

Estimation of

(iii) the marginal mean of response curve in the presence of dependent censoring by time varying factors

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*Obs Data : (Y, X, R)*

*Y = binary response*

*X = high dim vect of cont baseline confounders*

*R = binary treatment indicator*

Parameter of Interest:

*Average Treatment Effect =  $E[Y(1)] - E[Y(0)]$*

,

Identifiable Under Assumption of No Unmeasured Confounders

$(Y(1), Y(0)) \text{ ind } R|X$

$p[R = 1|X, Y(1)]$

as Functional

$\psi_1 - \psi_0$

of Observed data Distribution

*One Occassion*

$$O = (RY, X, R)$$

$$L = (Y, X, R)$$

$Y =$  binary response

$X =$  high dim vector of always observed cov

$R =$  binary missingness indicator

$$\psi = E[Y]$$

$$pr[R = 1|Y(1), X] = pr[R = 1|X], \text{ MAR}$$

$$\psi = E[b(X)] = E\left[\frac{R}{\omega(X)}Y\right]$$

$$b(X) = E[Y|X, R = 1]$$

$$\omega(X) = pr[R = 1|X] = E[R|X]$$

In desired missingness,  $\omega(X)$  known by design so HT estimator of  $\psi$

$$n^{-1} \sum_i \frac{I(R_i = 1)}{\omega_r(X_i)} Y_i$$

is unbiased (not efficient), AN,  $n^{1/2}$  – consistent.

Allows for asymptotically  $1-\alpha$  Wald confidence for the ATE  $\psi$

In observational studies  $\omega(X)$  is unknown.

# How do we proceed?

Longitudinal Studies:

Dependent Right Censoring -Monotone Missingness:

*Temporalex Obs Data :  $(X_0, R_0, R_0X_1, R_1, R_0R_1Y)$*

$Y = \text{binary response}$

$$\psi = E[Y]$$

CAR

$$E[R_0 = 1|X_0, (Y, X_1)] = E[R_0 = 1|X_0]$$

$$E[R_1|X_0, X_1, R_0 = 1, Y] = E[R_1|X_0, X_1, R_0 = 1]$$

$$b_1(X_0, X_1) = E[Y|X_0, X_1]$$

$$= E[Y|X_0, X_1, R_1 = 1, R_0 = 1]$$

$$b_0(X_0) = E[Y|X_0] =$$

$$E[b_1(X_0, X_1)|X_0, R_0 = 1]$$

$$\omega_1(X_0, X_1) = E[R_1|X_0, X_1, R_0 = 1]$$

$$\omega_0(X_0) = E[R_0|X_0]$$

$$\begin{aligned}
& \psi \\
&= \int b_1(X_0, X_1) f(X_1 | R_0 = 1, X_0) f(X_0) dX_0 dX_1 \\
&= E \left[ \frac{R_1 R_0}{\omega_1(X_0, X_1) \omega_0(X_0)} Y \right] \\
&= E[b_0(X_0)]
\end{aligned}$$

Sequential known design  $\omega_1(X_0, X_1), \omega_0(X_0)$  known

-

$$n^{-1} \sum_i \left[ \frac{R_{1i} R_{0i}}{\omega_1(X_{0i}, X_{1i}) \omega_0(X_{0i})} Y_i \right]$$

is unbiased AN,  $n^{1/2}$  – consistent

**Back to Point Exposure Study:** All models in book  
with van der laan on complex longitudinal data

Our goal is to construct confidence intervals for the non-parametric model subject only to smoothness restrictions.



**Specifically we will use the following smoothness restrictions.**

**Def:** Define  $h(X)$  to be Holder  $\beta$  with radius  $c$  if

(i) all partial derivatives up to order  $\text{int}[\beta]$  exist and

(ii) all  $\text{int}[\beta]$  partial derivatives  $m(X)$  satisfy

$$|m(x) - m(z)| < c ||x - z||^{\beta - \text{int}[\beta]}$$

for some known constant  $c$ .

Our goal is to construct asymptotic  $1-\alpha$  confidence intervals (length shrinking to 0 fastest rate ) given model that  $b(X), \omega(X), f(X)$  lie in the Holder balls

$$(\beta_b, c_b), (\beta_\omega, c_\omega), (\beta_f, c_f)$$

.

Not possible if no bounds on smoothness given. Robins and Ritov (1997) no uniform consistent estimates of  $\psi$

without restrictions on either  $(\beta_b, c_b)$  or  $(\beta_\omega, c_\omega)$ .

Uniform consistency required for CI

In practice sensitivity analysis as adaption not possible for CI.

Training on Prior Smoothness . Criteria Other than Derivatives

**Approx:** If a  $h(X)$  is a Holder  $\beta^*$ , optimal approximation bias based on  $k$  terms is

$$E \left[ \left\{ h(X) - \bar{h}_k(X) \right\}^2 \right] = O \left( k^{-2\beta^*/d} \right)$$

if

$$\bar{Z}_k = \bar{z}_k(X) = (z_1(X) \dots z_k(X))$$

is polynomial, spline or compact wavelet basis with appropriate no. of vanishing moments. .

$$\bar{h}_k(X) = \eta_{PLS}^T \bar{z}_k(X)$$

**Est:** If  $h(X)$  is a regression function or density, the optimal rate of estimation i.e.  $|\hat{h}(X) - h(X)|$  is  $n^{\frac{-\beta^*}{2\beta^*+d}}$  in  $L_p$  norms

Because Holder  $\beta^*$  functions are dense in  $L_2$ , we have nonparametric model.

We will use the theory of higher order influence functions to construct our intervals.

Obtain adaptive estimate  $\hat{\theta} = (\hat{b}, \hat{\omega}, \hat{f})$ ,

Consider plug in

$$\psi(\hat{\theta}) = \int \hat{f}(x) \hat{b}(x) dx.$$

Bias can be first order.

Usual Solution Use:  $\hat{\psi}_1 = \psi(\hat{\theta}) + IF_1(\hat{\theta})$

$$IF_1(\hat{\theta}) = n^{-1} \sum_i \frac{R_i}{\hat{\omega}(X_i)} (Y_1 - \hat{b}(X_i)) + \hat{b}(X_i) - \psi(\hat{\theta})$$

$$\hat{\psi}_1 = n^{-1} \sum_i \frac{R_i}{\hat{\omega}(X_i)} (Y_1 - \hat{b}(X_i)) + \hat{b}(X_i)$$

$$\begin{aligned} E[\hat{\psi}_1 - \psi(\theta) | \hat{\theta}] \\ = E\left[\left\{b(X_i) - \hat{b}(X_i)\right\} \left\{\omega(X_i) - \hat{\omega}(X_i)\right\} / \hat{\omega}(X_i)\right] \end{aligned}$$

Doubly robust.

But Confidence intervals  $\hat{\psi}_1$

$$\hat{\psi}_1 \pm \text{var} \left[ IF_1 \left( \hat{\theta} \right) \right]^{1/2} z_\alpha$$
$$\text{Width} = O \left( n^{-1/2} \right)$$

fail unless

$$\left\{ b \left( X_i \right) - \hat{b} \left( X_i \right) \right\} \left\{ \omega \left( X_i \right) - \hat{\omega} \left( X_i \right) \right\} \leq O_p \left( n^{-1/2} \right)$$

$$\begin{aligned} \left\{b\left(X_i\right)-\widehat{b}\left(X_i\right)\right\}\left\{\omega\left(X_i\right)-\widehat{\omega}\left(X_i\right)\right\} &\leq O_p\left(n^{-1 / 2}\right) \\ &\Leftrightarrow \\ n^{\frac{-\beta_{\omega}^*}{2 \beta_{\omega}^*+d}} n^{\frac{-\beta_b^*}{2 \beta_b^*+d}} &\leq n^{-1 / 2} \end{aligned}$$

This requires

$$\begin{aligned} \beta_b^* = \beta_{\omega}^* \geq .5 d, \text { then } \\ n^{\frac{-\beta^*}{2 \beta^*+d}} = n^{\frac{-.5 d}{2(.5) d+d}} = n^{-1 / 4} \end{aligned}$$

.

If this fails what then????

Use  $\hat{\psi}_m = \psi(\hat{\theta}) + IF_m(\hat{\theta})$  where  $IF_m(\hat{\theta})$  higher order IF and we sample split

$$\hat{\psi}_m \pm \text{var} [IF_m(\hat{\theta})]^{1/2} z_\alpha$$

$$\begin{aligned} IF_2(\hat{\theta}) &= IF_1(\hat{\theta}) + IF_{2,2}(\hat{\theta}) \\ IF_{2,2}(\hat{\theta}) &= [n(n-1)]^{-1} \sum_{i \neq j} h_2(O_i, O_j; \hat{\theta}) \\ h_2(O_i, O_j; \hat{\theta}) &= \frac{R_i}{\hat{\omega}(X_i)} (Y_i - \hat{b}(X_i)) \bar{Z}_{ki}^T \bar{Z}_{kj} \times \\ &\quad \left( \frac{R_j}{\hat{\omega}(X_j)} - 1 \right) \end{aligned}$$



Must choose  $k = k_2(n)$  such that

$$\begin{aligned}
& \text{var} \left\{ IF_2 \left( \widehat{\theta} \right) \right\} \\
&= O \left( \max \left\{ \frac{1}{n} \frac{k}{n}, \frac{1}{n} \right\} \right) \\
&= \\
& E \left[ IF_{2,2} \left( \widehat{\theta} \right) - \psi \right]^2 \\
&= \max \left\{ \left[ n^{-\frac{-2\beta_f^*}{2\beta_f^*+d}} + n^{\frac{-2\beta_\omega^*}{2\beta_\omega^*+d}} \right] n^{\frac{-2\beta_\omega^*}{2\beta_\omega^*+d}} n^{\frac{-2\beta_b^*}{2\beta_b^*+d}}, k^{-2(\beta_b^*+\beta_\omega^*)/d} \right\} \\
&= \max \{ EB^2, TB^2 \} \\
& EB . \\
&= E \left[ \left\{ b(X_i) - \widehat{b}(X_i) \right\}^2 \left\{ \omega(X_i) - \widehat{\omega}(X_i) \right\}^4 / \widehat{\omega}(X_i)^4 \right] \\
&+ E \left[ \left[ \frac{\left\{ f(X_i) - \widehat{f}(X_i) \right\}}{\widehat{f}(X_i)} \right]^2 \left\{ b(X_i) - \widehat{b}(X_i) \right\}^2 \left\{ \frac{\omega(X_i) - \widehat{\omega}(X_i)}{\widehat{\omega}(X_i)} \right\}^4 \right]
\end{aligned}$$

*If  $\beta_b^*/d = \beta_\omega^*/d < 1/4 \Rightarrow k > n$*

*CI does not shrink at  $n^{-1/2}$*

*Price of valid intervals*

*If  $1/2 > \beta_b^*/d = \beta_\omega^*/d > 1/4 \Rightarrow k < n$  if  $\beta_f^*$  is large*

*CI does shrink at  $n^{-1/2}$  for some  $m, m = 2$  if  $\beta_f^*/d > .$*

*Need higher order IF to get first order efficiency*

$$\begin{aligned}
IF_3\left(\widehat{\theta}\right) &= IF_2\left(\widehat{\theta}\right) + IF_{3,3}\left(\widehat{\theta}\right) \\
IF_{3,3}\left(\widehat{\theta}\right) &= [n\left(n-1\right)\left(n-2\right)]^{-1} \sum_{i \neq j \neq s} h_3\left(O_i, O_j, O_s; \widehat{\theta}\right) \\
&h_3\left(O_i, O_j, O_s; \widehat{\theta}\right) \\
&= \frac{R_i}{\widehat{\omega}\left(X_i\right)}\left(Y_i-\widehat{b}\left(X_i\right)\right) \times \\
&\overline{Z}_{k i}^T\left\{\overline{Z}_{k s} \overline{Z}_{k s}^T-I\right\} \overline{Z}_{k j} \times \\
&\left(\frac{R_j}{\widehat{\omega}\left(X_j\right)}-1\right)
\end{aligned}$$

Must choose  $k = k_3(n)$  such that

$$\begin{aligned}
 & \text{var} \left\{ IF_3 \left( \hat{\theta} \right) \right\} \\
 &= O \left( \frac{1}{n} \frac{k}{n} \frac{k}{n} \right) \\
 &= \\
 & E \left[ IF_{3,3} \left( \hat{\theta} \right) - \psi \right]^2 \\
 &= \max \left\{ \left[ n^{-\frac{-4\beta_f^*}{4\beta_f^*+d}} + n^{\frac{-4\beta_\omega^*}{4\beta_\omega^*+d}} \right] n^{\frac{-2\beta_\omega^*}{2\beta_\omega^*+d}} n^{\frac{-2\beta_b^*}{2\beta_b^*+d}}, k^{-2(\beta_b^*+\beta_\omega^*)/d} \right\}
 \end{aligned}$$

$EB$  .

$$\begin{aligned}
 &= E \left[ \left\{ b(X_i) - \hat{b}(X_i) \right\} \left\{ \omega(X_i) - \hat{\omega}(X_i) \right\}^3 / \hat{\omega}(X_i)^3 \right] \\
 &+ E \left[ \left[ \frac{\left\{ f(X_i) - \hat{f}(X_i) \right\}}{\hat{f}(X_i)} \right]^2 \left\{ b(X_i) - \hat{b}(X_i) \right\} \left\{ \frac{\omega(X_i) - \hat{\omega}(X_i)}{\hat{\omega}(X_i)} \right\} \right]
 \end{aligned}$$

The advantage of  $IF_3 \left( \hat{\theta} \right)$  is that if  $IF_2 \left( \hat{\theta} \right)$  has estimation bias dominate truncation bias

then  $IF_3 \left( \hat{\theta} \right)$  with smaller  $EB$

can improve rate of convergence.

Mapping from smoothness assumptions to optimal CI?

What smoothness or other size controlling assumptions.

Given a sufficiently smooth  $p -$  dimensional parametric submodel  $\tilde{\theta}(\varsigma)$  mapping  $\varsigma \in R^p$  injectively into  $\Theta$ , define

$$\psi_{\setminus i_1 \dots i_m}(\theta) = \left( \psi \circ \tilde{\theta} \right)_{\setminus i_1 \dots i_m}(\varsigma) \big|_{\varsigma = \tilde{\theta}^{-1}(\theta)}$$

and

$$f_{\setminus i_1 \dots i_m}(\mathbf{O}; \theta) = \left( f \circ \tilde{\theta} \right)_{\setminus i_1 \dots i_m}(\varsigma) \big|_{\varsigma = \tilde{\theta}^{-1}(\theta)}$$

where each  $i_s \in \{1, \dots, p\}$

$$f(\mathbf{O}; \theta) \triangleq \prod_{i=1}^n f(O_i; \theta)$$

## Canonical (Hoeffding) Representation of Order 1 and 2 Mean 0 U-stat-

$$U_1(\theta) = \sum_{i \neq j} u_1(O_i), E[u_1(O_i)] = 0 :$$

$u(\cdot, \cdot)$  not necc sym

$$U_2(\theta) = \sum_{i \neq j} u(O_i, O_j), E[u(O_i, O_j)] = 0 :$$

$u(\cdot, \cdot)$  not necc sym

$$U_2(\theta) = \sum_i d(O_i, \theta) + \sum_{i \neq j} m(O_i, O_j),$$

$$E_\theta[d(O_i, \theta)] = 0,$$

$$E[m(O_i, O_j) | O_i] = E[m(O_i, O_j) | O_j] = 0,$$

$m(\cdot, \cdot)$  not necc sym

$\sum_i d(O_i, \theta)$  and  $\sum_{i \neq j} m(O_i, O_j)$  uncorr



## Canonical Representation of Order 3 Mean 0 U-stat-

$$U_3(\theta) = U_2(\theta) + \sum_{i \neq j \neq X} t(O_i, O_j, O_X)$$

$$\begin{aligned} E[t(O_i, O_j, O_X) | O_i, O_j] &= E[t(O_i, O_j, O_X) | O_i, O_X] \\ &= E[t(O_i, O_j, O_X) | O_j, O_X] = 0, \end{aligned}$$

*t(·, ·, ·) not necc sym*

$$\sum_{i \neq j \neq X} m(O_i, O_j, O_X) \text{ and } U_2(\theta) \text{ uncorr}$$

Formula for higher order scores associated with  $\tilde{\theta}(\varsigma)$

$$S_{i_1 \dots i_m}(\theta) = f_{/i_1 \dots i_m}(\mathbf{O}; \theta) / f(\mathbf{O}; \theta)$$

$$f(\mathbf{O}; \theta) = \prod_{i=1}^n f(O_i; \theta)$$

of order  $m$  in terms of the subject specific scores (Waterman and Lindsay (1996)

$$S_{i_1 \dots i_m, j}(\theta) = f_{/i_1 \dots i_m, j}(O_j; \theta) / f_j(O_j; \theta), j = 1, \dots, n$$

(Waterman and Lindsay (1996) .

$$S_{i_1} = \sum_j S_{i_1, j}$$

$$S_{i_1 i_2} = \sum_j S_{i_1 i_2, j} + \sum_{X \neq j} S_{i_1, j} S_{i_2, X}$$

$$S_{i_1 i_2, j}(\theta) = S_{i_1, j}(\theta) S_{i_2, j}(\theta) + \partial S_{i_1, j}(\theta(\varsigma)) / \partial \varsigma_{i_2} |_{\tilde{\theta}(\varsigma) = \theta}$$

$$\begin{aligned}
& S_{i_1 i_2 i_3} \\
&= \sum_j S_{i_1 i_2 i_3, j} + \sum_{X \neq j} S_{i_1 i_2, j} S_{i_3, X} + S_{i_3 i_2, j} S_{i_1, X} + S_{i_1 i_3, j} S_{i_2, X} \\
&\quad \sum_{X \neq j \neq t} S_{i_1, j} S_{i_2, X} S_{i_3, t}
\end{aligned}$$

**Definition of a kth order influence function:** A U-statistic  $U_k(\theta) = u_k(\mathbf{O}; \theta)$  of order  $k$ , dimension  $p$  and finite variance is said to be an  $k$ th order influence function for  $\psi(\theta)$  if (i)

$$E_{\theta}[U_k(\theta)] = 0, \theta \in \Theta$$

(ii) for  $m = 1, 2, \dots, k$ , and every  $\tilde{\theta}(\varsigma)$ ,  $p = 1, 2, \dots$

$$\psi_{\setminus i_1 \dots i_m}(\theta) = E_{\theta}[U_k(\theta) S_{i_1 \dots i_m}(\theta)]$$

$p = k$  sufficient. We say that  $\psi(\theta)$  is  $k$ th order pathwise differentiable

**Theorem:** If the model is nonparametric .then there is at most one mth order estimation influence function  $IF_m^{est}(\theta)$ , the efficient mth order IF.

Lemma:  $IF_m^{est}(\theta) = IF_{m-1}^{est}(\theta) + IF_{mm}^{est}(\theta)$ ,

$IF_{mm}^{est}(\theta) = \sum_{\{i_1 \neq i_2 \neq \dots \neq i_m; i_X \in \{1, 2, \dots, n\}, X \in \{1, \dots, m\}\}} d_m(O_{i_1}, \dots, O_{i_m})$ ,  
where  $d_m(O_{i_1}, O_{i_2}, \dots, O_{i_m})$  is canonical

$\text{Var}[IF_m^{est}(\theta)]$  increases with  $m$

$\text{Var}[IF_m^{est}(\theta)] / \text{Var}[IF_m^{est}(\hat{\theta})] = 1 + o(1)$

The following Extended Information Theorem is closely related to result in McLeish and Small (1994).

**Theorem:** Given  $U_k(\theta)$ , for all  $\tilde{\theta}(\varsigma)$  for  $s \leq k$

$$\begin{aligned} & \partial^s E_{\theta} [U_k(\theta(\varsigma))] / \partial \varsigma_{i_1} \dots \partial \varsigma_{i_s} \\ &= -E_{\theta} [U_k(\theta) S_{i_1 \dots i_s}(\theta)] \\ &= -\psi_{\setminus i_1 \dots i_s}(\theta) \end{aligned}$$

$$E_{\theta} [U_k(\hat{\theta})] = -[\psi(\hat{\theta}) - \psi(\theta)] + O_p(\|\hat{\theta} - \theta\|^{k+1})$$

since as functions of  $\hat{\theta}$ , the functions  $E_{\theta} [U_k(\hat{\theta})]$  and  $-\left[\psi(\hat{\theta}) - \psi(\theta)\right]$  have the same Taylor expansion around  $\theta$  up to order  $k$

$$\hat{\psi}_m = \psi(\hat{\theta}) + IF_m(\hat{\theta})$$

where  $\hat{\theta}$  is an initial estimator of  $\theta$ . from a separate sample  
(no Donsker like needed).

But, by extended info equality

$$E_{\theta} [IF_m(\hat{\theta})] = -[\psi(\hat{\theta}) - \psi(\theta)] + O_p(\|\hat{\theta} - \theta\|^{m+1})$$

so (conditional ) bias of  $\hat{\psi}_m$  is

$$\{\psi(\hat{\theta}) + E_{\theta} [IF_m(\hat{\theta})] - \psi(\theta)\} = O_p(\|\hat{\theta} - \theta\|^{m+1}), \downarrow m$$

$\text{Var}[\hat{\psi}_m]$  increases with  $m$

$IF_m(\hat{\theta})$  and  $\hat{\psi}_m = \psi(\hat{\theta}) + IF_m(\hat{\theta})$  are AN given  $\hat{\theta}$  often normal.

Shortest conservative uniform asymptotic confidence intervals based on

$$\hat{\psi}_{m_{conf}} \pm \text{var} \left[ IF_{m_{conf}}(\hat{\theta}) | \hat{\theta} \right]^{1/2} z_\alpha$$

where  $k_{conf}$  is the smallest  $k$  with  $\text{var} [U_k(\theta)]$  higher order (or equal if constants dealt with) than the squared bias.



Example: Problem: If  $IF_1(\theta)$  depends on  $\theta$  through a nonparametric  $\rho(\theta)$  where  $\rho(\theta)$  infinite dimensional

$IF_m(\theta)$  does not exist for  $m \geq 2$

Example:

$$IF_1(\hat{\theta}) = n^{-1} \sum_i \frac{R_i}{\hat{\omega}(X_i)} (Y_1 - \hat{b}(X_i)) + \hat{b}(X_i) - \psi(\hat{\theta})$$

Use sieves ie  $k = k(n)$  dimensional submodels for  $b(X)$ ,  $\omega(X_i)$ . Then  $IF_m$  exists for all  $m$ .

But then truncation bias

$$TB_k = E \left[ \left\{ b(X_i) - \bar{b}_k(X_i) \right\} \left\{ \omega(X_i) - \bar{\omega}_k(X_i) \right\} / \bar{\omega}_k(X_i) \right]$$

added to estimation bias  $\left\| \hat{\theta} - \theta \right\|^{m+1}$

where  $\bar{b}_k(X_i)$  is the limit of the model

Specifically  $b(X) = b^* \left( Z_k^T B_k \right), \omega(X) = \omega^* \left( Z_k^T \alpha_k \right)$

where  $Z_k$  a basis in  $R^d$  as  $k \rightarrow \infty$