and lighting

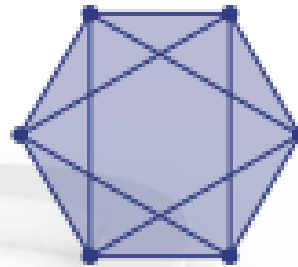
Low-dimensional complex

Cech / Rips

$$\mathcal{C}(P, \alpha) \neq \mathcal{R}(P, \alpha)$$



\simeq circle



\approx sphere

Rips and Čech complexes generally don't share **the same topology, but ...**