# Using Hybrid Dynamic Bayesian Networks to model Operational Risk in Finance

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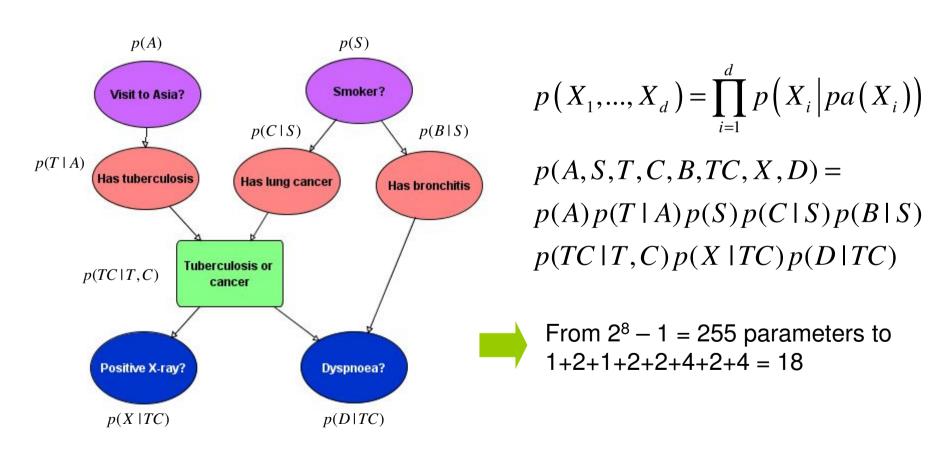
#### Contents

- Overview of Bayesian Networks
  - Discrete/Hybrid BNs
  - Dynamic discretization
- Operational Risk Application
  - Resiliency perspective
  - Rogue Trading

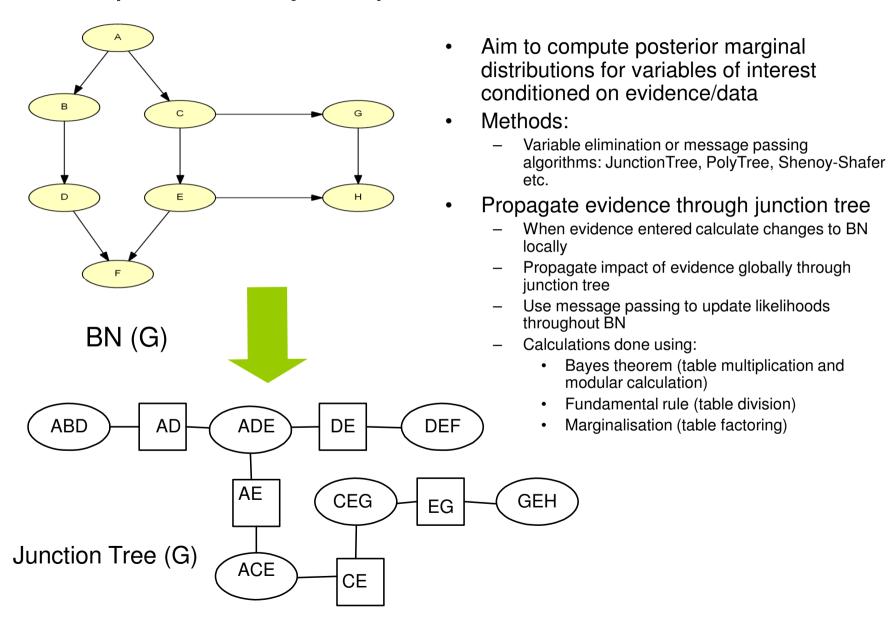
# Bayesian networks

# Use DAG to factorise Joint Distribution

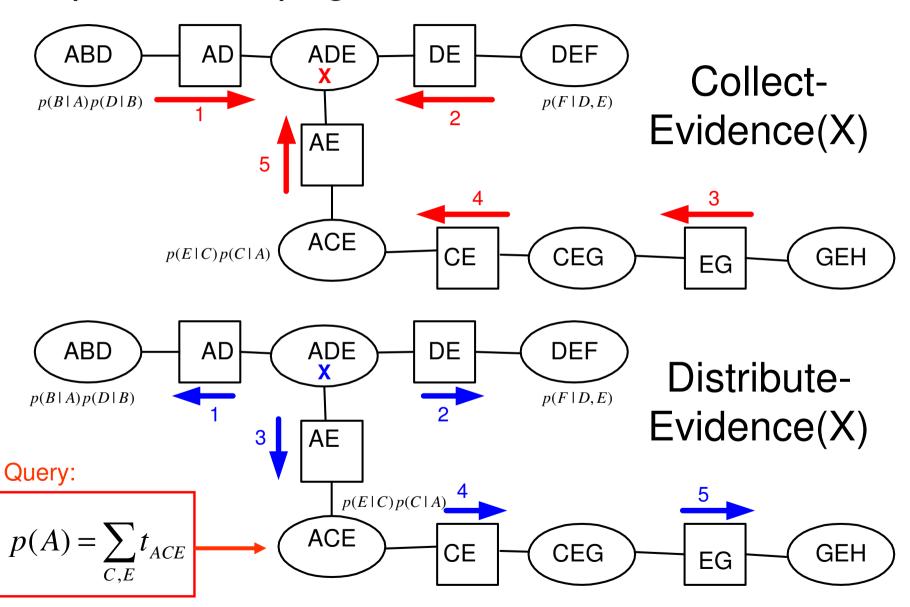
Full probability model specified by graph and by conditional probabilities:



#### Step 1: Identify Cliques and Create Junction Tree



#### Step Two: Propagation – Collect and Distribute

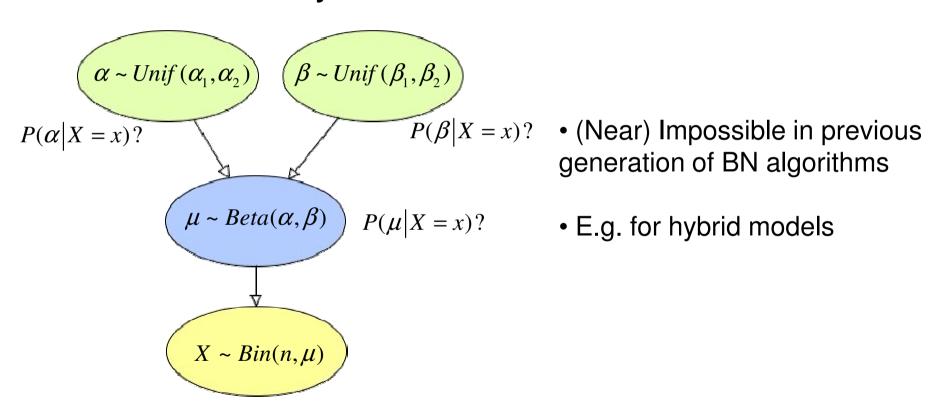


## Properties and Problems

- Inference in discrete models is:
  - Exact
  - Modular
  - NP hard in principle but in practice many models are feasible with acceptable performance
- If all variables are continuous then use analytical solutions (assuming conjugacy) or approximations
- But what about continuous variables in BNs?
  - Continuous Gaussian (CG) distributions
  - Uniform (static) discretisation

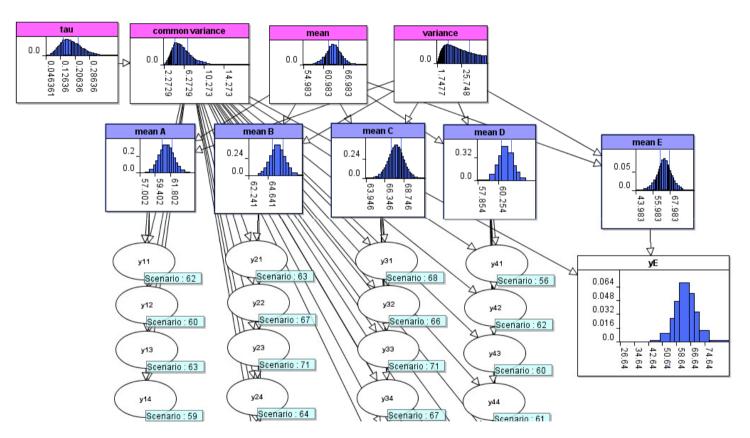
# Properties and Problems

What about Bayesian statistical inference?



Need to use stochastic approximations: Monte Carlo Markov Chain (MCMC) – Gibbs sampling

## Bayesian Hierarchical Models



- Two level hierarchical normal model as HBN
- Take four groups, A-D, learn hyper parameters from data
- Predict parameters for unknown, new group, E

#### Static Discretization

 $\chi$  Continuous valued node

$$\Omega_X = [x_1, x_2], ]x_1, x_2], \dots, ]x_{n-1}, x_n]$$

 $\Omega_{\!\scriptscriptstyle S} \quad \text{Cartesian product of } X \in S \quad \Omega_{\!\scriptscriptstyle S} = \otimes \{\Omega_{\!\scriptscriptstyle X} \mid X \in S\}$ 

$$P(X) = \sum_{\mathbf{y} \in \Omega_{S-X}} P(X, \mathbf{y})$$

Intervals of  $\Omega_{\!\scriptscriptstyle S}$  defined in advance

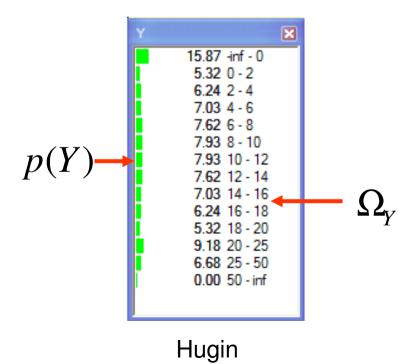
- 1. Discretize uniformly the domain  $\Omega_{\!\scriptscriptstyle X}$  of the density function f as  $\Omega_{\scriptscriptstyle X}=\bigcup \omega_{\!\scriptscriptstyle i}$
- 2. Define the discretized density function  $f_D$  as piecewise uniform (with constant value given by the mean value of f in each subregion )

# Problems with Static Discretization

- The discretization is defined in advance and remains fixed throughout all subsequent stages regardless of any new conditional evidence
- High density regions (HDRs) need to be known in advance
- Trade-off between precision and computational cost

Example:

$$f(Y) = N(10,100)$$



# Solution - Dynamic Discretisation

Stage 1: Given a discretisation  $\Omega = \bigcup_{\mathcal{O}_i}$  of the domain  $\Omega$  of the density function f, define the discretised density function  $f_D$  as piecewise constant in each subregion  $\mathcal{O}_i$  (with constant given by the mean value of f)

Stage 2: Find a discretisation  $\{\omega_i\}$  that minimises the relative entropy error

$$E_{j} = \left[ \frac{f_{\text{max}} - \overline{f}}{f_{\text{max}} - f_{\text{min}}} f_{\text{min}} \log \frac{f_{\text{min}}}{\overline{f}} + \frac{\overline{f} - f_{\text{min}}}{f_{\text{max}} - f_{\text{min}}} f_{\text{max}} \log \frac{f_{\text{max}}}{\overline{f}} \right] |\omega_{j}|$$

<sup>\*</sup> Upper bound approximation to Kullback-Leibler (KL) distance

# Outline of DD Algorithm

- Convert BN to Junction Tree
- Choose initial discretisation $\Omega^{(0)}$  for all continuous variables
- FOR iterations k = 1, 2, ...., n
  - FOR all continuous nodes  $X_i$  Calculate  $p^{(k)}(X_i \mid parents\{X\},e)$  on  $\Omega^{(k-1)}$ 
    - Propagate model using collect() and distribute()
    - Query model to get posterior marginal  $p^{(k)}(X_i \mid e)$
    - Calculate Sum Entropy Error  $E_k$  for  $p^{(k)}(X_i \mid e)$
    - IF  $E_k$  is acceptable STOP
    - ELSE create new  $\Omega^{(k)}$  by splitting interval with  $\max(E_j)$

**ENDFOR** 

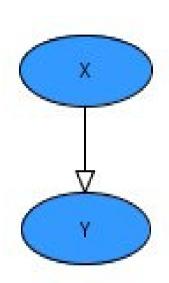
**ENDFOR** 

# Example: Mixture of Gaussians

#### Conditional distributions:

$$p(X = false) = 0.5, p(X = true) = 0.5$$

$$p(Y \mid X) = \begin{cases} Normal(10,100) & X = false \\ Normal(50,10) & X = true \end{cases}$$



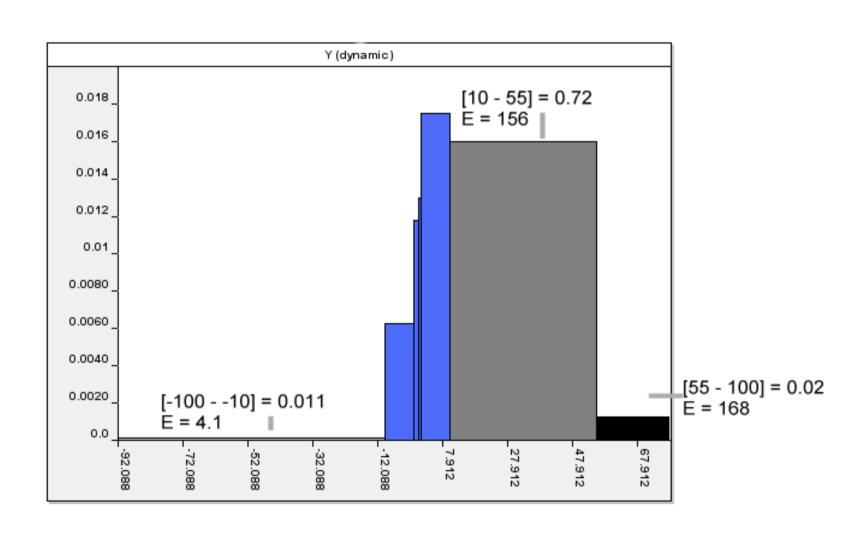
#### Marginal distribution:

$$p(Y) = \sum_{X} p(X) p(Y|X) = \frac{1}{2} [Normal(y;10,100) + Normal(y;50,10)]$$

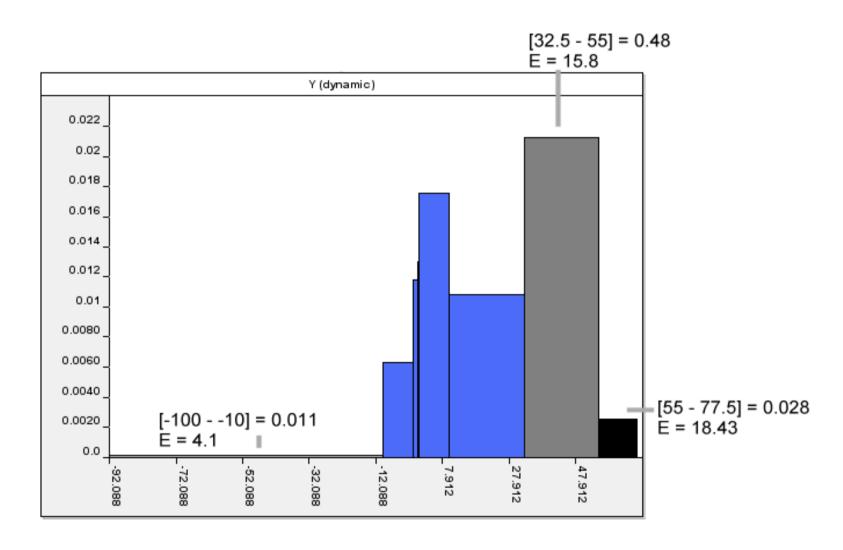
$$E[Y] = \int yf(y)dy = \lambda_1 \int yN(y \mid \mu_1, \sigma_1^2)dy + \lambda_2 \int yN(y \mid \mu_2, \sigma_2^2)dy = \lambda_1 \mu_1 + \lambda_2 \mu_2 = 30$$

$$Var[Y] = \lambda_1 (\sigma_1^2 + \mu_1^2) + \lambda_2 (\sigma_2^2 + \mu_2^2) - (\lambda_1 \mu_1 + \lambda_2 \mu_2)^2 = 455$$

## After 2 iterations

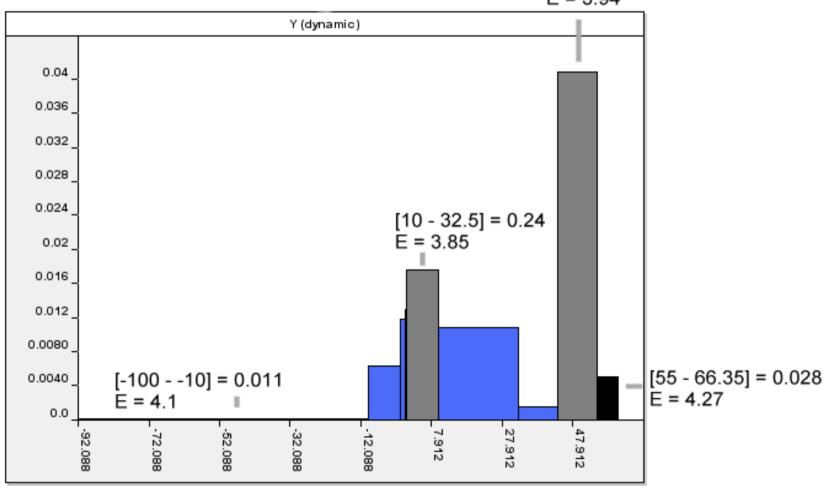


## After 4 iterations

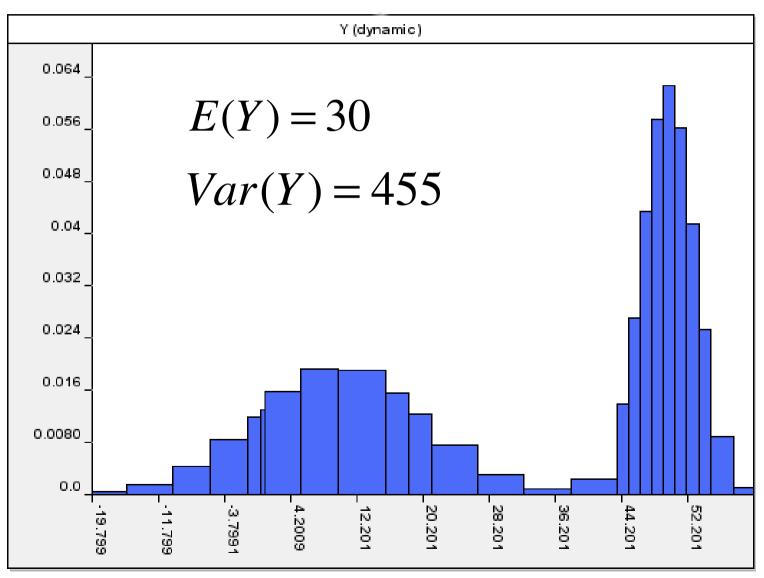


## After 6 iterations

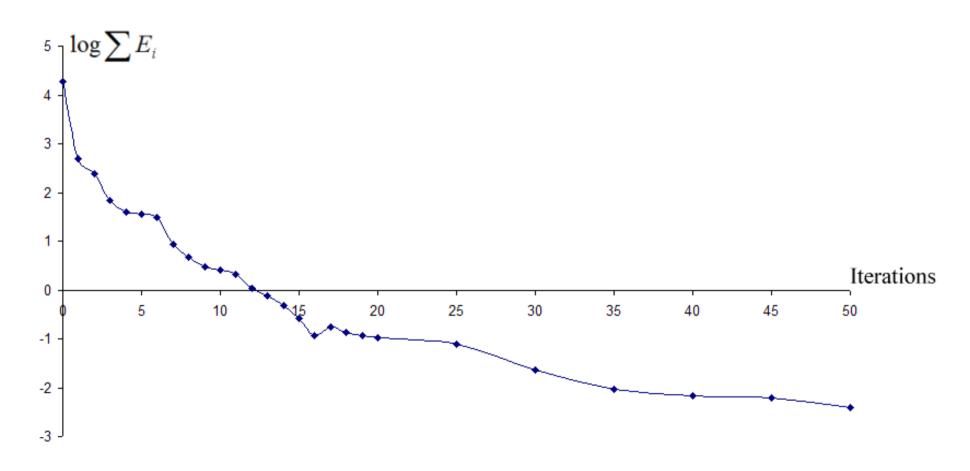
[43.75 - 55] = 0.45E = 3.94



### After 25 iterations



# Convergence of sum Entropy Errors for Y

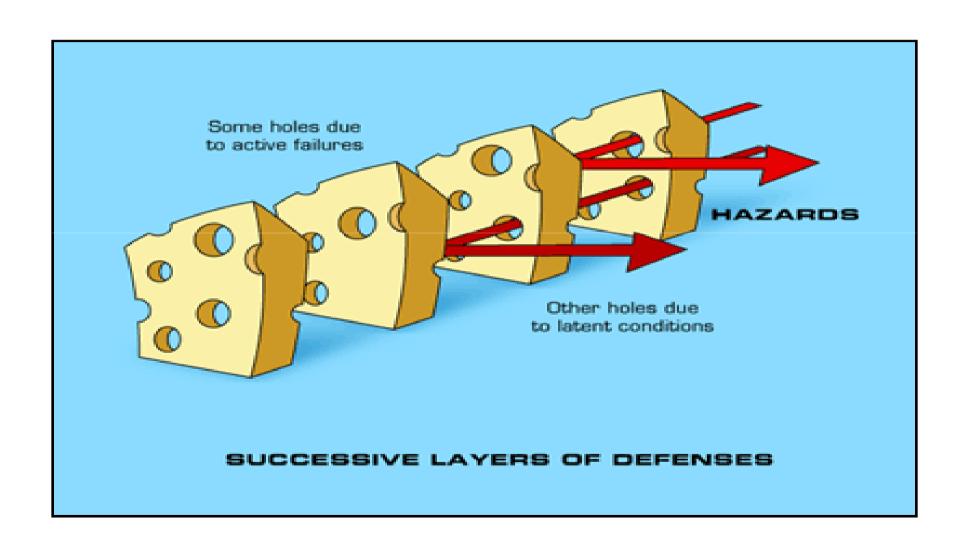


# Operational risk

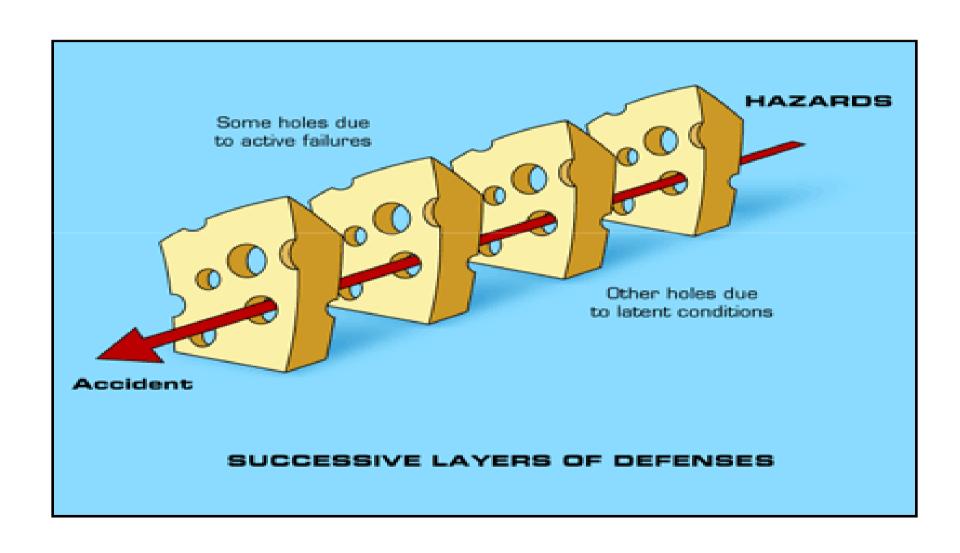
# Resiliency Perspective

- Operational risk is faced by all organisations.
  - Human error main cause of a catastrophic event
  - ....but without latent weaknesses in organisation the event would not reach catastrophic proportions.
- OpRisk modelling cannot solely involve the investigation of statistical phenomena

#### The "Swiss Cheese" Accident Model



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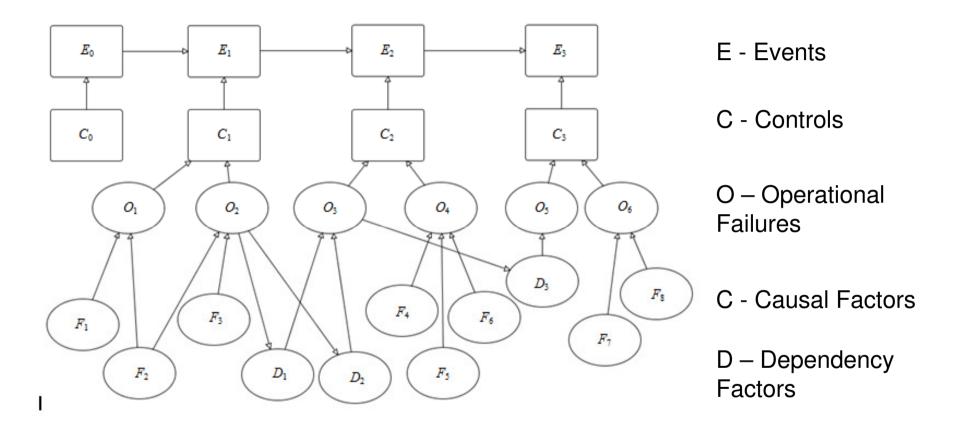


# Rogue Trading

#### Process

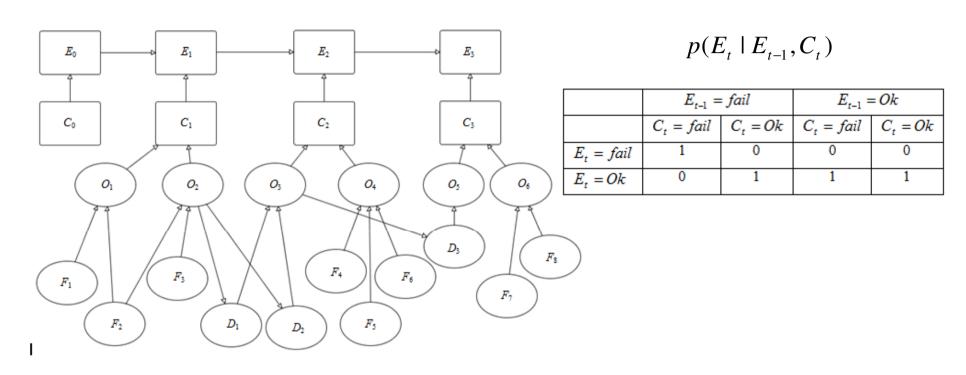
- Trade request Conduct Trade Registration of Trade –
   Reconciliation check, Settlement and Netting Entering of Trade on Trading Books
- Controls (prevent, limit and mitigate loss)
  - Front office control environment (the control environment affects the probability of unauthorised trading)
  - Back office reconciliation checks (performed per trade)
  - Market positions and results monitoring, VaR calculation (periodical)
  - Audit checks (periodical but not as often as the market checks)

### Loss Model



$$p(E,C,O,F,D) = \prod_{t=1}^{T} \prod_{s=1}^{t} \prod_{j=1}^{m} \prod_{i=1}^{n} \prod_{k=1}^{o} p(E_{t} \mid E_{t-1},C_{t}) p(C_{t} \mid O_{C_{t}}) p(O_{j} \mid F_{O_{j}},D_{O_{j}}) p(D_{k} \mid O_{C_{t-s}}) p(F_{i}) p(C_{0})$$

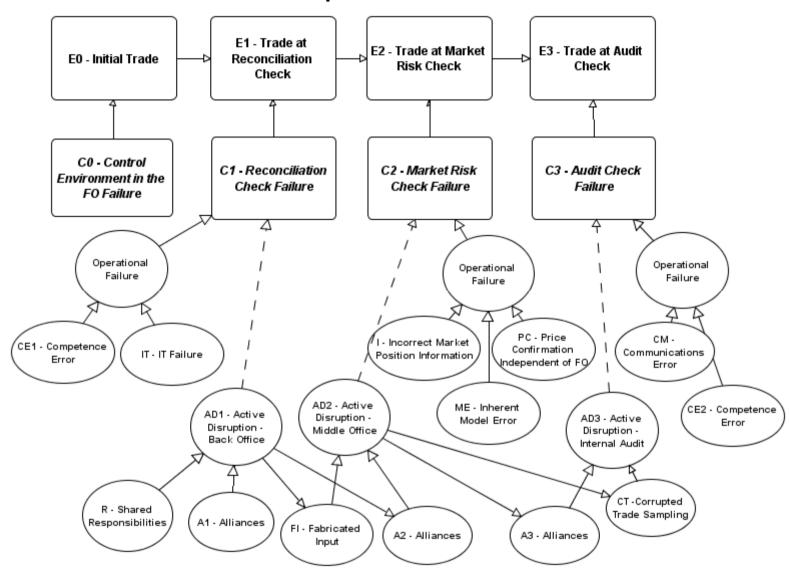
# Conditional Probability Tables



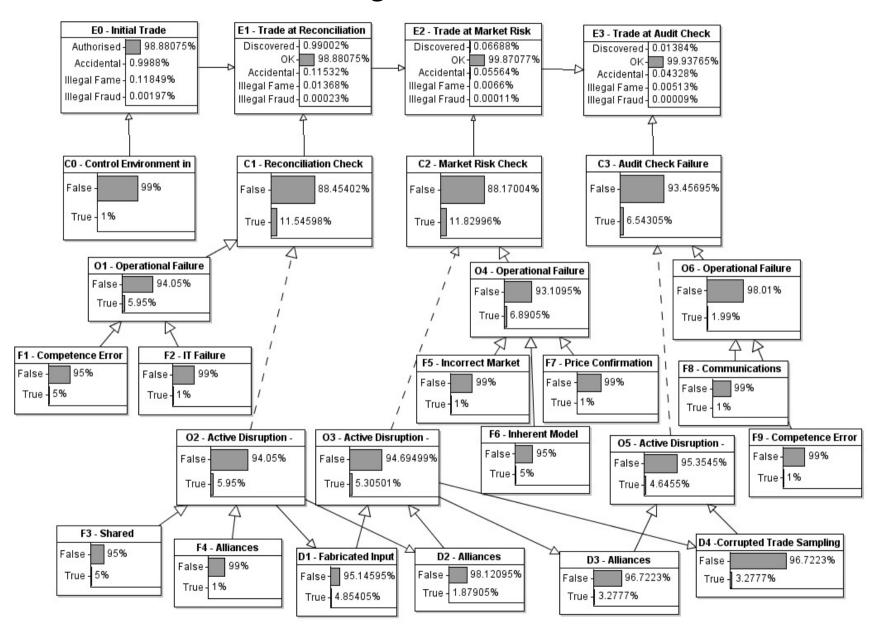
$$p(C_1 = fail \mid O_1, O_2) = \begin{cases} 1 & \text{if } O_1 \cup O_2 = fail \\ 0 & \text{otherwise} \end{cases}$$

	$O_1 = fail$	$O_1 = Ok$
$C_1 = fail$	0.8	0
$C_1 = Ok$	0.2	1

#### **Example Loss Model**



#### **Executing the Loss Model**



# Loss Severity Model

$$p(E_t = e_t^L) = p_{e_t^L}$$

Probability of loss for particular event type

$$N_{e_t^L} \sim Bin(W_{e_{t-1}^L}, p_{e_t^L})$$

 $N_{e_{\perp}^{L}} \sim Bin(W_{e_{\perp}^{L}}, p_{e_{\perp}^{L}})$  Number of events per type

$$W_{e_{t-1}^{L}} = V - \sum_{t=1}^{t-1} N_{e_{t-1}^{L}}$$

Volume of events (transactions)

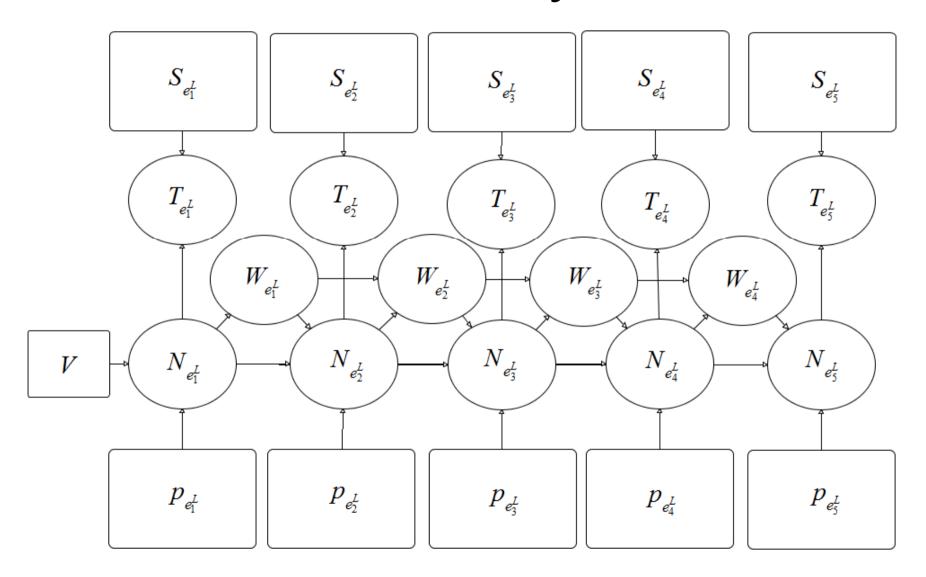
$$T_{e_t^L} = S_{e_t^L} \times N_{e_t^L}$$

Total losses = severity x number of events

$$f(T_{e_{t}^{L}}) = \sum_{S_{e_{t}^{L}}, N_{e_{t}^{L}}, W_{e_{t-1}^{L}}} f(T_{e_{t}^{L}} \mid S_{e_{t}^{L}}, N_{e_{t}^{L}}) f(N_{e_{t}^{L}} \mid W_{e_{t-1}^{L}}, p_{e_{t}^{L}}) f(S_{e_{t}^{L}})$$

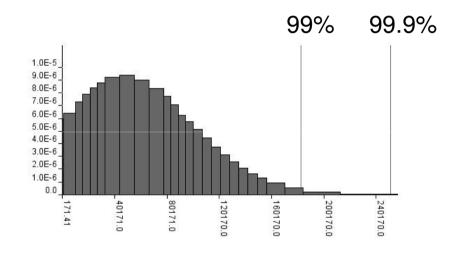
$$f(A) = \sum_{\mathbf{T}_{e_t^L}} f(A \mid \mathbf{T}_{e_t^L}) f(\mathbf{T}_{e_t^L})$$
 Total aggregated losses

# Loss Severity Model



# **Executing Loss Severity Model**

Loss severity	μ	$\sigma^2$
$S_{e_{\!\scriptscriptstyle 1}^{dis {\scriptscriptstyle  m cov} {\scriptscriptstyle ered}}}$	100	100,000
$S_{e_2^{dis { m cov} ered}}$	200	100,000
$S_{e_3^{ m discov}{ m ered}}$	500	100,000
$S_{e_{\!\scriptscriptstyle 1}^{accidental}}$	800	1,000,000
$S_{e_{\!\scriptscriptstyle 1}^{illegalfame}}$	1000	1,000,000
$S_{e_{\scriptscriptstyle \! 1}^{illegalfand}}$	5000	1,000,000



**Total losses for all events** 

#### Final Remarks

#### Structured Method

- Bayesian networks are extremely flexible
- Can combine subjective judgements with data
- Supports stress testing and scenarios

### Benefits for Operational Risk

- Supports LDA approach
- Supports causal modelling
- Flexible modelling framework
- Optimise capital allocation

### Some References

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#### Algorithm

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