



LHC & GOF

Richard
Lockhart

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The Large Hadron Collider and Goodness of Fit

Richard Lockhart

Simon Fraser University

DASF III, April 30 – May 1, 2010



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- “The statistical model has not always been a black box.”



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Summary

- “The statistical model has not always been a black box.”
- “And it need not be a black box now.”



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- Physics problems are hard.



For when I don't finish

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- Physics problems are hard.
- As is not usual – you really don't want the raw data.



For when I don't finish

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- Physics problems are hard.
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- The scientific null hypothesis is a point null.



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- Physics problems are hard.
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- The scientific null hypothesis is a point null.
- But the data analytic null is more nuanced.



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- Non-parametric priors lead to Neyman Pearson tests.



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- Gaussian priors lead to quadratic tests.



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- Sensible prior: decision won't be obvious *a priori* – sample size dependence.



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- Particle detection can be mixture of GOF with more traditional tests.
- Non-parametric priors lead to Neyman Pearson tests.
- Gaussian priors lead to quadratic tests.
- Sensible prior: decision won't be obvious *a priori* – sample size dependence.
- The real problems are strikingly hard – and the physicists want and expect smart solutions.



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- Elementary particle; one of 5 elementary bosons.
- Existence predicted by Standard Model of particle physics.
- Not yet observed.
- Major target of experiments at Large Hadron Collider at CERN.



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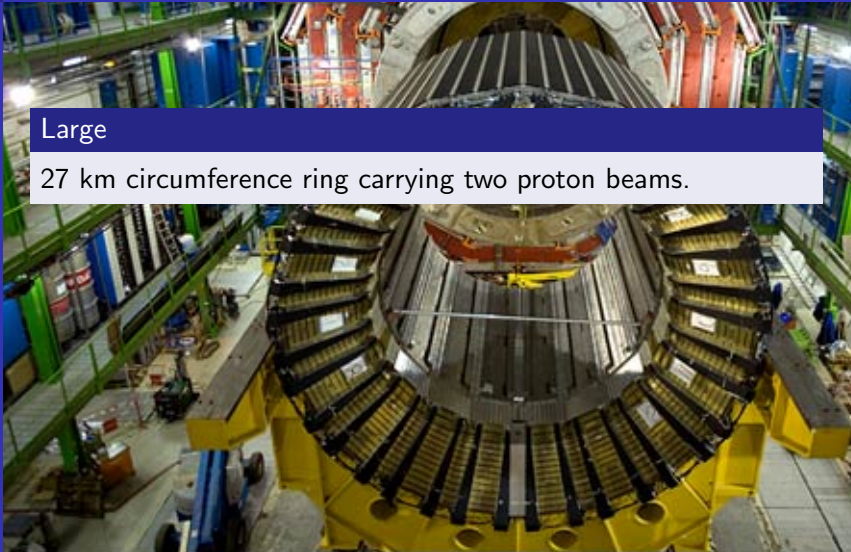
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Large

27 km circumference ring carrying two proton beams.



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Large

27 km circumference ring carrying two proton beams.

High Energy

Beams to collide at up to 14 Trillion Electron Volts.



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Collider

Many collisions. Each collision measured on complex detector.



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- Model data as Poisson Process of events in time.



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Summary

- Model data as Poisson Process of events in time.
- At each event measure a response X – the marks.



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Summary

- Model data as Poisson Process of events in time.
- At each event measure a response X – the marks.
- The event space is huge, huge, huge.



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- Model data as Poisson Process of events in time.
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- Model data as Poisson Process of events in time.
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- Collapse data over time to get sample of N values of X_i .



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- Given times of events, marks are nearly iid.
- Collapse data over time to get sample of N values of X_i .
- Poisson process on the mark space.



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- Null hypothesis is



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- Null hypothesis is

There is no such thing as a Higgs particle



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Summary

- Null hypothesis is

There is no such thing as a Higgs particle

- More general null hypothesis is standard physics “The Standard Model”.



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- Null hypothesis is

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- Alternative hypothesis is some other model of physics.



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- Null hypothesis is

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The Higg's particle is not produced at LHC energies.



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Summary

- Null hypothesis is N has $\text{Poisson}(\Lambda)$ distribution and given N the X_i are iid with some density f .



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Summary

- Null hypothesis is N has $\text{Poisson}(\Lambda)$ distribution and given N the X_i are iid with some density f .
- Alternative is N has $\text{Poisson}(\Lambda + M)$ distribution and given N the X_i are iid with some density g given by

$$g = \frac{\Lambda}{\Lambda + M} f + \frac{M}{\Lambda + M} f^*$$

with $f^* \neq f$.



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$$g = \frac{\Lambda}{\Lambda + M} f + \frac{M}{\Lambda + M} f^*$$

with $f^* \neq f$.

- The density f^* is the density of the marks in events which produce Higgs particles.



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Summary

- With f^* , g and M known use Neyman Pearson:

$$\ell \equiv N \log(1 + M/\Lambda) + \sum_i \log \left(\frac{g(X_i)}{f(X_i)} \right).$$



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$$\ell \equiv N \log(1 + M/\Lambda) + \sum_i \log \left(\frac{g(X_i)}{f(X_i)} \right).$$

- Not much to discuss but none of the things you “know” is known exactly.



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$$\ell \equiv N \log(1 + M/\Lambda) + \sum_i \log \left(\frac{g(X_i)}{f(X_i)} \right).$$

- Not much to discuss but none of the things you “know” is known exactly.
- And there is too much data.



One Data Point

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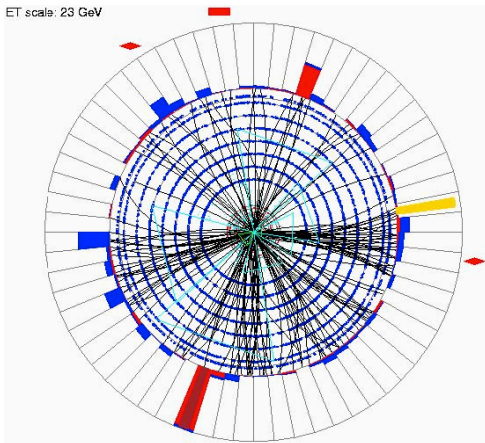
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Summary

The LHC experiments represent about 150 million sensors delivering data 40 million times per second. After filtering there will be about 100 collisions of interest per second.



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Summary

The LHC experiments represent about 150 million sensors delivering data 40 million times per second. After filtering there will be about 100 collisions of interest per second.

- For a year's worth of data

$$\Lambda \approx 10^{15}$$

and

$$M \approx 10^3$$



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- No information at all unless f^* is nothing like f .



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- No information at all unless f^* is nothing like f .
- So what do we really do?



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- In fact f^* is known or expected to be concentrated on 'small' region of mark space.



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Summary

- In fact f^* is known or expected to be concentrated on 'small' region of mark space.
- As events are registered 'triggering' algorithms determine whether or not the event is conceivably 'interesting'.



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- In fact f^* is known or expected to be concentrated on 'small' region of mark space.
- As events are registered 'triggering' algorithms determine whether or not the event is conceivably 'interesting'.
- Triggering lowers event rate from 40M per second to roughly 100 per second.



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- As events are registered 'triggering' algorithms determine whether or not the event is conceivably 'interesting'.
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- Now apply same model to reduced part of the mark space.



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- In fact f^* is known or expected to be concentrated on 'small' region of mark space.
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- Triggering lowers event rate from 40M per second to roughly 100 per second.
- Now apply same model to reduced part of the mark space.
- Still have

$$\Lambda \approx 10^9$$

and

$$M \approx 10^3$$

or a bit less.



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- When serious analysis begins make further cuts.



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- When serious analysis begins make further cuts.
- This amounts to trimming the mark space further to reduce Λ a lot and M hopefully only a bit.



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Summary

- When serious analysis begins make further cuts.
- This amounts to trimming the mark space further to reduce Λ a lot and M hopefully only a bit.
- So now I imagine my problem as posed above:

$$H_o : M = 0$$

versus

$$H_1 : M = M_0, \text{ density is } g.$$



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Summary

- Treat f^* (so too alternative g) as imprecisely known.



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Summary

- Treat f^* (so too alternative g) as imprecisely known.
- Test combination of two hypotheses:

$$H_{0,\text{count}} : M = 0 \quad \text{and} \quad H_{0,\text{shape}} : g = f$$



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- Second part is goodness-of-fit.
- GOF is somewhat disreputable.



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- No really, it is.



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- No really, it is.
- Ad hoc, ad hoc, ad hoc.



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Summary

- Must carry out fixed level α test.



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Summary

- Must carry out fixed level α test.
- Must publish a protocol.



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Summary

- Must carry out fixed level α test.
- Must publish a protocol.
- Wants to reject H_o .



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Summary

- Must carry out fixed level α test.
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- Wants to reject H_0 .
- Uses prior on alternative to design Neyman-Pearson test.



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Summary

- Must carry out fixed level α test.
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Summary

- Must carry out fixed level α test.
- Must publish a protocol.
- Wants to reject H_0 .
- Uses prior on alternative to design Neyman-Pearson test.
- Maximizes expected power.

A frequentist can use the idea to design tests.



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Stochastic Process Prior

Think of unknown density g as a random function (= stochastic process) which happens to be positive and integrate to 1.



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Stochastic Process Prior

Think of unknown density g as a random function (= stochastic process) which happens to be positive and integrate to 1.

If g is random then the joint density of $\mathbf{X} \equiv (X_1, \dots, X_n)$ at the point $\mathbf{x} \equiv (x_1, \dots, x_m)$ is

$$\Psi(\mathbf{x}) \equiv \mathbb{E} \{g(x_1) \cdots g(x_n)\}$$

where it is g not the x_i s that are being averaged over!



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So NP Likelihood ratio test statistic is

$$(1 + M/\Lambda)^N e^{-\Lambda \Psi(\mathbf{x})}.$$



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Now I need computable examples.



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- Idea: $\epsilon Z(x)$ Gaussian process approximating (up to location and scale) log likelihood ratio.



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Summary

- Idea: $\epsilon Z(x)$ Gaussian process approximating (up to location and scale) log likelihood ratio.
- Problem:

$$\int \exp\{\epsilon Z(x)\} f(x) dx \neq 1$$

so define our random density by

$$g(x) = \exp\{\epsilon Z(x)\} f(x) / \int \exp\{\epsilon Z(x)\} f(x) dx.$$



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- Additive invariance: wlog take $\int Z(x) f(x) dx = 0$.
- Problem: denominator. Solution: choose ϵ depending on sample size.



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Summary

- 1 Statistical tests are useful when $0.05 < \text{power} < 1$:
alternatives of interest are neither undetectably nor grossly
different from the null hypothesis.



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Summary

- 1 Statistical tests are useful when $0.05 < \text{power} < 1$:
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- 4 Data structure and model at hand can be embedded in **any** convenient sequence to get approximation.
- 5 Pick sequence to get quick convergence to computable limit!



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Summary

- Principle: design tests for good properties when alternative detectably but not obviously different from null.
- Precise large sample version: take $\epsilon = a/\sqrt{M}$.
- Log-likelihood ratio given Z is approximately

$$\sum \log\{g(x_i)/f(x_i)\} \approx W \equiv \frac{a \sum Z(x_i)}{\sqrt{M}} - a^2 \int Z^2(u) f(u) du / 2$$

Now: compute marginal joint density of

$$X_1, \dots, X_n$$

by averaging density over Z .



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Test rejects for large values of

$$e^{-M}(1 + M/\Lambda)^N \exp\{\text{GOF Statistic}(N, M)\}$$

where “GOF statistic” is generalization of EDF type tests.



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But I do have a formula in terms of eigenvalues,
eigenfunctions, non-centrality parameters and data.



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Large sample approximate P -values are computable.



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Summary

- Specify alternative in two pieces.
- Alternative $g(x) = f(x, \theta) \exp\{\epsilon Z(x, \theta)\}$.
- Apply prior π_1 to θ .
- Prior on alternative decomposed into conditional alternative given θ averaged over θ .
- Null: apply prior π_0 .



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Summary

- Neyman-Pearson likelihood ratio is product of two terms.
- Conditional joint density of X_1, \dots, X_n given θ is

$$\Psi(\mathbf{x}, \theta)$$

computed as before for $Z(x, \theta)$.

- First term in likelihood ratio is posterior expectation

$$\Psi(\mathbf{x}) \equiv \int \Psi(\mathbf{x}, \theta) \pi_1(d\theta|\mathbf{x}).$$

where $\pi_1(d\theta|\mathbf{x})$ is posterior computed under null for prior π_1 .

- Second is ratio of marginals under null:

$$\frac{\int \prod f(x_i, \theta) \pi_1(\theta) d\theta}{\int \prod f(x_i, \theta) \pi_0(\theta) d\theta}.$$

- Adjust π_0 to get level α .



Simulation Results

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“Not today, sir.”



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Are you kidding?



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- The density f^* is computed by measurement, approximation, and simulation.



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- The density f^* is computed by measurement, approximation, and simulation.
- The density g is computed by measurement, approximation, and simulation – from extreme tails.



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- In fact M is product of parameter of interest cross-section and other things — prior information available for the other things.



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- Null intensity Λ is computed by approximation and simulation.
- The analysis will be carried out over several energy ranges; multiple comparisons.



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Summary

- An experimenter wanting to provide evidence convincing to others should use prior on alternative and publish a data analysis protocol.



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Summary

- An experimenter wanting to provide evidence convincing to others should use prior on alternative and publish a data analysis protocol.
- A fairly natural prior leads to pooling quadratic GOF tests with a test based on N .



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- An experimenter wanting to provide evidence convincing to others should use prior on alternative and publish a data analysis protocol.
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- I need to find more priors.



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- The data analysis null hypothesis is uncertain; is Bayes avoidable?



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- What is the foundational status of “systematics”?



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- I need to find more priors.
- The data analysis null hypothesis is uncertain; is Bayes avoidable?
- What is the foundational status of “systematics”?
- Blind analysis?