

A study of the CMAM-DAS using simulated observations

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 - An estimation of background error covariances
 - A separation of the impacts of different sources of errors
 - model
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 - An estimation of the forecast errors in the mesosphere
 - An assessment of the extent of the predictability of the mesosphere

CMAM-DAS

- CMAM model
 - 71 vertical levels with the lid at 95km.
 - T47 spectral resolution
- Observations
 - surface obs.
 - 1000-10 mb: radiosondes, aircrafts,
 - 1000- 1mb : AMSU-A, satellite winds
 - No observations higher 1mb
- Assimilation
 - 3dVAR

Simulation of observations

- Use a free model run as a truth
- Create “perfect obs” at locations of REAL measurements
- Add random error with $std = \sigma_{obs}$
- Assimilate simulated obs

By definition:

$$\text{Error}(t) = \text{Forecast}(t) - \text{truth}(t)$$

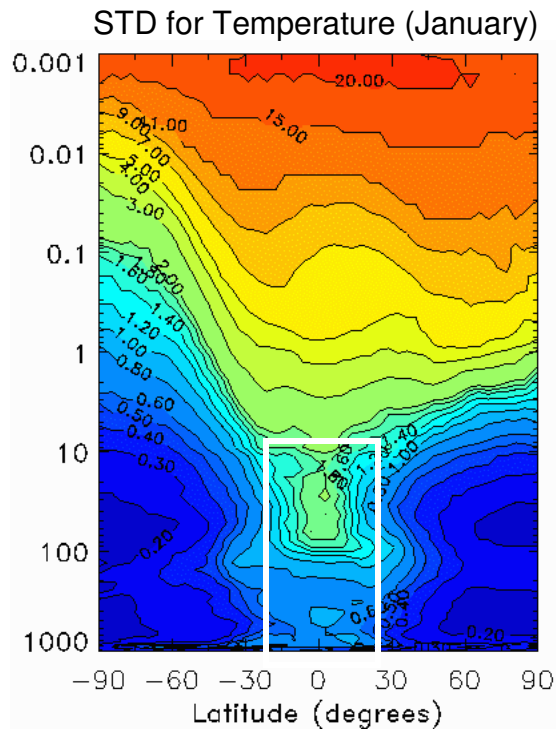
To estimate a stationary part of error covariances take samples from a monthly cycle with assimilation every 6 hours (~120 error samples):

$$VAR = \langle (\text{Forecast}(t_i) - \text{truth}(t_i))(\text{Forecast}(t_i) - \text{truth}(t_i))^T \rangle$$

A study case:

Assimilation of **rounded** 'perfect' Obs:

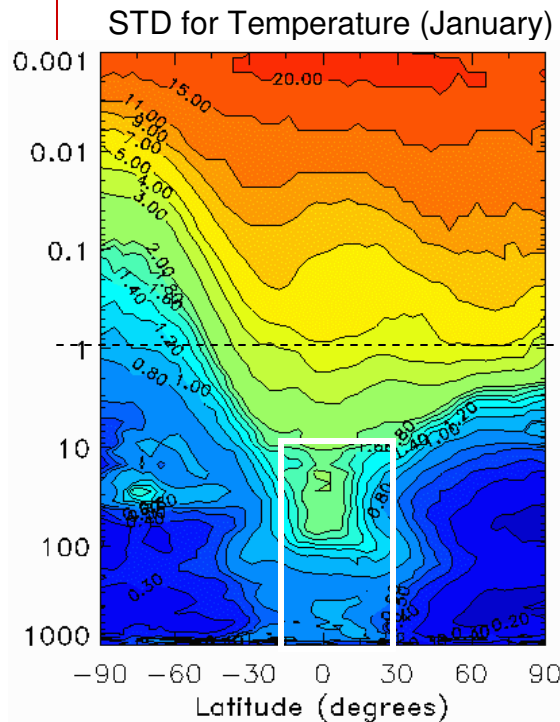
After a month of assimilation
STD (forecast –truth):



a perfect model
and perfect obs → The errors of
the method of
assimilation

It includes the impact of all the components
of the 3dVAR (the minimization, error
covariances modeling, balance control,...)
and also, the observational network

Assimilation of 'perfect' Obs with perturbed initial state:



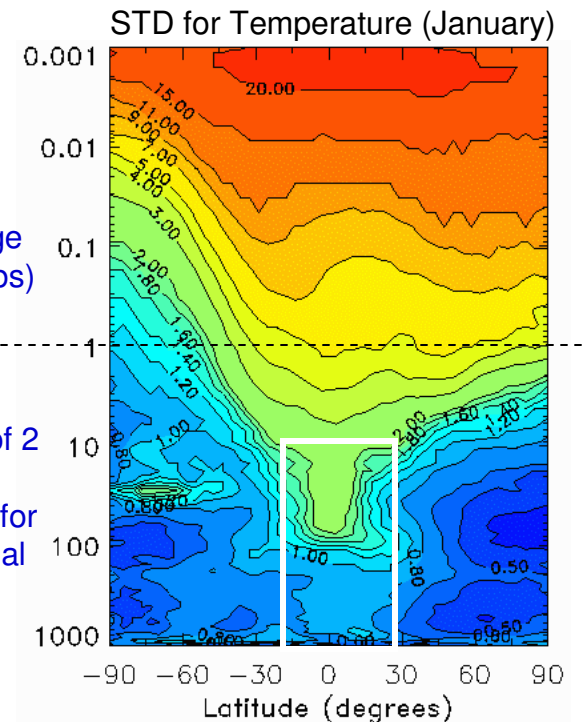
Small
change
(no obs)

Factor of 2
change
(except for
equatorial
regions)

$$J_{obs} = \sum_{i=1}^N \frac{(o_i - p_i)^2}{\sigma_{obs}^2} \neq 0$$

$$\Delta J = \sum_{i=1}^N \frac{(round(p_i) - p_i)^2}{\sigma_{obs}^2}$$

Assimilation of perturbed 'perfect' Obs, perturbed initial state:



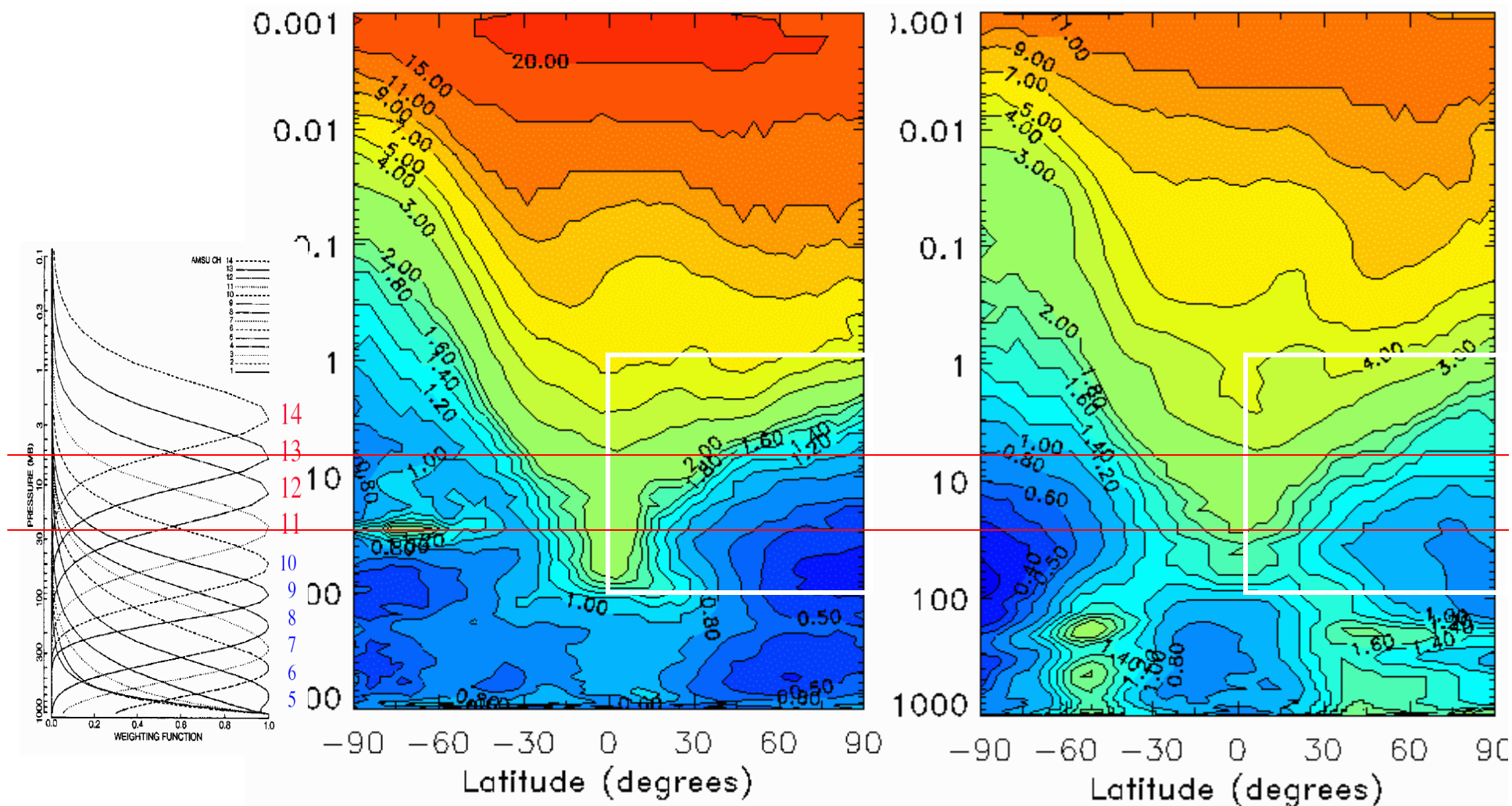
An efficiency of equatorial
observations ?

Do new Bg. error variances improve the forecast?

Background error STD for Temperatures (January)

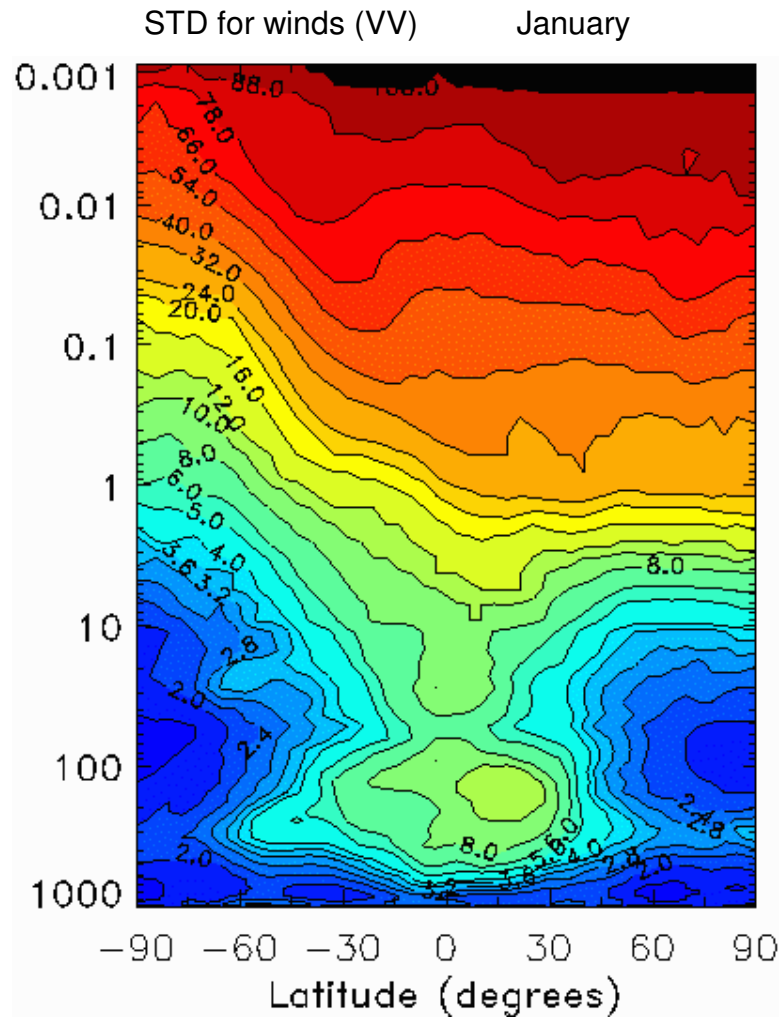
From simulations:

Specified in the CMAM-DAS:

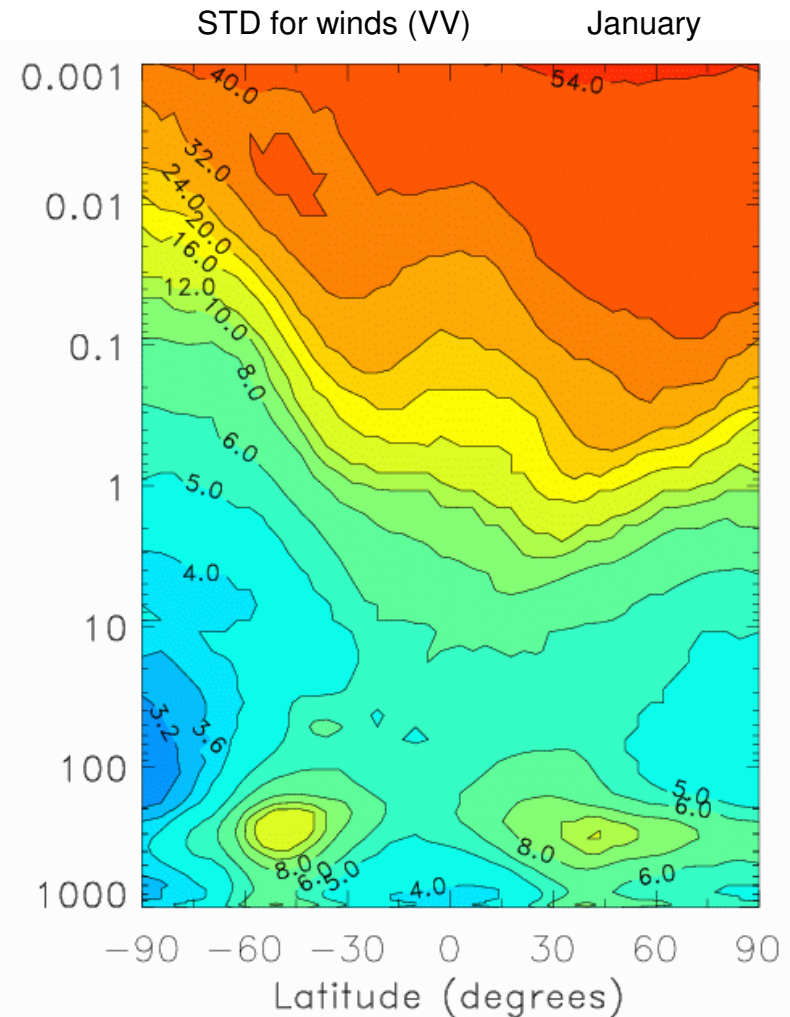


Background error STD for winds (January)

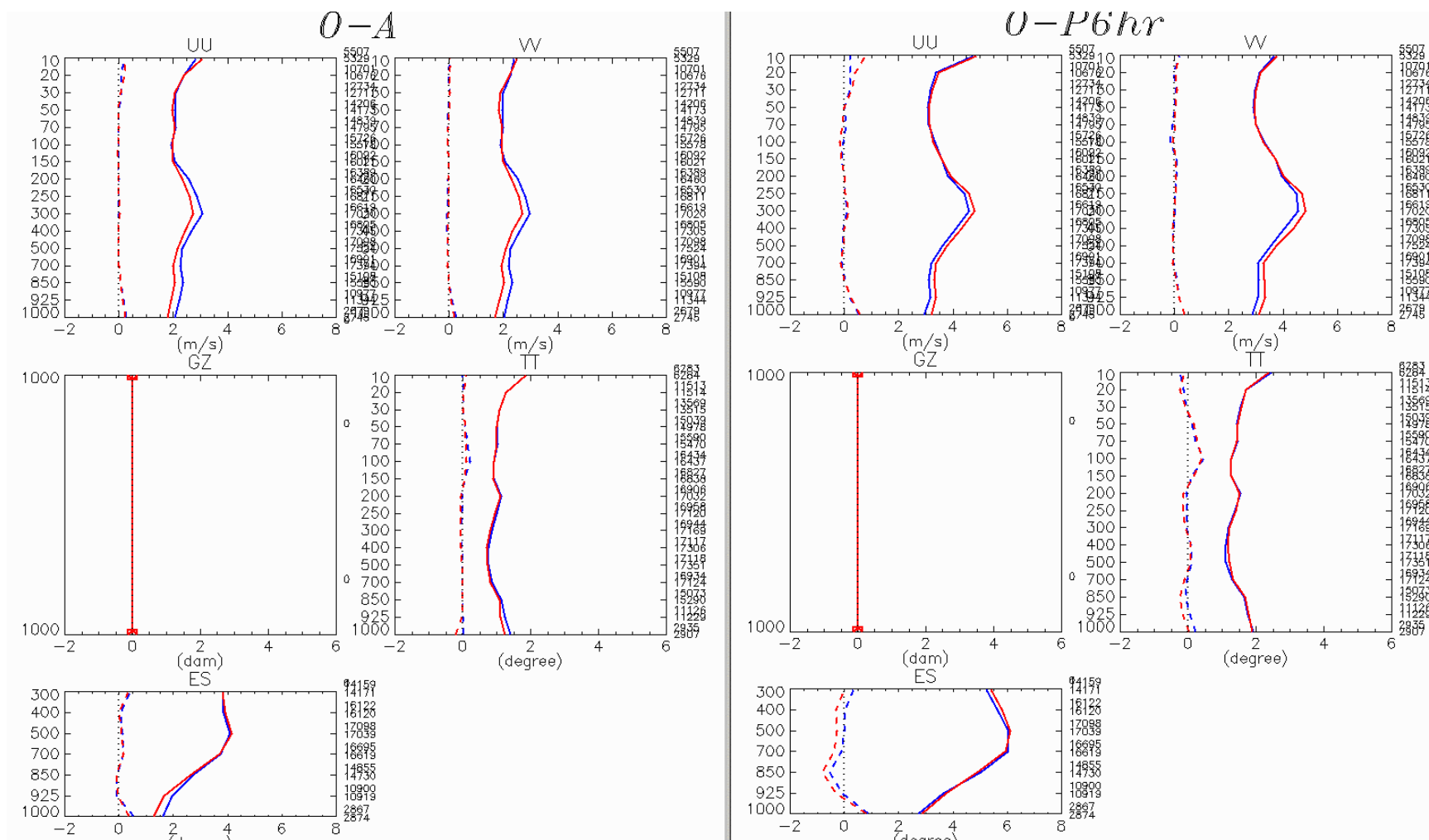
From simulations:



Specified in the CMAM-DAS:



Global Scores (vertical profiles) against radiosondes



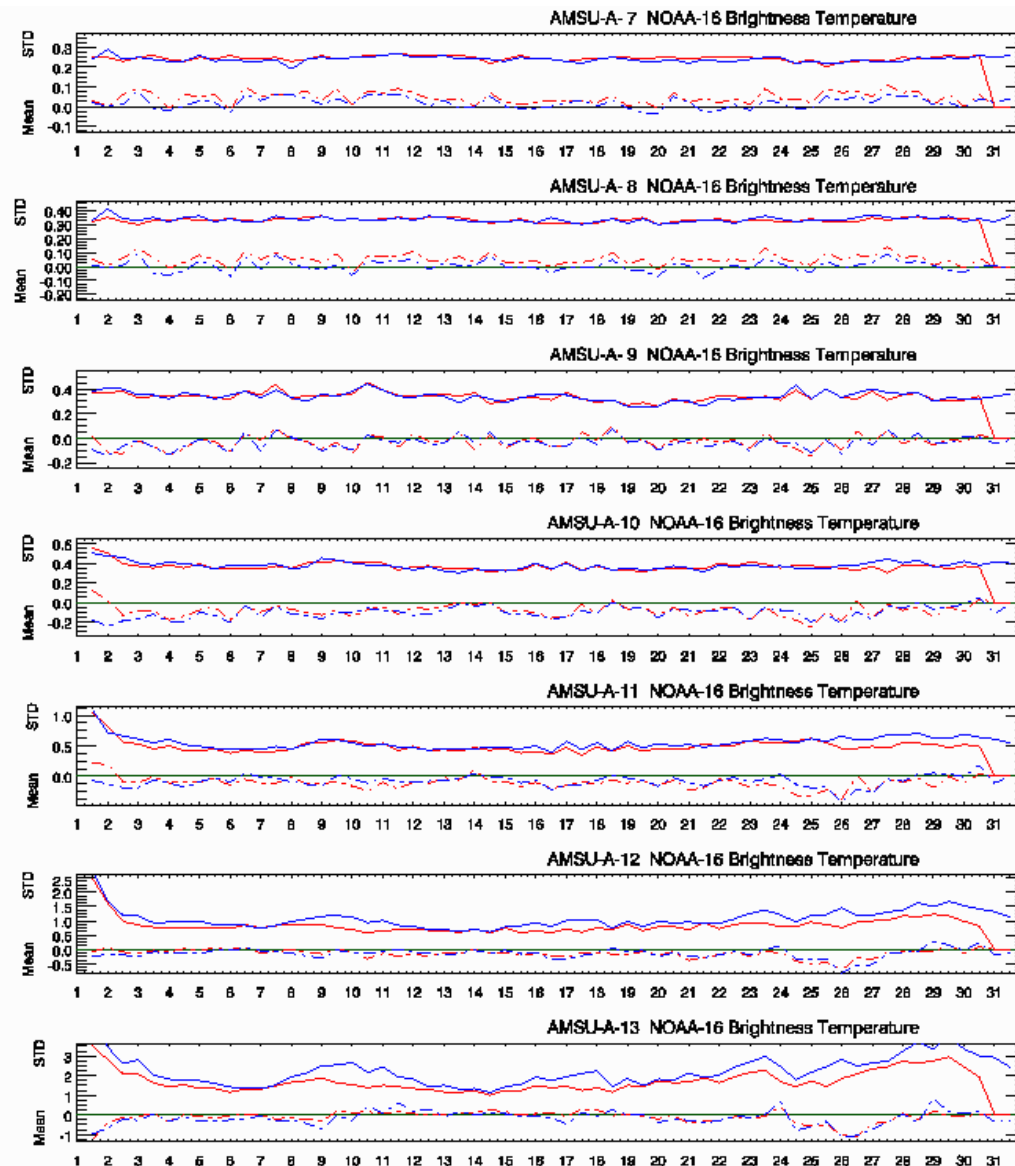
Bg. variances from simulations

Bg. variances Specified in the CMAM_DAS

O-P scores are improved with the new statistics!

O-P Scores (time series) against AMSU

(January 2002, North hemisphere)



Bg. variances from
simulations

Specified in the
CMAM_DAS

Improvement for upper
channels (11-13)

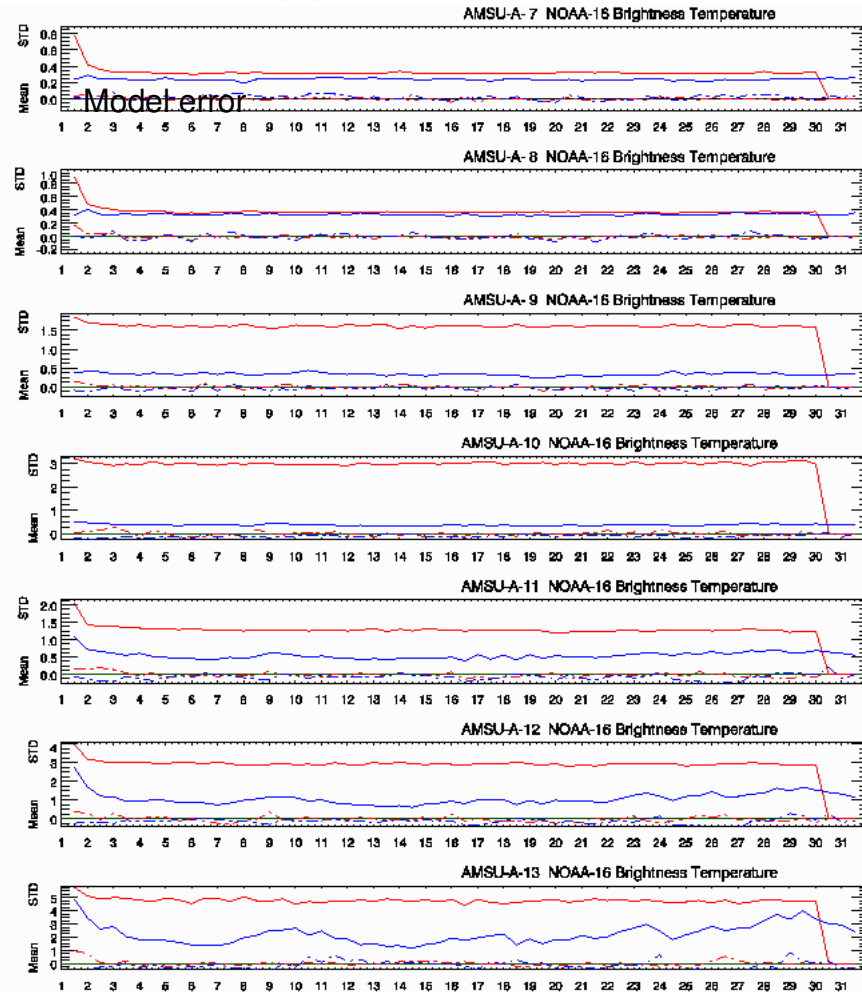
The new error statistics improved the assimilation

- O-P scores against radiosondes are improved
- O-P scores against AMSU-A are improved for upper channels
- A minimization procedure is now optimized (65 iterations against 130)

A nice property of the derived error variances: a fast convergence

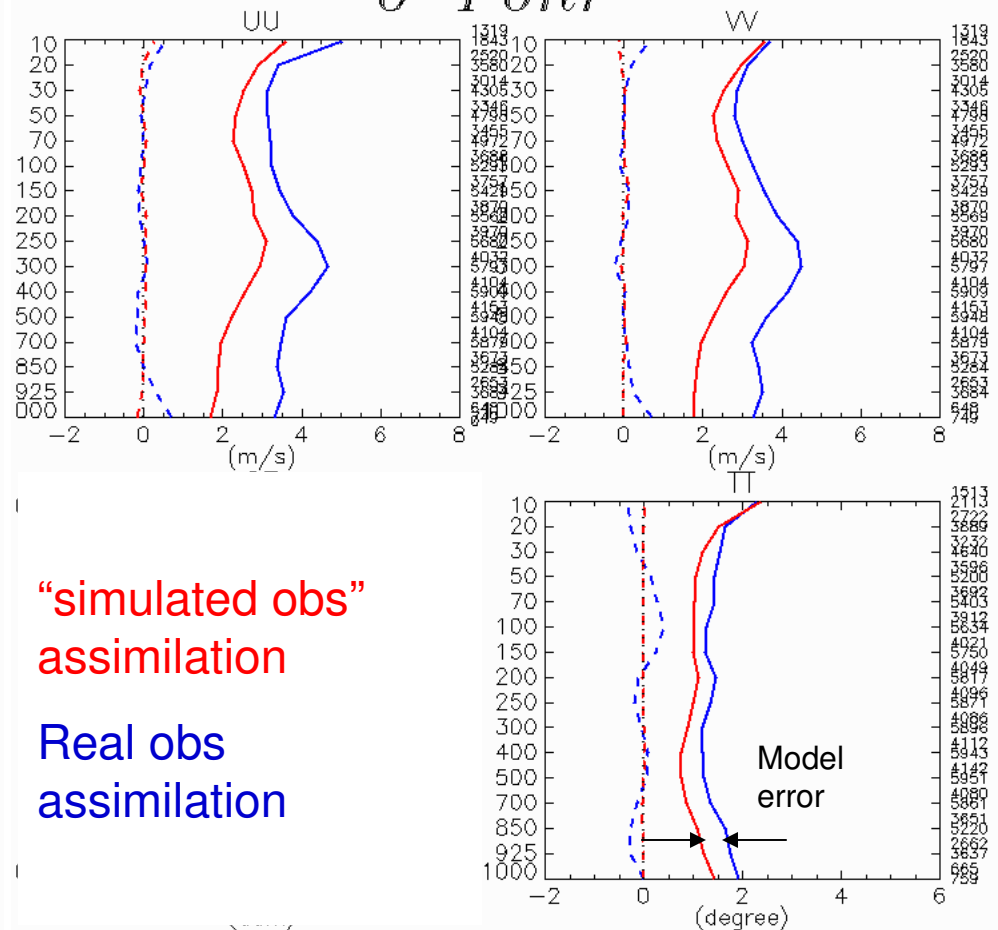
How to verify the variances of Observational errors? the scores with Simulated/real obs (January)

AMSU-A



radiosondes

0-P6hr



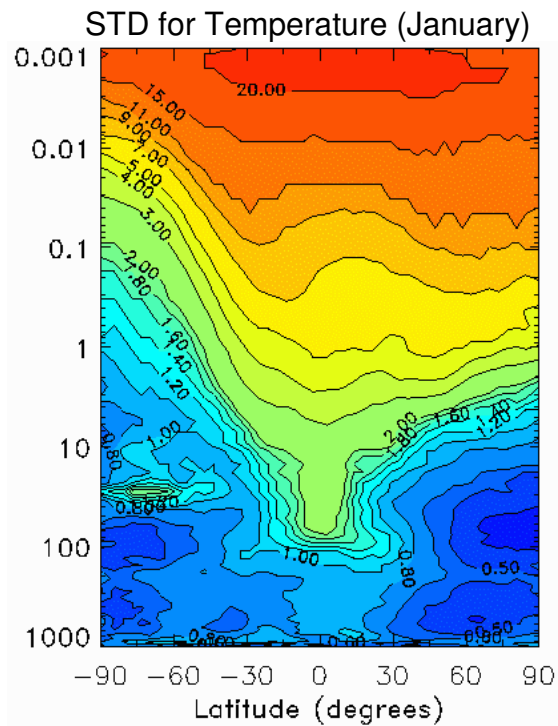
“simulated obs”
assimilation

Real obs
assimilation

Are the AMSU errors overestimated?

Forecast errors (from simulations)

After a month of assimilation
STD (forecast – truth):



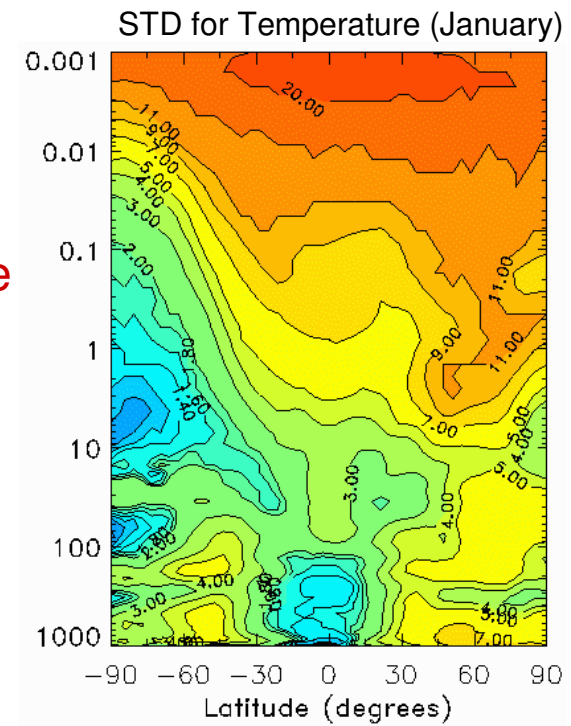
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Predictability of the
mesosphere ???

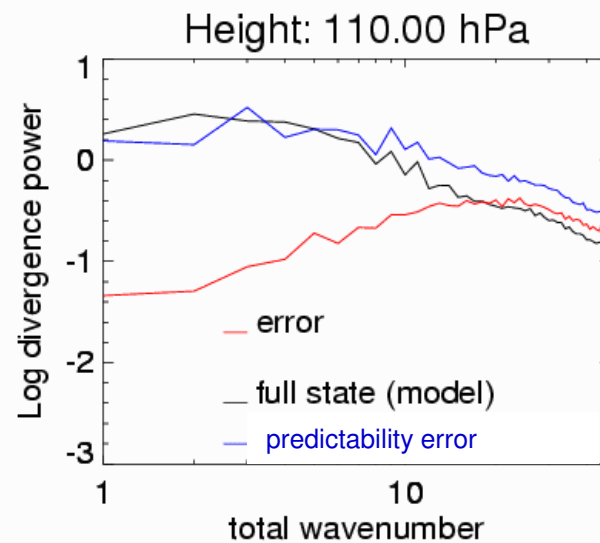
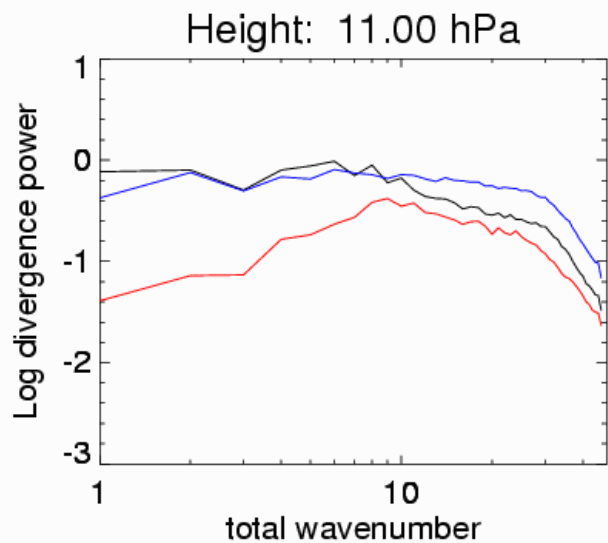
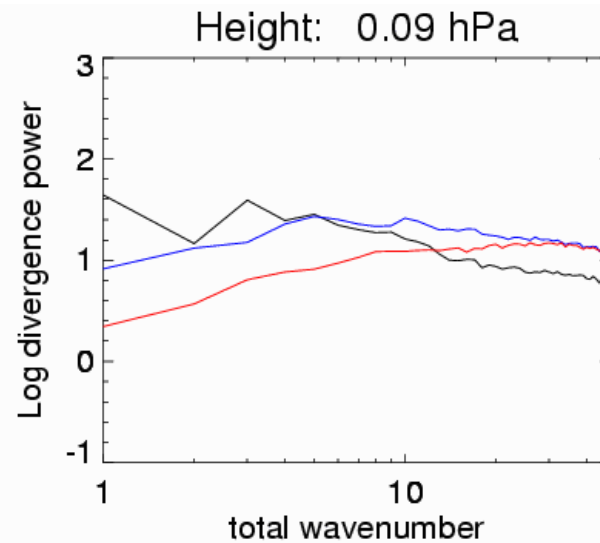
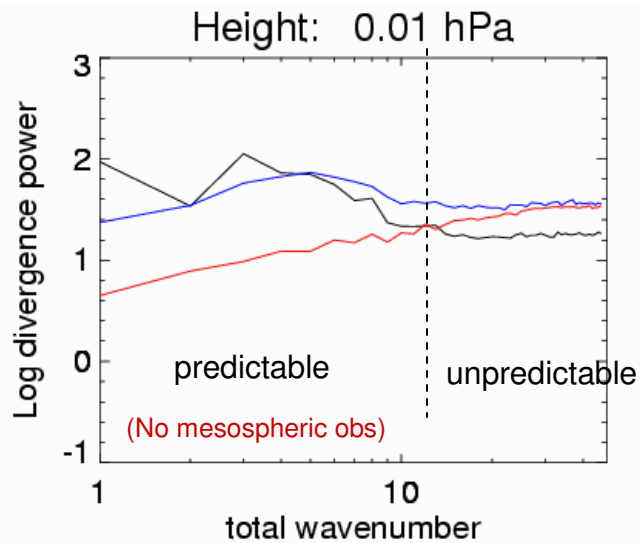
Predictability errors

After a month of a model run

STD (truth2 – truth):

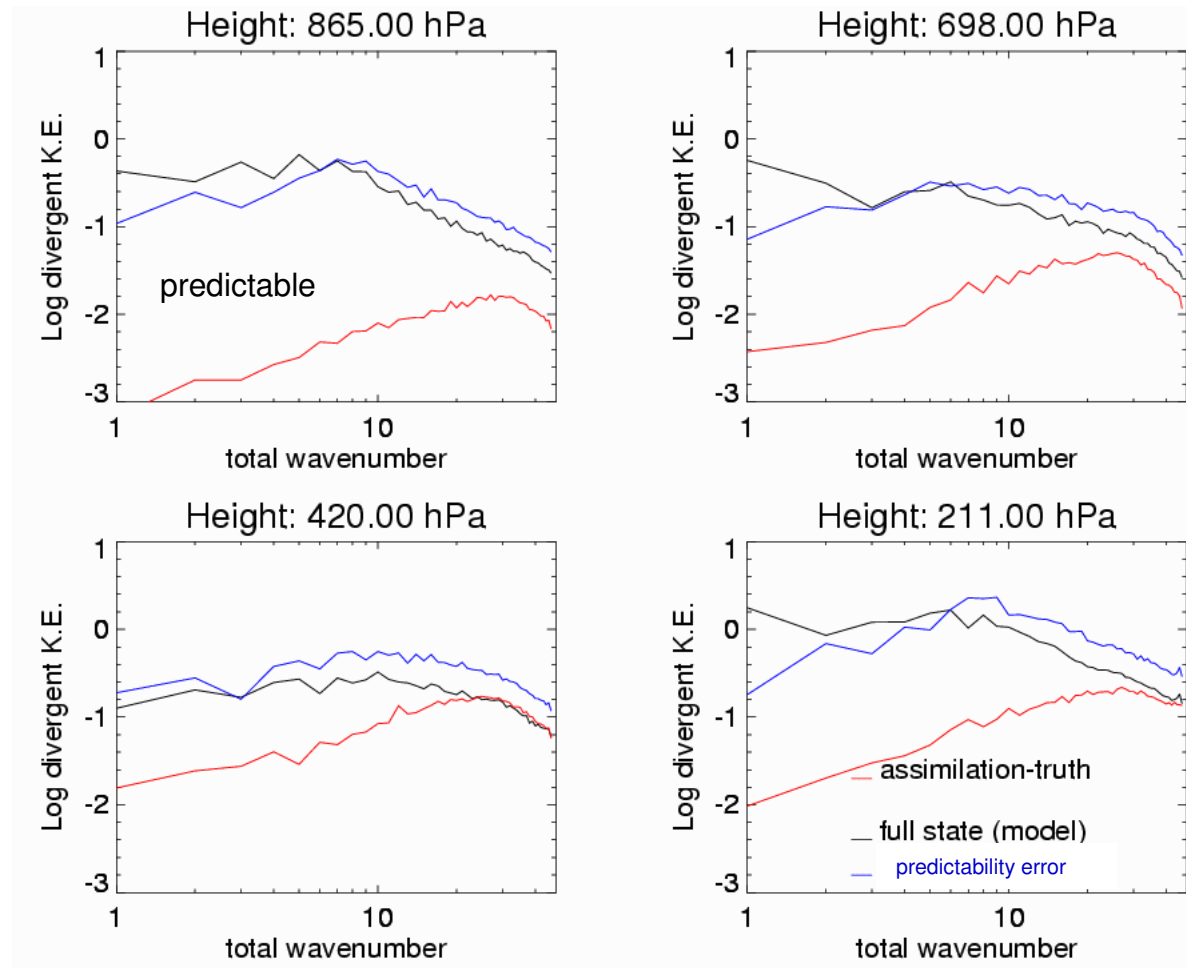


Error's spectra



6-h forecast errors
Full state (model)
Predictability errors

In the troposphere



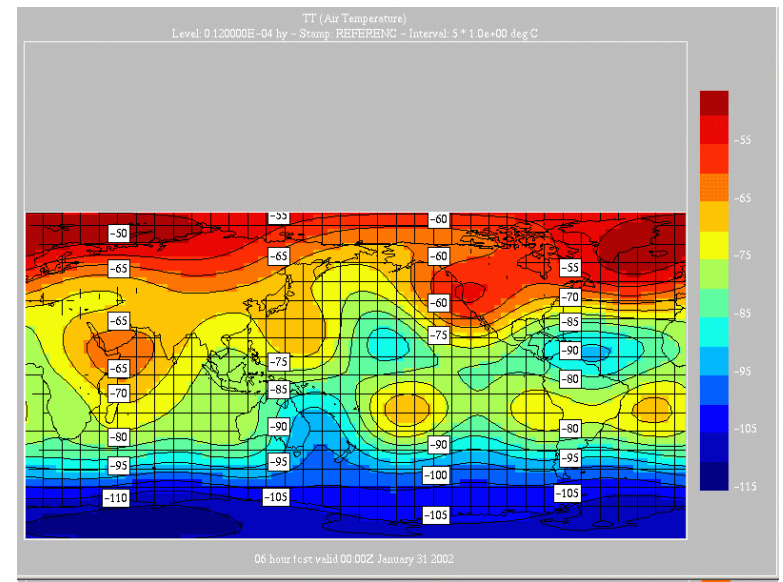
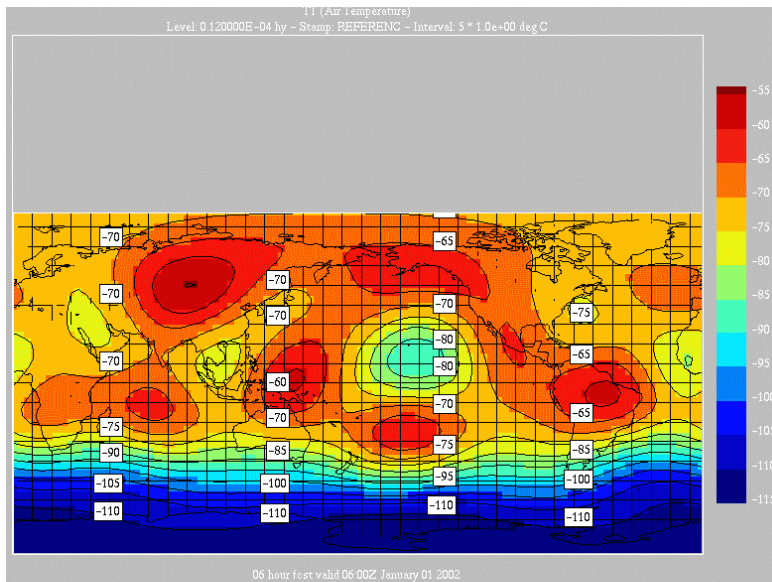
6-h forecast errors
Full state (model)
Predictability errors

temperatures (T6 truncated) at 0.012mb

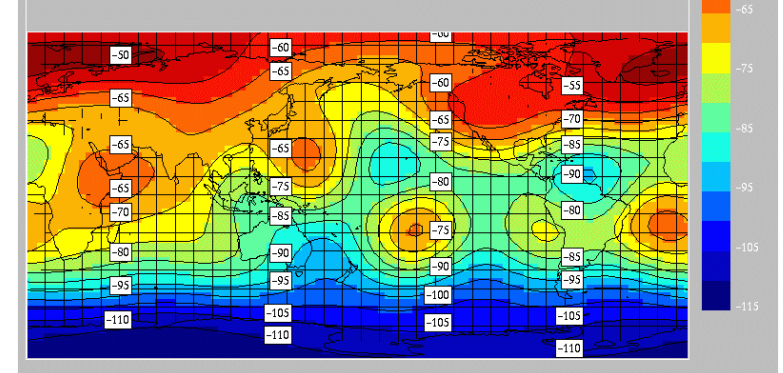
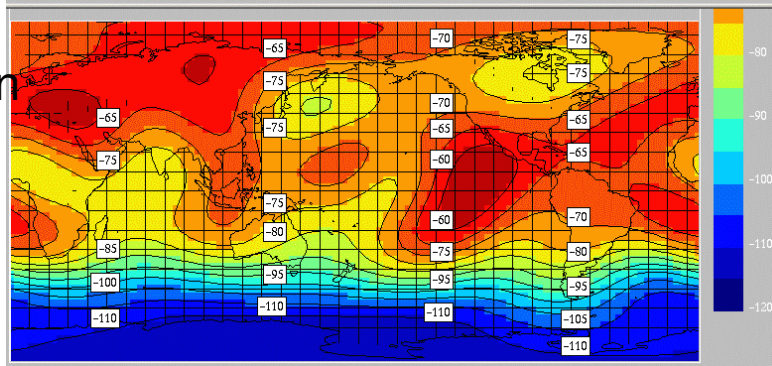
Initial states

After 30 days

truth



assimilation



lat
lon

conclusion

- We have found that the method of simulations may be very useful in controlling a DAS
- applied to the CMAM-DAS it brought quite a few interesting results:
 - We learned about forecast errors in the system,
 - The impact of observational errors is relatively small in the current system, and the dominating error component arises from the assimilation method itself
 - we also respecified the background error covariances in the system
 - We saw the way to verify the observational errors and will, probably use it to tune the AMSU variances
 - we assessed the predictability of the mesosphere and found the scale dependent limits of the current system to predict the mesosphere
 - And we are going to use this method to simulate mesospheric observations in order to see a possible impact.