

How to achieve universality in a CA using the same local function but different neighborhoods

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Outline

Introduction

How to simulate a finite number of arbitrary CA with one local function

How to achieve universality

Discussion of the embeddings used

Outline

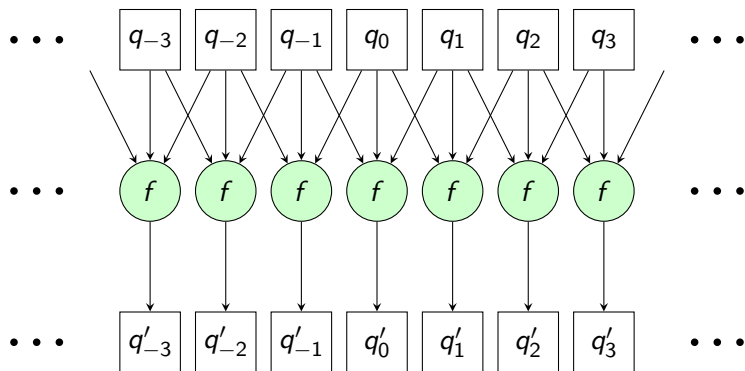
Introduction

How to simulate a finite number of arbitrary CA with one local function

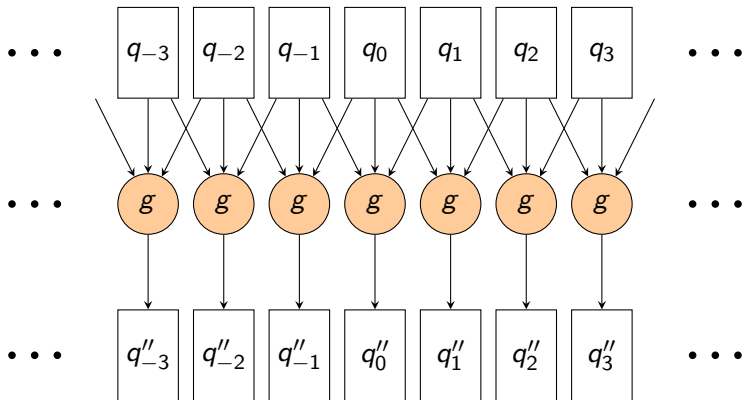
How to achieve universality

Discussion of the embeddings used

The basic picture



The basic picture



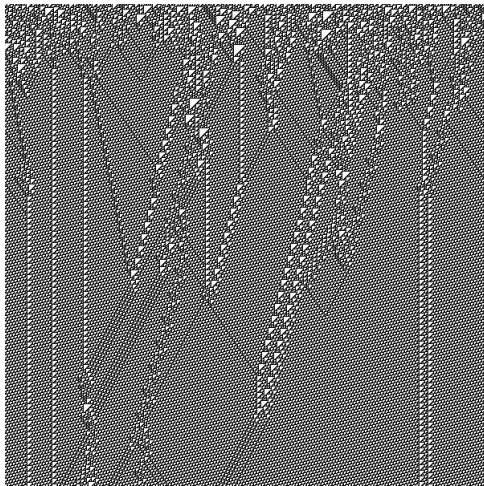
Basic notation

- ▶ R : set of all cells
- ▶ Q : finite set of states for each cell
- ▶ $c : R \rightarrow Q$ global configuration
 - ▶ $c(j)$ is the state of cell j in configuration c
 - ▶ Q^R set of all global configurations
- ▶ $f : Q^n \rightarrow Q$: local function
- ▶ $\nu : \{0, \dots, n-1\} \rightarrow R$: neighborhood
 - ▶ neighbors of cell j are $j + \nu(0), j + \nu(1), \dots, j + \nu(n-1)$
- ▶ f induces the global function $\mathcal{A} : Q^R \rightarrow Q^R$ via: $\forall c \ \forall j$

$$\mathcal{A}(c)(j) = f(c(j + \nu(0)), c(j + \nu(1)), \dots, c(j + \nu(n-1)))$$

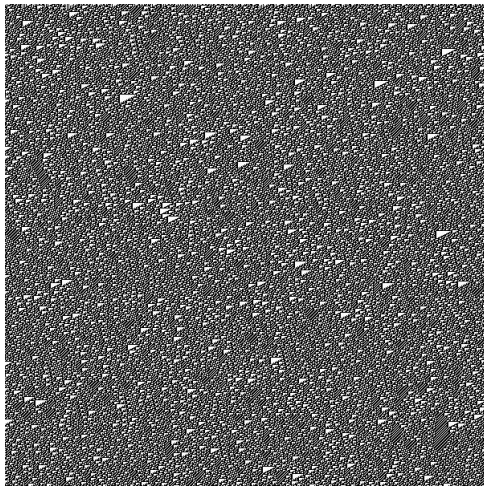
Example: Rule 110 with different neighborhoods

$$\nu = (-1, 0, 1)$$



Example: Rule 110 with different neighborhoods

$$\nu = (-1, 0, \textcolor{red}{2})$$



Observation

Fact

Each non-constant local function induces an infinite number of different global functions by changing the positions of neighbors.

Question

“How different” can those different global functions be/look like?

Answer

in general not known (to us) ...

... but if one selects the right local functions ...

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Given m CA $\mathcal{A}_i = (R, Q_A, \nu_A, f_i)$ for $0 \leq i < m$

- ▶ the *same* set of states, “ \mathcal{A} -configurations”
- ▶ w.l.o.g. the same ν_A
- ▶ *different* local functions

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find m CA $\mathcal{B}_i = (R, Q_B, \nu_i, f_B)$ for $0 \leq i < m$

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provide one embedding $E : Q_A^R \rightarrow Q_B^R$ (and only one)
independent of the \mathcal{A}_i to be simulated

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such that \mathcal{B}_i simulates \mathcal{A}_i in an obvious sense.

Simulation: embedding, e.g. for $m = 3$

embed \mathcal{A} -configuration
$$\cdots \boxed{q_{-5}} \boxed{q_{-4}} \boxed{q_{-3}} \boxed{q_{-2}} \boxed{q_{-1}} \boxed{q_0} \boxed{q_1} \boxed{q_2} \boxed{q_3} \boxed{q_4} \boxed{q_5} \cdots$$

into \mathcal{B} -configuration

[illegible]

Simulation: embedding, e.g. for $m = 3$

embed \mathcal{A} -configuration

\cdots	q_{-5}	q_{-4}	q_{-3}	q_{-2}	q_{-1}	q_0	q_1	q_2	q_3	q_4	q_5	\cdots
----------	----------	----------	----------	----------	----------	-------	-------	-------	-------	-------	-------	----------

into \mathcal{B} -configuration

\cdots	q_{-5}	q_{-4}	q_{-3}	q_{-2}	q_{-1}	q_0	q_1	q_2	q_3	q_4	q_5	\cdots
\cdots	1	2	0	1	2	0	1	2	0	1	2	\cdots

formally:

- ▶ $Q_B = Q_A \times \{0, 1, \dots, m-1\}$
- ▶ $E : Q_A^R \rightarrow Q_B^R$ where $E(c)(j) = (c(j), j \bmod m)$

Simulation: an example for von Neumann neighborhood

► for \mathcal{A}_i assume

j	0	1	2
$\nu_A(j)$	-1	0	1

for \mathcal{B}_i use

j	0	1	2	3
$\nu_0(j)$	-1	0	1	6
$\nu_1(j)$	-1	0	1	5
$\nu_2(j)$	-1	0	1	4

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► example: use ν_1 for simulation of f_1

...	q_{-5}	q_{-4}	q_{-3}	q_{-2}	q_{-1}	q_0	q_1	q_2	q_3	q_4	q_5	...
...	1	2	0	1	2	0	1	2	0	1	2	...

$$\begin{array}{|c|} \hline q'_{-2} \\ \hline 1 \\ \hline \end{array} = f_{1-0}(q_{-3}, q_{-2}, q_{-1})$$

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► for example when using ν_1 :

...	q_{-5}	q_{-4}	q_{-3}	q_{-2}	q_{-1}	q_0	q_1	q_2	q_3	q_4	q_5	...
...	1	2	0	1	2	0	1	2	0	1	2	...

$$\begin{array}{|c|} \hline q'_{-1} \\ \hline 2 \\ \hline \end{array} = f_{2-1}(q_{-2}, q_{-1}, q_0)$$

Simulation: an example for von Neumann neighborhood

► for \mathcal{A}_i assume

j	0	1	2
$\nu_A(j)$	0	-1	1

for \mathcal{B}_i use

j	0	1	2	3
$\nu_0(j)$	0	-1	1	6
$\nu_1(j)$	0	-1	1	5
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► for example when using ν_1 :

...	q_{-5}	q_{-4}	q_{-3}	q_{-2}	q_{-1}	q_0	q_1	q_2	q_3	q_4	q_5	...
...	1	2	0	1	2	0	1	2	0	1	2	...

$$\begin{array}{|c|} \hline q'_0 \\ \hline 0 \\ \hline \end{array} = f_{0-2}(q_{-1}, q_0, q_1)$$

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Universality can be considered from different points of view:

- ▶ "... for each computable function ..."
- ▶ "... for each CA ..." (of a sufficiently large class)

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Universality can be considered from different points of view:

- ▶ "... for each computable function ..."
- ▶ "... for each CA ..." (of a sufficiently large class)

Here we only

- ▶ **show the trick**
which allows to do "all" of the above.
- ▶ The rest is tedious routine work.

Starting point

Consider all CA \mathcal{A}_i with

- ▶ some fixed Q_A ,
- ▶ arbitrary local functions $f_i : Q_A^{n_i} \rightarrow Q_A$ and
- ▶ arbitrary neighborhoods ν_i of size n_i (matching f_i).

Each computable function can be computed by such a CA for some reasonable definition of initial and final configurations.

Observe, that in contrast to the previous section one must allow for **different neighborhoods**.

Goal

Devise

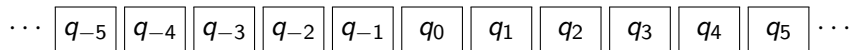
- ▶ one set Q_B of states,
- ▶ a simple embedding $E : Q_A^R \rightarrow Q_B^R$ of configurations and
- ▶ one local function f_B of fixed arity b ,

such that

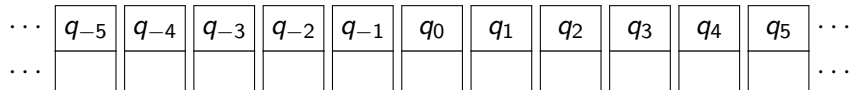
- ▶ for each \mathcal{A}_i
- ▶ there is a computable neighborhood ν_j of size b such that
- ▶ the CA $\mathcal{B}_j = (R, Q_B, \nu_j, f_B)$
- ▶ for each \mathcal{A} -configuration c_A
- ▶ when started with the embedded configuration $c_B = E(c_A)$
- ▶ simulates each step of each cell of \mathcal{A}_i for c_A .

Embedding of configurations

\mathcal{A} -configuration

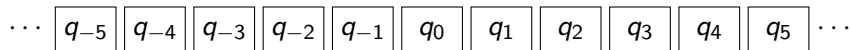


corresponding \mathcal{B} -configuration

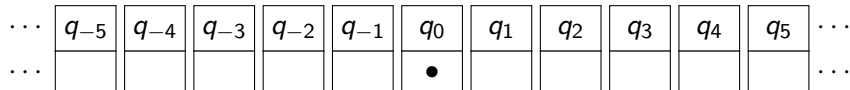


Embedding of configurations

\mathcal{A} -configuration



corresponding \mathcal{B} -configuration



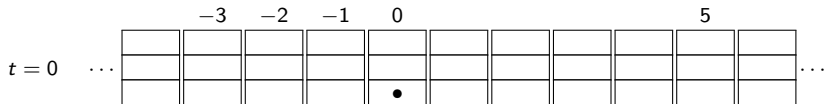
The trick

- ▶ Neighborhood $N_r = \{-r, -1, 0, 1, r\}$, where $r \geq 2$.
- ▶ Call the neighbor at position r the “*remote*” neighbor.

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- ▶ Neighborhood $N_r = \{-r, -1, 0, 1, r\}$, where $r \geq 2$.
- ▶ Call the neighbor at position r the “*remote*” neighbor.
- ▶ Use the marker \bullet to compute the distance of the remote neighbor
- ▶ and represent it as a binary number.
- ▶ Use this representation as that of the CA \mathcal{A}_i (if any) to be simulated.

The trick for $N_5 = \{-5, -1, 0, 1, 5\}$



The trick for $N_5 = \{-5, -1, 0, 1, 5\}$

			-3	-2	-1	0				5		
$t = 0$
						•						
$t = 1$...				0							
				0	1							...
					•	>						

The trick for $M_5 = \{-5, -1, 0, 1, 5\}$

		-3	-2	-1	0				5	
$t = 0$...				•					...
$t = 1$...			0	1	>				...
$t = 2$...			1	1		>			...
$t = 3$...			0	1		>			...
$t = 4$...		1	1	1			>		...
$t = 5$...		1	0	1				<	...

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		-3	-2	-1	0					5	
$t = 0$
					•						
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$t = 2$...			1							...
			0	1	•	>					
$t = 3$...			0							...
			1	1	•	>					
$t = 4$...		1	1							...
			0	0	1				>		
					•						
$t = 5$...		1	0							...
			0	1	1						
					•				<		

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		-3	-2	-1	0					5		
			1	0								
$t = 5$...		0	1	1							...
					•					<		

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		-3	-2	-1	0					5	
$t = 5$...			1	0						
				0	1	1					...
						•				<	
$t = 6$...			0	1						
				1	0	0					...
						•			<		
$t = 7$...		1	0	1						
			0	0	0	0					...
						•			<		
$t = 8$...		1	0	1						
			0	0	0	0					...
						•		<			
$t = 9$...		1	0	1						
			0	0	0	0					...
						•	<				
$t = 10$...		1	0	1						
			0	0	0	0					...
						○					

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		-3	-2	-1	0					5	
$t = 5$...			1	0						
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					•					<	
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			1	0	0						...
					•				<		
$t = 7$...	1	0	1							
		0	0	0	0						...
					•			<			
$t = 8$...	1	0	1							
		0	0	0	0						...
					•		<				
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		0	0	0	0						...
					○						

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A step aside:

simulation of irreversible CA by reversible CA
for infinite configurations

- ▶ Theorem (Hertling): This is impossible.
- ▶ Theorem (Durand-Lose): This is possible.

Both are right

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simulation of irreversible CA by reversible CA
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- ▶ Theorem (Hertling): This is impossible.
- ▶ Theorem (Durand-Lose): This is possible.

Both are right for their respective notions of simulation:

- ▶ Hertling requires the embedding of configurations to commute with shifts ...
- ▶ Durand-Lose uses one marker bit.

What about our embeddings?

First: Does not commute with the shift, but at least preserves spatial periodicity.

Second: Even destroys spatial periodicity.

Conjecture

If one wants to simulate an infinite number of \mathcal{A}_i using only different neighborhoods, one *must* use an embedding which destroys spatial periodicity of configurations.

Proof

Just to be sure, let me sleep a few more nights about this.

Conclusion

- ▶ There is a set of states and a local function for CA such that by choosing the appropriate neighborhood any CA (with Q_A) can be simulated (no matter which local function and neighborhood the latter uses).
- ▶ The above technique can be generalized to higher dimensions.
- ▶ In both cases the embeddings do not commute with the shift, in the second case even spatial periodicity is broken.
- ▶ So, this was a first step . . .

Thank you very much for your attention!