

# 1-D Schrödinger's Equation with Quadratic Nonlinearity

Normal form approach

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# Problem of local well-posedness in low regularity

In this presentation, we will consider the local well-posedness (l.w.p) of the equation

$$\left\{ \begin{array}{l} u_t + iu_{xx} = u^2 \\ u(0, x) \in H^{-\alpha}(\mathbf{R}). \end{array} \right. \quad (1)$$

By *local well-posedness*, we mean that there exists  $T := T(\|u(0)\|_{H^{-\alpha}}) > 0$  and a continuous solution map of (1) from  $H^{-\alpha}(\mathbf{R})$  to  $C_t H_x^{-\alpha}([0, T] \times \mathbf{R})$ .

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## Previous works on (1)

- Kenig, Ponce and Vega '96 established local well-posedness of (1) up to  $H^{-\frac{3}{4}+}$ .
- Bejenaru and Tao '06 established that (1) is locally well-posed up to  $H^{-1}$  and ill-posed below  $H^{-1}$ .

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# Preliminaries

We define the spatial Fourier transform of  $f(x) \in \mathcal{S}(\mathbf{R})$

$$\widehat{f}(\xi) = \int_{\mathbf{R}} f(x) e^{-ix\xi} dx.$$

and space-time Fourier transform of  $f(t, x) \in \mathcal{S}(\mathbf{R} \times \mathbf{R})$

$$\widetilde{f}(\tau, \xi) = \iint_{\mathbf{R} \times \mathbf{R}} f(t, x) e^{-i(t\tau + x\xi)} dx dt.$$

For a reasonable function  $p$ , We define the symbol  $p(\nabla)$  via the Fourier transform:  $\widehat{p(\nabla)f}(\xi) = p(\xi)\widehat{f}(\xi)$ .

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# Free solution and $X^{s,b}$ spaces

The solution of linear Schrödinger's equation  $u_t + iu_{xx} = 0$  with  $u(0) = f \in L^2$  is  $e^{-it\partial_x^2} f$ , defined via Fourier transform as before.

Note  $(\tau - \xi^2)\widetilde{u}(\tau, \xi) = 0$ . So  $\widetilde{e^{-it\partial_x^2} f}$  is supported on  $\tau = \xi^2$ .

$$\|u\|_{X^{s,b}} := \|\langle \xi \rangle^s \langle \tau - \xi^2 \rangle^b \widetilde{u}\|_{L^2_{\tau, \xi}}.$$

For all Strichartz pairs  $(p, q)$ :  $\frac{2}{p} + \frac{1}{q} = \frac{1}{2}$ ,  $2 \leq p, q \leq \infty$

$$\|u\|_{L_t^q L_x^p} \lesssim \|u\|_{X^{0, \frac{1}{2}+}}.$$

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# Change of Variable

We begin by changing the variable in (1) by setting  $v = \langle \nabla \rangle^{-\alpha} u$ .

$$\left\{ \begin{array}{l} v_t + i v_{xx} = \langle \nabla \rangle^{-\alpha} (\langle \nabla \rangle^{\alpha} v \langle \nabla \rangle^{\alpha} v) \\ v(0, x) = f(x) \in L^2(\mathbf{R}). \end{array} \right. \quad (2)$$

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## Another change of variable

Another change of variable:  $v = e^{-it\partial_x^2} f_{>0} + z_{>0}$ .

$$\begin{cases} z_t + iz_{xx} = \langle \nabla \rangle^{-\alpha} \left( \langle \nabla \rangle^{\alpha} (e^{-it\partial_x^2} f_{>0} + z_{>0}) \langle \nabla \rangle^{\alpha} (e^{-it\partial_x^2} f_{>0} + z_{>0}) \right) \\ z(0, x) = 0. \end{cases} \quad (3)$$

We want to construct an explicit solution  $h$  (normal form) for

$$h_t + ih_{xx} = \langle \nabla \rangle^{-\alpha} \left( \langle \nabla \rangle^{\alpha} e^{-it\partial_x^2} f_{>0} \langle \nabla \rangle^{\alpha} e^{-it\partial_x^2} f_{>0} \right). \quad (4)$$



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# Construction of Normal Form

We define a bilinear multiplier  $T_\sigma$  with symbol  $\sigma = \sigma(\xi, \eta)$

$$T_\sigma(u, v)(x) := \frac{1}{4\pi^2} \iint_{\mathbf{R} \times \mathbf{R}} \sigma(\xi, \eta) \widehat{u}_{>0}(\xi) \widehat{v}_{>0}(\eta) e^{i(\xi+\eta)x} d\xi d\eta.$$

Formally, applying  $\partial_t + i\partial_x^2$  to the integrand above would give the following symbol multiplied to  $\sigma$ :

$$i(\tau + \omega) - i(\xi + \eta)^2 = i(\tau - \xi^2) + i(\omega - \eta^2) - 2i\xi\eta.$$

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Thus

$$\begin{aligned}(\partial_t + i\partial_x^2)T_\sigma(u, v) &= T\left((\partial_t + i\partial_x^2)u, v\right) \\ &\quad + T_\sigma\left(u, (\partial_t + i\partial_x^2)v\right) - 2iT_{\xi\eta\cdot\sigma(\xi,\eta)}(u, v).\end{aligned}$$

If  $u = v = e^{-it\partial_x^2}f$ , the first two terms disappear.

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## Normal form (continued)

In order to satisfy (4), we want

$$-2iT_{\xi\eta\cdot\sigma(\xi,\eta)}(e^{-it\partial_x^2}f, e^{-it\partial_x^2}f) = \langle\nabla\rangle^{-\alpha} \left( \langle\nabla\rangle^{\alpha} e^{-it\partial_x^2}f \langle\nabla\rangle^{\alpha} e^{-it\partial_x^2}f \right)$$

So we let  $\sigma(\xi, \eta) = -\frac{1}{2i} \frac{1}{\xi\eta} \frac{\langle\xi\rangle^{\alpha}\langle\eta\rangle^{\alpha}}{\langle\xi+\eta\rangle^{\alpha}}.$

Thus  $h(t, x) = T_{\sigma}(e^{-it\partial_x^2}f, e^{-it\partial_x^2}f)$  satisfies equation (4) with the initial condition  $h(0, x) = T_{\sigma}(f, f).$

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We claim  $T : L^2 \times L^2 \rightarrow H^{\frac{1}{2}}$   
 and also  $T : X^{0, \frac{1}{2}+\delta} \times X^{0, \frac{1}{2}+\delta} \rightarrow L_t^2 H_x^1$ .

Now  $v = e^{-it\partial_x^2} f + h + w$  where  $w$  solves

$$\begin{cases} w_t + iw_{xx} = \mathcal{N}(e^{-it\partial_x^2} f, w + h) + \mathcal{N}(h + w, h + w) \\ w(0, x) = -T(f, f)(x) \in H^{\frac{1}{2}}(\mathbf{R}). \end{cases} \quad (5)$$

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## $X^{s,b}$ estimate

We have the Strichartz estimate for  $b > 1/2$

$$\left\| \int_0^t e^{-i(t-s)\partial_x^2} \mathcal{N}(s) ds \right\|_{X_T^{s,b}} \leq \|\mathcal{N}\|_{X^{s,b-1}}.$$

So if we want to construct a fixed point argument for  $w_t + iw_{xx} = \mathcal{N}$ , then we need to estimate  $\|\mathcal{N}\|_{X_T^{s,b-1}}$ .

We construct this argument for  $w \in X^{\alpha-\frac{1}{2}, \frac{1}{2}+\delta}$ , so we need to estimate

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## Non-linearities of (5)

We need to consider

$$\mathcal{N}(e^{-it\partial_x^2} f, w), \mathcal{N}(w, w), \mathcal{N}(h, h), \mathcal{N}(w, h), \mathcal{N}(e^{-it\partial_x^2} f, h),$$

After some work, we arrive at the estimates:

$$\|\mathcal{N}(u, v)\|_{X_T^{\alpha-\frac{1}{2}, -\frac{1}{2}+\delta}} \leq C_{T,\delta} \|u\|_{X^{0, \frac{1}{2}+\delta}} \|v\|_{X^{\alpha-\frac{1}{2}, \frac{1}{2}+\delta}}$$

$$\|\mathcal{N}(u, v)\|_{X_T^{\alpha-\frac{1}{2}, -\frac{1}{2}+\delta}} \leq C_{T,\delta} \|u\|_{L_t^2 H_x^1} \|v\|_{L_t^2 H_x^1}$$

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## Problematic case

But the estimate

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is false!

However,  $h = T(e^{-it\partial_x^2} f, e^{-it\partial_x^2} f)$ .

So the problematic term is in a trilinear form  $\mathcal{N}(T(f, g), v)$  with  $f, g, v \in X^{0, \frac{1}{2}+\delta}$ . Using the trilinear form, we show

$$\|\mathcal{N}(T(f, g), v)\|_{X^{\alpha-\frac{1}{2}, -\frac{1}{2}+\delta}} \leq C \|f\|_{X^{0, \frac{1}{2}+\delta}} \|g\|_{X^{0, \frac{1}{2}+\delta}} \|v\|_{X^{0, \frac{1}{2}+\delta}}.$$

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## Derivative quadratic non-linearity

$$\left| \begin{array}{l} u_t + iu_{xx} = \langle \nabla \rangle^\beta [u^2] \\ u(0, x) \in H^{-\alpha}(\mathbf{R}). \end{array} \right. \quad (6)$$

- M. Christ: (6) is ill-posed when  $\beta = 1$  for large data.
- A. Stefanov, '07: (6) is l.w.p. for small data in  $H^1$  when  $\beta = 1$ .
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# Main result

## Theorem

(6) is l.w.p. in  $H^{-\alpha}$  when  $\alpha + \beta < 1$ ,  $\beta < 1/2$ .

Also, we can write  $u = e^{-it\partial_x^2} u(0) + h + w$  where  
 $h \in L_t^\infty H_x^{\frac{1}{2}-\alpha} \cap L_t^2 H_x^{1-\alpha}$  and  $w \in X_T^{-\frac{1}{2}, \frac{1}{2}+\delta}$ .

We can also write a Lipschitz property for a smoother space

$$\|u - v\|_{L_T^\infty H_x^{-\frac{1}{2}}} \leq C \|u_0 - v_0\|_{H^{-\frac{1}{2}}}$$

where  $C := C(\|u_0\|_{H^{-\alpha}}, \|v_0\|_{H^{-\alpha}})$ .