

Capacity, Carleson Measures, and Exceptional Sets

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January 2008

The Dirichlet Space

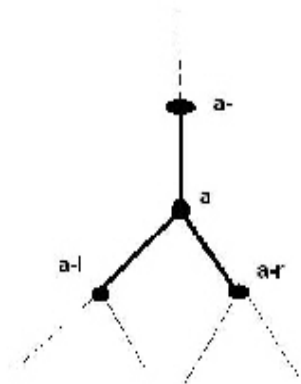
The Dirichlet space, \mathcal{D} :

$$f \in \text{Hol}(\mathbb{D}), \quad \|f\|_{\mathcal{D}}^2 = |f(0)|^2 + \int_{\mathbb{D}} |f'|^2 < \infty.$$

The Dyadic Dirichlet Space

The Tree

The tree, T , a rooted loopless graph, every point other than the root has three nearest neighbors.



The Dyadic Dirichlet Space

The Tree Boundary

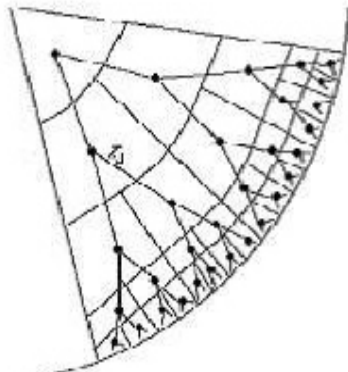
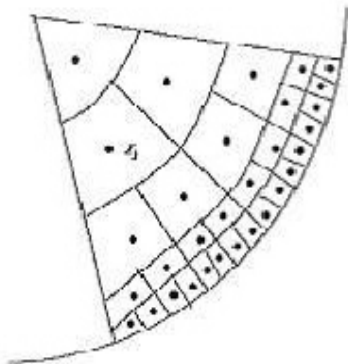
A point of ∂T is an equivalence class of geodesics infinite in one direction;
a path to the abstract boundary,

The Dyadic Dirichlet Space

The Tree in the Disk

Think of T as sitting inside \mathbb{D} with the root o at 0.

Think of ∂T as being the same as \mathbb{T} .



The Dyadic Dirichlet Space

Operations on functions and measures on T

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$$If(\alpha) = \sum_{o \prec \beta \prec \alpha} f(\beta).$$

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- A measure μ on $\overline{\mathbb{D}}$ induces a measure μ_T on $\overline{T} = T \cup \partial T$ by.....

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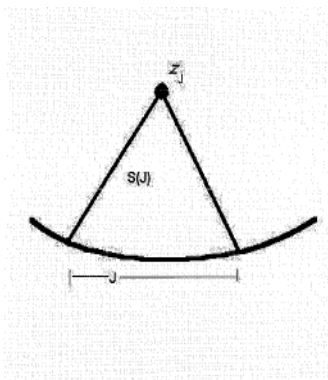
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- \mathcal{D}_d is a simple but useful model for \mathcal{D} .
- More generally, function spaces on T model function spaces on \mathbb{D} ; Besov spaces, spaces of p -harmonic functions,...

Tents

Tents in the Disk

The tent over J , the shadow region below z_J .



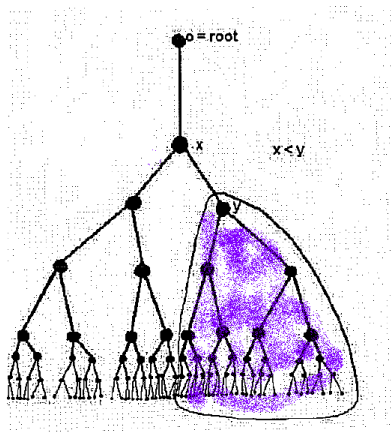
$$S(z) = S(J)$$

and set $\partial S(\alpha) = \overline{S(\alpha)} \cap \partial T$

Tents

Tents in the Tree

Here $\mathbf{S}(y)$ is the shadow region under y , etc.



- A Carleson measure for \mathcal{D} is a measure μ on $\overline{\mathbb{D}}$ such that $\exists C > 0$ so that $\forall f \in \mathcal{D}$

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- In either case $\|\mu\|$ is defined to be the smallest C such that works.

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- For $E \subset \partial\overline{\mathcal{T}}$, $\text{Cap}_{\mathcal{T}}(E) = \inf \left\{ \|f\|_{\mathcal{D}_d}^2 : f \geq 1 \text{ on } E \right\}$.
- In fact $\text{Cap}(E) = 0$ iff $\text{Cap}_{\mathcal{T}}(E) = 0$ which is one of the tools in pulling results on \mathcal{D}_d back to results on \mathcal{D} .

Characterization of Carleson Measures

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- ③ μ_T satisfies a tree capacity condition. There is a constant C so that for all sets $E = \cup_j \partial S(x_j)$ in ∂T ,

$$\mu_T \left(\overline{\cup_j S(x_j)} \right) \leq C \operatorname{Cap}_T(\cup_j \partial S(x_j)).$$

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$$\mu_T \left(\overline{\cup_j S(x_j)} \right) \leq C \operatorname{Cap}_T(\cup_j \partial S(x_j)).$$

- ④ μ_T satisfies the tree condition. There is a constant C so that $\forall \alpha \in T$

$$I^*(I^*\mu_T)^2(\alpha) \leq CI^*\mu_T(\alpha)$$

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- 2 This establishes equivalence of two classes of null sets and gives an alternative approach to exceptional sets for boundary convergence.

Theorem (ARS '07)

For E , a compact subset of $\partial\overline{T}$,

$$\text{Cap}_T(E) = \sup_{\text{Supp}(\mu) \subset E} \frac{\mu(E)}{\|\mu\|_{CM(T)}}.$$

Corollary

E has capacity zero if and only if E is μ -null set for every Carleson measure μ .

It is sometimes easier to show a set carries no nontrivial Carleson measures than to estimate its capacity directly.

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- Hence, roughly, the tree condition compares the energy of the measure with its mass.

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 - For approach regions with contact between algebraic and fully exponential there is convergence with an exceptional set of capacity* zero; capacity* is defined with respect to a different space.

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- The approach focuses on tree geometry and tree combinatorics; in terms of the boundary values the approach is doing bookkeeping according to scale and position.

Beurling's Theorem for the Dyadic Dirichlet Space

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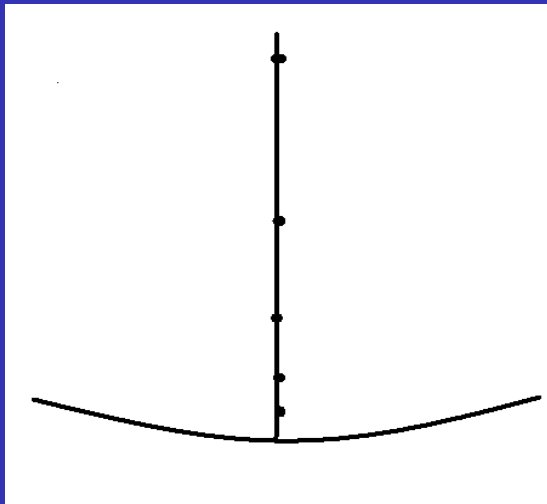
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- 5 and thus finite radial limits off a set of capacity zero.



Extending this analysis to more complicated geometries.

Radial Approach



We control F on the radius using $|DF|$ at the nodes.

NonTangential Approach

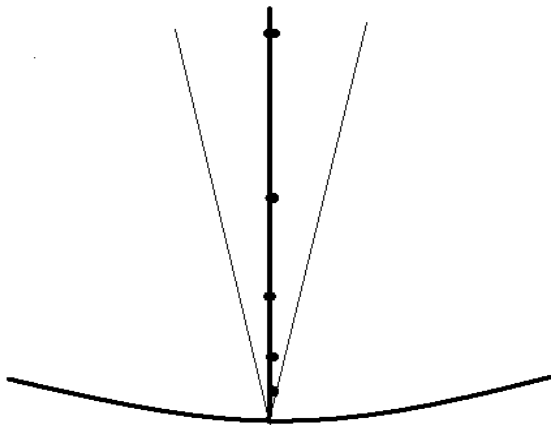


Figure: For control in a wedge we need to use $|DF|$ at more points.

NonTangential Approach—Constructing a Majorant

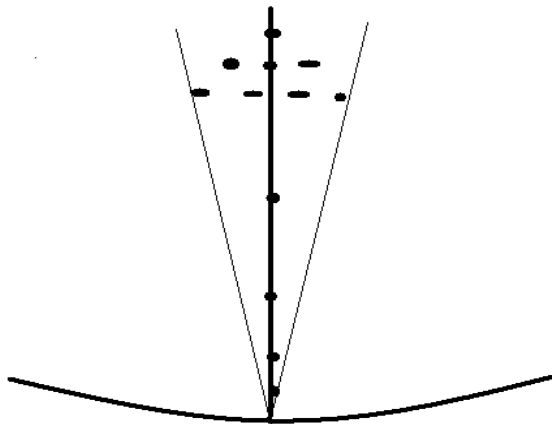


Figure: Each point on the radius looks after finitely many other points, and then the previous proof works.

Approach with Algebraic Contact

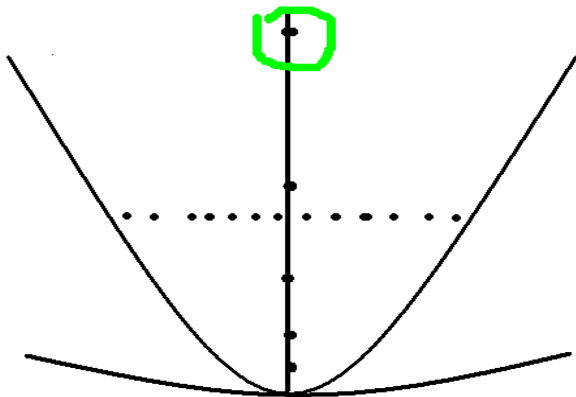


Figure: With algebraic contact there are more loci of variation to control. We use one point to control several long rows.

Approach with Algebraic Contact

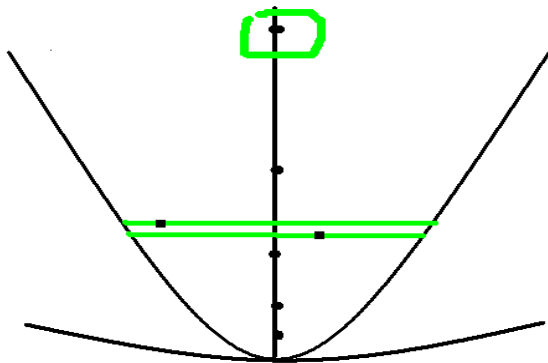
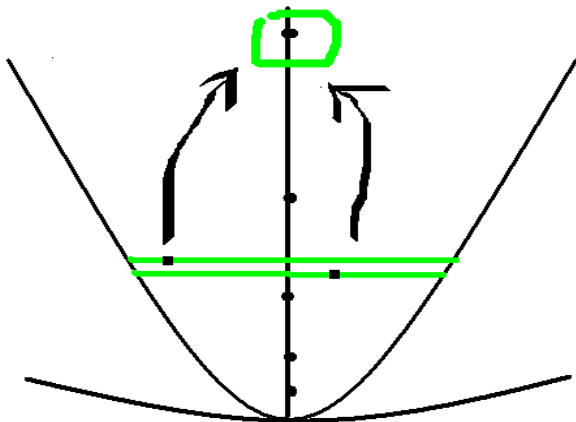


Figure: Use $\sum \max \{|DF| \text{ on a row} \}$.

Approach with Algebraic Contact

The values of the majorant at the circled point controls the variation down two the green rows.

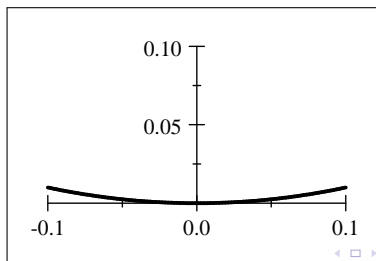


In Terms of Euclidean Geometry

Think of the upper halfplane and a contact region that touches the boundary at the origin. The coordinates of an index point n steps from o are $\sim (0, 2^{-n})$. The rows being majorized are kn steps further so their y coordinates are $\sim 2^{-n-kn}$. At that height the horizontal step size is 2^{-n-kn} . These rows are kn steps below the index point so the width of the row is

$$\text{number of steps} \times \text{step size} = 2^{kn} 2^{-n-kn} = 2^{-n}$$

Hence the coordinates of the edge of the row are $(2^{-n}, 2^{-n-kn})$; we are on the curve $y = |x|^{k+1}$.



Semi-exponential Contacts–Constructing a Majorant

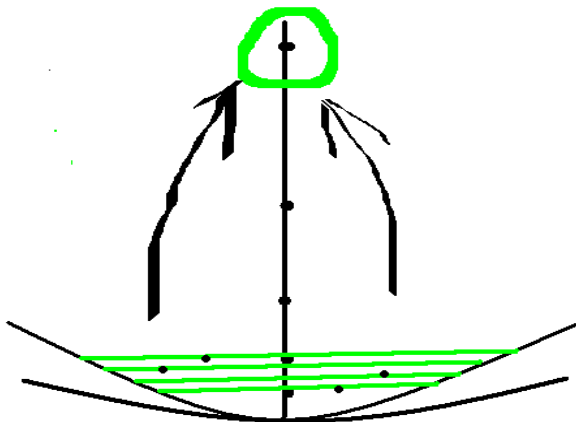


Figure: Now there are more rows to deal with.

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- Hence the previous proof goes through but now it shows that the set on which G is infinite—and hence F has boundary limits—will have null capacity but for the capacity associated to $l^2(T, 2^{\alpha d(o, \cdot)})$.

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- Use the fact that such a G has limits on a set of full measure.
- And hence on a set of full measure $\text{Osc}(G) \rightarrow 0$
- Use this to get the *a.e.* $d\theta$ convergence for F .

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- Discrete vs. Continuous; would like to know *discrete capacity*(E) = 0 if and only if *continuous capacity*(E) = 0, compare both to a graph capacity.
- In general when a tree model captures the geometry and there is summability information for the local oscillation these ideas can be used; for instance p -harmonic functions.

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 - F has boundary limits through sets making doubly exponential contact except of a set of measure zero.