

Optimal and Better Transports

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jointly with M. Beiglböck, M. Goldstern and W. Schachermayer

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Fields Institute, Toronto

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- ▶ The Kantorovich Problem is to minimize the functional

$$I_c[\pi] : \pi \mapsto \int_{X \times Y} c(x, y) d\pi(x, y)$$

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over all transport plans $\pi \in \Pi(\mu, \nu)$.

$\Pi(\mu, \nu) \dots$ measures with X -marginal μ and Y -marginal ν .

Moving Croissants

Topics in Optimal Transportation



X ... bakeries, Y ... cafes

Cyclical Rerouting

Definition

A Borel set $\Gamma \subseteq X \times Y$ is called *c-monotone* if

$$\sum_{i=1}^n c(x_i, y_i) \leq \sum_{i=1}^n c(x_i, y_{\sigma(i)})$$

for every permutation $\sigma \in S(n)$.

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for all pairs $(x_1, y_1), \dots, (x_n, y_n) \in \Gamma$. (where $y_{n+1} := y_1$)

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for all pairs $(x_1, y_1), \dots, (x_n, y_n) \in \Gamma$. (where $y_{n+1} := y_1$)

- ▶ A transport plan π is called *c-monotone* if there exists such a Γ with $\pi(\Gamma) = 1$.

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X and Y finite: Suppose π is a transport plan on whose support c -monotonicity is violated.

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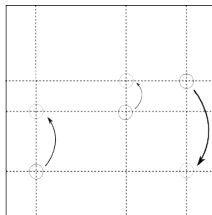
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'96, W. Gangbo and R. McCann

Improve π :

$$\pi^\beta := \pi + \alpha \sum_{i=1}^n \delta_{(x_i, y_{i+1})} - \alpha \sum_{i=1}^n \delta_{(x_i, y_i)}.$$

'96, W. Gangbo and R. McCann

Improve π :

$$I_c[\pi^\beta] = I_c[\pi] + \alpha \sum_{i=1}^n \left(c(x_i, y_{i+1}) - c(x_i, y_i) \right).$$

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Proposition

Let X, Y compact spaces equipped with Borel probability measures ν, μ . Let $c : X \times Y \rightarrow \mathbb{R}_{\geq 0}$ be a continuous cost function. Then every optimal transport plan is c -monotone.

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Necessary ...

Proposition ('09, BGMS)

Let X and Y be *Polish spaces* equipped with Borel probability measures ν, μ . Let $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ be a *measurable* cost function. Then every optimal transport plan is c -monotone.

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- ▶ Makes use of deep duality results by H. Kellerer in the multimarginal setting.
- ▶ Dichotomy of Borel subsets of $(X \times Y)^n$.

... but not sufficient

Example ('01, Ambrosio and Pratelli)

Let $X = Y = [0, 1]$ be the torus, equipped with Lebesgue measure.

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Let $\Gamma_2 = \{(x, x + \alpha) : x \in X\}$.

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Let $c = a$ on Γ_1 , $c = b$ on Γ_2 and ∞ else.

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- ▶ Both Γ_1 and Γ_2 are c -monotone.
- ▶ Both Γ_1 or Γ_2 support a unique transport plan π_1 resp. π_2 .
- ▶ $I_c[\pi_1] = a$ and $I_c[\pi_2] = b$.

'96, W. Gangbo and R. McCann

Proposition

Let $X = Y = \mathbb{R}^n$ and $c : X \times Y \rightarrow \mathbb{R}_{\geq 0}$ strictly convex. Then every π which is c -monotone is optimal.

'01, L. Ambrosio and A. Pratelli

Proposition

Let X, Y be Polish spaces and $c : X \times Y \rightarrow \mathbb{R}_{\geq 0}$ l.s.c. fulfilling the moment conditions

$$\mu \left(\left\{ x : \int_Y c(x, y) d\nu(y) < \infty \right\} \right) > 0,$$
$$\nu \left(\left\{ y : \int_X c(x, y) d\mu(x) < \infty \right\} \right) > 0.$$

Then every π which is c -monotone is optimal.

'07, A. Pratelli; W. Schachermayer and J. Teichmann

Proposition

Let X, Y be Polish spaces and $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ a continuous cost function. Then every π which is c -monotone is optimal.

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Let X, Y be Polish spaces and $c : X \times Y \rightarrow \mathbb{R}_{\geq 0}$ a finite and l.s.c. cost function. Then every π which is c -monotone is optimal.

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M. Beiglböck, M. Goldstern, W. Schachermayer, G. M.

Theorem

Let X and Y be Polish spaces. Let $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ be Borel measurable and such that the set $\{(x, y) : c(x, y) = \infty\}$ is

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Theorem

*Let X and Y be Polish spaces. Let $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ be Borel measurable and such that the set $\{(x, y) : c(x, y) = \infty\}$ is **closed**:*

Then every finite c -monotone transport is optimal.

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Theorem

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Remark

Transport plans are usually supported on a $\mu \otimes \nu$ -null set.

Towards Better Optimality

Definition

A Borel set $\Gamma \subseteq X \times Y$ is *strongly c-monotone* iff there exist Borel measurable functions $\varphi : X \rightarrow \mathbb{R} \cup \{-\infty\}$ and $\psi : Y \rightarrow \mathbb{R} \cup \{-\infty\}$ such that

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Consistency

- ▶ A transport plan $\pi \in \Pi(\mu, \nu)$ is strongly c -monotone if it is concentrated on a strongly c -monotone Borel set Γ .

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□

- ▶ Strong monotonicity implies optimality.

... but not necessary.

Example

- ▶ Let $X = Y = [0, 1]$ equipped with Lebesgue measure λ .

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Example

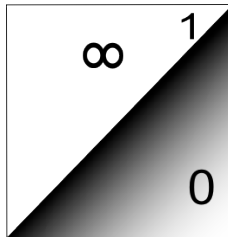
- ▶ Let $X = Y = [0, 1]$ equipped with Lebesgue measure λ .
- ▶ Take $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ to be infinite above the diagonal, 1 on the diagonal and 0 below.

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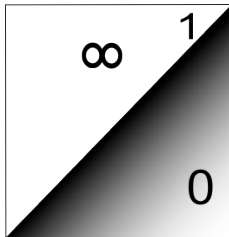
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- ▶ Take $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ to be infinite above the diagonal, 1 on the diagonal and 0 below.
- ▶ Let $\Gamma = \{(x, x) : x \in [0, 1]\}$ be the diagonal in $X \times Y$.

Counterexample

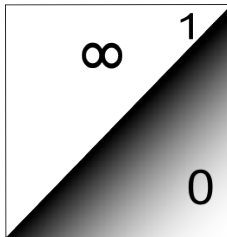


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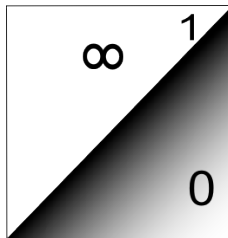
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- ▶ Γ is c -monotone,
- ▶ Γ is not strongly c -monotone,
- ▶ $\text{Id}: X \rightarrow Y$ induces an optimal transport, which is concentrated Γ .

Robust Optimality

Z	c finite	0
Y	c	c finite
	X	Z

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Theorem

For a finite transport plan robust optimality is equivalent to strong c -monotonicity.

The almost finite situation

When we put all our results together we get:

Theorem

Let $c : X \times Y \rightarrow \mathbb{R}_{\geq 0} \cup \{\infty\}$ be Borel measurable and $\mu \otimes \nu$ -a.s. finite. For a finite transport plan π t.f.a.e.

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2. π is strongly c -monotone.
3. π is optimal.

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1. π is c -monotone.
2. π is strongly c -monotone.
3. π is optimal.
4. π is robustly optimal.

Thank you for your attention!

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