

Workshop on Computational Topology – November 7-11, 2011

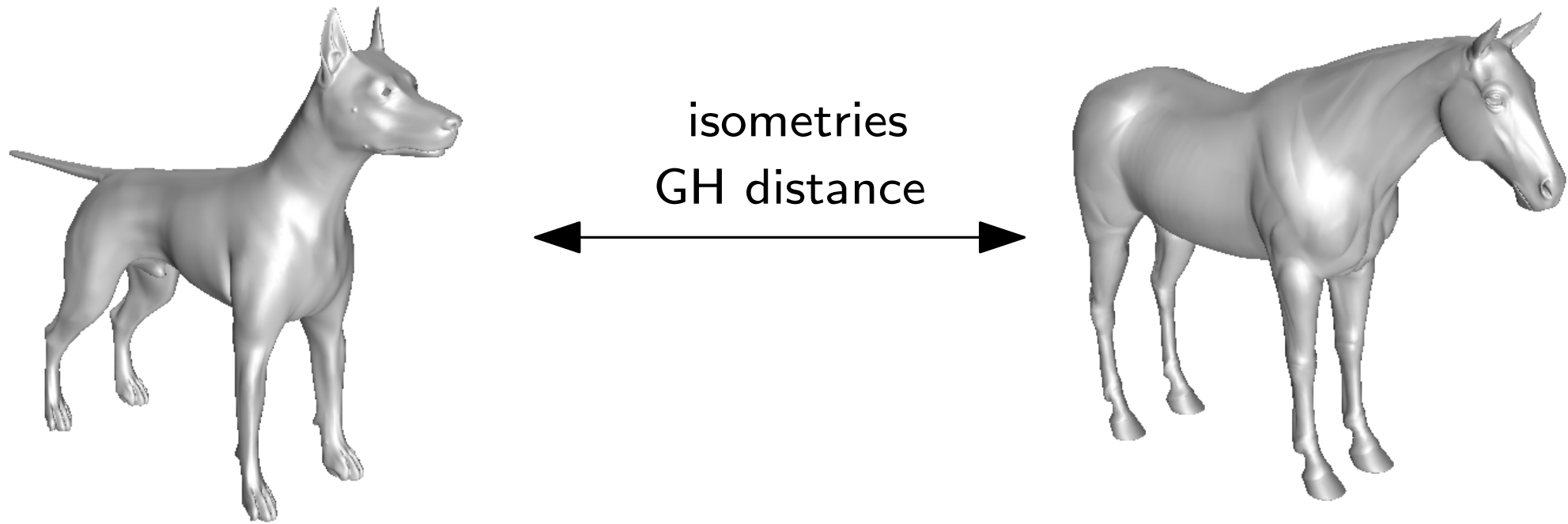
Stable Multi-Scale Signatures for Shapes using Topological Persistence

Steve Oudot – Geometrica group, INRIA Saclay – Île-de-France

joint work (still in progress..) with Frédéric Chazal and Alexandre Bos



Comparing Shapes via Signatures



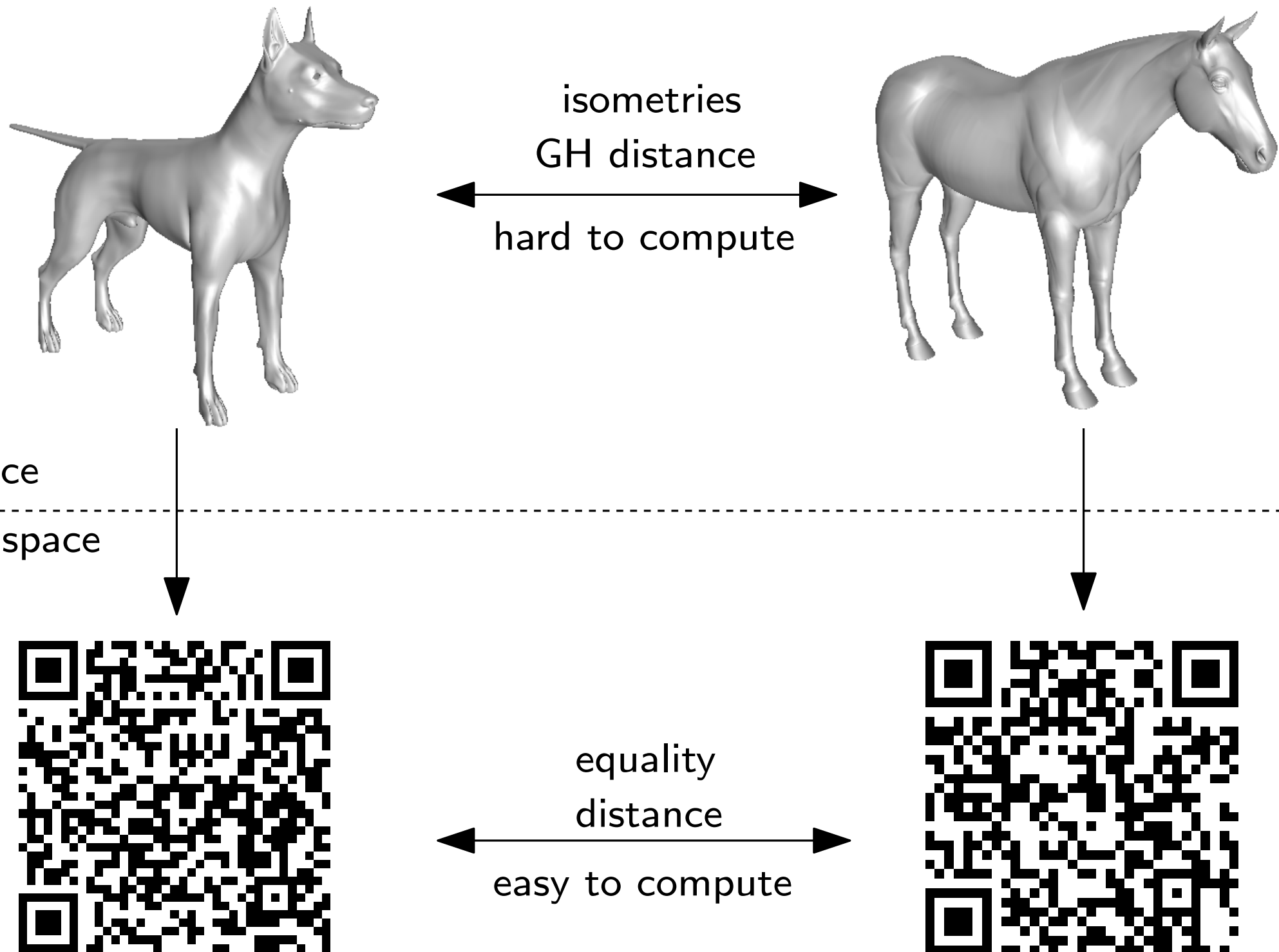
shapes space

Mathematical formulation:

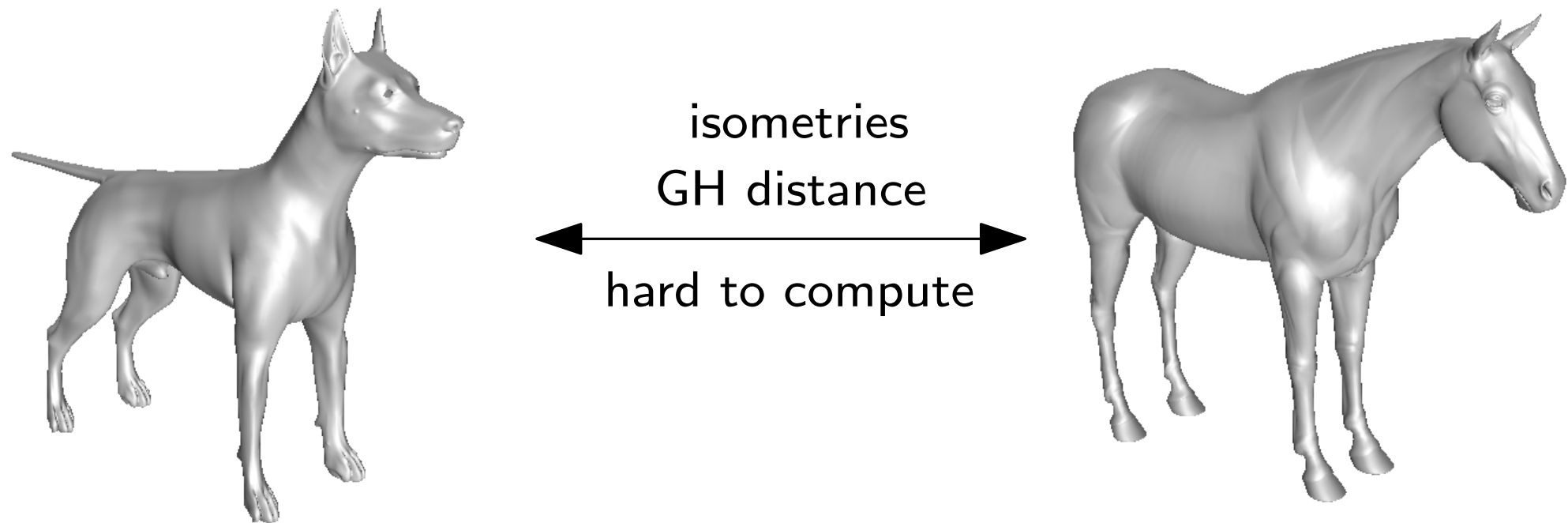
shapes \equiv compact metric spaces

distance between shapes \equiv Gromov-Hausdorff (GH) distance

Comparing Shapes via Signatures



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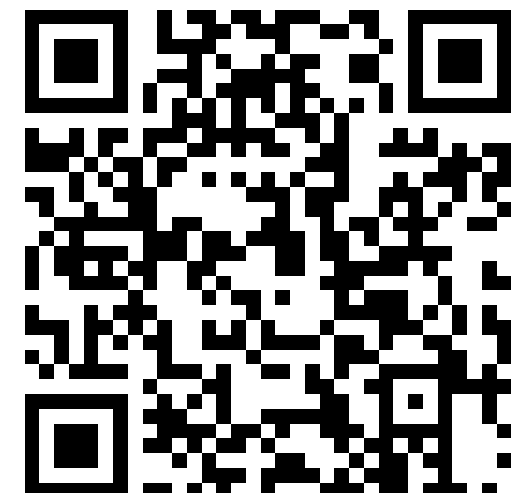
isometries
GH distance

hard to compute

shapes space

Ideally, signatures distance = GH distance

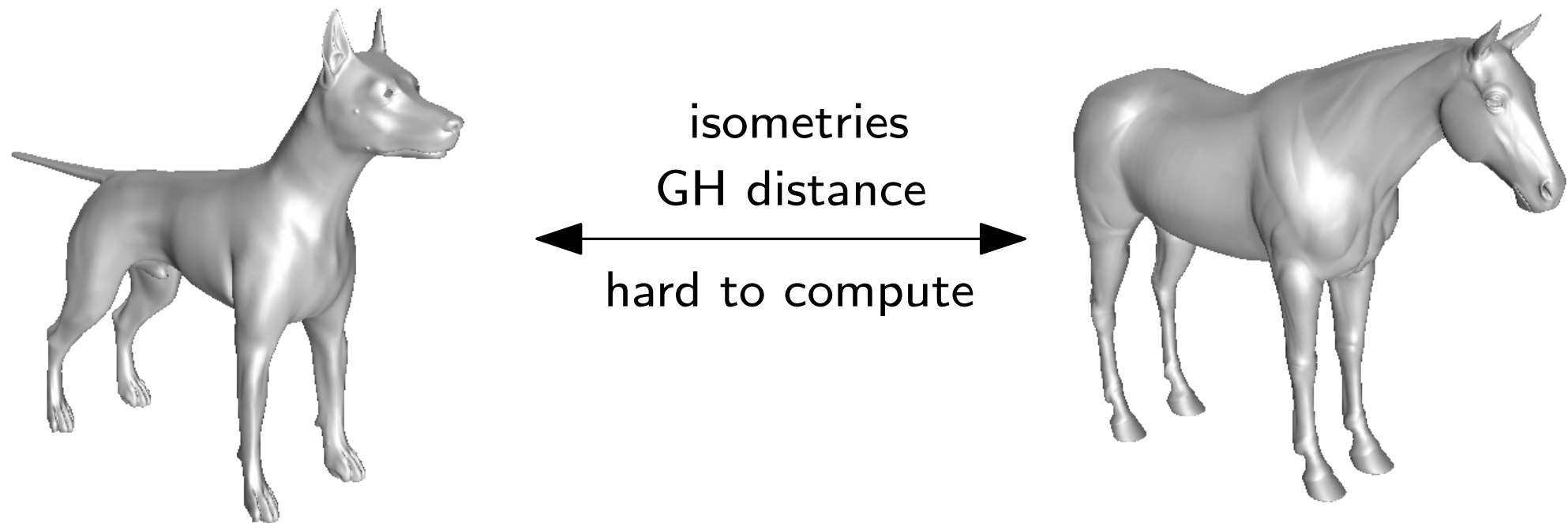
signatures space



equality
distance

easy to compute

Comparing Shapes via Signatures



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In reality,

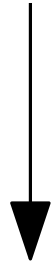
\leq



equality
distance
easy to compute

Persistence: from Signatures for Functions...

$f : X \rightarrow \mathbb{R}$ tame

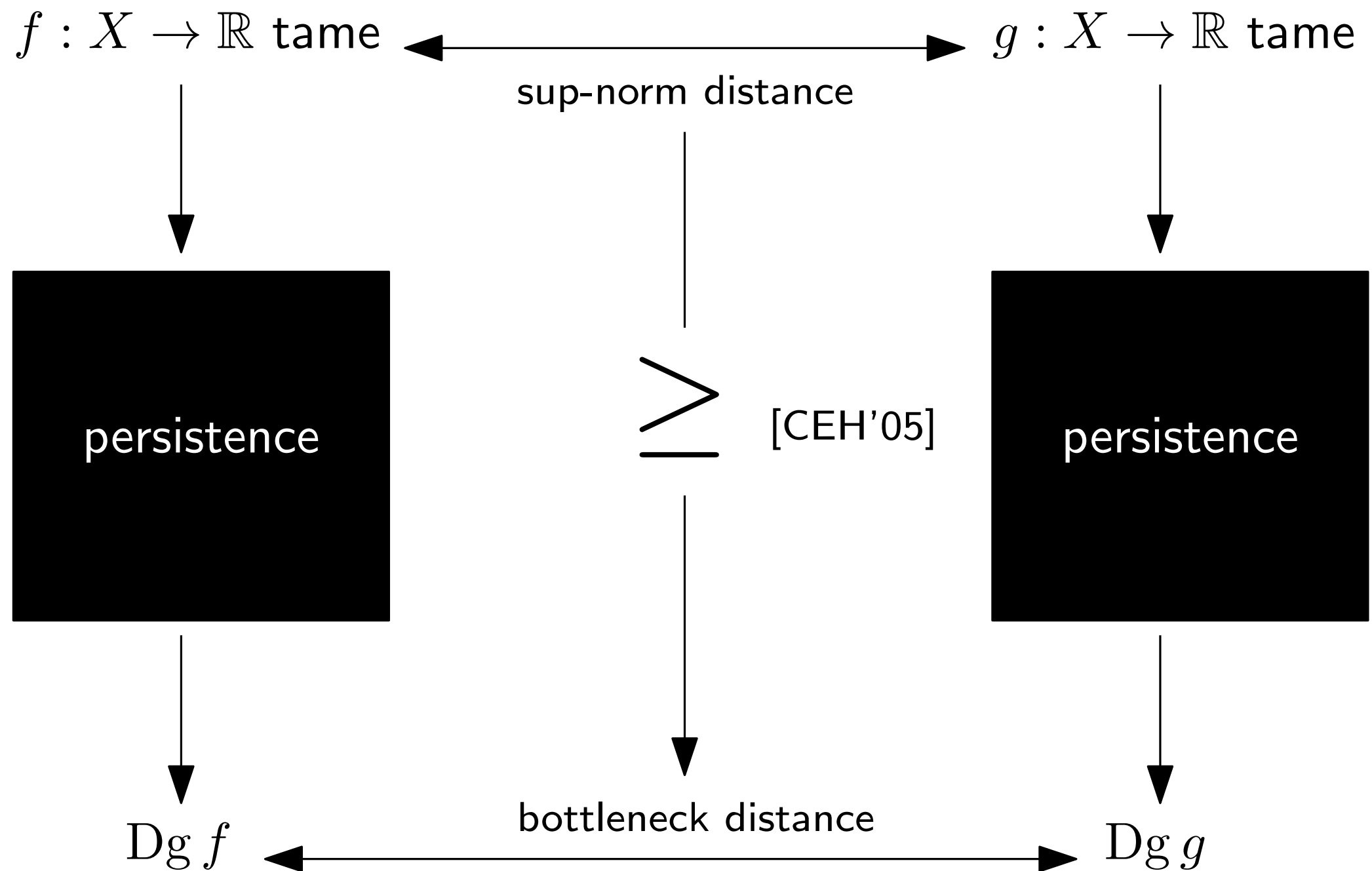


persistence

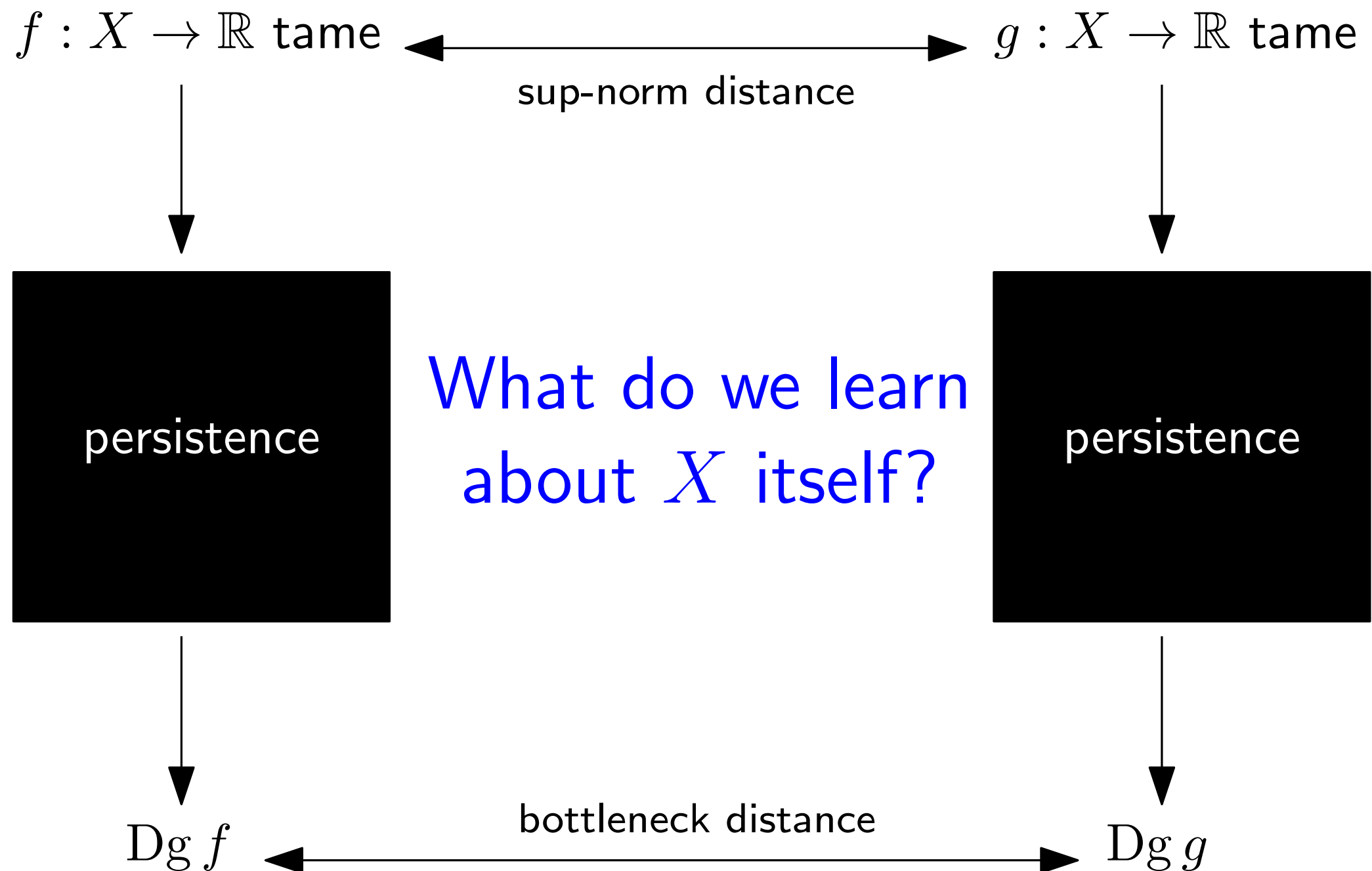


$\text{Dg } f$

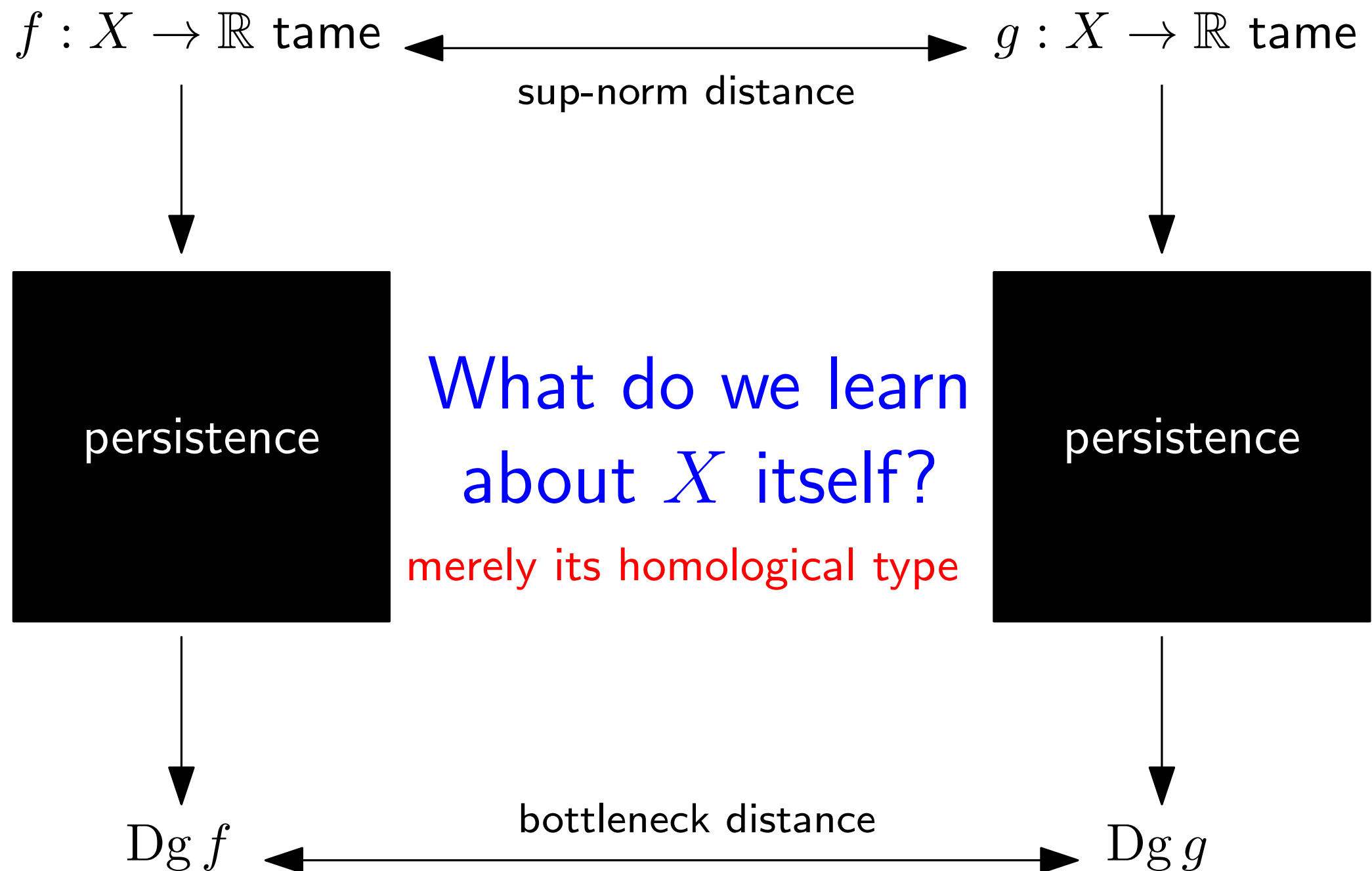
Persistence: from Signatures for Functions...



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Persistence: from Signatures for Functions...



... to Signatures for Spaces

Input: a compact metric space (X, d_X)

Parameter: a Lipschitz continuous function $f : X \rightarrow \mathbb{R}$ *derived from* d_X

Signature: $Dg f$

Our hope: that $Dg f$ reveals part of the structure of (X, d_X)

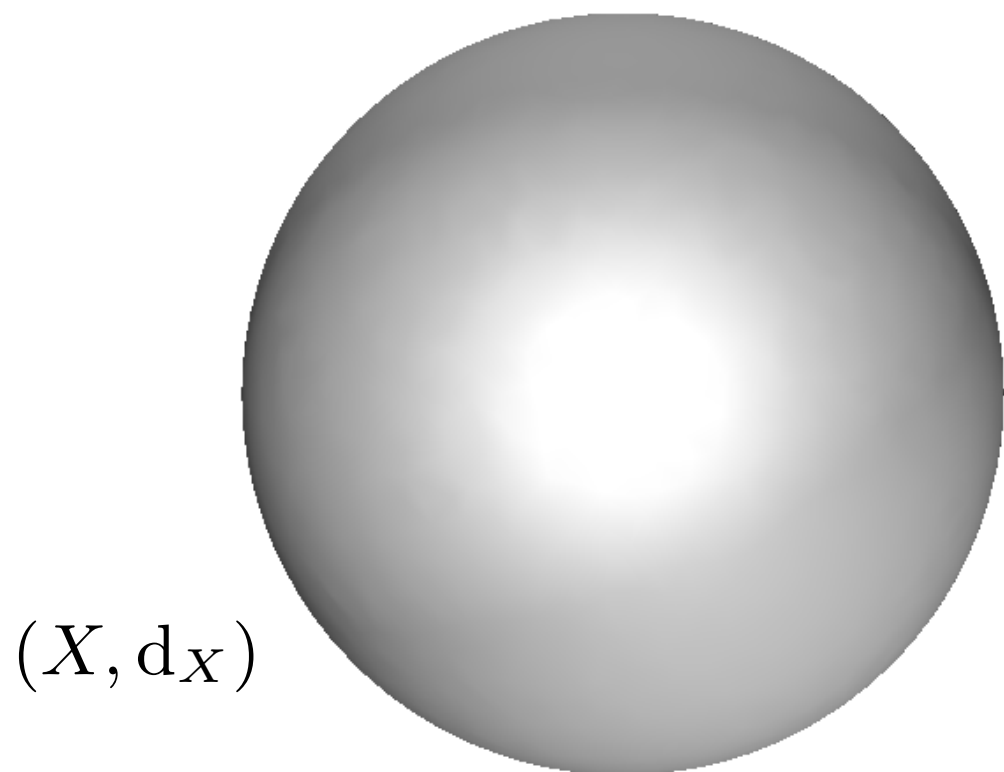
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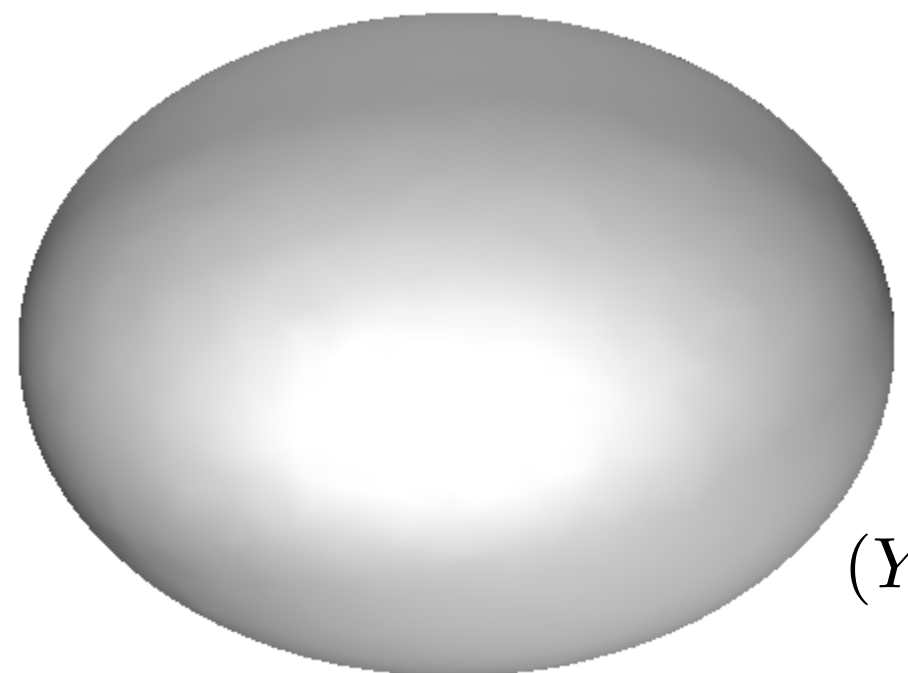
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Illustration: distinguishing between a sphere and an ellipsoid:



(X, d_X)



(Y, d_Y)

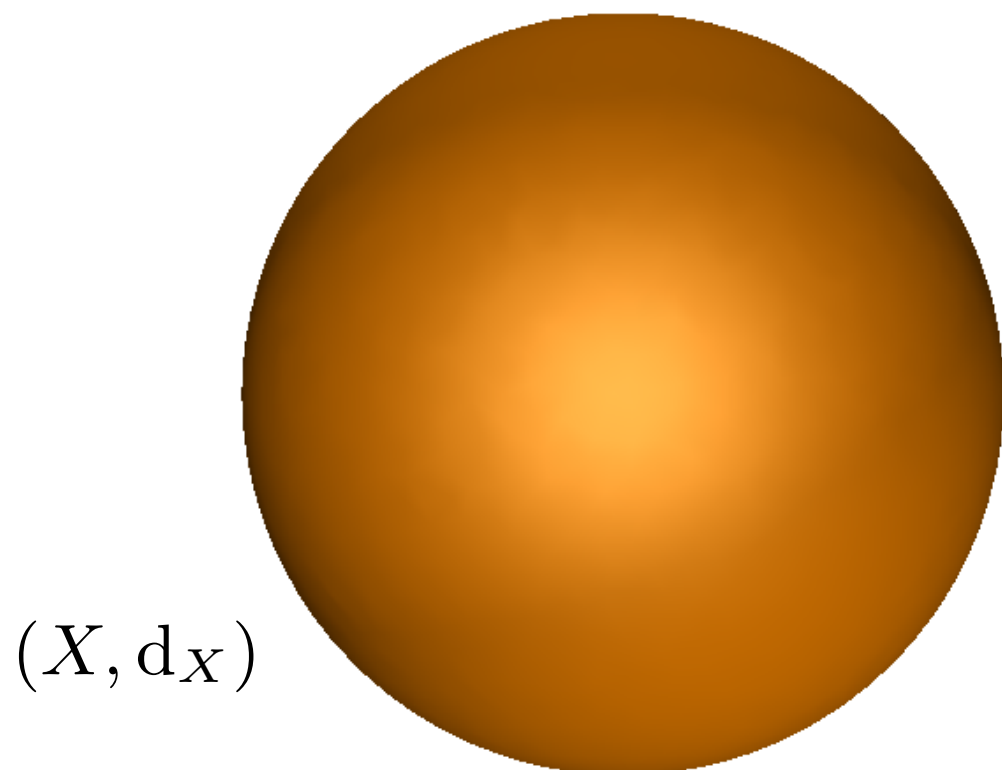
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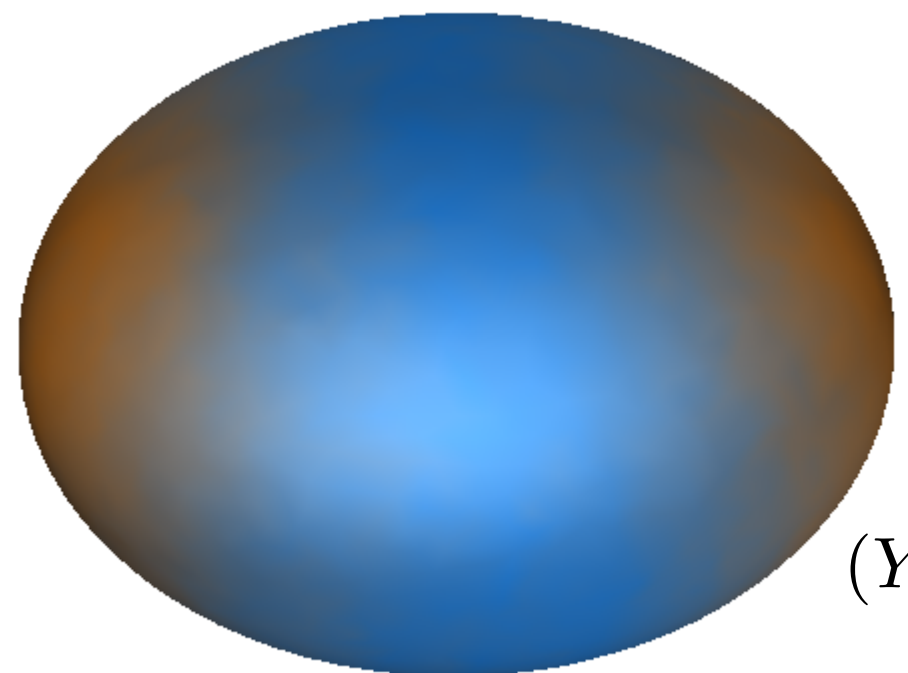
Signature: $Dg f$

Illustration: distinguishing between a sphere and an ellipsoid: \rightarrow eccentricity



(X, d_X)

$$f(x) = \max_{x' \in X} d_X(x, x')$$



(Y, d_Y)

$$g(x) = \max_{y' \in Y} d_X(y, y')$$

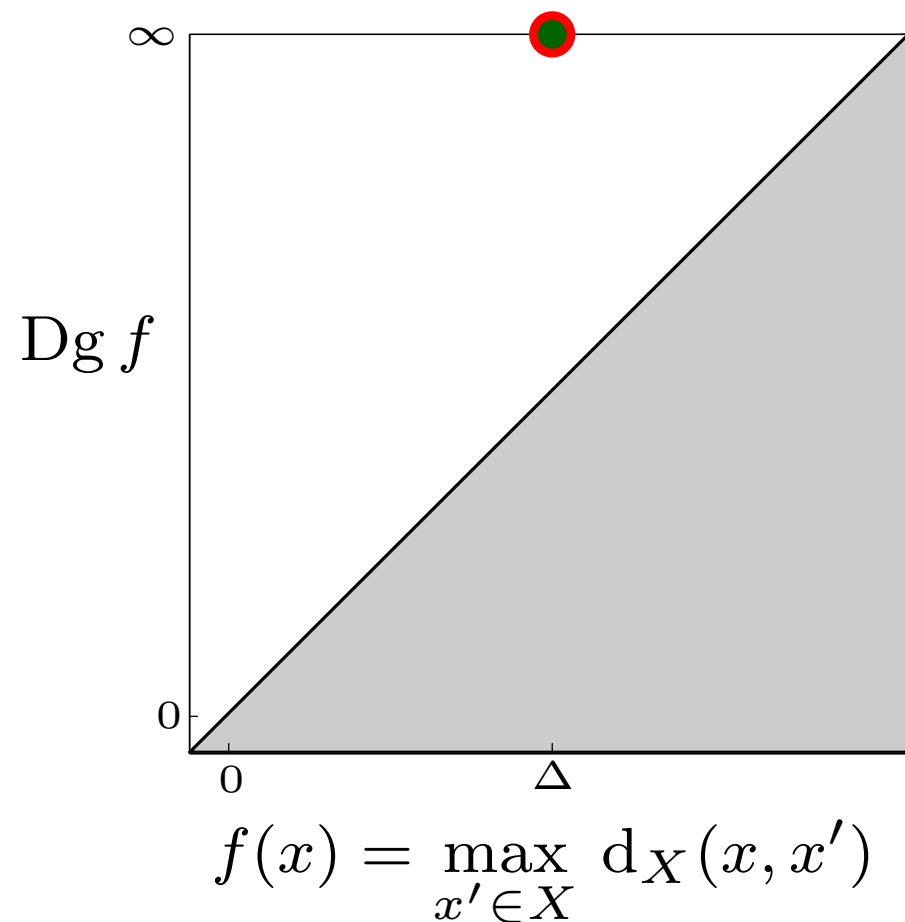
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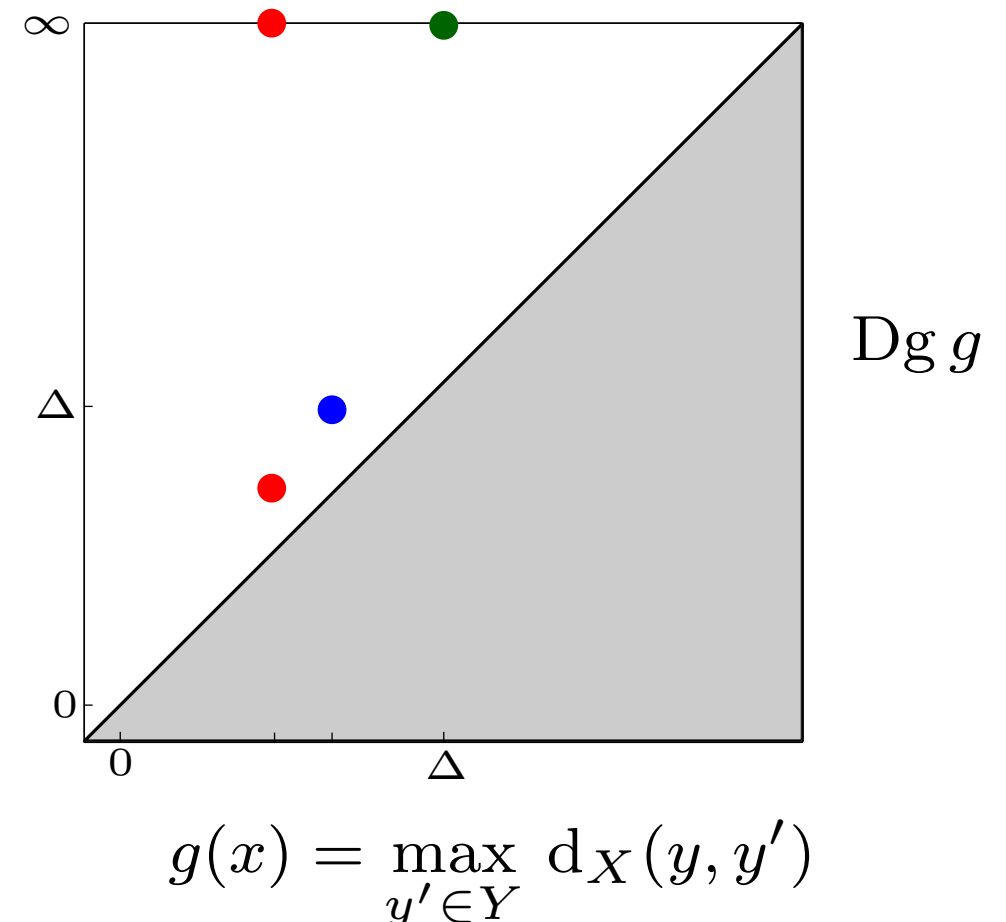
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2-dim
1-dim
0-dim



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Other examples of functions derived from d_X :

- higher-order eccentricities

... to Signatures for Spaces

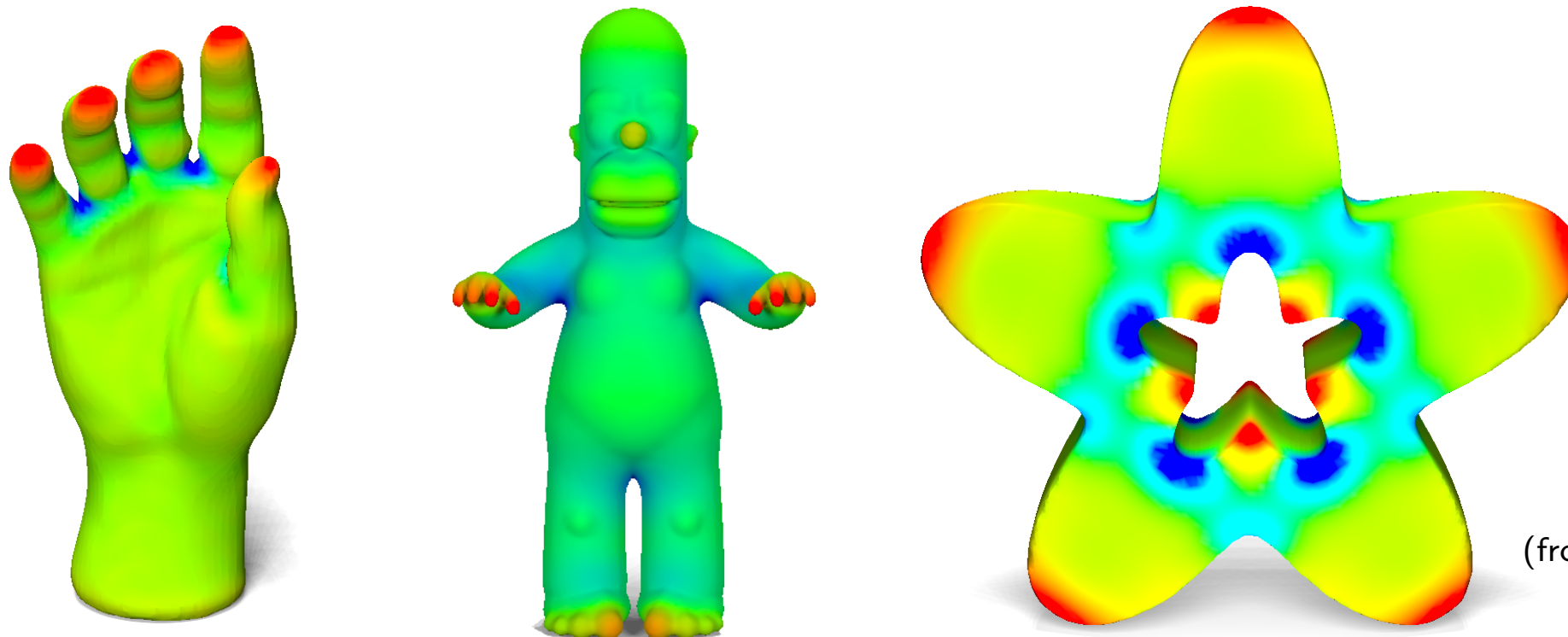
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Other examples of functions derived from d_X :

- *heat-kernel signature* [Sun, Ovsjanikov, Guibas 09] (hyp: X Riemannian manifold)



(from [Sun, Ovsjanikov, Guibas 09])

... to Signatures for Spaces

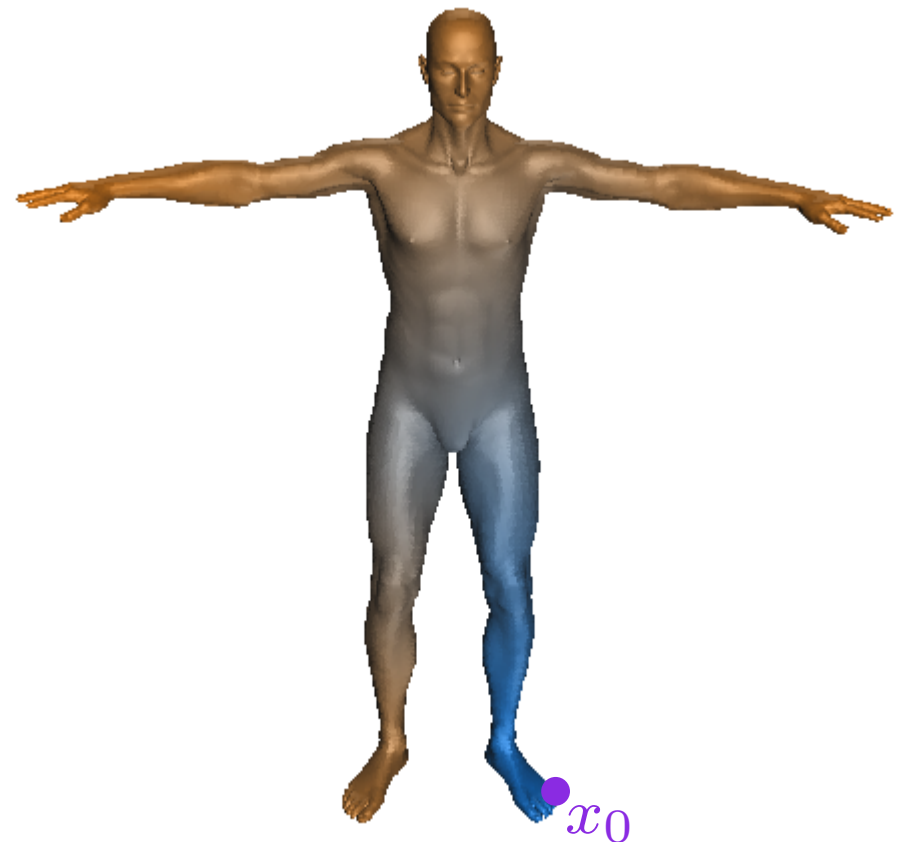
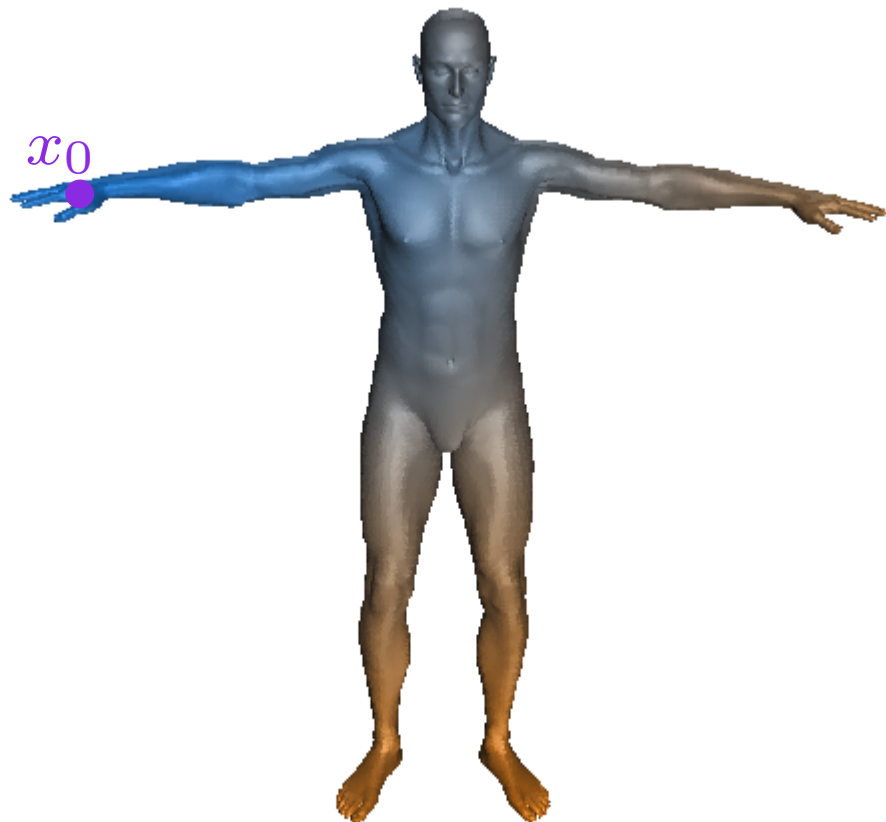
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Other examples of functions derived from d_X : (parametrized by base points)

- distance to a base point $x_0 \in X$



... to Signatures for Spaces

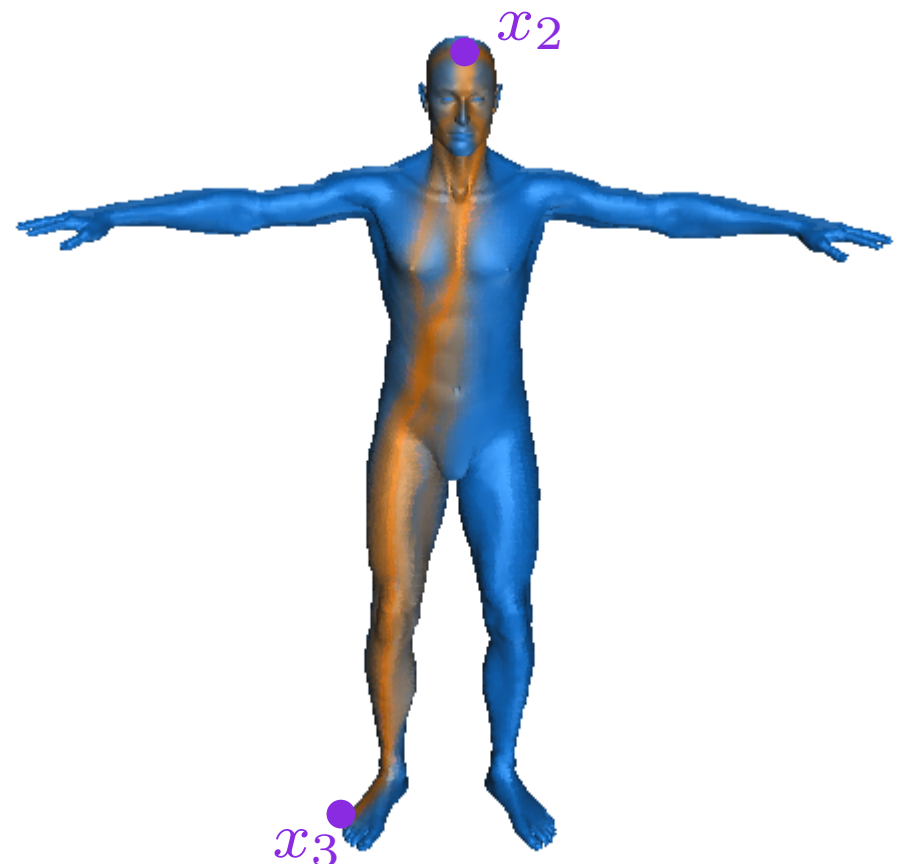
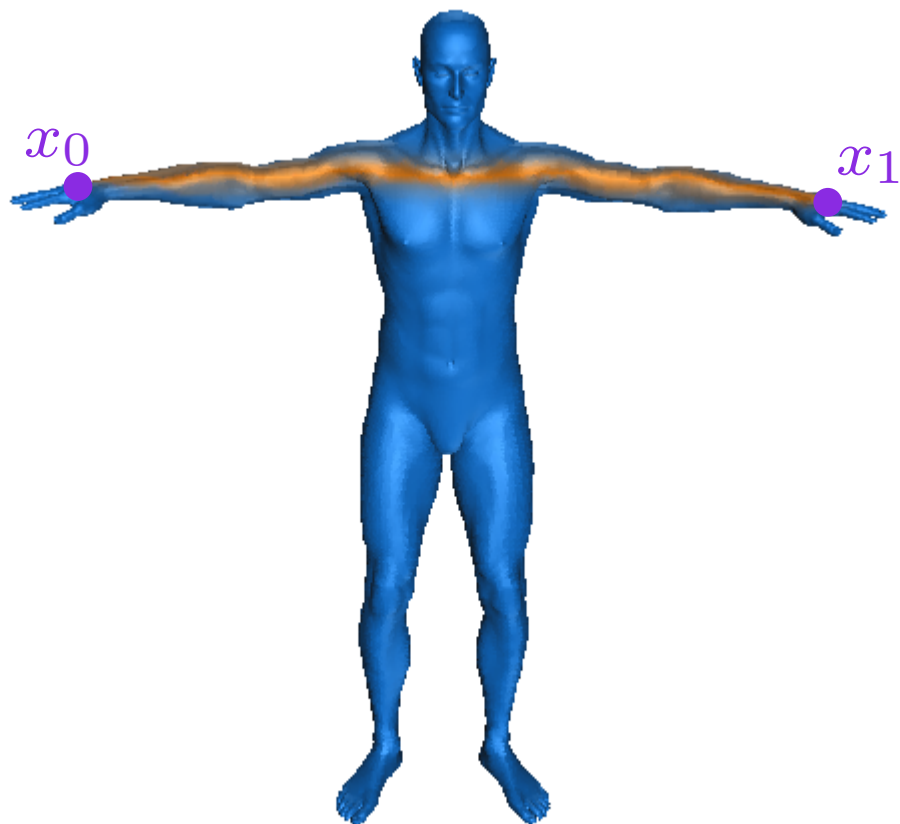
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Other examples of functions derived from d_X : (parametrized by base points)

- *fuzzy geodesic* [Sun, Chen, Funkhouser 10]



... to Signatures for Spaces

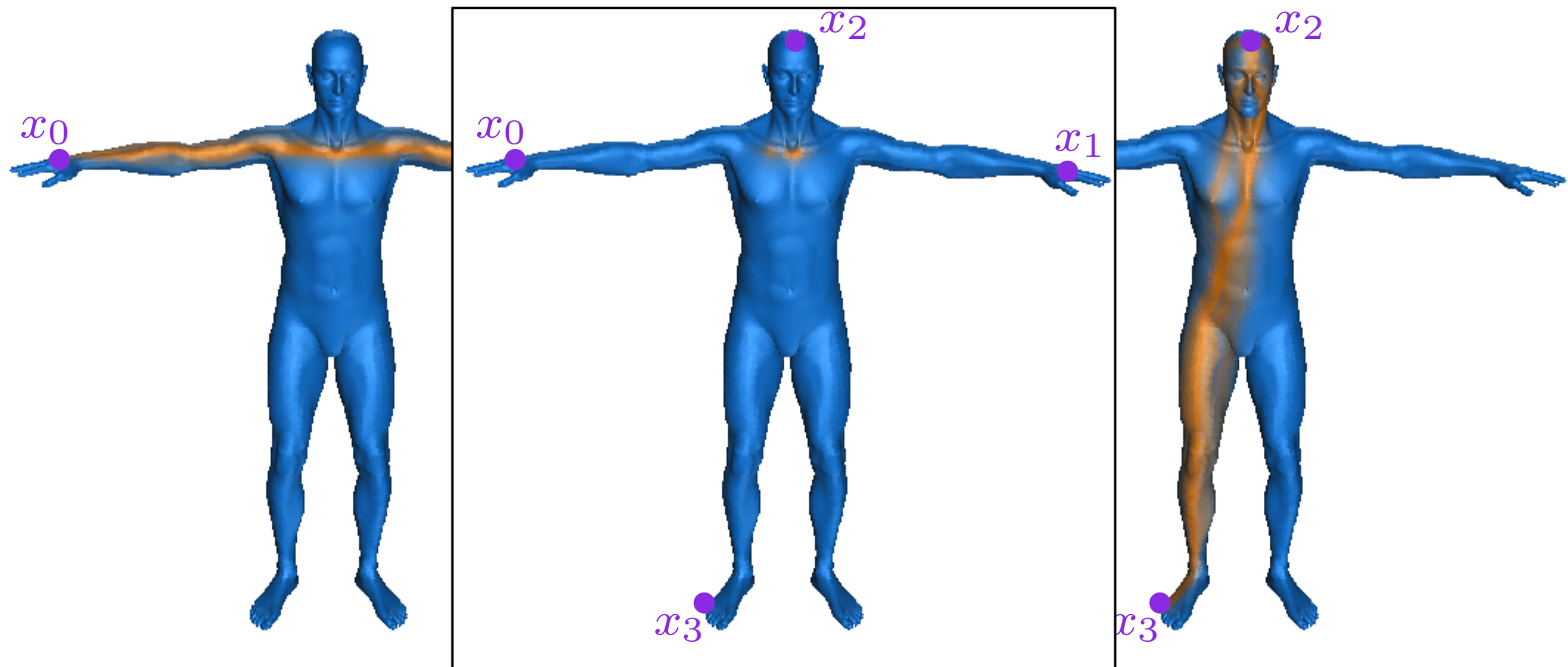
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- *intersection configuration* [Sun, Chen, Funkhouser 10]



... to Signatures for Spaces

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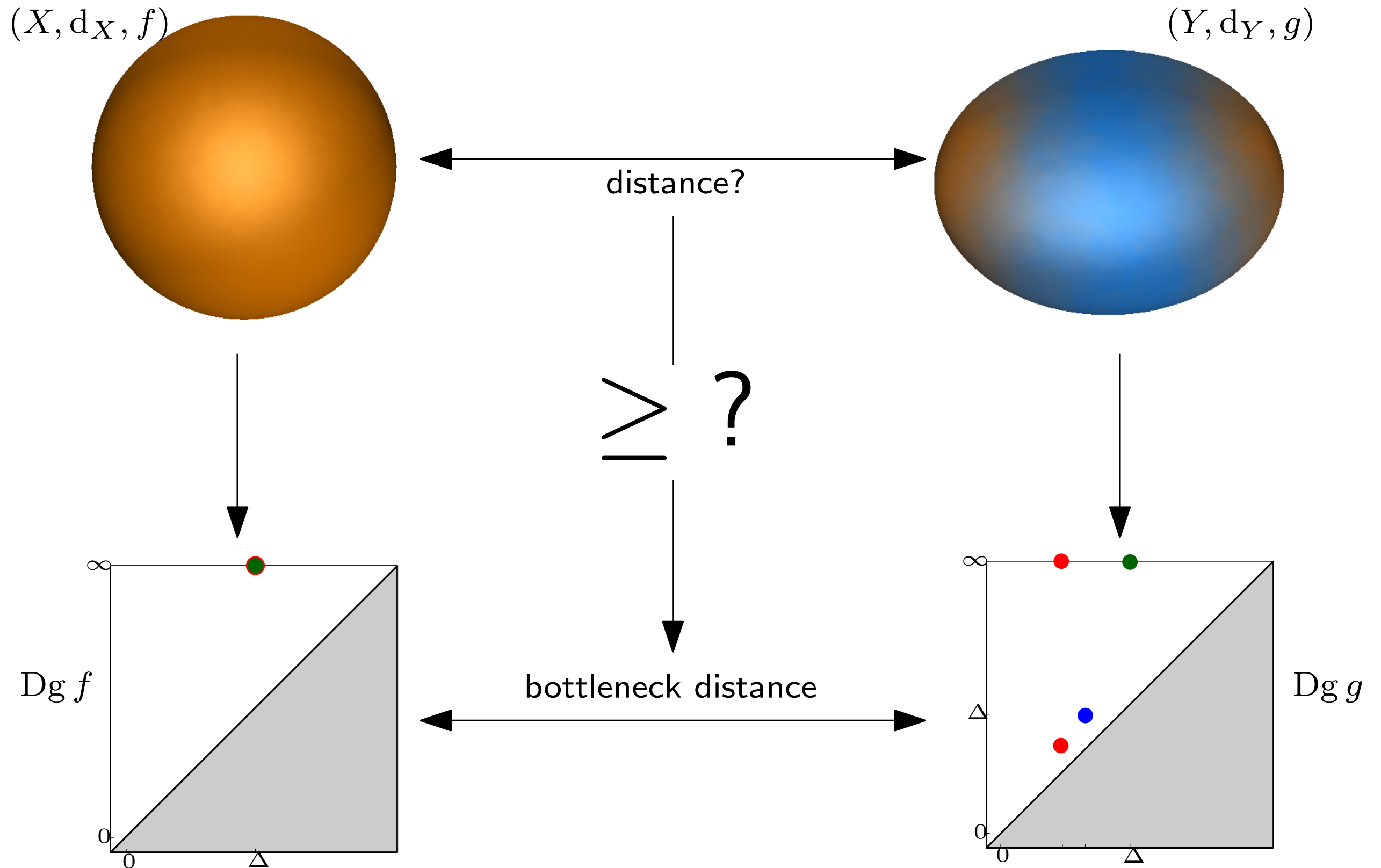
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Observations:

- same spirit as size theory for shape comparison [d'Amico, Frosini, Landi 05]
- setting is more general

Stability of our Signatures



Stability of our Signatures

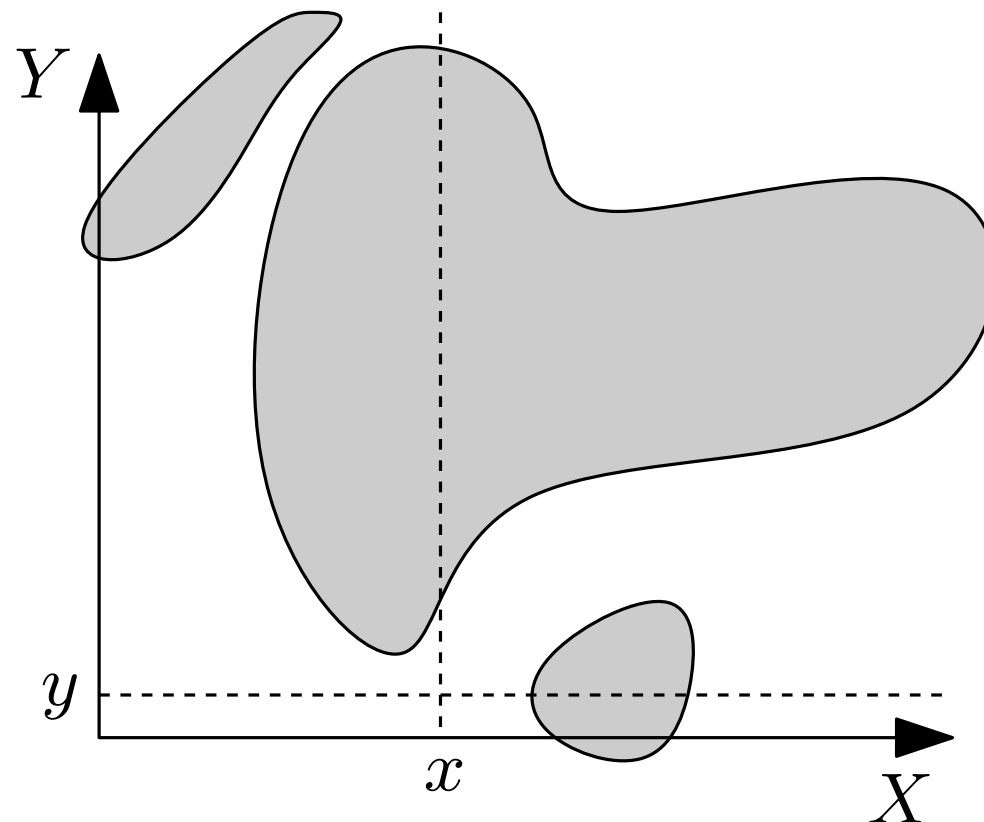
Definitions: Given (X, d_X, f) and (Y, d_Y, g) ,

- correspondence:

a set $C \subseteq X \times Y$ such that:

$$\forall x \in X, \exists y \in Y \text{ s.t. } (x, y) \in C$$

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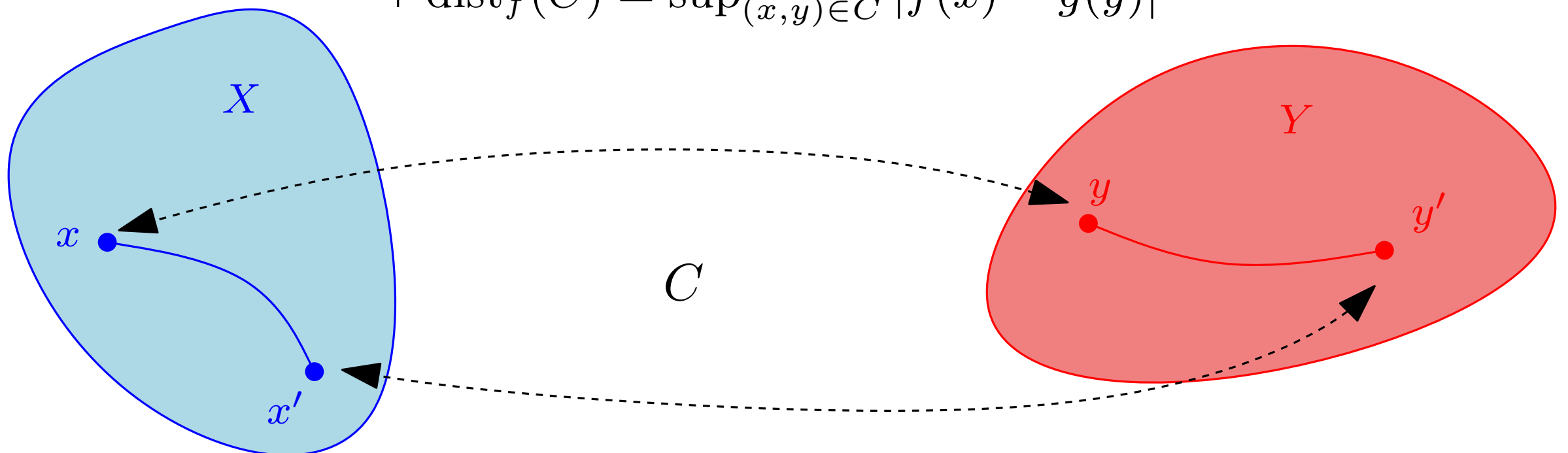
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- distortion:

$$\left| \text{dist}_m(C) = \sup_{(x,y), (x',y') \in C} |d_X(x, x') - d_Y(y, y')| \right.$$

$$\left| \text{dist}_f(C) = \sup_{(x,y) \in C} |f(x) - g(y)| \right.$$



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- Gromov-Hausdorff distance:

$$d_{\text{GH}}(X, Y) = \frac{1}{2} \inf_{C \in \mathcal{C}(X, Y)} \text{dist}_m(C)$$

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- Gromov-Hausdorff distance:

$$d_{\text{GH}}(X, Y) = \frac{1}{2} \inf_{C \in \mathcal{C}(X, Y)} \text{dist}_m(C)$$

→ In our bounds we decouple $\text{dist}_m(C)$ and $\text{dist}_f(C)$

Stability of our Signatures

Desired stability result:

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact metric spaces equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$,

$$d_B^\infty(Dg f, Dg g) \in O(c \operatorname{dist}_m(C) + \operatorname{dist}_f(C)).$$

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Note: this is nothing but a stability theorem for persistence diagrams

- improves over [CEH'05] (functions have different domains)
- improves over [dAFL'08] (domains are in different homeomorphism classes)
- relies on [CCGGGO'09] with more explicit conditions

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But it is false in such generality:

- $d_B^\infty(Dg f, Dg g) < \infty \Rightarrow (X, d_X)$ and (Y, d_Y) are homologically equivalent
- $\operatorname{dist}_m(C)$ and $\operatorname{dist}_f(C)$ are finite regardless of homological types of X, Y

$$X = \bullet \qquad Y = \bullet \longleftrightarrow^\varepsilon \bullet$$

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→ Restrict the focus to a class of *sufficiently regular* metric spaces

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Obtained stability result:

length spaces of curvature bounded above

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$$\begin{aligned} d_B^\infty(Dg f, Dg g) &\in \cancel{O(c \text{dist}_m(C) + \text{dist}_f(C))}. \\ &\leq 19 c \text{dist}_m(C) + \text{dist}_f(C) \end{aligned}$$

Stability of our Signatures

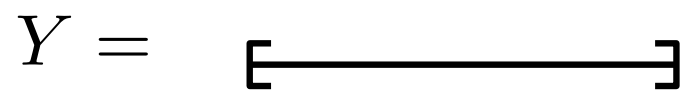
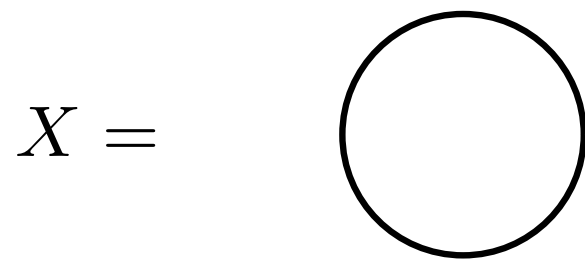
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Prerequisite: $d_{\text{GH}}(X, Y) < \frac{1}{20} \min\{\varrho(X), \varrho(Y)\}$



$$d_{\text{GH}}(X, Y) < \infty = \varrho(Y)$$

$$d_B^\infty(Dg f, Dg g) = \infty$$

Stability of our Signatures

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact length spaces with curvature bounded above, equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(Dg f, Dg g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

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Corollary 1: If $d_{\text{GH}}(X, Y) < \frac{1}{20} \min\{\varrho(X), \varrho(Y)\}$, then $d_B^\infty(\text{Dg } \text{ecc}_X, \text{Dg } \text{ecc}_Y) \leq 40 d_{\text{GH}}(X, Y)$.

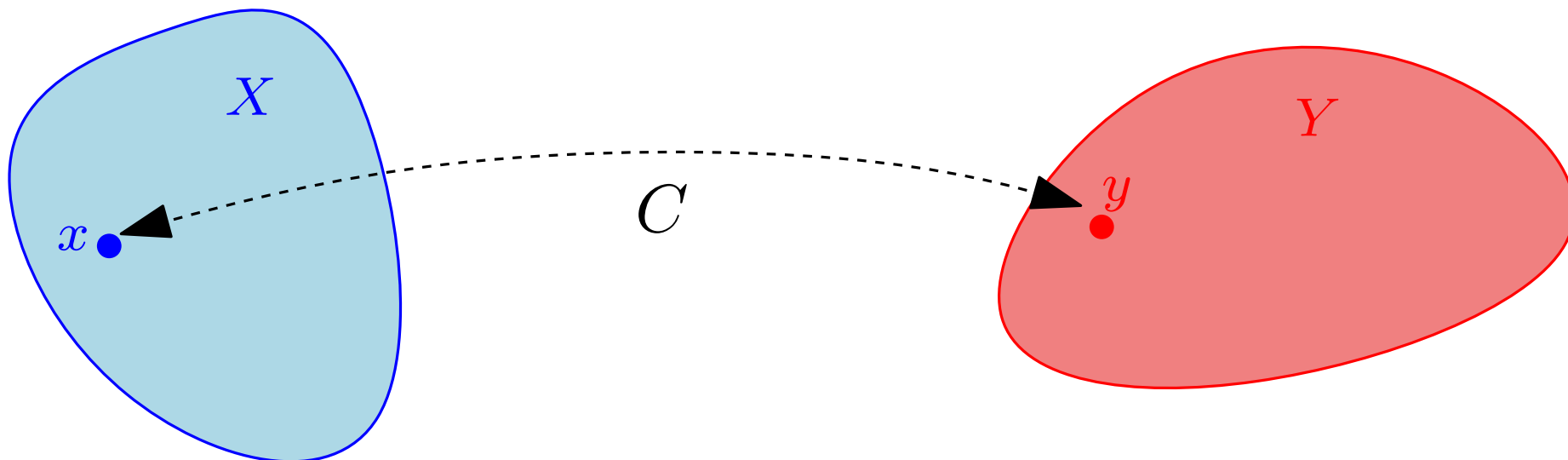
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Corollary 2: For any base points $x \in X$ and $y \in Y$,

$$d_B^\infty(\text{Dg } d_X(x, \cdot), \text{Dg } d_Y(y, \cdot)) \leq 20 \inf_{\substack{C \in \mathcal{C}(X, Y) \\ \text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\} \\ (x, y) \in C}} \text{dist}_m(C).$$



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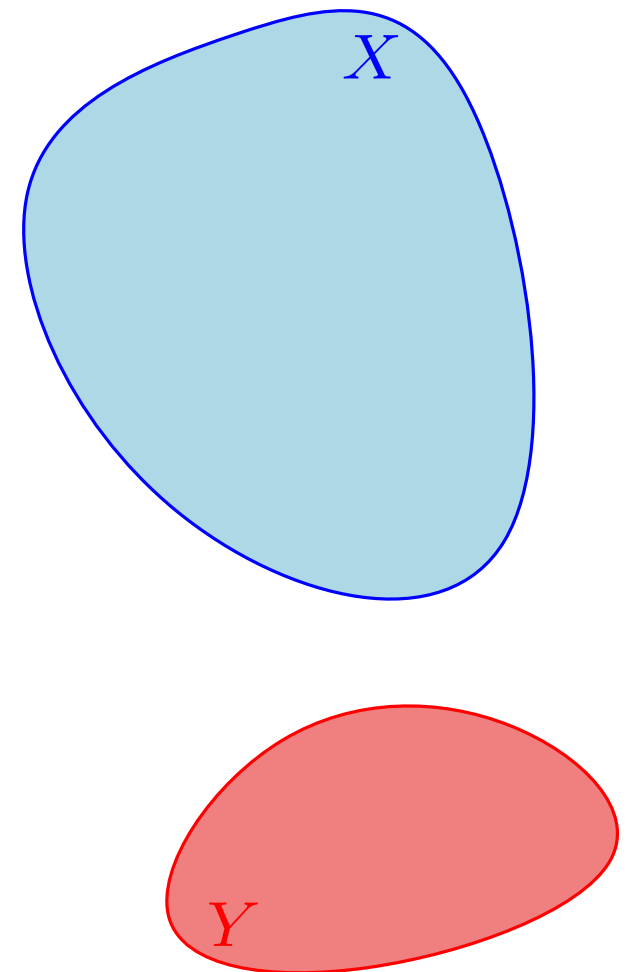
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Corollary 3: If $d_{\text{GH}}(X, Y) < \frac{1}{20} \min\{\varrho(X), \varrho(Y)\}$, then given any base point $x \in X$, for any $\varepsilon > 0$ there is a basepoint $y \in Y$ such that $d_B^\infty(\text{Dg } d_X(x, \cdot), \text{Dg } d_Y(y, \cdot)) \leq 40 d_{\text{GH}}(X, Y) + \varepsilon$.

Stability of our Signatures

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact length spaces with curvature bounded above, equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(Dg f, Dg g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

Proof: by reduction to *Scalar Fields Analysis from Point Cloud Data*:
[Chazal, Guibas, O., Skraba 11]



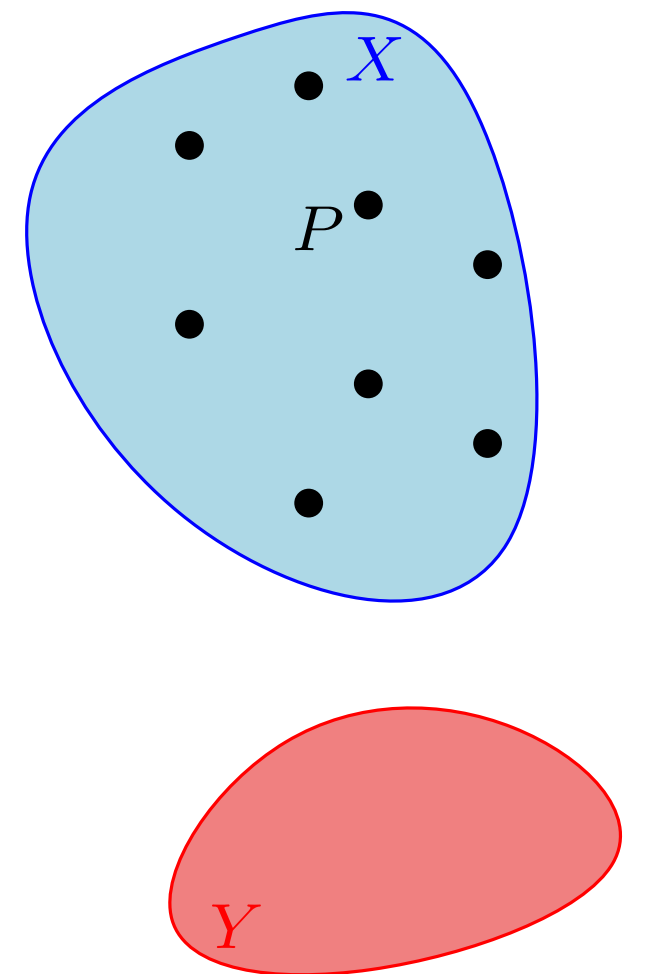
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Given any positive $\varepsilon < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\} - \text{dist}_m(C)$,

- take a finite ε -sample P of X ($P \subseteq X$)
- equip it with the induced metric $d_P = d_X|_{P \times P}$
- equip it with the restriction $h = f|_P$



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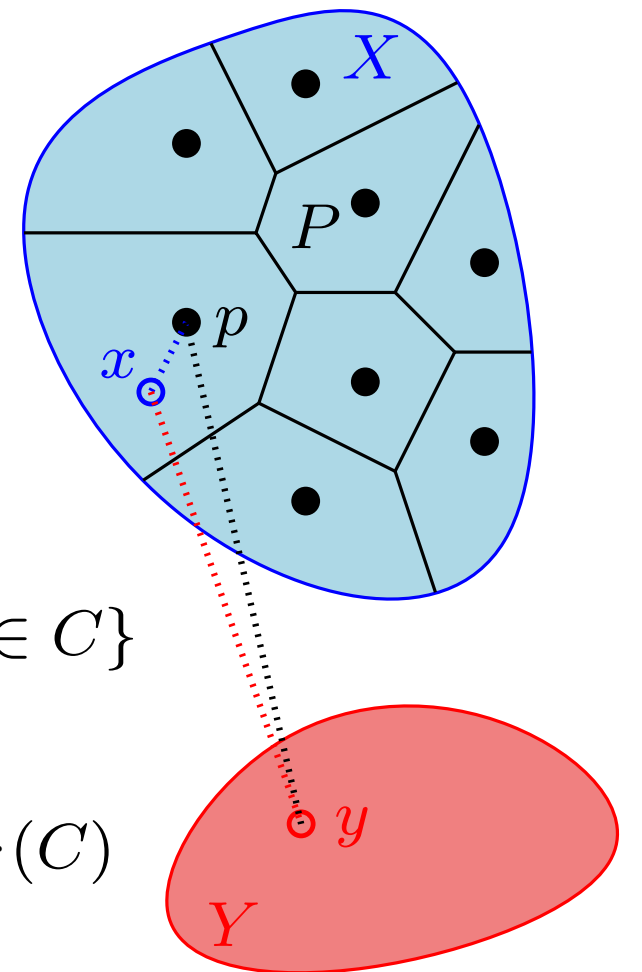
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$$C_{PX} = \{(p, x) \in P \times X : d_X(x, p) = \min_{q \in P} d_X(x, q)\}$$

$$C_{PY} = \{(p, y) \in P \times Y : \exists x \in X \text{ s.t. } (p, x) \in C_{PX} \text{ and } (x, q) \in C\}$$

$$\rightarrow \begin{cases} \text{dist}_m(C_{PX}) \leq 2\varepsilon \text{ and } \text{dist}_f(C_{PX}) = c\varepsilon \\ \text{dist}_m(C_{PY}) \leq 2\varepsilon + \text{dist}_m(C) \text{ and } \text{dist}_f(C_{PY}) \leq c\varepsilon + \text{dist}_f(C) \end{cases}$$



Stability of our Signatures

Theorem (Stability): Let (X, d_X) and (Y, d_Y) be two compact length spaces with curvature bounded above, equipped with c -Lipschitz functions $f : X \rightarrow \mathbb{R}$ and $g : Y \rightarrow \mathbb{R}$. Then, for any correspondence $C \in \mathcal{C}(X, Y)$ such that $\text{dist}_m(C) < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\}$, $d_B^\infty(Dg f, Dg g) \leq 19c \text{dist}_m(C) + \text{dist}_f(C)$.

Proof: by reduction to *Scalar Fields Analysis from Point Cloud Data*:

Given any positive $\varepsilon < \frac{1}{10} \min\{\varrho(X), \varrho(Y)\} - \text{dist}_m(C)$,

- take a finite ε -sample P of X ($P \subseteq X$)
- equip it with the induced metric $d_P = d_X|_{P \times P}$
- equip it with the restriction $h = f|_P$

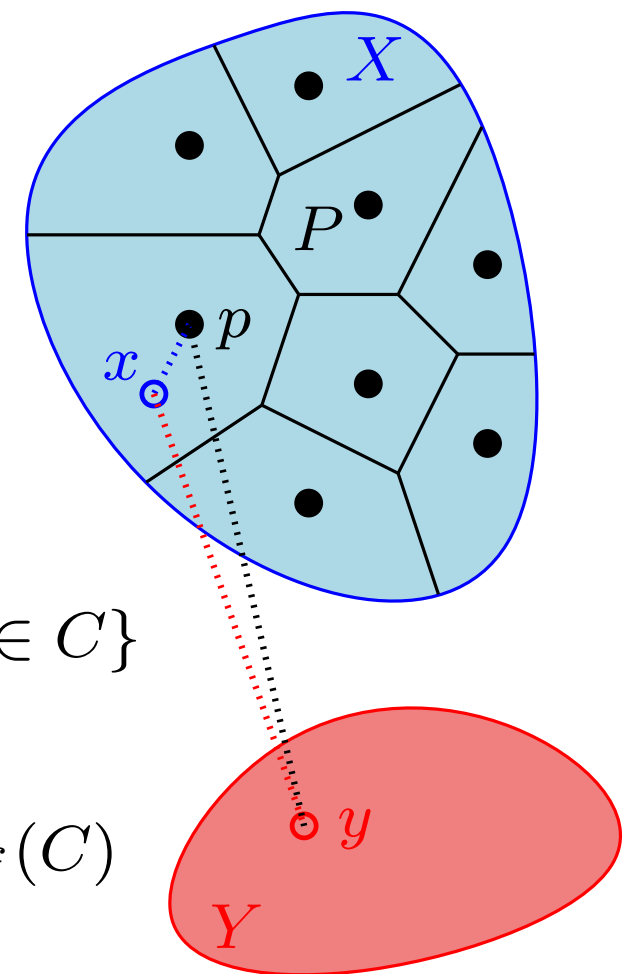
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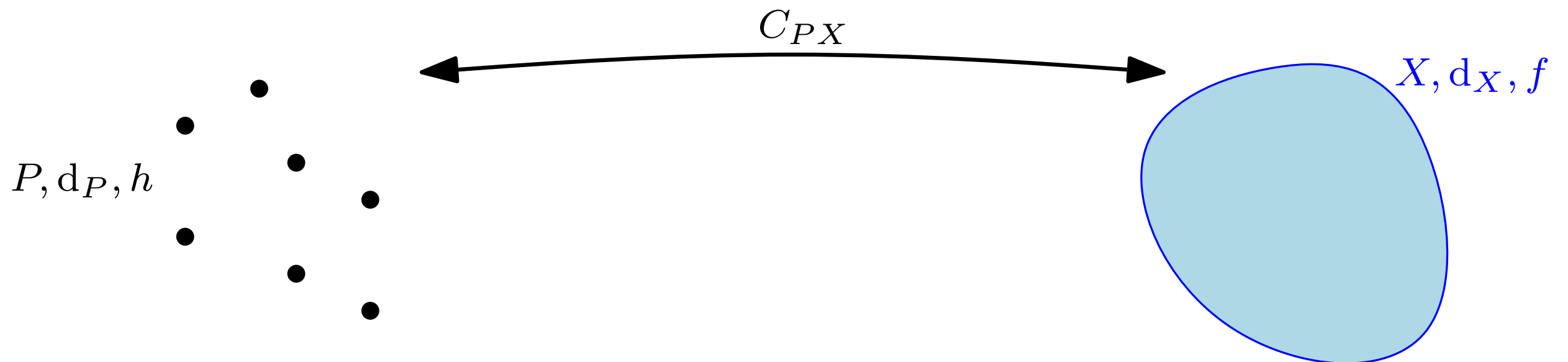
→ goal: approximate persistence diagram from GH-close finite metric space



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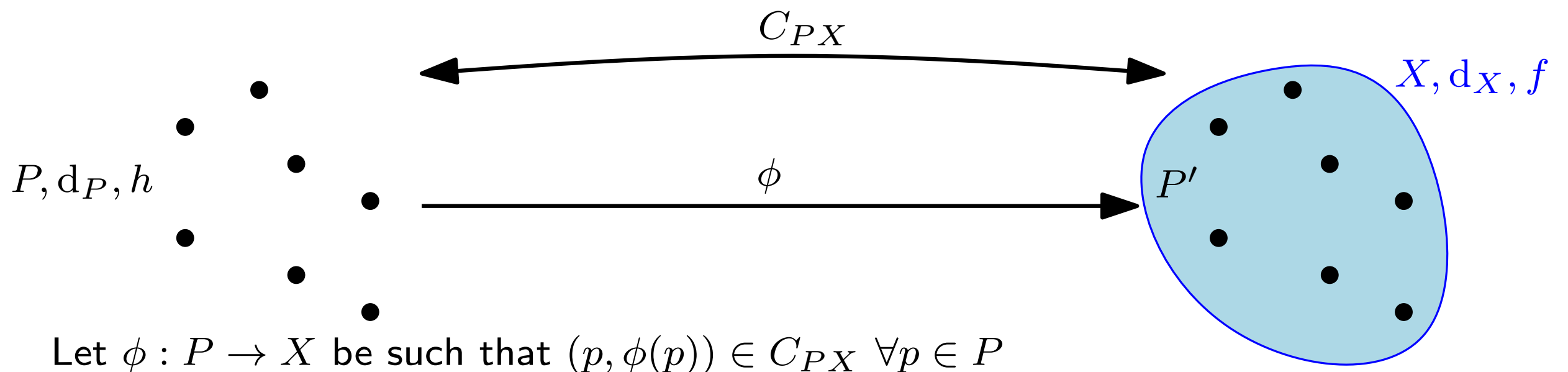
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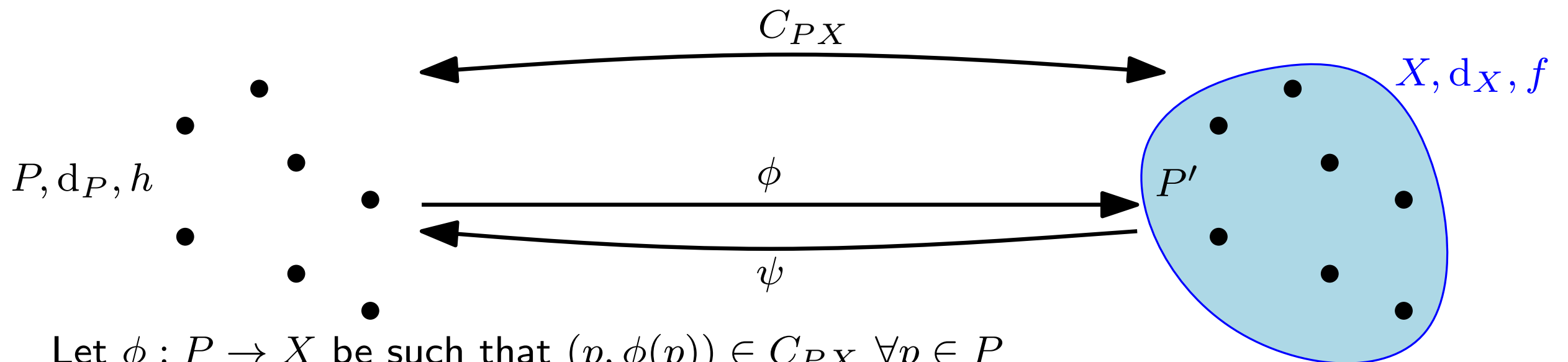
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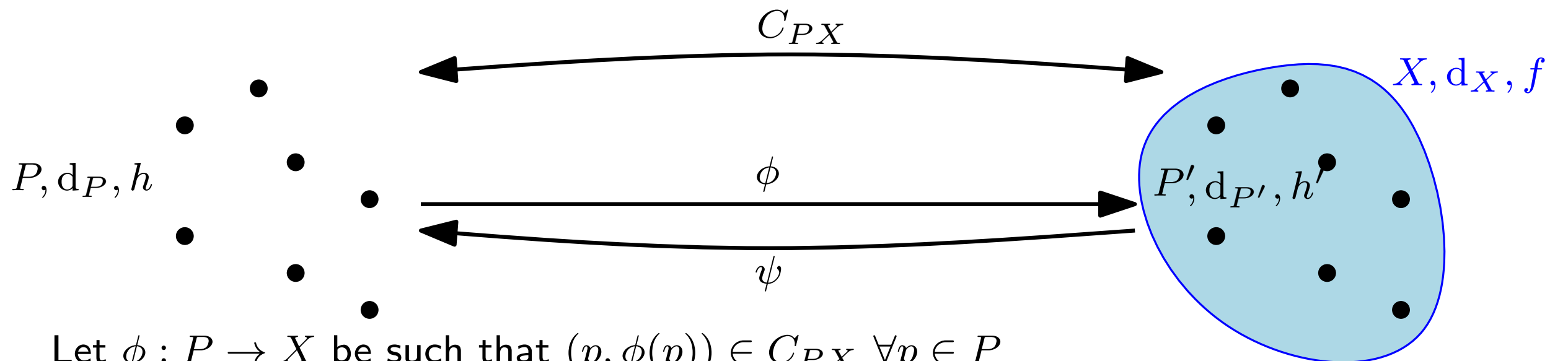
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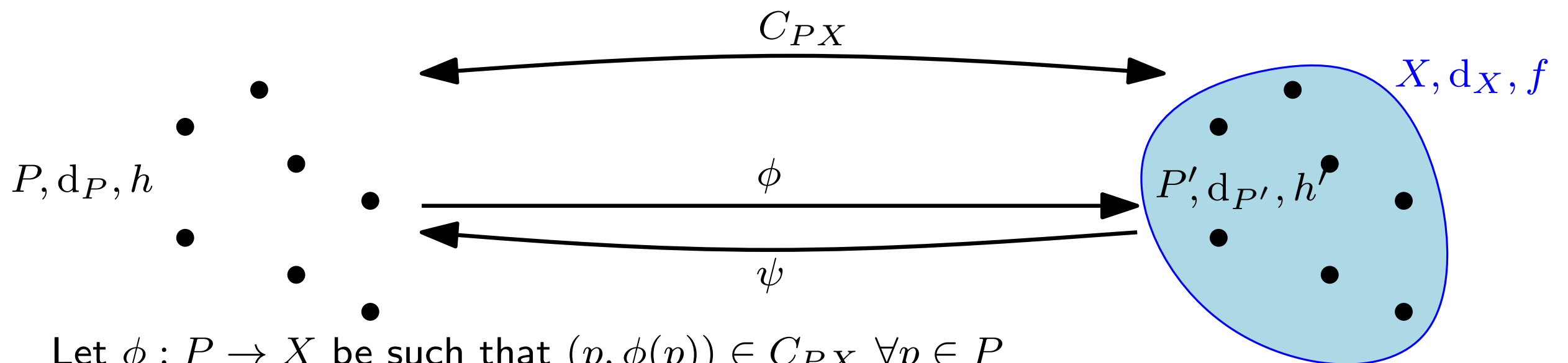
Equip $P' = \phi(P)$ with $d_{P'} = d_P(\psi(\cdot), \psi(\cdot))$ and $h' = h \circ \psi$

$$\rightarrow \left| \begin{array}{l} d_H(P', X) \leq \text{dist}_m(C_{PX}) \\ \|h' - f\|_{P'} \leq \text{dist}_f(C_{PX}) \text{ and } \|d_{P'} - d_X\|_{P' \times P'} \leq \text{dist}_m(C_{PX}) \end{array} \right.$$

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Computing our Signatures

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- when a triangulation of the space X is given:
 - replace f by its PL interpolation \hat{f} over the triangulation
 - compute $\text{Dg } \hat{f}$
 - $d_B^\infty(\text{Dg } f, \text{Dg } \hat{f})$ is controlled by the stability theorem for PDs [CEH'05]

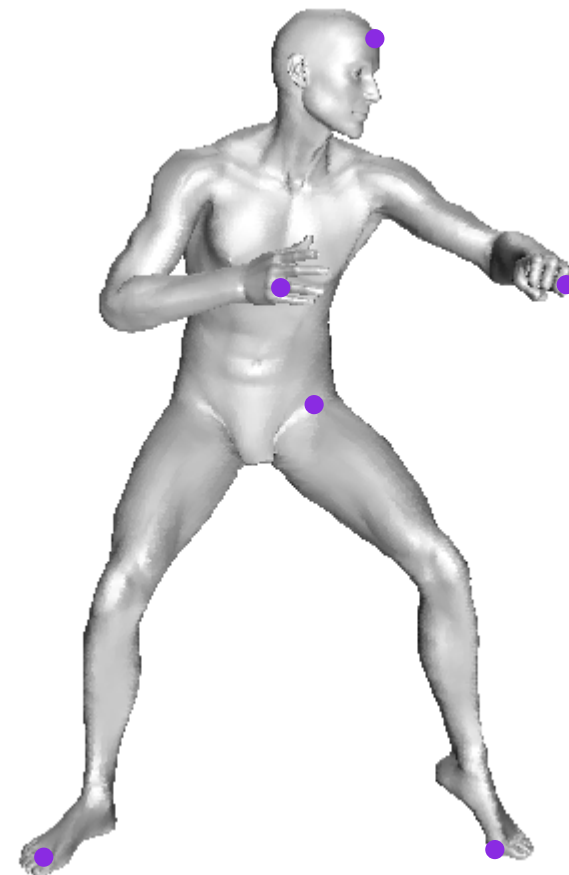
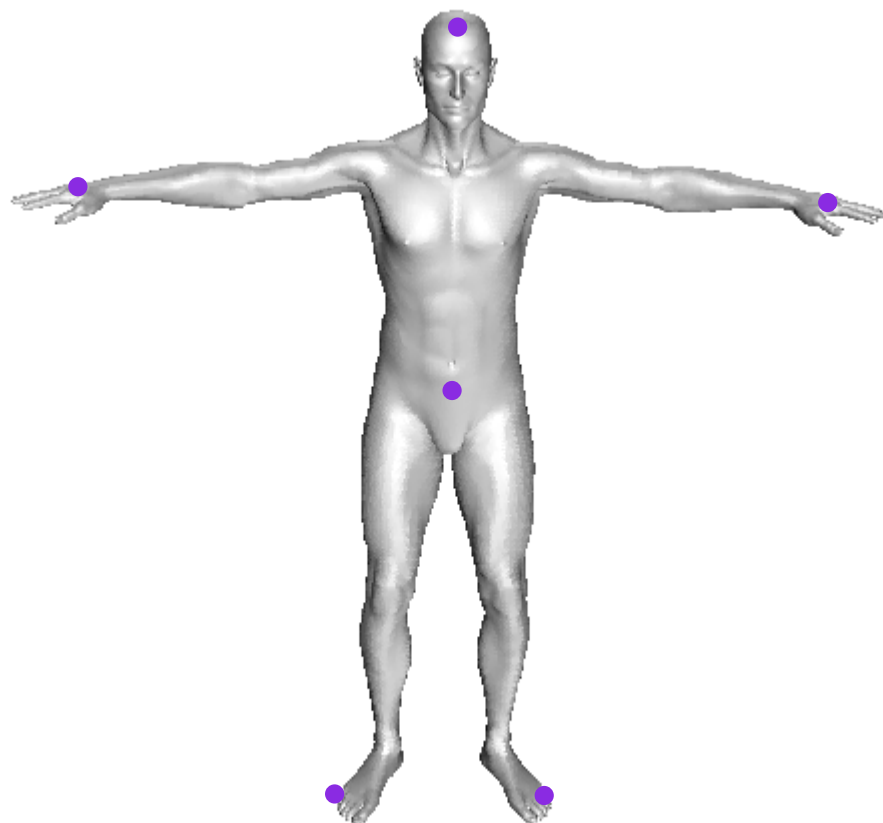
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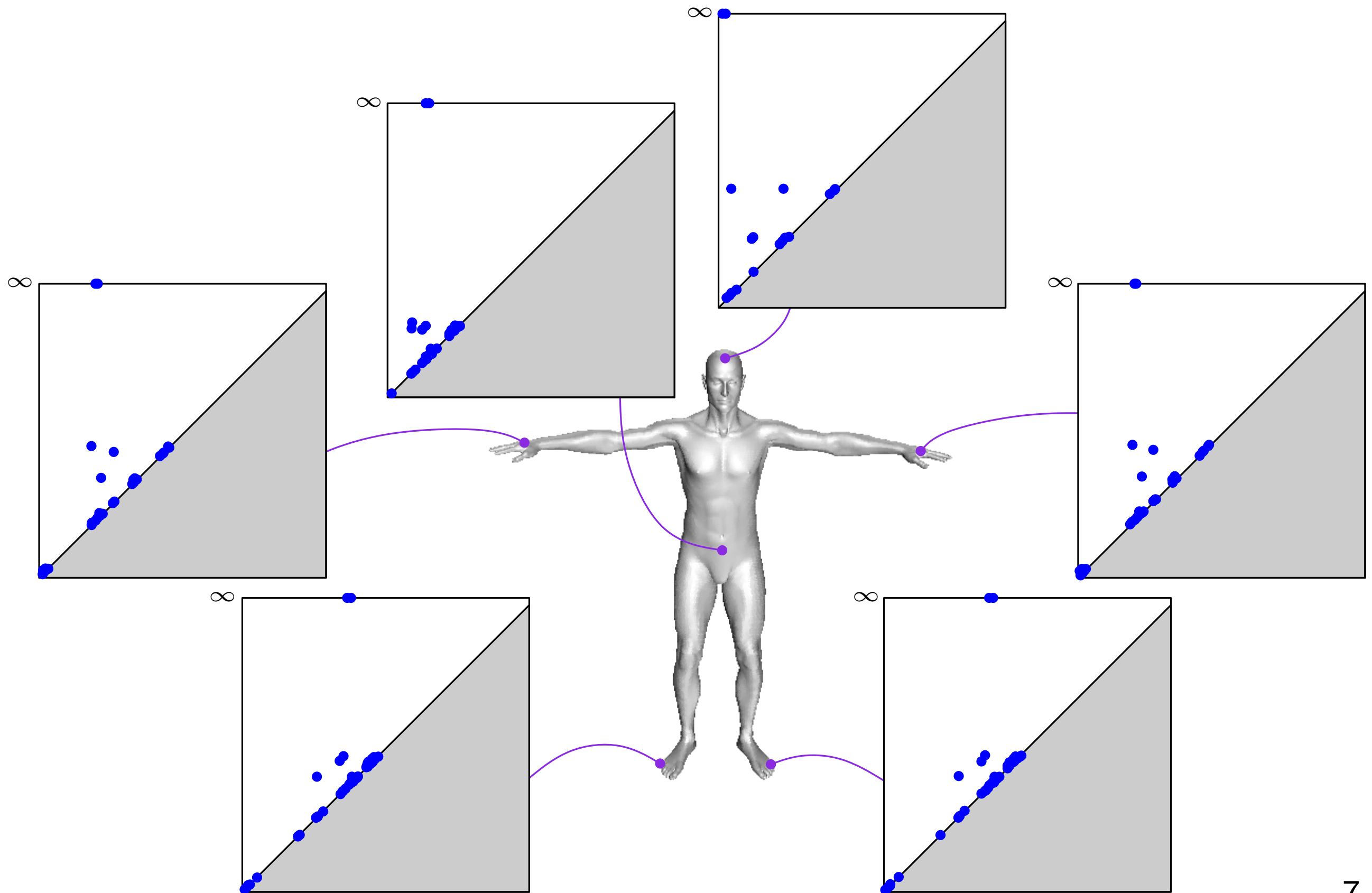
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 - $d_B^\infty(Dg f, Dg \hat{f})$ is controlled by the stability theorem for PDs [CEH'05]
- when a finite approximation (P, d_P, g) of (X, d_X, f) is given:
 - choose a neighborhood parameter $\delta > 0$
 - build the filtrations $\{R_\delta(g^{-1}((-\infty, \alpha]))\}_{\alpha \in \mathbb{R}}$ and $\{R_{3\delta}(g^{-1}((-\infty, \alpha]))\}_{\alpha \in \mathbb{R}}$
 - compute the PD of the image persistence module induced by inclusions:
$$\{\mathrm{Im} H_*(R_\delta(g^{-1}((-\infty, \alpha]))) \rightarrow H_*(R_{3\delta}(g^{-1}((-\infty, \alpha])))\}_{\alpha \in \mathbb{R}}$$
 - bottleneck distance to $Dg f$ is controlled by the results in [CGOS'11]

Some Experimental Results

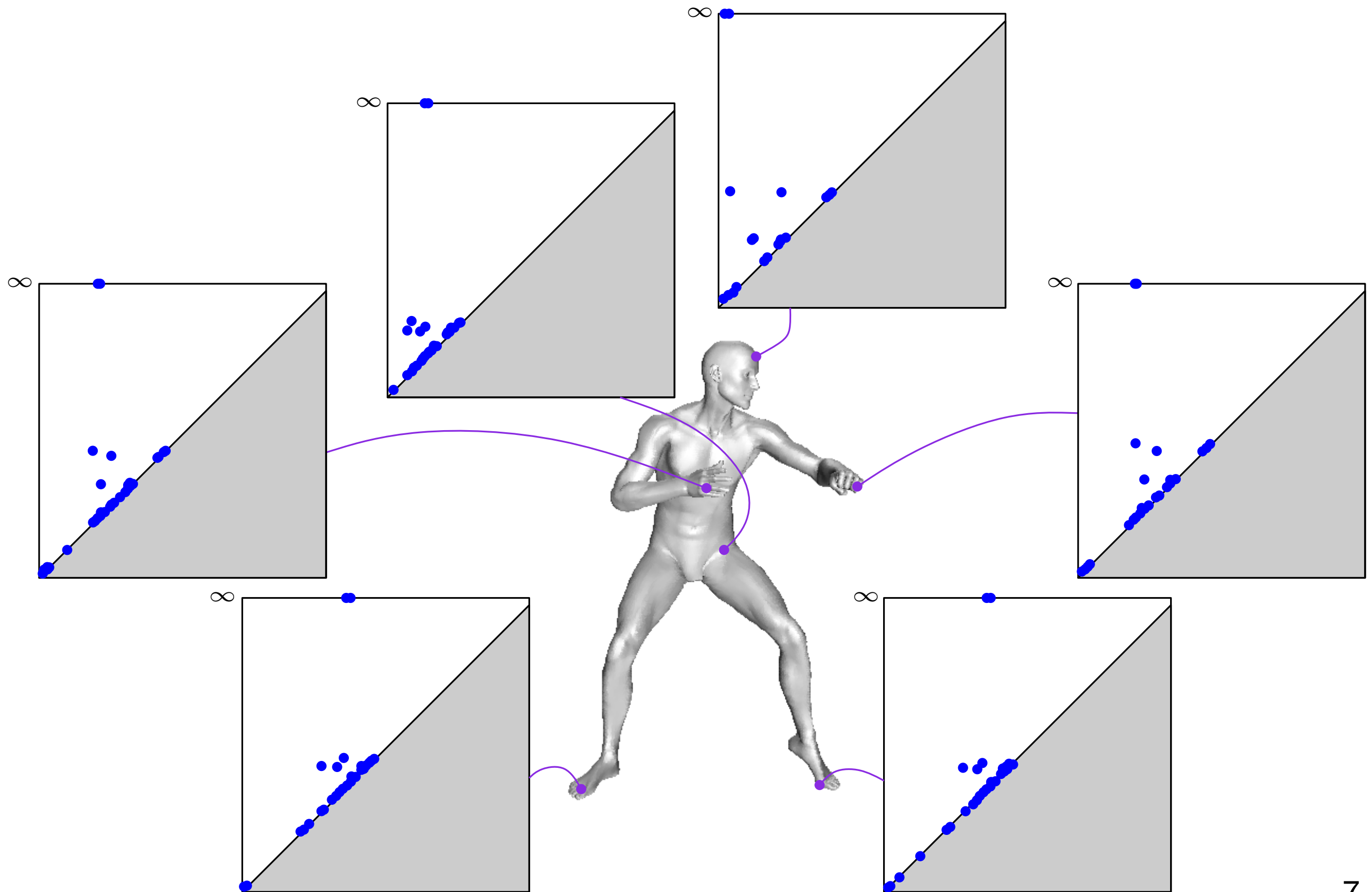
- input: shapes from the TOSCA database, in *mesh* form
- select a few base points by hand on each shape
- approximate geodesic distances to base points using the 1-skeleton graph
- use the PDs of the PL interpolations over the meshes as signatures



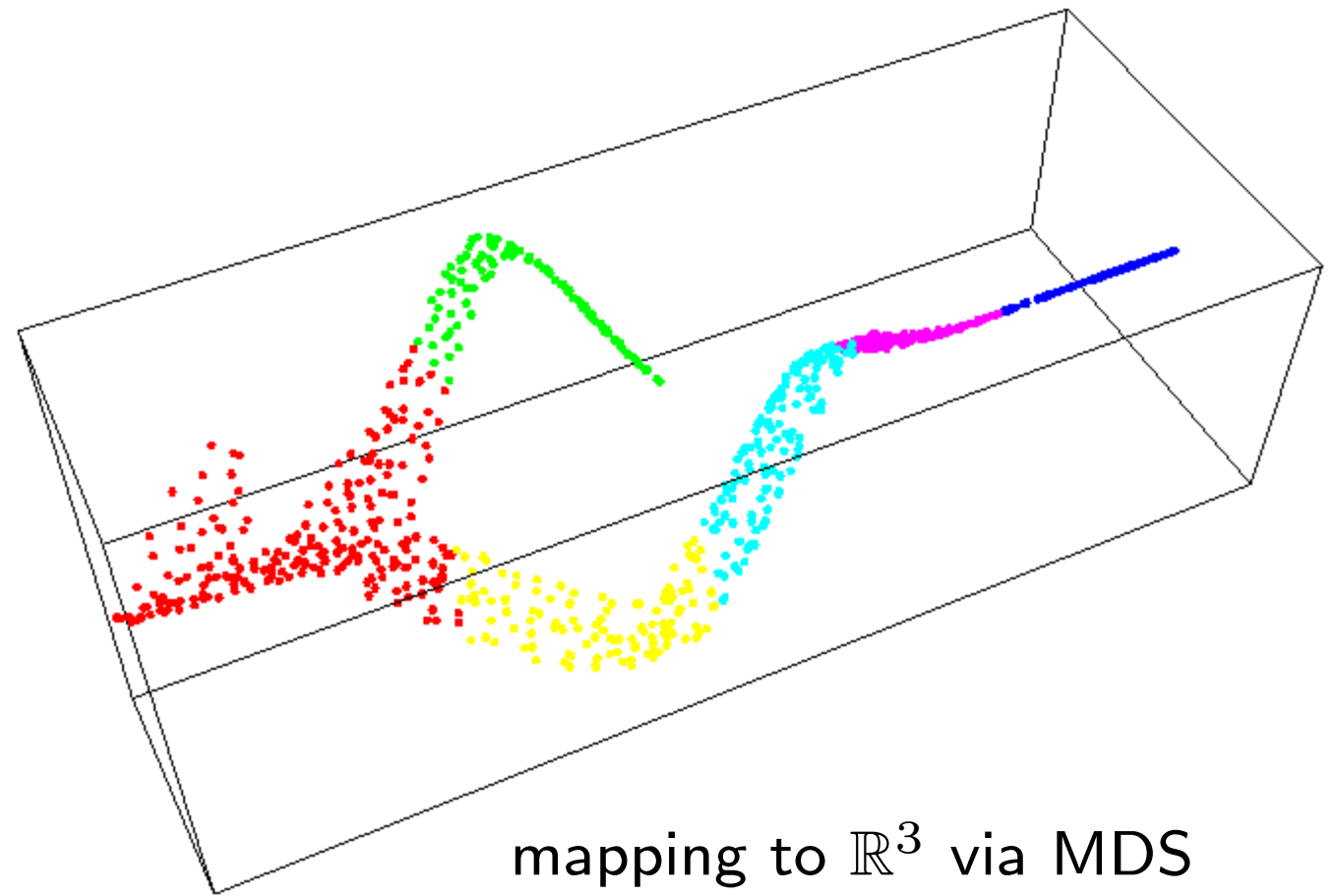
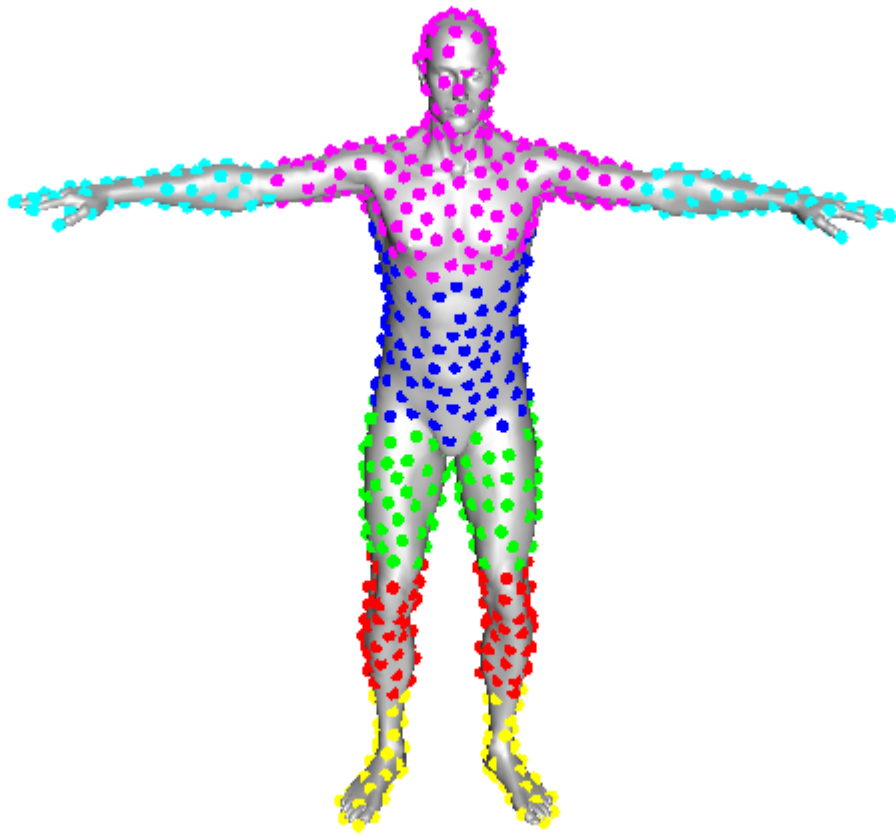
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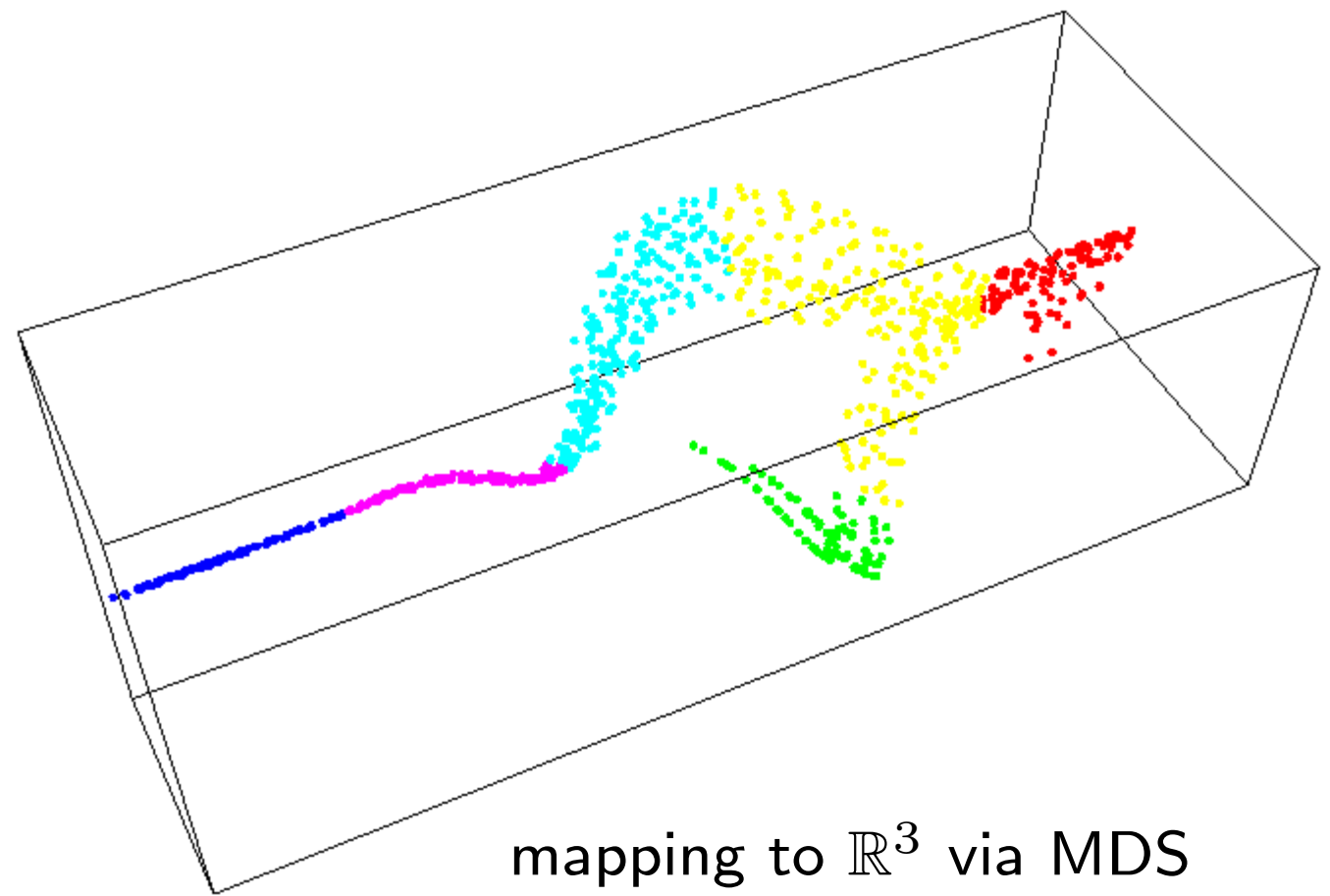
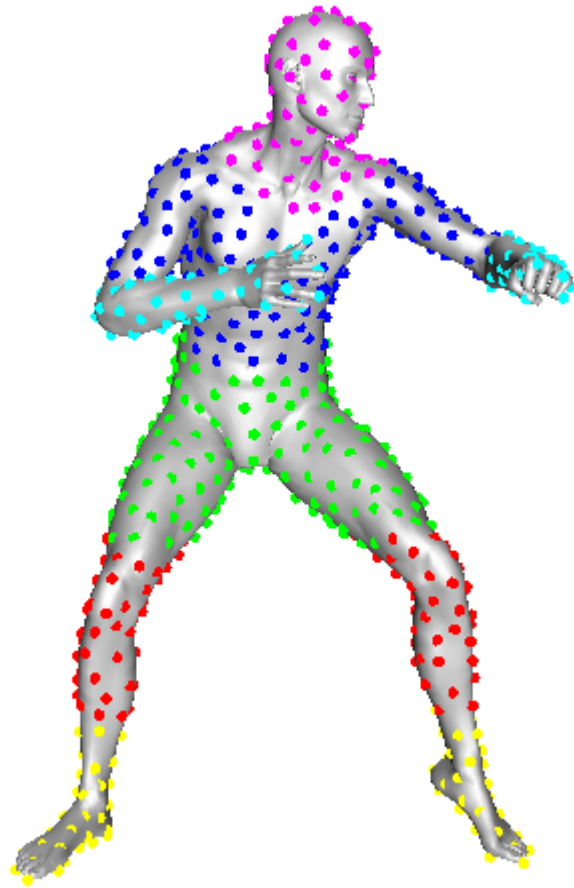
Some Experimental Results



mapping to \mathbb{R}^3 via MDS

k -means in \mathbb{R}^3

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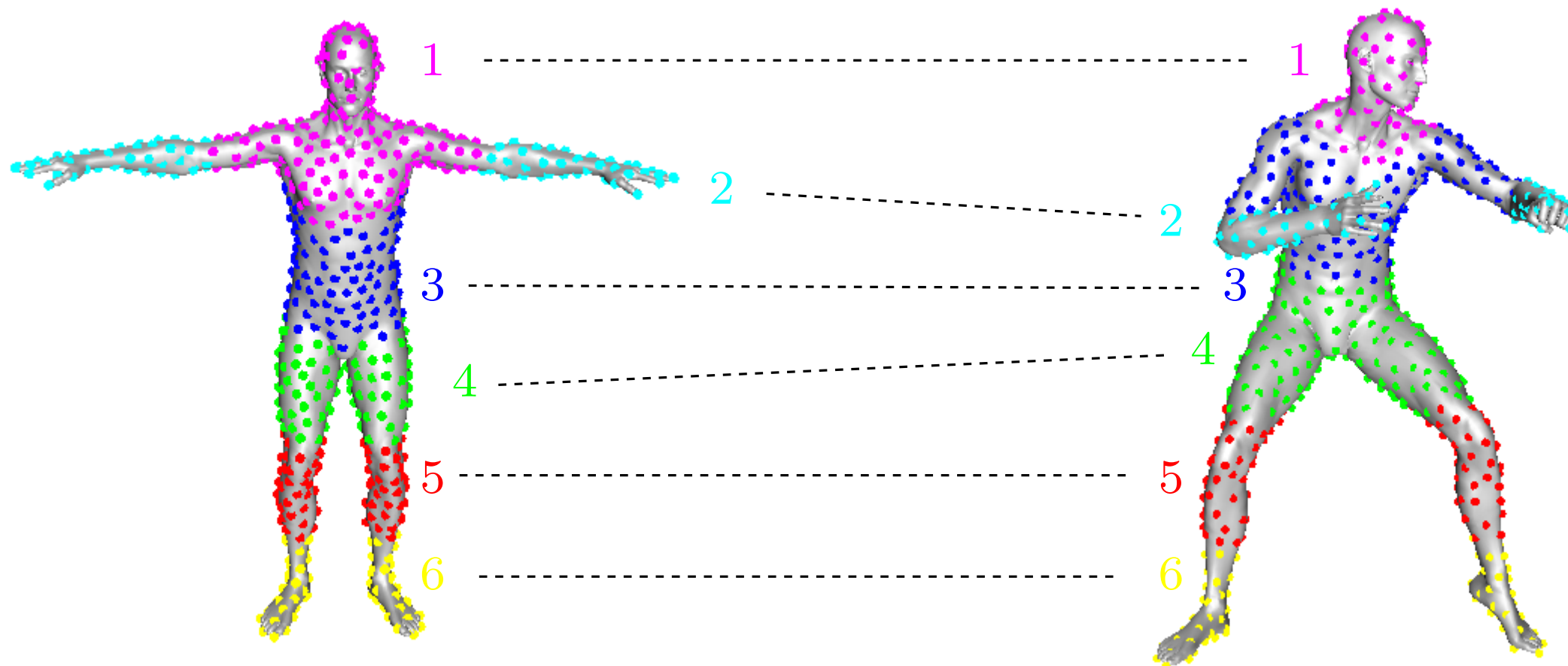


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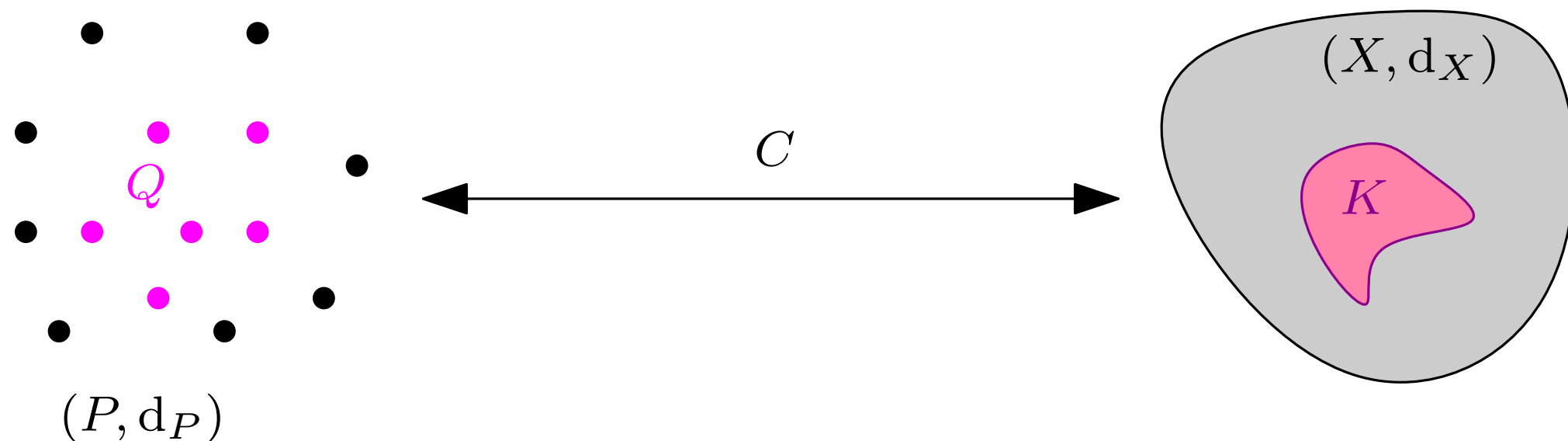
Some Experimental Results

	1	2	3	4	5	6
1	20.322	107.945	71.9286	102.34	130.602	189.146
2	85.3632	21.872	67.7957	67.7957	43.098	93.697
3	54.843	69.1745	21.609	45.2831	73.5451	132.089
4	90.0162	69.1745	29.3636	15.327	35.5291	89.044
5	104.753	69.1745	45.1231	26.101	23.927	74.307
6	172.427	74.568	110.585	81.213	52.951	15.161



Current / Future Directions

- Remote analysis of the distance to a compact set:



Idea: approximate $Dg d_X(\cdot, K)$ by the diagram of the filtration of $R_\delta(P, d_P) \hookrightarrow R_{3\delta}(P, d_P)$ defined by $d_P(\cdot, Q)$.

Current / Future Directions

- Remote analysis of the distance to a compact set:
- Upper bounds on the Gromov-Hausdorff distance:
 - by picking up sufficiently many functions (e.g. distances to all points), can one obtain a constant-factor approximation of the GH-distance?

Current / Future Directions

- Remote analysis of the distance to a compact set:
- Upper bounds on the Gromov-Hausdorff distance:
- Relaxation of the hypotheses of the stability theorem:
 - remove the assumption that $d_{\text{GH}}(X, Y) < \frac{1}{20} \varrho(Y)$

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- Remote analysis of the distance to a compact set:
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Thank You