



Non completely positive maps

in physics



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History, references, etc

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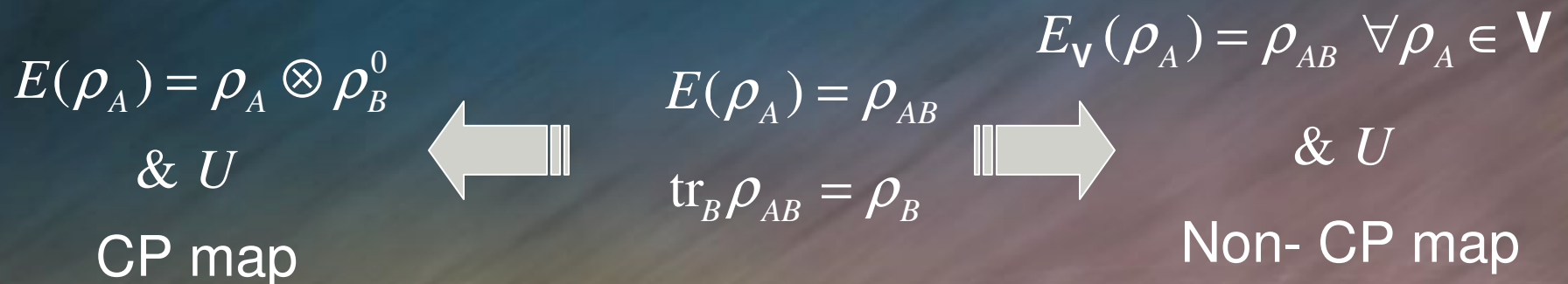
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Maps, extensions & non-linearity

Explicit form of a non-unitary evolution: extensions



$$\rho_{AB} = \frac{1}{d_A d_B} \left(1_A \otimes 1_B + \alpha_i \sigma_i^A \otimes 1_B + \beta_j 1_A \otimes \sigma_j^B + \gamma_{ij} \sigma_i^A \otimes \sigma_j^B \right)$$

$$\rho_A \otimes \rho_B \Leftrightarrow \gamma_{ij} = \alpha_i \beta_j$$

Non-CP maps: definitions

Defs: $\Xi(\rho)$ Non-CP map with domain of positivity W

• assignment map $E_V(\rho_A) \quad \forall \rho \in V \subset W$

$$E_V(\rho_A) = \rho_{AB}$$

• unitary transformation U

$\Xi(\rho)$ is physically accessible

Without restrictions it is trivial

$$\Xi(\rho) = \rho^T : \quad E(\rho_A) = \rho_A \otimes \rho_A^T \quad \& \quad U = \text{SWAP}$$

A warning & three conclusions

Assignments: definitions

Linear assignments: motivated by (uncontrolled) interactions

$$\beta_j = \beta_j^0 + \vec{B}_j \cdot \vec{\alpha}, \quad \gamma_{ij} = \gamma_{ij}^0 + \vec{C}_{ij} \cdot \vec{\alpha}$$

Non-linear assignments: motivated by quantum comp hardware

$$\beta_j = \beta_j^0 + \varepsilon \beta_j^1(\vec{\alpha}), \quad \gamma_{ij} = \alpha_i \beta_j^0 + \varepsilon \gamma_{ij}^0(\vec{\alpha}) \quad \varepsilon \ll 1$$

Example
$$E(\rho_A) = \frac{1}{4_B} \left(\mathbf{1}_A \otimes \mathbf{1}_B + \alpha_i \sigma_i^A \otimes \mathbf{1}_{B \setminus i} + a \sigma_i^A \otimes \sigma_i^B \right)$$

$$\rho_A = \frac{1}{2} (\mathbf{1}_A + \alpha_i \sigma_i^A) \quad 0 \leq |a| \leq a_{\max} = \left(\sqrt{4 - 3|\alpha|^2} - 1 \right) / 3$$

Maps & dynamical matrices

Dynamical (Choi) matrix $\rho' = \Phi(\rho) \implies \rho_{mn} = D(\Phi)_{ms,nt} \rho_{st}$

$$\begin{aligned} &\implies \rho_{mn} \rightarrow r_b \\ &D_{ms;nt}^R \square D_{mn;st} \rightarrow \bar{D}_{ab} \end{aligned}$$

Properties

- Hermitian $(D^\dagger)_{ms;nt} = D_{nt;ms}^*$

- If trace-preserving $\sum_m D_{ms;mt} = \delta_{st} \implies \sum_a \lambda_a = d$

- If unital $\Phi(1) = 1 \implies \sum_s D_{ms;ns} = \delta_{mn}$

- Choi theorem $D \geq 0$, iff Φ is CP

$$(\Phi_A \otimes 1_B) \rho_{AB} \geq 0$$

Maps & dynamical matrices

Eigendecomposition

$$D_{ms;nt} = \sum_a \lambda_a (M_a)_{ms} (M_a^\dagger)_{nt}$$

Kraus form of a CP map

$$\rho' = \Lambda(\rho) = \sum_a M_a \rho M_a^\dagger$$

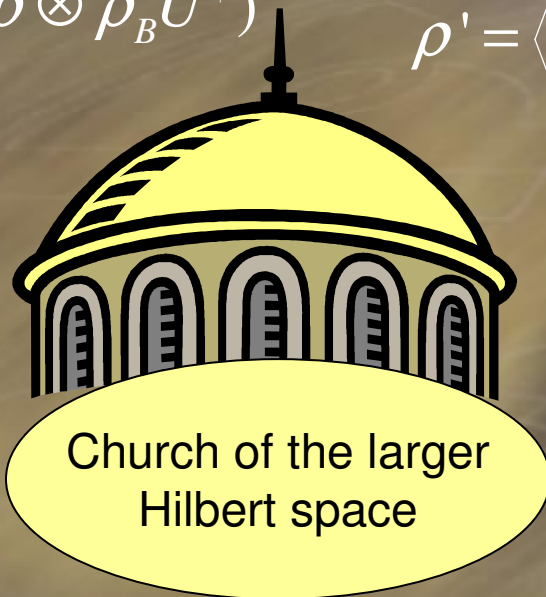
Difference form

$$\rho' = \Lambda_1(\rho) - \Lambda_2(\rho)$$

$$\Lambda(\rho) = \text{tr}_B (U \rho \otimes \rho_B U^\dagger)$$

$$\rho' = \langle \mu | \sqrt{p_\nu} U | \nu \rangle \rho_A \langle \nu | \sqrt{p_\nu} U^\dagger | \mu \rangle$$

$$M_{\mu\nu} = \langle \mu | \sqrt{p_\nu} U | \nu \rangle$$



Non-CP maps: physics

$$\rho_{AB} = \frac{1}{d_A d_B} \left(\mathbf{1}_A \otimes \mathbf{1}_B + \alpha_i \sigma_i^A \otimes \mathbf{1}_B + \beta_j \mathbf{1}_A \otimes \sigma_j^B + \gamma_{ij} \sigma_i^A \otimes \sigma_j^B \right)$$

Unitary evolution & partial trace

$$\Xi(\rho_A) = \sum_{\mu, \nu} M_{\mu\nu} \rho_A M_{\mu\nu}^\dagger + \sum_{\mu} \langle \mu | \Gamma_{ij} U \sigma_i^A \otimes \sigma_j^B U^\dagger | \mu \rangle$$

$$\Gamma_{ij} = (\gamma_{ij} - \alpha_i \beta_j) / d_A d_B$$

$$\rho'_{mn} = G_{ms;nt} \rho_{st} + \xi \cdot \sigma_{mn}$$



$$D_{ms;nt} = G_{ms;nt} + \xi \cdot \sigma_{mn} \delta_{st}$$

$$G_{ms;nt} = \sum_{\mu, \nu} (M_{\mu\nu})_{ms} (M_{\mu\nu}^\dagger)_{nt}$$

$$\xi_i \sigma_i^A = \sum_{\mu} \langle \mu | \Gamma_{ij} U \sigma_i^A \otimes \sigma_j^B U^\dagger | \mu \rangle$$

Non-CP maps: examples

$$E(\rho_A) = \frac{1}{4_B} \left(\mathbf{1}_A \otimes \mathbf{1}_B + \alpha_i \sigma_i^A \otimes \mathbf{1}_B + a \sigma_i^A \otimes \sigma_i^B \right)$$

$$U_1 = \begin{pmatrix} e^{i\theta} \cos \phi_1 & 0 & 0 & ie^{i\theta} \sin \phi_1 \\ 0 & \cos \phi_2 & i \sin \phi_2 & 0 \\ 0 & i \sin \phi_2 & \cos \phi_2 & 0 \\ ie^{i\theta} \sin \phi_1 & 0 & 0 & e^{i\theta} \cos \phi_1 \end{pmatrix}$$

$$[U, \sigma_i^A \otimes \sigma_i^B] = 0$$

CP map

$$U_2 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \phi & \sin \phi & 0 \\ 0 & -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\xi \cdot \sigma = \frac{1}{2} \begin{pmatrix} a \sin 2\phi & 0 \\ 0 & -a \sin 2\phi \end{pmatrix}$$

so what?

Entanglement

PPT test:

$$\forall \rho: a_{\text{ent}} > a_{\text{max}}$$

*No entanglement
both before & after*



Necessary condition 1

$\Xi(\rho)$ is physically accessible through linear extension, then

$$\Xi(\rho) = \sum_a M_a \rho M_a^\dagger + \xi_i \sigma_i$$

- Finite-dim extension: trivial
- Infinite-dim extension: no decomposition à la Bloch

$$\rho_{AB} = [\rho_A \otimes \rho_B] + [\rho_{AB} - \rho_A \otimes \rho_B]$$

$$\rho'_{AB} = U[\rho_A \otimes \rho_B]U^\dagger + U[\rho_{AB} - \rho_A \otimes \rho_B]U^\dagger$$

$$\rho'_A = \Lambda(\rho_A) + \text{traceless part}$$



Example: transposition

$$D_T = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$D_T(\rho) = G\rho + \xi \cdot \boldsymbol{\sigma}$$

$$G(\xi) > 0$$

Difference form:

$$T(\rho) = -(i\sigma_y)\rho(i\sigma_y)^\dagger / 2 + (\sigma_+\rho\sigma_+ + \sigma_-\rho\sigma_- + \sigma_x\rho\sigma_x)$$

Negative eigenvalue:

$$\lambda_- = -\sqrt{1 + \xi^2}$$



Necessary condition 2

$\Xi(\rho)$ is physically accessible with state-independent affine form & unital, then it is CP

$$\Xi(\rho) = \Lambda(\rho) + \xi \cdot \sigma$$

$$\Lambda(\rho) = \Lambda_0(\rho) + \zeta \cdot \sigma$$

$$\Xi(\rho) = \Lambda_0(\rho)$$

Non-linear assignment...

$$\beta_j = \beta_j^0 + \varepsilon \beta_j^1(\vec{\alpha}), \quad \gamma_{ij} = \alpha_i \beta_j^0 + \varepsilon \gamma_{ij}^0(\vec{\alpha}) \quad \varepsilon \ll 1$$

$$H_{AB} = H_A \otimes 1 + \eta H_{\text{int}},$$

At the first order of perturbation theory the reduced dynamics is linear and CP

Proof:

$$U_{AB} = U \otimes 1 - i\eta t \left(\sum_{ij} h_{ij} U_A \sigma_i^A \otimes \sigma_j^B + \sum_{ijkl} h_i h_{jk} C_{lij} U_A \sigma_l^A \otimes \sigma_j^B / 2 \right) +$$

+affine form + perturbation theory

Summary & questions

- Accessibility= (interesting) extension & unitary
- Necessary conditions for linear extension
- No entanglement is required
- May not occur
- Good gates=> linear & CP
- Variety of systems...

Sufficient conditions
Non-linear & non-Markovian
Channels