

WELLPOSEDNESS OF SECOND ORDER BSDEs

Nizar TOUZI

Ecole Polytechnique Paris

Joint with Mete SONER and Jianfeng ZHANG

Foundations of Financial Mathematics
Fields Institute, Toronto
January 11-15, 2010



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



Hedging under Gamma constraints

- nonrisky asset $S^0 \equiv 1$ normalized to unity
- Risky asset defined by BS model $dS_t = S_t \sigma dW_t$
- Wealth process : $Y_t^Z = Y_0 + \int_0^t Z_u dS_u$, where Z is the portfolio strategy assumed to be a semimartingale with

$$d\langle Z, S \rangle_t = \Gamma_t d\langle S \rangle_t \quad (\text{the so-called Gamma})$$

- Given a payoff $\xi \in \mathbb{L}^0(\mathcal{F}_T)$, superhedging problem :

$$V_0 := \inf \left\{ Y_0 : \exists Z \in \mathcal{Z}, \underline{\Gamma} \leq \Gamma \leq \bar{\Gamma} \text{ and } Y_T^Z \geq \xi \text{ } \mathbb{P} - \text{a.s.} \right\}$$

- Or the corresponding hedging problem : find $Z \in \mathcal{Z}$ and some "minimal" nondecreasing process K , $K_0 = 0$, such that

$$Y_T^Z - K_T = \xi, \text{ } \mathbb{P} - \text{a.s.}$$



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



Market illiquidity Çetin, Jarrow and Protter 2004

$S^0 \equiv 1$ and Risky asset price is defined by

- the marginal price S_t , $t \geq 0$
- the supply curve $\nu \mapsto \mathcal{S}(\cdot, \nu)$ with $\mathcal{S}(s, 0) = s$:

$\mathcal{S}(S_t, \nu)$ price per share of ν risky assets

The self-financing condition leads to :

$$Y_T = Y_0 + \sum Z_{t_{i-1}} \Delta S_{t_i} - \sum \Delta Z_{t_i} [\mathcal{S}(S_{t_i}, \Delta Z_{t_i}) - \mathcal{S}(S_{t_i}, 0)]$$

Assume $\nu \mapsto \mathcal{S}(\cdot, \nu)$ is smooth (unlike proportional transaction costs models), then :

$$Y_T = Y_0 + \int_0^T Z_t dS_t - \int_0^T \frac{\partial \mathcal{S}}{\partial \nu}(S_t, 0) d\langle Z^c \rangle_t - \sum_{t \leq T} \Delta Z_t [\mathcal{S}(S_t, \Delta Z_t) - S_t]$$

The Hedging Problem

- Let $dS_t = S_t \sigma dW_t$, then

$$d\langle Z^c \rangle_t = \Gamma_t^2 d\langle S \rangle_t : \quad \text{the so-called Gamma...}$$

- Wealth process (jumps in portfolio are sub-optimal) :

$$dY_t = Z_t dS_t - \frac{\partial \mathcal{S}}{\partial \nu}(S_t, 0) \Gamma_t^2 d\langle S \rangle_t \quad \text{where} \quad d\langle Z, S \rangle_t =: \Gamma_t d\langle S \rangle_t$$

- For a contingent claim ξ , **Super-hedging problem**

$$V := \inf \left\{ y : Y_T^{y,Z} \geq \xi \text{ } \mathbb{P} - \text{a.s. for some "admissible" } Z \right\}$$

or, the corresponding **hedging problem**

$$Y_T^{y,Z} - K_T = \xi, \text{ } \mathbb{P} - \text{a.s. for some "admissible" } Z$$



Main difficulty

Without further restrictions on trading strategies, the continuous-time problem reduces to Black-Scholes !

Lemma (Bank-Baum 04) *For predictable W -integ. càdlàg process ϕ , and $\varepsilon > 0$, there exists an absolutely continuous predictable process $\phi_t^\varepsilon = \phi_0^\varepsilon + \int_0^t \alpha_r dr$ such that*

$$\sup_{0 \leq t \leq 1} \left| \int_0^t \phi_r dW_r - \int_0^t \phi_r^\varepsilon dW_r \right| \leq \varepsilon$$

\implies If the "admissibility" set allows for arbitrary a.c. portfolio $Z_t = Z_0 + \int_0^t \alpha_u du$, then $V = V^{\text{BS}}$ (with $\Gamma = 0$!)



Asymptotics of the discrete-time solution

BUT Gokay and Soner 09 showed that the discrete-time super-hedging cost (with time step $\frac{1}{n}$)

$$V^n \longrightarrow V^\infty \neq V^{\text{BS}} !$$

V^∞ is characterized as the unique viscosity solution of

$$-V_t^\infty(t, s) + \frac{1}{4}s^2\sigma(t, s)^2\ell(s) \left[1 - \left(\frac{V_{ss}^\infty(t, s)}{\ell(s)} + 1 \right)^+ \right]^2 = 0$$

with $V^\infty(T, \cdot) = g$ and $-C \leq V^\infty \leq C(1 + s)$. Here $\ell := (4\frac{\partial S}{\partial \nu})^{-1}$

In the continuous-time problem, Cetin, Soner and T. derive directly this nonlinear PDE under appropriate restrictions on the trading strategies... similar to previous work on Gamma constraints Cheridito, Soner, T.



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



Intuitive introduction of the scheme

- Isolate a diffusion part in the equation :

$$0 = -v_t(t, x) - \frac{1}{2} \Delta v(t, x) - f(x, Dv(t, x), D^2v(t, x))$$

- The Monte Carlo component Let $X_s = x + W_{s-t+h}$, $s \geq t-h$, evaluate at (s, X_s) , and take expectations :

$$\begin{aligned} 0 &= \mathbb{E} \left[\int_{t-h}^t -(v_t + \frac{1}{2} \Delta v)(s, X_s) ds - \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \\ &= v(t-h, x) - \mathbb{E} \left[v(t, X_t) + \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \end{aligned}$$

- The Finite Differences component Natural approximation

$$\hat{v}(t-h, x) = \mathbb{E}[\hat{v}(t, X_t)] + h f(x, \mathbb{E}[D\hat{v}(t, X_t)], \mathbb{E}[D^2\hat{v}(t, X_t)])$$

To get rid of differentiation, apply an ibp argument



Intuitive introduction of the scheme

- Isolate a diffusion part in the equation :

$$0 = -v_t(t, x) - \frac{1}{2} \Delta v(t, x) - f(x, Dv(t, x), D^2v(t, x))$$

- The Monte Carlo component** Let $X_s = x + W_{s-t+h}$, $s \geq t-h$, evaluate at (s, X_s) , and take expectations :

$$\begin{aligned} 0 &= \mathbb{E} \left[\int_{t-h}^t -(v_t + \frac{1}{2} \Delta v)(s, X_s) ds - \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \\ &= v(t-h, x) - \mathbb{E} \left[v(t, X_t) + \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \end{aligned}$$

- The Finite Differences component** Natural approximation

$$\hat{v}(t-h, x) = \mathbb{E}[\hat{v}(t, X_t)] + h f(x, \mathbb{E}[D\hat{v}(t, X_t)], \mathbb{E}[D^2\hat{v}(t, X_t)])$$

To get rid of differentiation, apply an ibp argument



Intuitive introduction of the scheme

- Isolate a diffusion part in the equation :

$$0 = -v_t(t, x) - \frac{1}{2} \Delta v(t, x) - f(x, Dv(t, x), D^2v(t, x))$$

- The Monte Carlo component** Let $X_s = x + W_{s-t+h}$, $s \geq t-h$, evaluate at (s, X_s) , and take expectations :

$$\begin{aligned} 0 &= \mathbb{E} \left[\int_{t-h}^t -(v_t + \frac{1}{2} \Delta v)(s, X_s) ds - \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \\ &= v(t-h, x) - \mathbb{E} \left[v(t, X_t) + \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \end{aligned}$$

- The Finite Differences component** Natural approximation

$$\hat{v}(t-h, x) = \mathbb{E}[\hat{v}(t, X_t)] + h f(x, \mathbb{E}[D\hat{v}(t, X_t)], \mathbb{E}[D^2\hat{v}(t, X_t)])$$

To get rid of differentiation, apply an ibp argument



Intuitive introduction of the scheme

- Isolate a diffusion part in the equation :

$$0 = -v_t(t, x) - \frac{1}{2} \Delta v(t, x) - f(x, Dv(t, x), D^2v(t, x))$$

- The Monte Carlo component** Let $X_s = x + W_{s-t+h}$, $s \geq t-h$, evaluate at (s, X_s) , and take expectations :

$$\begin{aligned} 0 &= \mathbb{E} \left[\int_{t-h}^t -(v_t + \frac{1}{2} \Delta v)(s, X_s) ds - \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \\ &= v(t-h, x) - \mathbb{E} \left[v(t, X_t) + \int_{t-h}^t f(., Dv, D^2)(s, X_s) ds \right] \end{aligned}$$

- The Finite Differences component** Natural approximation

$$\hat{v}(t-h, x) = \mathbb{E}[\hat{v}(t, X_t)] + h f(x, \mathbb{E}[D\hat{v}(t, X_t)], \mathbb{E}[D^2\hat{v}(t, X_t)])$$

To get rid of differentiation, apply an ibp argument



Intuition From Greeks Calculation

- Using the approximation $f'(x) \sim_{h=0} \mathbb{E}[f'(x + W_h)]$:

$$\begin{aligned} f'(x) &\sim \int f'(x+y) \frac{e^{-y^2/(2h)}}{\sqrt{2\pi}} dy \\ &= \int f(x+y) \frac{y}{h} \frac{e^{-y^2/(2h)}}{\sqrt{2\pi}} dy \\ &= \mathbb{E} \left[f(x + W_h) \frac{W_h}{h} \right] \end{aligned}$$

- Similarly, by an additional integration by parts :

$$\begin{aligned} f''(x) &= \int f(x+y) \frac{y^2 - h}{h^2} \frac{e^{-y^2/(2h)}}{\sqrt{2\pi}} dy \\ &= \mathbb{E} \left[f(x + W_h) \left(\frac{W_h^2 - h}{h^2} \right) \right] \end{aligned}$$



A probabilistic numerical scheme for fully nonlinear PDEs

This suggests the following discretization :

$$\begin{aligned}
 Y_{t_n}^n &= g(X_{t_n}^n) , \\
 Y_{t_{i-1}}^n &= \mathbb{E}_{i-1}^n [Y_{t_i}^n] + f(X_{t_{i-1}}^n, Y_{t_{i-1}}^n, Z_{t_{i-1}}^n, \Gamma_{t_{i-1}}^n) \Delta t_i , \quad 1 \leq i \leq n , \\
 Z_{t_{i-1}}^n &= \mathbb{E}_{i-1}^n \left[Y_{t_i}^n \frac{\Delta W_{t_i}}{\Delta t_i} \right] \\
 \Gamma_{t_{i-1}}^n &= \mathbb{E}_{i-1}^n \left[Y_{t_i}^n \frac{|\Delta W_{t_i}|^2 - \Delta t_i}{|\Delta t_i|^2} \right]
 \end{aligned}$$

Convergence results :

- $f_\gamma = f_z = 0$: Bally, Pagès 2003
- $f_\gamma = 0$: Bouchard, T. (2004) and Zhang (2004)
- General : Fahim, T., Warin (2009)



A probabilistic numerical scheme for fully nonlinear PDEs

This suggests the following discretization :

$$\begin{aligned}
 Y_{t_n}^n &= g(X_{t_n}^n) , \\
 Y_{t_{i-1}}^n &= \mathbb{E}_{i-1}^n [Y_{t_i}^n] + f(X_{t_{i-1}}^n, Y_{t_{i-1}}^n, Z_{t_{i-1}}^n, \Gamma_{t_{i-1}}^n) \Delta t_i , \quad 1 \leq i \leq n , \\
 Z_{t_{i-1}}^n &= \mathbb{E}_{i-1}^n \left[Y_{t_i}^n \frac{\Delta W_{t_i}}{\Delta t_i} \right] \\
 \Gamma_{t_{i-1}}^n &= \mathbb{E}_{i-1}^n \left[Y_{t_i}^n \frac{|\Delta W_{t_i}|^2 - \Delta t_i}{|\Delta t_i|^2} \right]
 \end{aligned}$$

Convergence results :

- $f_\gamma = f_z = 0$: Bally, Pagès 2003
- $f_\gamma = 0$: Bouchard, T. (2004) and Zhang (2004)
- General : Fahim, T., Warin (2009)



Outline

- 1 Motivations
 - Hedging under Gamma constraints
 - Hedging under market illiquidity
 - Probabilistic numerics for nonlinear PDEs
- 2 Backward SDEs : a quick review
- 3 2nd order backward SDEs
 - The CSTV framework
 - An alternative formulation of 2BSDEs
- 4 Main results
 - Representation, uniqueness
 - Existence
 - Connection with PDEs and stochastic control



Backward SDEs

Pardoux and Peng (1990, 1992) : W BM on $(\Omega, \mathcal{F}, \mathbb{P})$, $\mathbb{F} = \mathbb{F}^W$

- For $\xi \in \mathbb{L}^2$, $H_t(y, z)$ Lipschitz in (y, z) , $H_t(0, 0) \in \mathbb{H}^2$ the BSDE

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

has a unique solution $(Y, Z) \in \mathbb{S}^2 \times \mathbb{H}^2$

- For $H \equiv 0$, this is just the martingale representation theorem
- Easy proof by means of a fixed point argument
- Other (important) extensions : obstacle, quadratic in z , multidimensional Y , ...



Backward SDEs

Pardoux and Peng (1990, 1992) : W BM on $(\Omega, \mathcal{F}, \mathbb{P})$, $\mathbb{F} = \mathbb{F}^W$

- For $\xi \in \mathbb{L}^2$, $H_t(y, z)$ Lipschitz in (y, z) , $H.(0, 0) \in \mathbb{H}^2$ the BSDE

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

has a unique solution $(Y, Z) \in \mathbb{S}^2 \times \mathbb{H}^2$

- For $H \equiv 0$, this is just the martingale representation theorem
- Easy proof by means of a fixed point argument
- Other (important) extensions : obstacle, quadratic in z , multidimensional Y , ...



Backward SDEs

Pardoux and Peng (1990, 1992) : W BM on $(\Omega, \mathcal{F}, \mathbb{P})$, $\mathbb{F} = \mathbb{F}^W$

- For $\xi \in \mathbb{L}^2$, $H_t(y, z)$ Lipschitz in (y, z) , $H_t(0, 0) \in \mathbb{H}^2$ the BSDE

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

has a unique solution $(Y, Z) \in \mathbb{S}^2 \times \mathbb{H}^2$

- For $H \equiv 0$, this is just the martingale representation theorem
- Easy proof by means of a fixed point argument
- Other (important) extensions : obstacle, quadratic in z , multidimensional Y , ...

Backward SDEs

Pardoux and Peng (1990, 1992) : W BM on $(\Omega, \mathcal{F}, \mathbb{P})$, $\mathbb{F} = \mathbb{F}^W$

- For $\xi \in \mathbb{L}^2$, $H_t(y, z)$ Lipschitz in (y, z) , $H.(0, 0) \in \mathbb{H}^2$ the BSDE

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

has a unique solution $(Y, Z) \in \mathbb{S}^2 \times \mathbb{H}^2$

- For $H \equiv 0$, this is just the martingale representation theorem
- Easy proof by means of a fixed point argument
- Other (important) extensions : obstacle, quadratic in z , multidimensional Y , ...

Connection with PDEs

In the previous context of the BSDE :

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

- Assume further that $H_t(y, z) = h(t, X_t, y, z)$, $\xi = g(X_1)$, and

$$dX_t = b(t, X_t)dt + \sigma(t, X_t)dW_t$$

Then $Y_t = V(t, X_t)$ for some deterministic measurable function V

- V is a viscosity solution of the **semilinear** PDE

$$\partial_t V + \frac{1}{2} \sigma^2 D^2 V + bDV + h(t, x, V, \sigma DV) = 0, \quad V(1, x) = g(x)$$



Connection with PDEs

In the previous context of the BSDE :

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

- Assume further that $H_t(y, z) = h(t, X_t, y, z)$, $\xi = g(X_1)$, and

$$dX_t = b(t, X_t)dt + \sigma(t, X_t)dW_t$$

Then $Y_t = V(t, X_t)$ for some deterministic measurable function V

- V is a viscosity solution of the **semilinear** PDE

$$\partial_t V + \frac{1}{2} \sigma^2 D^2 V + bDV + h(t, x, V, \sigma DV) = 0, \quad V(1, x) = g(x)$$



Motivation from finance

The BSDE

$$dY_t = -H_t(Y_t, Z_t)dt + Z_t dW_t, \quad Y_1 = \xi$$

appeared in many contexts :

- Classical hedging problem in finance ($H \equiv 0$)
- Hedging under different lending and borrowing rates, hedging under portfolio constraints (+ nondecreasing process),
- Recursive utility, Risk measures/monetary utility functions
- Portfolio optimization (only in exponential or power expected utility framework)



Outline

- 1 Motivations
 - Hedging under Gamma constraints
 - Hedging under market illiquidity
 - Probabilistic numerics for nonlinear PDEs
- 2 Backward SDEs : a quick review
- 3 2nd order backward SDEs
 - The CSTV framework
 - An alternative formulation of 2BSDEs
- 4 Main results
 - Representation, uniqueness
 - Existence
 - Connection with PDEs and stochastic control



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



Second Order Backward SDEs

Cheridito, Soner, T. and Victoir 07 (CSTV) :

- 2BSDE :

$$dY_t = -H_t(Y_t, Z_t, \Gamma_t)dt + Z_t \circ dW_t, \quad \Gamma_t dt := d\langle Z, W \rangle_t, \quad Y_1 = \xi$$

where

$$Z_t \circ dW_t = Z_t dW_t + \frac{1}{2} d\langle Z, W \rangle_t = Z_t dW_t + \frac{1}{2} \Gamma_t dt$$

is the Fisk-Stratonovich stochastic integration.

- If $H_t = h(t, W_t, Y_t, Z_t, \Gamma_t)$ and $\xi = g(W_1)$, then $Y_t = V(t, W_t)$, where V is associated with the **fully nonlinear** PDE :

$$\partial_t V + h(t, x, V, DV, D^2 V) = 0 \quad \text{and} \quad V(1, x) = g(x).$$



Second Order Backward SDEs

Cheridito, Soner, T. and Victoir 07 (CSTV) :

- 2BSDE :

$$dY_t = -H_t(Y_t, Z_t, \Gamma_t)dt + Z_t \circ dW_t, \quad \Gamma_t dt := d\langle Z, W \rangle_t, \quad Y_1 = \xi$$

where

$$Z_t \circ dW_t = Z_t dW_t + \frac{1}{2} d\langle Z, W \rangle_t = Z_t dW_t + \frac{1}{2} \Gamma_t dt$$

is the Fisk-Stratonovich stochastic integration.

- If $H_t = h(t, W_t, Y_t, Z_t, \Gamma_t)$ and $\xi = g(W_1)$, then $Y_t = V(t, W_t)$, where V is associated with the **fully nonlinear** PDE :

$$\partial_t V + h(t, x, V, DV, D^2 V) = 0 \quad \text{and} \quad V(1, x) = g(x).$$



The uniqueness result of CSTV (only Markov case)

- **Existence** : if corresponding PDE has a smooth solution, then

$$Y_t = V(t, W_t), \quad Z_t = DV(t, W_t), \quad \Gamma_t = D^2V(t, W_t).$$

- **Uniqueness** : Second Order Stochastic Target Problem

$$V(t, x) := \inf \left\{ y : Y_1^{y, Z} \geq g(W_1) \text{ for some } Z \in \mathcal{Z} \right\}$$

$$U(t, x) := \sup \left\{ y : Y_1^{y, Z} \leq g(W_1) \text{ for some } Z \in \mathcal{Z} \right\}$$

V and U are resp. viscosity super and subsolution of the PDE

If the comparison principle for viscosity solutions of PDE holds, then 2BSDE has a **unique solution in class \mathcal{Z}**



The uniqueness result of CSTV (only Markov case)

- **Existence** : if corresponding PDE has a smooth solution, then

$$Y_t = V(t, W_t), \quad Z_t = DV(t, W_t), \quad \Gamma_t = D^2 V(t, W_t).$$

- **Uniqueness** : Second Order Stochastic Target Problem

$$V(t, x) := \inf \left\{ y : Y_1^{y, Z} \geq g(W_1) \text{ for some } Z \in \mathcal{Z} \right\}$$

$$U(t, x) := \sup \left\{ y : Y_1^{y, Z} \leq g(W_1) \text{ for some } Z \in \mathcal{Z} \right\}$$

V and U are resp. viscosity super and subsolution of the PDE

If the comparison principle for viscosity solutions of PDE holds, then 2BSDE has a **unique solution in class \mathcal{Z}**



The admissibility set \mathcal{Z} in CSTV

Definition $Z \in \mathcal{Z}$ if it is of the form

$$Z_t = \sum_{n=0}^{N-1} z_n \mathbf{1}_{\{t < \tau_{n+1}\}} + \int_0^t \alpha_s ds + \int_0^t \Gamma_s dW_s$$

- (τ_n) is an \nearrow seq. of stop. times, z_n are \mathcal{F}_{τ_n} -measurable, $\|N\|_\infty < \infty$
- Z_t and Γ_t are \mathbb{L}^∞ -bounded up to some polynomial of X_t
- $\Gamma_t = \Gamma_0 + \int_0^t a_s ds + \int_0^t \xi_s dW_s$, $0 \leq t \leq T$, and

$$\|\alpha\|_{B,b} + \|a\|_{B,b} + \|\xi\|_{B,2} < \infty, \quad \|\phi\|_{B,b} := \left\| \sup_{0 \leq t \leq T} \frac{|\phi_r|}{1 + X_t^B} \right\|_{\mathbb{L}^b}$$



Uniqueness in larger class

Counter-example The following linear 2BSDE with constant coefficients has a nonzero solution in \mathbb{L}^2 :

$$dY_t = -\frac{1}{2}c\Gamma_t dt + Z_t \circ dW_t, \quad Y_1 = 0,$$

whenever $c \neq 1$



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



General framework

$\Omega := C([0, 1], \mathbb{R}^d)$, B : coordinate process, \mathbb{P}_0 : Wiener measure
 $\mathbb{F} := \{\mathcal{F}_t\}_{0 \leq t \leq 1}$: filtration generated by B , \mathbb{F}^+

\mathbb{P} is a **local martingale measure** if B local martingale under \mathbb{P}

Karandikar 95 : $\int_0^t B_s dB_s$, defined ω -wise, and coincides with the Itô integral, \mathbb{P} -a.s. for all local martingale measure \mathbb{P} . Then

$$\langle B \rangle_t := B_t B_t^T - 2 \int_0^t B_s dB_s^T \quad \text{and} \quad \hat{a}_t := \overline{\lim}_{\varepsilon \downarrow 0} \frac{1}{\varepsilon} \left(\langle B \rangle_t - \langle B \rangle_{t-\varepsilon} \right),$$

defined ω -wise

$\overline{\mathcal{P}}_W$: set of all local martingale measures \mathbb{P} such that

$\langle B \rangle_t$ is a. c. in t and \hat{a} takes values in $S_d^{>0}(\mathbb{R})$, \mathbb{P} - a.s.



General framework, continued

For every \mathbb{F} -prog. meas. α valued in $\mathbb{S}_d^{>0}(\mathbb{R})$ with $\int_0^1 |\alpha_t| dt < \infty$, \mathbb{P}_0 -a.s. Define

$$\mathbb{P}^\alpha := \mathbb{P}_0 \circ (X^\alpha)^{-1} \quad \text{where} \quad X_t^\alpha := \int_0^t \alpha_s^{1/2} dB_s, t \in [0, 1], \mathbb{P}_0 - \text{a.s.}$$

$\overline{\mathcal{P}}_S \subset \overline{\mathcal{P}}_W$: collection of all such \mathbb{P}^α

Then every $\mathbb{P} \in \overline{\mathcal{P}}_S$

- satisfies the Blumenthal zero-one law
- and the martingale representation property



Nonlinear generators

$$H_t(\omega, y, z, \gamma) : [0, 1] \times \Omega \times \mathbb{R} \times \mathbb{R}^d \times D_H \rightarrow \mathbb{R}$$

$D_H \subset \mathbb{R}^{d \times d}$ given, containing 0

- For fixed (y, z, γ) , H is \mathbb{F} –progressively measurable
- H is uniformly Lipschitz in (y, z) , lsc in γ
- H is uniformly continuous in ω under the \mathbb{L}^∞ –norm

$$F_t(\omega, y, z, a) := \sup_{\gamma \in D_H} \left\{ \frac{1}{2} a : \gamma - H_t(\omega, y, z, \gamma) \right\}, \quad a \in \mathbb{S}_d^{>0}(\mathbb{R});$$

$$\hat{F}_t(y, z) := F_t(y, z, \hat{a}_t) \quad \text{and} \quad \hat{F}_t^0 := \hat{F}_t(0, 0)$$

\mathcal{P}_H : set of all $\mathbb{P} \in \overline{\mathcal{P}}_S$ such that

$$\underline{a}_{\mathbb{P}} \leq \hat{a} \leq \bar{a}_{\mathbb{P}}, \text{ for some } \underline{a}_{\mathbb{P}}, \bar{a}_{\mathbb{P}} \text{ and } \mathbb{E}^{\mathbb{P}} \left[\int_0^1 |\hat{F}_t^0|^2 dt \right] < \infty.$$

Def \mathcal{P}_H –q.s. means \mathbb{P} –a.s. for all $\mathbb{P} \in \mathcal{P}_H$ (Denis-Martini 04)



Nonlinear generators

$$H_t(\omega, y, z, \gamma) : [0, 1] \times \Omega \times \mathbb{R} \times \mathbb{R}^d \times D_H \rightarrow \mathbb{R}$$

$D_H \subset \mathbb{R}^{d \times d}$ given, containing 0

- For fixed (y, z, γ) , H is \mathbb{F} –progressively measurable
- H is uniformly Lipschitz in (y, z) , lsc in γ
- H is uniformly continuous in ω under the \mathbb{L}^∞ –norm

$$F_t(\omega, y, z, a) := \sup_{\gamma \in D_H} \left\{ \frac{1}{2} a : \gamma - H_t(\omega, y, z, \gamma) \right\}, \quad a \in \mathbb{S}_d^{>0}(\mathbb{R});$$

$$\hat{F}_t(y, z) := F_t(y, z, \hat{a}_t) \quad \text{and} \quad \hat{F}_t^0 := \hat{F}_t(0, 0)$$

\mathcal{P}_H : set of all $\mathbb{P} \in \overline{\mathcal{P}}_S$ such that

$$\underline{a}_{\mathbb{P}} \leq \hat{a} \leq \bar{a}_{\mathbb{P}}, \text{ for some } \underline{a}_{\mathbb{P}}, \bar{a}_{\mathbb{P}} \text{ and } \mathbb{E}^{\mathbb{P}} \left[\int_0^1 |\hat{F}_t^0|^2 dt \right] < \infty.$$

Def \mathcal{P}_H –q.s. means \mathbb{P} –a.s. for all $\mathbb{P} \in \mathcal{P}_H$ (Denis-Martini 04)



Nonlinear generators

$$H_t(\omega, y, z, \gamma) : [0, 1] \times \Omega \times \mathbb{R} \times \mathbb{R}^d \times D_H \rightarrow \mathbb{R}$$

$D_H \subset \mathbb{R}^{d \times d}$ given, containing 0

- For fixed (y, z, γ) , H is \mathbb{F} –progressively measurable
- H is uniformly Lipschitz in (y, z) , lsc in γ
- H is uniformly continuous in ω under the \mathbb{L}^∞ –norm

$$F_t(\omega, y, z, a) := \sup_{\gamma \in D_H} \left\{ \frac{1}{2} a : \gamma - H_t(\omega, y, z, \gamma) \right\}, \quad a \in \mathbb{S}_d^{>0}(\mathbb{R});$$

$$\hat{F}_t(y, z) := F_t(y, z, \hat{a}_t) \quad \text{and} \quad \hat{F}_t^0 := \hat{F}_t(0, 0)$$

\mathcal{P}_H : set of all $\mathbb{P} \in \overline{\mathcal{P}}_S$ such that

$$\underline{a}_{\mathbb{P}} \leq \hat{a} \leq \bar{a}_{\mathbb{P}}, \text{ for some } \underline{a}_{\mathbb{P}}, \bar{a}_{\mathbb{P}} \text{ and } \mathbb{E}^{\mathbb{P}} \left[\int_0^1 |\hat{F}_t^0|^2 dt \right] < \infty.$$

Def \mathcal{P}_H –q.s. means \mathbb{P} –a.s. for all $\mathbb{P} \in \mathcal{P}_H$ (Denis-Martini 04)



Nonlinear generators

$$H_t(\omega, y, z, \gamma) : [0, 1] \times \Omega \times \mathbb{R} \times \mathbb{R}^d \times D_H \rightarrow \mathbb{R}$$

$D_H \subset \mathbb{R}^{d \times d}$ given, containing 0

- For fixed (y, z, γ) , H is \mathbb{F} –progressively measurable
- H is uniformly Lipschitz in (y, z) , lsc in γ
- H is uniformly continuous in ω under the \mathbb{L}^∞ –norm

$$F_t(\omega, y, z, a) := \sup_{\gamma \in D_H} \left\{ \frac{1}{2} a : \gamma - H_t(\omega, y, z, \gamma) \right\}, \quad a \in \mathbb{S}_d^{>0}(\mathbb{R});$$

$$\hat{F}_t(y, z) := F_t(y, z, \hat{a}_t) \quad \text{and} \quad \hat{F}_t^0 := \hat{F}_t(0, 0)$$

\mathcal{P}_H : set of all $\mathbb{P} \in \overline{\mathcal{P}}_S$ such that

$$\underline{a}_{\mathbb{P}} \leq \hat{a} \leq \bar{a}_{\mathbb{P}}, \text{ for some } \underline{a}_{\mathbb{P}}, \bar{a}_{\mathbb{P}} \text{ and } \mathbb{E}^{\mathbb{P}} \left[\int_0^1 |\hat{F}_t^0|^2 dt \right] < \infty.$$

Def \mathcal{P}_H –q.s. means \mathbb{P} –a.s. for all $\mathbb{P} \in \mathcal{P}_H$ (Denis-Martini 04)



Target problem and relaxations $\mathcal{V}(\xi) \geq \bar{\mathcal{V}}(\xi) = \bar{\bar{\mathcal{V}}}(\xi)$

- $Z \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathcal{SM}^2(\mathbb{P})$, $d\langle Z, B \rangle_t = \Gamma_t d\langle B \rangle_t$, \mathcal{P}_H -q.s. and

$$Y_t^Z = Y_0^Z - \int_0^t H_s(Y_s, Z_s, \Gamma_s) ds + \int_0^t Z_s \circ dB_s$$

$$\mathcal{V}(\xi) := \inf \left\{ Y_0 : Y_T^Z \geq \xi \text{ } \mathcal{P}_H\text{-q.s. } Z \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathcal{SM}^2(\mathbb{P}) \right\}$$

Relaxation 1

$$\bar{Y}_t^{\mathbb{P}, \bar{Z}, \bar{\Gamma}} = \bar{Y}_0 + \int_0^t \left(\frac{1}{2} \hat{a}_s : \bar{\Gamma}_s - H_s(\bar{Y}_s^{\mathbb{P}, \bar{Z}, \bar{\Gamma}}, \bar{Z}_s, \bar{\Gamma}_s) \right) ds + \int_0^t \bar{Z}_s dB_s,$$

$$\bar{\mathcal{V}}(\xi) := \inf \left\{ \bar{Y}_0 : \exists \bar{Z}, \bar{G} \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathbb{H}^2(\mathbb{P}), \bar{Y}_T^{\mathbb{P}, \bar{Z}} \geq \xi \text{ } \mathbb{P}\text{-a.s. } \mathbb{P} \in \mathcal{P}_H \right\}$$

$$\text{Relaxation 2 } \bar{\bar{Y}}_t^{\mathbb{P}, \bar{\bar{Z}}} = \bar{\bar{Y}}_0 + \int_0^t \hat{F}_s(\bar{\bar{Y}}_s, \bar{\bar{Z}}_s) ds + \int_0^t \bar{\bar{Z}}_s dB_s,$$

$$\bar{\bar{\mathcal{V}}}(\xi) := \inf \left\{ \bar{\bar{Y}}_0 : \exists \bar{\bar{Z}} \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathbb{H}^2(\mathbb{P}), \bar{\bar{Y}}_T^{\mathbb{P}, \bar{\bar{Z}}} \geq \xi \text{ } \mathbb{P}\text{-a.s. } \mathbb{P} \in \mathcal{P}_H \right\}$$



Target problem and relaxations $\mathcal{V}(\xi) \geq \bar{\mathcal{V}}(\xi) = \bar{\bar{\mathcal{V}}}(\xi)$

- $Z \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathcal{SM}^2(\mathbb{P})$, $d\langle Z, B \rangle_t = \Gamma_t d\langle B \rangle_t$, \mathcal{P}_H -q.s. and

$$Y_t^Z = Y_0^Z - \int_0^t H_s(Y_s, Z_s, \Gamma_s) ds + \int_0^t Z_s \circ dB_s$$

$$\mathcal{V}(\xi) := \inf \left\{ Y_0 : Y_T^Z \geq \xi \text{ } \mathcal{P}_H\text{-q.s. } Z \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathcal{SM}^2(\mathbb{P}) \right\}$$

Relaxation 1

$$\bar{Y}_t^{\mathbb{P}, \bar{Z}, \bar{\Gamma}} = \bar{Y}_0 + \int_0^t \left(\frac{1}{2} \hat{a}_s : \bar{\Gamma}_s - H_s(\bar{Y}_s^{\mathbb{P}, \bar{Z}, \bar{\Gamma}}, \bar{Z}_s, \bar{\Gamma}_s) \right) ds + \int_0^t \bar{Z}_s dB_s,$$

$$\bar{\mathcal{V}}(\xi) := \inf \left\{ \bar{Y}_0 : \exists \bar{Z}, \bar{G} \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathbb{H}^2(\mathbb{P}), \bar{Y}_T^{\mathbb{P}, \bar{Z}} \geq \xi \text{ } \mathbb{P}\text{-a.s. } \mathbb{P} \in \mathcal{P}_H \right\}$$

$$\text{Relaxation 2 } \bar{\bar{Y}}_t^{\mathbb{P}, \bar{\bar{Z}}} = \bar{\bar{Y}}_0 + \int_0^t \hat{F}_s(\bar{\bar{Y}}_s, \bar{\bar{Z}}_s) ds + \int_0^t \bar{\bar{Z}}_s dB_s,$$

$$\bar{\bar{\mathcal{V}}}(\xi) := \inf \left\{ \bar{\bar{Y}}_0 : \exists \bar{\bar{Z}} \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathbb{H}^2(\mathbb{P}), \bar{\bar{Y}}_T^{\mathbb{P}, \bar{\bar{Z}}} \geq \xi \text{ } \mathbb{P}\text{-a.s. } \mathbb{P} \in \mathcal{P}_H \right\}$$



Target problem and relaxations $\mathcal{V}(\xi) \geq \bar{\mathcal{V}}(\xi) = \bar{\bar{\mathcal{V}}}(\xi)$

- $Z \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathcal{SM}^2(\mathbb{P})$, $d\langle Z, B \rangle_t = \Gamma_t d\langle B \rangle_t$, \mathcal{P}_H -q.s. and

$$Y_t^Z = Y_0^Z - \int_0^t H_s(Y_s, Z_s, \Gamma_s) ds + \int_0^t Z_s \circ dB_s$$

$$\mathcal{V}(\xi) := \inf \left\{ Y_0 : Y_T^Z \geq \xi \text{ } \mathcal{P}_H\text{-q.s. } Z \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathcal{SM}^2(\mathbb{P}) \right\}$$

Relaxation 1

$$\bar{Y}_t^{\mathbb{P}, \bar{Z}, \bar{\Gamma}} = \bar{Y}_0 + \int_0^t \left(\frac{1}{2} \hat{a}_s : \bar{\Gamma}_s - H_s(\bar{Y}_s^{\mathbb{P}, \bar{Z}, \bar{\Gamma}}, \bar{Z}_s, \bar{\Gamma}_s) \right) ds + \int_0^t \bar{Z}_s dB_s,$$

$$\bar{\mathcal{V}}(\xi) := \inf \left\{ \bar{Y}_0 : \exists \bar{Z}, \bar{G} \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathbb{H}^2(\mathbb{P}), \bar{Y}_T^{\mathbb{P}, \bar{Z}} \geq \xi \text{ } \mathbb{P}\text{-a.s. } \mathbb{P} \in \mathcal{P}_H \right\}$$

Relaxation 2

$$\bar{\bar{Y}}_t^{\mathbb{P}, \bar{\bar{Z}}} = \bar{\bar{Y}}_0 + \int_0^t \hat{F}_s(\bar{\bar{Y}}_s, \bar{\bar{Z}}_s) ds + \int_0^t \bar{\bar{Z}}_s dB_s,$$

$$\bar{\bar{\mathcal{V}}}(\xi) := \inf \left\{ \bar{\bar{Y}}_0 : \exists \bar{\bar{Z}} \in \bigcap_{\mathbb{P} \in \mathcal{P}_H} \mathbb{H}^2(\mathbb{P}), \bar{\bar{Y}}_T^{\mathbb{P}, \bar{\bar{Z}}} \geq \xi \text{ } \mathbb{P}\text{-a.s. } \mathbb{P} \in \mathcal{P}_H \right\}$$



Definition

For \mathcal{F}_1 -meas. ξ , consider the 2BSDE :

$$dY_t = \hat{F}_t(Y_t, Z_t)dt + Z_t dB_t - dK_t, \quad 0 \leq t \leq 1, \quad Y_T = \xi, \quad \mathcal{P}_H - \text{q.s.}$$

We say $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ is a solution to the 2BSDE if

- $Y_T = \xi, \mathcal{P}_H$ -q.s.
- For each $\mathbb{P} \in \mathcal{P}_H$, $K^\mathbb{P}$ has nondecreasing paths, \mathbb{P} -a.s. :

$$K_t^\mathbb{P} := Y_0 - Y_t + \int_0^t \hat{F}_s(Y_s, Z_s)ds + \int_0^t Z_s dB_s, \quad t \in [0, 1], \quad \mathbb{P} - \text{a.s.}$$

- The family of processes $\{K^\mathbb{P}, \mathbb{P} \in \mathcal{P}_H\}$ satisfies :

$$K_t^\mathbb{P} = \operatorname{ess\,inf}_{\mathbb{P}' \in \mathcal{P}_H(t, \mathbb{P})} \mathbb{E}_t^{\mathbb{P}'}[K_1^{\mathbb{P}'}], \quad \mathbb{P} - \text{a.s. for all } \mathbb{P} \in \mathcal{P}_H, t \leq T$$



Definition

For \mathcal{F}_1 -meas. ξ , consider the 2BSDE :

$$dY_t = \hat{F}_t(Y_t, Z_t)dt + Z_t dB_t - dK_t, \quad 0 \leq t \leq 1, \quad Y_T = \xi, \quad \mathcal{P}_H - \text{q.s.}$$

We say $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ is a solution to the 2BSDE if

- $Y_T = \xi, \mathcal{P}_H - \text{q.s.}$
- For each $\mathbb{P} \in \mathcal{P}_H$, $K^\mathbb{P}$ has nondecreasing paths, \mathbb{P} -a.s. :

$$K_t^\mathbb{P} := Y_0 - Y_t + \int_0^t \hat{F}_s(Y_s, Z_s)ds + \int_0^t Z_s dB_s, \quad t \in [0, 1], \quad \mathbb{P} - \text{a.s.}$$

- The family of processes $\{K^\mathbb{P}, \mathbb{P} \in \mathcal{P}_H\}$ satisfies :

$$K_t^\mathbb{P} = \operatorname{ess\,inf}_{\mathbb{P}' \in \mathcal{P}_H(t, \mathbb{P})} \mathbb{E}_t^{\mathbb{P}'}[K_1^{\mathbb{P}'}], \quad \mathbb{P} - \text{a.s. for all } \mathbb{P} \in \mathcal{P}_H, t \leq T$$



Definition

For \mathcal{F}_1 -meas. ξ , consider the 2BSDE :

$$dY_t = \hat{F}_t(Y_t, Z_t)dt + Z_t dB_t - dK_t, \quad 0 \leq t \leq 1, \quad Y_T = \xi, \quad \mathcal{P}_H - \text{q.s.}$$

We say $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ is a solution to the 2BSDE if

- $Y_T = \xi, \mathcal{P}_H$ -q.s.
- For each $\mathbb{P} \in \mathcal{P}_H$, $K^\mathbb{P}$ has nondecreasing paths, \mathbb{P} -a.s. :

$$K_t^\mathbb{P} := Y_0 - Y_t + \int_0^t \hat{F}_s(Y_s, Z_s)ds + \int_0^t Z_s dB_s, \quad t \in [0, 1], \quad \mathbb{P} - \text{a.s.}$$

- The family of processes $\{K^\mathbb{P}, \mathbb{P} \in \mathcal{P}_H\}$ satisfies :

$$K_t^\mathbb{P} = \operatorname{ess\,inf}_{\mathbb{P}' \in \mathcal{P}_H(t, \mathbb{P})} \mathbb{E}_t^{\mathbb{P}'}[K_1^{\mathbb{P}'}], \quad \mathbb{P} - \text{a.s. for all } \mathbb{P} \in \mathcal{P}_H, t \leq T$$



Definition

For \mathcal{F}_1 -meas. ξ , consider the 2BSDE :

$$dY_t = \hat{F}_t(Y_t, Z_t)dt + Z_t dB_t - dK_t, \quad 0 \leq t \leq 1, \quad Y_T = \xi, \quad \mathcal{P}_H - \text{q.s.}$$

We say $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ is a solution to the 2BSDE if

- $Y_T = \xi, \mathcal{P}_H$ -q.s.
- For each $\mathbb{P} \in \mathcal{P}_H$, $K^\mathbb{P}$ has nondecreasing paths, \mathbb{P} -a.s. :

$$K_t^\mathbb{P} := Y_0 - Y_t + \int_0^t \hat{F}_s(Y_s, Z_s)ds + \int_0^t Z_s dB_s, \quad t \in [0, 1], \quad \mathbb{P} - \text{a.s.}$$

- The family of processes $\{K^\mathbb{P}, \mathbb{P} \in \mathcal{P}_H\}$ satisfies :

$$K_t^\mathbb{P} = \operatorname{ess\,inf}_{\mathbb{P}' \in \mathcal{P}_H(t, \mathbb{P})} \mathbb{E}_t^{\mathbb{P}'}[K_1^{\mathbb{P}'}], \quad \mathbb{P} - \text{a.s. for all } \mathbb{P} \in \mathcal{P}_H, t \leq T$$



Back to standard BSDEs

For standard BSDEs

$$dY_t := -H_t^0(Y_t, Z_t)dt + Z_t dB_t, \quad Y_T = \xi$$

the nonlinearity and the corresponding conjugate :

$$H_t(., \gamma) := \frac{-1}{2} I_d : \gamma + H_t^0(.), \quad F_t(., a) = \begin{cases} -H_t^0(.) & \text{for } a = I_d \\ \infty & \text{otherwise} \end{cases}$$

Then $\mathcal{P} = \{\mathbb{P}^0\}$, $K^{\mathbb{P}^0} \equiv 0$, and the previous definition reduces to the standard definition

$$dY_t := -H_t^0(Y_t, Z_t)dt + Z_t dB_t, \quad Y_T = \xi, \quad \mathbb{P}^0 - \text{a.s.}$$



Benchmark example : uncertain volatility model, G -expectation (Peng)

Let $d = 1$, and $H_t(y, z, \gamma) := G(\gamma) = \bar{a}\gamma^+ - \underline{a}\gamma^-$, and suppose that the PDE

$$\frac{\partial u}{\partial t} + G(u_{xx}) = 0, \quad \text{and} \quad u(T, \cdot) = g$$

has a smooth solution. Then

$$Y_t := u(t, B_t), \quad Z_t := Du(t, B_t),$$

is a solution of the 2BSDE with

$$K_t := \int_0^t \left(G(u_{xx}) - \frac{1}{2} \hat{a}_s u_{xx} \right) (s, B_s) ds$$



Outline

- 1 Motivations
 - Hedging under Gamma constraints
 - Hedging under market illiquidity
 - Probabilistic numerics for nonlinear PDEs
- 2 Backward SDEs : a quick review
- 3 2nd order backward SDEs
 - The CSTV framework
 - An alternative formulation of 2BSDEs
- 4 Main results
 - Representation, uniqueness
 - Existence
 - Connection with PDEs and stochastic control



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- Existence
- Connection with PDEs and stochastic control



Spaces and norms

- $\mathbb{L}_H^p := \{ \xi \text{ } \mathcal{F}_1 - \text{meas.} : \|\xi\|_{\mathbb{L}_H^p}^p < \infty \}$
- $\mathbb{H}_H^p := \{ Z \text{ } \mathbb{F}^+ - \text{prog. meas. in } \mathbb{R}^d : \|Z\|_{\mathbb{H}_H^p}^p < \infty \}$

$$\|\xi\|_{\mathbb{L}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}}[|\xi|^p], \quad \|Z\|_{\mathbb{H}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\left(\int_0^1 |\hat{a}_t^{1/2} Z_t|^2 dt \right)^{p/2} \right]$$

- $\mathbb{D}_H^p := \{ Y \text{ } \mathbb{F}^+ - \text{prog. in } \mathbb{R} \text{ càdlàg } \mathcal{P}_H - \text{q.s.} : \|Y\|_{\mathbb{D}_H^p}^p < \infty \}$

$$\|Y\|_{\mathbb{D}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} |Y_t|^p \right]$$

- $\mathbb{L}_{H,*}^2 := \{ \xi \in \mathbb{L}_H^2 : \|\xi\|_{\mathbb{L}_{H,*}^2} < \infty \}$

$$\|\xi\|_{\mathbb{L}_{H,*}^2} := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} \mathbb{E}_t^{H,\mathbb{P}}[|\xi|^2] \right], \quad \mathbb{E}_t^{H,\mathbb{P}}[\xi] := \text{ess sup}_{\mathbb{P}' \in \mathcal{P}_H(t,\mathbb{P})} \mathbb{E}^{\mathbb{P}'}[\xi | \mathcal{F}_t]$$

- $\hat{\mathbb{L}}_H^2 := \text{closure of } \text{UC}_b(\Omega) \text{ under the norm } \|\cdot\|_{\mathbb{L}_H^2}$



Spaces and norms

- $\mathbb{L}_H^p := \{ \xi \text{ } \mathcal{F}_1 - \text{meas.} : \|\xi\|_{\mathbb{L}_H^p}^p < \infty \}$
- $\mathbb{H}_H^p := \{ Z \text{ } \mathbb{F}^+ - \text{prog. meas. in } \mathbb{R}^d : \|Z\|_{\mathbb{H}_H^p}^p < \infty \}$

$$\|\xi\|_{\mathbb{L}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}}[|\xi|^p], \quad \|Z\|_{\mathbb{H}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\left(\int_0^1 |\hat{a}_t^{1/2} Z_t|^2 dt \right)^{p/2} \right]$$

- $\mathbb{D}_H^p := \{ Y \text{ } \mathbb{F}^+ - \text{prog. in } \mathbb{R} \text{ càdlàg } \mathcal{P}_H - \text{q.s.} : \|Y\|_{\mathbb{D}_H^p}^p < \infty \}$

$$\|Y\|_{\mathbb{D}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} |Y_t|^p \right]$$

- $\mathbb{L}_{H,*}^2 := \{ \xi \in \mathbb{L}_H^2 : \|\xi\|_{\mathbb{L}_{H,*}^2} < \infty \}$

$$\|\xi\|_{\mathbb{L}_{H,*}^2} := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} \mathbb{E}_t^{H,\mathbb{P}}[|\xi|^2] \right], \quad \mathbb{E}_t^{H,\mathbb{P}}[\xi] := \text{ess sup}_{\mathbb{P}' \in \mathcal{P}_H(t,\mathbb{P})}^{\mathbb{P}} \mathbb{E}^{\mathbb{P}'}[\xi | \mathcal{F}_t]$$

- $\hat{\mathbb{L}}_H^2 := \text{closure of } \text{UC}_b(\Omega) \text{ under the norm } \|\cdot\|_{\mathbb{L}_H^2}$



Spaces and norms

- $\mathbb{L}_H^p := \{ \xi \text{ } \mathcal{F}_1 - \text{meas.} : \| \xi \|_{\mathbb{L}_H^p}^p < \infty \}$
- $\mathbb{H}_H^p := \{ Z \text{ } \mathbb{F}^+ - \text{prog. meas. in } \mathbb{R}^d : \| Z \|_{\mathbb{H}_H^p}^p < \infty \}$

$$\| \xi \|_{\mathbb{L}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} [|\xi|^p], \quad \| Z \|_{\mathbb{H}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\left(\int_0^1 |\hat{a}_t^{1/2} Z_t|^2 dt \right)^{p/2} \right]$$

- $\mathbb{D}_H^p := \{ Y \text{ } \mathbb{F}^+ - \text{prog. in } \mathbb{R} \text{ càdlàg } \mathcal{P}_H - \text{q.s.} : \| Y \|_{\mathbb{D}_H^p}^p < \infty \}$

$$\| Y \|_{\mathbb{D}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} |Y_t|^p \right]$$

- $\mathbb{L}_{H,*}^2 := \{ \xi \in \mathbb{L}_H^2 : \| \xi \|_{\mathbb{L}_{H,*}^2} < \infty \}$

$$\| \xi \|_{\mathbb{L}_{H,*}^2} := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} \mathbb{E}_t^{H,\mathbb{P}} [|\xi|^2] \right], \quad \mathbb{E}_t^{H,\mathbb{P}} [\xi] := \text{ess sup}_{\mathbb{P}' \in \mathcal{P}_H(t,\mathbb{P})}^{\mathbb{P}} \mathbb{E}^{\mathbb{P}'} [\xi | \mathcal{F}_t]$$

- $\hat{\mathbb{L}}_H^2 := \text{closure of } \text{UC}_b(\Omega) \text{ under the norm } \| \cdot \|_{\mathbb{L}_{H,*}^2}$



Spaces and norms

- $\mathbb{L}_H^p := \{ \xi \text{ } \mathcal{F}_1 - \text{meas.} : \| \xi \|_{\mathbb{L}_H^p}^p < \infty \}$
- $\mathbb{H}_H^p := \{ Z \text{ } \mathbb{F}^+ - \text{prog. meas. in } \mathbb{R}^d : \| Z \|_{\mathbb{H}_H^p}^p < \infty \}$

$$\| \xi \|_{\mathbb{L}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} [|\xi|^p], \quad \| Z \|_{\mathbb{H}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\left(\int_0^1 |\hat{a}_t^{1/2} Z_t|^2 dt \right)^{p/2} \right]$$

- $\mathbb{D}_H^p := \{ Y \text{ } \mathbb{F}^+ - \text{prog. in } \mathbb{R} \text{ càdlàg } \mathcal{P}_H - \text{q.s.} : \| Y \|_{\mathbb{D}_H^p}^p < \infty \}$

$$\| Y \|_{\mathbb{D}_H^p}^p := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} |Y_t|^p \right]$$

- $\mathbb{L}_{H,*}^2 := \{ \xi \in \mathbb{L}_H^2 : \| \xi \|_{\mathbb{L}_{H,*}^2} < \infty \}$

$$\| \xi \|_{\mathbb{L}_{H,*}^2} := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} \mathbb{E}_t^{H,\mathbb{P}} [|\xi|^2] \right], \quad \mathbb{E}_t^{H,\mathbb{P}} [\xi] := \text{ess sup}_{\mathbb{P}' \in \mathcal{P}_H(t,\mathbb{P})}^{\mathbb{P}} \mathbb{E}^{\mathbb{P}'} [\xi | \mathcal{F}_t]$$

- $\hat{\mathbb{L}}_H^2 := \text{closure of } \text{UC}_b(\Omega) \text{ under the norm } \| \cdot \|_{\mathbb{L}_{H,*}^2}$



Representation and uniqueness

Assumption $\sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} \mathbb{E}_t^{H, \mathbb{P}} \left[\int_t^1 |\hat{F}_s^0|^2 ds \right] \right] < \infty$, and :

$$|\hat{F}_t(y, z_1) - \hat{F}_t(y, z_2)| \leq C |\hat{a}_t^{1/2}(z_1 - z_2)|, \quad dt \times d\mathbb{P} - \text{a.s. for all } \mathbb{P} \in \mathcal{P}_H$$

Theorem Let $\xi \in \mathbb{L}_{H,*}^2$ and suppose $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ is a solution of the 2BSDE. Then, for any $\mathbb{P} \in \mathcal{P}_H$ and $0 \leq t_1 < t_2 \leq 1$,

$$Y_{t_1} = \operatorname{ess\,sup}_{\mathbb{P}' \in \mathcal{P}_H(t_1, \mathbb{P})}^{\mathbb{P}} \mathcal{Y}_{t_1}^{\mathbb{P}'}(t_2, Y_{t_2}), \quad \mathbb{P} - \text{a.s.}$$

$\mathcal{Y}_{t_1}^{\mathbb{P}}(t_2, Y_{t_2}) = y_{t_1}$, where $(y_t)_{t \leq t_2}$ is the solution of

$$y_t = Y_{t_2} - \int_t^{t_2} \hat{F}_t(y_s, z_s) ds + \int_t^{t_2} z_s dB_s, \quad \mathbb{P} - \text{a.s.}$$

Corollary The 2BSDE has at most one solution in $\mathbb{D}_H^2 \times \mathbb{H}_H^2$, and comparison holds true



Outline

1 Motivations

- Hedging under Gamma constraints
- Hedging under market illiquidity
- Probabilistic numerics for nonlinear PDEs

2 Backward SDEs : a quick review

3 2nd order backward SDEs

- The CSTV framework
- An alternative formulation of 2BSDEs

4 Main results

- Representation, uniqueness
- **Existence**
- Connection with PDEs and stochastic control



A priori estimates

Theorem (i) Let $\xi \in \mathbb{L}_{H,*}^2$ and $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ a solution of the 2BSDE. Then

$$\|Y\|_{\mathbb{D}_H^2}^2 + \|Z\|_{\mathbb{H}_H^2}^2 + \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}}[|K_1^{\mathbb{P}}|^2] \leq C(\|\xi\|_{\mathbb{L}_{H,*}^2}^2 + \|\hat{F}^0\|_{\mathbb{H}_{H,*}^2}^2)$$

(ii) Let $\xi^i \in \mathbb{L}_{H,*}^2$ and $(Y^i, Z^i) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ corresponding solutions to the 2BSDE, $i = 1, 2$. Then, with $\delta\xi := \xi^1 - \xi^2$, $\delta Y := Y^1 - Y^2$, $\delta Z := Z^1 - Z^2$, and $\delta K^{\mathbb{P}} := K^{1,\mathbb{P}} - K^{2,\mathbb{P}}$:

$$\begin{aligned} \|\delta Y\|_{\mathbb{D}_H^2} &\leq C\|\delta\xi\|_{\mathbb{L}_{H,*}^2} \text{ and} \\ \|\delta Z\|_{\mathbb{H}_H^2}^2 &+ \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} |\delta K_t^{\mathbb{P}}|^2 \right] \\ &\leq C\|\delta\xi\|_{\mathbb{L}_{H,*}^2}^2 + C(\|\xi^1\|_{\mathbb{L}_{H,*}^2}^2 + \|\hat{F}^0\|_{\mathbb{H}_{H,*}^2}^2) \|\delta\xi\|_{\mathbb{L}_{H,*}^2} \end{aligned}$$



A priori estimates

Theorem (i) Let $\xi \in \mathbb{L}_{H,*}^2$ and $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ a solution of the 2BSDE. Then

$$\|Y\|_{\mathbb{D}_H^2}^2 + \|Z\|_{\mathbb{H}_H^2}^2 + \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}}[|K_1^{\mathbb{P}}|^2] \leq C(\|\xi\|_{\mathbb{L}_{H,*}^2}^2 + \|\hat{F}^0\|_{\mathbb{H}_{H,*}^2}^2)$$

(ii) Let $\xi^i \in \mathbb{L}_{H,*}^2$ and $(Y^i, Z^i) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$ corresponding solutions to the 2BSDE, $i = 1, 2$. Then, with $\delta\xi := \xi^1 - \xi^2$, $\delta Y := Y^1 - Y^2$, $\delta Z := Z^1 - Z^2$, and $\delta K^{\mathbb{P}} := K^{1,\mathbb{P}} - K^{2,\mathbb{P}}$:

$$\begin{aligned} \|\delta Y\|_{\mathbb{D}_H^2} &\leq C\|\delta\xi\|_{\mathbb{L}_{H,*}^2} \text{ and} \\ \|\delta Z\|_{\mathbb{H}_H^2}^2 &+ \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} |\delta K_t^{\mathbb{P}}|^2 \right] \\ &\leq C\|\delta\xi\|_{\mathbb{L}_{H,*}^2}^2 + C(\|\xi^1\|_{\mathbb{L}_{H,*}^2}^2 + \|\hat{F}^0\|_{\mathbb{H}_{H,*}^2}^2) \|\delta\xi\|_{\mathbb{L}_{H,*}^2} \end{aligned}$$



Existence

Theorem For any $\xi \in \hat{\mathbb{L}}_H^2$, the 2BSDE admits a unique solution $(Y, Z) \in \mathbb{D}_H^2 \times \mathbb{H}_H^2$.

Recall $\hat{\mathbb{L}}_H^2 := \text{closure of } \text{UC}_b(\Omega) \text{ under the norm } \|\cdot\|_{\mathbb{L}_{H,*}^2}$, where

$$\|\xi\|_{\mathbb{L}_{H,*}^2} := \sup_{\mathbb{P} \in \mathcal{P}_H} \mathbb{E}^{\mathbb{P}} \left[\sup_{0 \leq t \leq 1} \mathbb{E}_t^{H,\mathbb{P}} [|\xi|^2] \right]$$

and

$$\mathbb{E}_t^{H,\mathbb{P}}[\xi] := \text{ess sup}_{\mathbb{P}' \in \mathcal{P}_H(t,\mathbb{P})}^{\mathbb{P}} \mathbb{E}^{\mathbb{P}'}[\xi | \mathcal{F}_t]$$



Outline

- 1 Motivations
 - Hedging under Gamma constraints
 - Hedging under market illiquidity
 - Probabilistic numerics for nonlinear PDEs
- 2 Backward SDEs : a quick review
- 3 2nd order backward SDEs
 - The CSTV framework
 - An alternative formulation of 2BSDEs
- 4 Main results
 - Representation, uniqueness
 - Existence
 - Connection with PDEs and stochastic control



Connection with PDEs

Theorem Under "natural conditions", the solution of the 2BSDE satisfies $Y_t = u(t, B_t)$, $t \in [0, T]$, \mathcal{P}_H -q.s. and u is a viscosity solution of

$$\frac{\partial u}{\partial t}(t, x) + \hat{H}\left(t, x, u(t, x), Du(t, x), D^2u(t, x)\right) = 0, \quad 0 \leq t < 1$$

$$u(1, x) = g(x)$$

where

$$\hat{H}(t, x, y, z, \gamma) = \sup_{a \in \mathbb{S}_d^+(\mathbb{R})} \left\{ \frac{1}{2} a : \gamma - F(t, x, y, z, a) \right\}, \quad \gamma \in \mathbb{R}^{d \times d}.$$

We also have a Feynman-Kac representation theorem for the Cauchy problem with the latter fully nonlinear PDE



Connection with G -expectation

Denis-Martini (2004), Peng's G -expectation (2007) :

$$H_t(y, z, \gamma) = G(\gamma) := \frac{1}{2} \sup_{\underline{a} \leq a \leq \bar{a}} a : \gamma \quad \text{Then} \quad F_t(a) = \begin{cases} 0 & \text{on } [\underline{a}, \bar{a}] \\ \infty & \text{otherwise} \end{cases}$$

The corresponding PDE is

$$\frac{\partial u}{\partial t} + G(D^2 u) = 0$$

given the terminal data $u(T, \cdot) = g$, this is the DPE for the problem of superhedging under uncertain volatility :

$$\inf \left\{ Y_0 : Y_0 + \int_0^T Z_s dB_s \geq g(B_T), \mathcal{P}_H - \text{q.s.} \right\}$$

where $\mathcal{P}_H = \{ \mathbb{P} \in \mathcal{P}_S : \hat{a} \in [\underline{a}, \bar{a}], \mathbb{P} - \text{a.s.} \}$



Connection with stochastic control

In classical stochastic control theory, define :

$$Y_t^{\mathbb{P}} := \operatorname{ess\,sup}_{\mathbb{P} \in \mathcal{P}_H(t, \mathbb{P})} \mathbb{E} [\xi | \mathcal{F}_t], \quad \mathbb{P} - \text{a.s. for all } \mathbb{P} \in \mathcal{P}_H$$

Then

- $\{Y_t^{\mathbb{P}}\}$ can be aggregated into a \mathbb{P} -supermartingale for all $\mathbb{P} \in \mathcal{P}_H$
- $\{Y_t^{\mathbb{P}^*}\}$ is a \mathbb{P}^* -martingale for some $\mathbb{P}^* \in \mathcal{P}_H \implies \mathbb{P}^*$ optimal

However, it is not clear how to aggregate the family of processes

$$\{Y^{\mathbb{P}}, \mathbb{P} \in \mathcal{P}_H\}$$

i.e. find a process Y such that $Y = Y^{\mathbb{P}}, \mathbb{P}$ -a.s. for all $\mathbb{P} \in \mathcal{P}_H$

