Hilbert transform approach to options valuation

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Options pricing

- BIS: global OTC option market size (notional amounts outstanding) more than \$65 trillion by the end of June 09
- 13,920,865 S&P 500 index options traded on CBOE in January 2010
- GBM model Black Scholes 73, Merton 73: contradicts volatility smile effects observed in option markets
- Jump diffusion/Lévy: Merton 76, Kou 02, Madan Carr Chang 98, Barndorff-Nielsen 98, Eberlein Keller Prause 98, Carr Geman Madan Yor 02, Carr Wu 03; local volatility: Dupire 94, Derman Kani 94; stochastic volatility: Hull and White 87, Heston 93; stochastic volatility jump diffusion: Bates 96, Duffie Pan Singleton 00

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Transform methods

- Numerical methods often needed for computing option prices in alternative models: numerical solution to PIDEs, monte carlo simulation, transform methods
- Fourier transform based methods for models with known characteristic functions
- Fourier inverse representation for European vanilla options Carr Madan 99, Lee 04
- Coupled with the **fast Fourier transform** (computing convolution integrals using FFT for options pricing Eydeland 94)
- Hilbert transform approach to options valuation Feng Linetsky 08, 09 (illustrated with Bermudan options in Lévy models, Feng Lin 09)

Hilbert transform

• Hilbert transform of $f \in L^p(\mathbb{R})$, $1 \le p < \infty$

$$\mathcal{H}f(x) = \frac{1}{\pi} p.v. \int_{-\infty}^{\infty} \frac{f(y)}{x-y} dy$$

• For any $f\in L^1(\mathbb{R})$ with $\hat{f}\in L^1(\mathbb{R})$, and $l\in\mathbb{R}$,

$$\hat{f}(\xi) = \mathcal{F}f(\xi) = \int_{\mathbb{R}} e^{i\xi x} f(x) dx$$

 $\mathcal{F}(1_{(I,\infty)} \cdot f)(\xi) = \frac{1}{2}\hat{f}(\xi) + \frac{i}{2}e^{i\xi I}\mathcal{H}(e^{-i\eta I}\hat{f}(\eta))(\xi)$

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European vanilla options

• European vanilla options $(S_t = S_0 e^{X_t})$:

$$\mathbb{E}[(K - S_{\mathcal{T}})^+] = K\mathbb{E}[\mathbf{1}_{\{S_{\mathcal{T}} < K\}}] - \mathbb{E}[S_{\mathcal{T}}\mathbf{1}_{\{S_{\mathcal{T}} < K\}}]$$

$$\mathbb{P}(X \leq x) = \int_{\mathbb{R}} \mathbf{1}_{(-\infty,x)}(y) p(y) dy = \frac{1}{2} - \frac{i}{2} \mathcal{H}(e^{-i\xi x} \phi(\xi))(0)$$

where ϕ is the c.f. of X

• Inverting c.f. of a distribution to obtain the cdf; monte carlo simulation Feng Lin 10

Barriers and lookbacks

 European discrete barrier options/defaultable bonds in Lévy models: Feng Linetsky 08

$$f^{j}(x) = \mathbf{1}_{(l,u)} \cdot \mathbb{E}_{t_{j},x}[f^{j+1}(X_{t_{j+1}})]$$

 Exponential moments of the discrete maximum of a Lévy process, European discrete lookbacks in Lévy models: Feng Linetsky 09

$$M_j - X_j = \max(M_{j-1}, X_j) - X_j = \max(0, M_{j-1} - X_{j-1} - (X_j - X_{j-1}))$$

Discrete Hilbert transform

• **Discrete Hilbert transform** with step size h > 0

$$\mathcal{H}_h f(x) = \sum_{m=-\infty}^{\infty} f(mh) \frac{1 - \cos[\pi(x - mh)/h]}{\pi(x - mh)/h}, \quad x \in \mathbb{R}$$

• For f analytic in a horizontal strip $\{z \in \mathbb{C} : |\Im(z)| < d\}$

$$||\mathcal{H}f - \mathcal{H}_h f||_{L^{\infty}(\mathbb{R})} \leq \frac{Ce^{-\pi d/h}}{\pi d(1 - e^{-\pi d/h})}$$

Related to Whittaker cardinal series

Whittaker cardinal series

• Whittaker cardinal series (sinc expansion) Whittaker 1915

$$c(f,h)(x) = \sum_{k=-\infty}^{\infty} f(kh) \frac{\sin(\pi(x-kh)/h)}{\pi(x-kh)/h}$$

- For entire functions of exponential type π/h, sinc expansion is exact: c(f, h) = f
- For functions analytic in a strip $\{z \in \mathbb{C} : |\Im(z)| < d\}$, Stenger 93

$$|f - c(f, h)||_{L^{\infty}} \leq \frac{Ce^{-\pi d/h}}{\pi d(1 - e^{-2\pi d/h})}$$

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Trapezoidal rule

- Take Hilbert transform on c(f, h), obtain discrete Hilbert transform
- Trapezoidal rule very accurate for f analytic in a strip $\{z \in \mathbb{C} : |\Im(z)| < d\}$

$$\left|\int_{\mathbb{R}} f(x) dx - \sum_{m=-\infty}^{\infty} f(kh) h\right| \leq \frac{C e^{-2\pi d/h}}{1 - e^{-2\pi d/h}}$$

• We use trapezoidal rule to compute Fourier inverse integral

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Backward induction in state space Backward induction in Fourier space Discrete approximation Example

Bermudan vanilla options

• **Bermudan put**: payoff $G(S) = (K - S)^+$, discrete monitoring

$$\mathbb{T} = \{t_0, t_1, \cdots, t_N\} = \{0, \Delta, 2\Delta, \cdots, N\Delta = T\}$$

Exponential Lévy model: X_t a Lévy process in (Ω, F, F, P), start from 0, equivalent martingale measure P is given

$$S_t = S_0 e^{X_t}$$

Optimal stopping

$$V^0(S_0) = \sup_{\tau} \mathbb{E}_0[e^{-r\tau} G(S_{\tau})]$$

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Backward induction in state space

• Variable change
$$x = \ln(S/K)$$
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$$g(x) = G(Ke^{x}) = K(1 - e^{x})^{+}, \quad f^{0}(x) = V^{0}(Ke^{x})$$

. .

Backward induction

$$\begin{split} f^N(x) &= g(x) \\ f^j(x) &= \max\left(g(x), e^{-r\Delta} \mathbb{E}_{j\Delta,x}[f^{j+1}(X_{(j+1)\Delta})]\right), \quad 0 \leq j < N \\ V^0(S_0) &= f^0(\ln(S_0/K)) \end{split}$$

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Backward induction in state space Backward induction in Fourier space Discrete approximation Example

Implementation

• For each time step, need to compute

$$\mathbb{E}_{j\Delta,x}[f^{j+1}(X_{(j+1)\Delta})]$$

- Monte carlo simulation: Longstaff Schwartz 01, Glasserman 04
- Double exponential fast Gauss transform: Broadie Yamamoto 05
- Lattice approximation of the transition density Kellezi Webber 04
- Conditional expectation is a convolution, its Fourier transform is a product; FT of f^{j+1} → multiply by c.f. → FI representation of the conditional expectation → take max → FT of f^j Jackson Jaimungal Surkov 08:

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Dampening for integrability

• For $\alpha > 0$ (for puts), define

$$f^j_{\alpha}(x) = e^{\alpha x} f^j(x), \quad g_{\alpha}(x) = e^{\alpha x} g(x)$$

• Esscher transform: Radon-Nikodým derivative

$$rac{d\mathbb{P}^{lpha}}{d\mathbb{P}}|_{\mathcal{F}_t}=e^{-lpha X_t}/\phi_t(ilpha)$$

$$e^{\alpha \times} \mathbb{E}_{j\Delta, \times}[f^{j+1}(X_{(j+1)\Delta})] = \phi_{\Delta}(i\alpha) \mathbb{E}^{\alpha}_{j\Delta, \times}[f^{j+1}_{\alpha}(X_{(j+1)\Delta})]$$

• Esscher transformed Lévy process is still a Lévy process

$$\phi_t^{\alpha}(\xi) = \phi_t(\xi + i\alpha) / \phi_t(i\alpha)$$

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Dampened backward induction

Dampened backward induction

$$f_{\alpha}^{N}(x) = g_{\alpha}(x)$$

For $0 \le j < N$, let x_j^* be the **early exercise boundary** at $j\Delta$

$$f_{\alpha}^{j}(x) = \max\left(g_{\alpha}(x), e^{-r\Delta}\phi_{\Delta}(i\alpha)\mathbb{E}_{j\Delta,x}^{\alpha}[f_{\alpha}^{j+1}(X_{(j+1)\Delta})]
ight)$$

$$= g_{\alpha}(x) \cdot \mathbf{1}_{(-\infty, x_j^*)}(x)$$

$$+e^{-r\Delta}\phi_{\Delta}(i\alpha)\mathbb{E}^{\alpha}_{j\Delta,x}\left[f^{j+1}_{\alpha}(X_{(j+1)\Delta})\right]\cdot\mathbf{1}_{[x^*_{j},\infty)}(x)$$

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Backward induction in Fourier space

By convolution theorem,

$$\mathcal{F}\left(\mathbb{E}^{\alpha}_{j\Delta,x}\left[f^{j+1}_{\alpha}(X_{(j+1)\Delta})\right]\right)(\xi) = \hat{f}^{j+1}_{\alpha}(\xi)\phi^{\alpha}_{\Delta}(-\xi)$$

• Backward induction in Fourier space

$$\widehat{f}^{N}_{lpha}(\xi)=\widehat{g}_{lpha}(\xi)$$

$$\begin{aligned} \hat{f}^{j}_{\alpha}(\xi) &= \mathcal{F}(g_{\alpha}\mathbf{1}_{(-\infty,x_{j}^{*})})(\xi) + e^{-r\Delta}\phi_{\Delta}(i\alpha)\left(\frac{1}{2}\hat{f}^{j+1}_{\alpha}(\xi)\phi_{\Delta}^{\alpha}(-\xi)\right. \\ &\left. + \frac{i}{2}e^{i\xi x_{j}^{*}}\mathcal{H}\left(e^{-i\eta x_{j}^{*}}\hat{f}^{j+1}_{\alpha}(\eta)\phi_{\Delta}^{\alpha}(-\eta)\right)(\xi)\right)\end{aligned}$$

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Early exercise boundary

• Early exercise boundary solves

$$g_{\alpha}(x) = e^{-r\Delta}\phi_{\Delta}(i\alpha)\mathbb{E}^{\alpha}_{j\Delta,x}[f^{j+1}_{\alpha}(X_{(j+1)\Delta})]$$

• Using Fourier inverse representation

$$g_{\alpha}(x) = \frac{1}{2\pi} e^{-r\Delta} \phi_{\Delta}(i\alpha) \int_{\mathbb{R}} e^{-i\xi x} \hat{f}_{\alpha}^{j+1}(\xi) \phi_{\Delta}^{\alpha}(\xi) d\xi$$

• $x_N^* = K$. To solve for x_j^* , use Newton-Raphson, with starting point x_{j+1}^*

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Algorithm summarized

- Start with Fourier transform of dampened payoff $\hat{f}^N_lpha=\hat{g}_lpha$
- At time jΔ, with f^{j+1}_α, compute early exercise boundary x^{*}_j using Newton Raphson (Fourier inverse)
- Compute \hat{t}_{α}^{j} from \hat{t}_{α}^{j+1} and x_{i}^{*} (Hilbert transform)
- With \hat{f}^1_{α} , option value at time 0 (Fourier inverse)

$$f^{0}_{\alpha}(x) = \max\left(g_{\alpha}(x), \frac{1}{2\pi}e^{-r\Delta}\phi_{\Delta}(i\alpha)\int_{\mathbb{R}}e^{-i\xi x}\hat{f}^{1}_{\alpha}(\xi)\phi^{\alpha}_{\Delta}(\xi)d\xi\right)$$

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Discrete approximation

- Need to repeatedly evaluate Fourier inverse integrals and $\mathcal{H}\psi(\xi)$
- **Trapezoidal rule** for Fourier inverse integral, truncate infinite series with truncation level *M*, computational cost *O*(*M*)
- Replace $\mathcal{H}\psi$ by **discrete Hilbert transform**, truncate resulting infinite series

$$\mathcal{H}\psi(\xi) \Leftarrow \sum_{m=-M}^{M} \psi(mh) rac{1-\cos[\pi(\xi-mh)/h]}{\pi(\xi-mh)/h}$$

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Toeplitz matrix vector multiplication

Evaluate

$$\mathcal{H}\psi(\xi) \Leftarrow \sum_{m=-M}^{M} \psi(mh) rac{1 - \cos[\pi(\xi - mh)/h]}{\pi(\xi - mh)/h}$$

for $\xi = -Mh, \cdots, Mh$

- Correspond to Toeplitz matrix vector multiplication
- FFT based method for such multiplications: $O(M \log(M))$
- Total computational cost of the method: $O(NM \log(M))$

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Error estimate

- Discretization error $O(\exp(-\pi d/h))$
- With $\phi_t(\xi) \sim \exp(-ct|\xi|^{\nu})$, truncation error is essentially

 $O(\exp(-\Delta c(Mh)^{\nu}))$

$$h(M) = \left(\frac{\pi d}{\Delta c}\right)^{\frac{1}{1+\nu}} M^{-\frac{\nu}{1+\nu}}$$

• Total error: $O(\exp(-CM^{\frac{\nu}{1+\nu}}))$

Introduction Hilbert transform Backward induction in state space Backward induction in Fourier space Discrete approximation Example

NIG model

- Pricing Bermudan put option in NIG
- Characteristic exponent

$$-i\mu\xi + \delta_{NIG}(\sqrt{\alpha_{NIG}^2 - (\beta_{NIG} + i\xi)^2} - \sqrt{\alpha_{NIG}^2 - \beta_{NIG}^2})$$

• $\phi_t(\xi)$ has exponential tails with $\nu = 1$; error estimate in M: $O(e^{-C\sqrt{M}})$

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Bermudan put in the NIG model

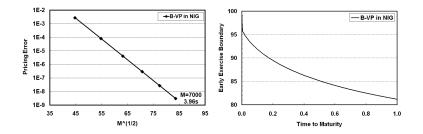


Figure: T = 1, **N=252**, $S_0 = 100$, K = 100, r = 5%, q = 2%, $\alpha_{NIG} = 15$, $\beta_{NIG} = -5$, $\delta_{NIG} = 0.5$, Matlab R2009a, Lenovo T400 Laptop with 2.53GHz CPU, 2G RAM; average number of NR iterations per time step 4.08

Bermudan barriers/lookbacks

• Bermudan barrier options

$$\begin{aligned} f^{j}(x) &= \mathbf{1}_{(I,u)}(x) \cdot \left(g(x) \cdot \mathbf{1}_{(-\infty,x_{j}^{*}]}(x) \right. \\ &+ e^{-r\Delta} \mathbb{E}_{j\Delta,x}[f^{j+1}(X_{(j+1)\Delta})] \cdot \mathbf{1}_{(x_{j}^{*},\infty)}(x) \right) \end{aligned}$$

- Bermudan floating strike lookback options: standard backward induction involves two state variables: asset price, maximum asset price
- Can be reduced to one state variable, maximum asset price/asset price; double exponential fast Gauss transform method for BSM and Merton's models Yamamoto 05

Image: A Image: A

Bermudan down-and-out put in Kou's model

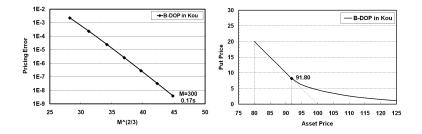


Figure: T = 1, **N=252**, $S_0 = 100$, K = 100, L = 80, r = 5%, q = 2%, $\sigma = 0.1$, $\lambda = 3$, p = 0.3, $\eta_1 = 40$, $\eta_2 = 12$, Matlab R2009a, Lenovo T400 Laptop with 2.53GHz CPU, 2G RAM

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Bermudan floating strike lookback put in CGMY

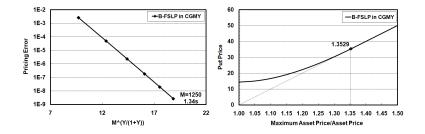


Figure: T = 1, **N=252**, $S_0 = 100$, r = 5%, q = 2%, C = 4, G = 50, $M_{cgmy} = 60$, Y = 0.7, Matlab R2009a, Lenovo T400 Laptop with 2.53GHz CPU, 2G RAM

American options

- In BSM convergence of Bermudan options to American options O(1/N) Howison 07
- Richardson extrapolation: from two approximations P_1 with N_1 and P_2 with N_2

$$P_{\infty} \approx \frac{N_1 P_1 - N_2 P_2}{N_1 - N_2}$$

Ν	B-VP in BSM	Extrap
5	6.58462398	
10	6.62146556	6.65831
20	6.64073760	6.66001
40	6.65061811	6.66050
80	6.65562807	6.66064

Table: American vanilla put in the Black-Scholes-Merton model.

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Summary

- Hilbert transform method for pricing Bermudan style options in Lévy process models
- Very accurate with exponentially decaying errors
- Fast with computational cost $O(NM \log(M))$
- European vanilla, barrier, lookback, defaultable bonds, Bermudan vanilla, barrier, floating strike lookback, inverting c.f., monte carlo simulation etc.