

I. variant tone for
Hamiltonian PDE

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Hamiltonian PDE

$$(1) \quad \partial_t v = J \Delta_u H(v)$$

$$v(x, 0) = v_0(x)$$

phase space $\mathcal{H}$ is a Hilbert space

symplectic form $\omega(X, Y) = \langle X, J^* Y \rangle_{\mathcal{H}}$

$$J^T = -J$$

- flow of the dynamical system

$$v(x, t) = \varphi_t(v_0(x)),$$

tracing a curve in $\mathcal{H}$ through v_0

Contents:

- Hamiltonian PDE - examples
- Invariant tori - a variational problem
- Results
- Estimates of the linearized problem

1) Principal examples

(1) nonlinear wave equations

$$(2) \quad \partial_t^2 u - \Delta u = g(x, u) \quad 0$$

$t \in \mathbb{R}^d \quad \mathbb{R}^d / \Gamma \quad \text{periodic boundary}$
 else
 $x \in \Omega \subseteq \mathbb{R}^d \quad \partial\Omega \ni \quad t \in \mathbb{R} \quad 0 \quad \text{Dirichlet}$

The Hamiltonian functional

$$H(u, p) = \int_{\mathbb{R}^d} \left(\frac{1}{2} p^2 + \frac{1}{2} |\nabla u|^2 + G(x, u) \right) dx$$

then

$$\partial_t u = p \quad \partial_p H$$

$$\partial_t p = -\Delta u - \partial_u G(x, u) \quad \partial_u H$$

$$g(x, u) = \partial_u G(x, u)$$

The system has the form

$$\partial_t \begin{pmatrix} u \\ p \end{pmatrix} = J \delta H$$

th

$$\begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix} \quad \text{Darboux coordinates}$$

Assume that

$$G(x, u) = \frac{1}{2} g_1(x) u^2 + \frac{1}{3} g_2(x) u^3 + \dots$$

Then $H = H^{(2)} + H^{(3)} + \dots$ Taylor expansion
about $v = \begin{pmatrix} u \\ p \end{pmatrix} = 0$

- The quadratic Hamiltonian is

$$\begin{aligned} H^{(2)} &= \int_{\mathbb{R}^d} \frac{1}{2} p^2 + \frac{1}{2} |\nabla u|^2 + \frac{1}{2} g_1(x) u^2 dx \\ &= \sum_n \frac{1}{2} |p_n|^2 + \frac{\omega_n^2}{2} |u_n|^2, \end{aligned}$$

expansion in terms of eigenfunctions

$$\begin{pmatrix} u(x) \\ p(x) \end{pmatrix} = \sum_n \begin{pmatrix} u_n \\ p_n \end{pmatrix} \phi_n(x)$$

satisfying

$$L(g_1) \phi_n = (-\Delta + g_1(x)) \phi_n = \omega_n^2 \phi_n$$

$(\phi_n(x), \omega_n^2)$ eigenfunction, eigenvalue pair

- This is a harmonic oscillator, with frequencies ω_n

Solutions of the linearized equations

$$(3) \quad \partial_t \begin{pmatrix} u \\ p \end{pmatrix} = J \delta H^{(2)} \begin{pmatrix} u \\ p \end{pmatrix}$$

are of the form

$$\begin{pmatrix} u(x,t) \\ p(x,t) \end{pmatrix} = \sum_n \psi_n \begin{pmatrix} \cos(\omega_n t + \xi_n) & \frac{1}{\omega_n} \sin(\omega_n t + \xi_n) \\ -\omega_n \sin(\omega_n t + \xi_n) & \cos(\omega_n t + \xi_n) \end{pmatrix} //$$

$$= \Phi_t \begin{pmatrix} u^0 \\ p^0 \end{pmatrix} \quad \text{the linear flow.}$$

• Facts:

• The Hamiltonian is preserved along the flow

$$H^{(2)}(\Phi_t(v)) = H^{(2)}(v)$$

• Actions are preserved along the flow

$$I_n = \frac{1}{2} (\omega_n |u_n|^2 + \frac{1}{\omega_n} |p_n|^2)$$

such that

$$I_n(\Phi_t(v)) = I_n(v)$$

• Angles evolve linearly in time: $\xi_n \mapsto \omega_n t + \xi_n$

• All solutions are

+ periodic

all action $\omega_n = j_n \omega_0$ $j_n \in \mathbb{Z}$

+ quasi-periodic

or $\omega_n = \langle j_n, \vec{\omega}_0 \rangle$ $j_n \in \mathbb{Z}$

+ almost-periodic,

no finite # suffice

- Basic questions :

- + (1) Whether some solutions of the nonlinear problem have the same properties:

- + periodic
- + quasi-periodic
- + almost-periodic

(KAM theory)

- + (2) Whether all solutions with $\psi_0 \in B_{2n}(\omega) \subseteq \mathcal{X}$ remain in $B_{2n}(\omega)$

(well-posedness)

Whether action variables are preserved for long time intervals

$$|I_k(\psi(t)) - I_k(\psi_0)| < \varepsilon^2$$

for $|t| < T(\varepsilon) \sim \exp(1/\varepsilon^p)$

(Nekhoroshev stability)

- + (3) Upper and lower bounds on growth of the action variables, or on higher Sobolev norms

(Arnold diffusion)

II) nonlinear Schrödinger equation

$$\partial_t u = i \Delta u + Q(u) \quad (1)$$

$x \in \mathbb{R}^d / \Gamma \quad \mathbb{T}^d$ periodic boundary conditions
 else Dirichlet boundary conditions
 $x \in \Omega \subset \mathbb{R}^d \quad 0$ for $\partial\Omega$

Initial data

u_0 $\partial\Omega$
 flow of the dynamical system
 $t \mapsto \varphi_t u_0$

The Hamiltonian is

$$H(u) = \int_{\mathbb{R}^d} \frac{1}{2} |\nabla u|^2 + G(u) \, dx$$

where

$G(u) = \int_{\mathbb{R}^d} Q(u) \, dx$ real valued when u is real

$$\partial_x \partial_{\bar{x}} G = Q$$

Then (1) can be expressed as

$$\partial_t u = J \nabla_x H(u)$$

here $J = \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}$ plus symplectic coordinates

(III) Korteweg de Vries equation

$$(5) \quad \partial_t q = \frac{1}{6} \partial_x^3 q - \partial_x (\partial_x^2 G(x, q))$$

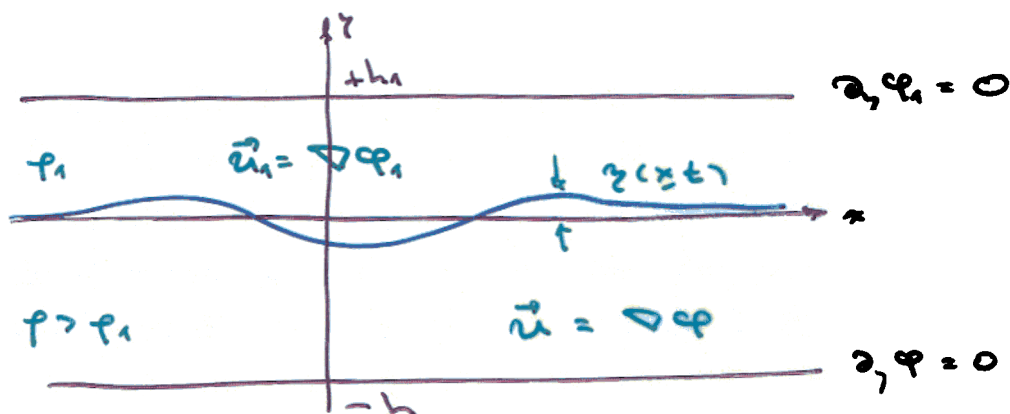
$$x \in \mathbb{R}' / \Gamma = \mathbb{T}'$$

The Hamiltonian

$$H = \int_{\mathbb{T}'} \frac{1}{12} (\partial_x q)^2 + G(x, q) dx$$

symplectic form given by $J = -\partial_x$

(IV) Large amplitude long waves in an interface



Equations for the interface

$$(6) \quad \partial_t \begin{pmatrix} \eta \\ u \end{pmatrix} = \begin{pmatrix} 0 & -\partial_x \\ -\partial_x & 0 \end{pmatrix} \begin{pmatrix} \delta_\eta H \\ \delta_u H \end{pmatrix}$$

symplectic form

$$\omega(X, Y) = \int (\partial_x^{-1} X_\eta) Y_u + (\partial_x^{-1} X_u) Y_\eta dx$$

same as for the Boussinesq equation

Hamiltonian

$$H = \frac{1}{2} R_0(z) u^2 + \frac{1}{2} R_1(z) u^2 + \frac{1}{4} R_2(z) u^4 + \frac{1}{6} R_3(z) u^6$$

with rational coefficients

$$R_0(z) = \frac{(h+z)(h-z)}{r_1(h+z) + r_2(h-z)} \quad \text{nonlinear propagation velocity}$$

$$R_1(z) = \frac{(h+z)^2(h-z)^2}{[r_1(h+z) + r_2(h-z)]^2}$$

$$R_2(z) = \frac{\frac{1}{3} r_1 r_2 (h+z)(h-z) [(h-z)^3 - (h+z)^3]}{[r_1(h+z) + r_2(h-z)]^3}$$

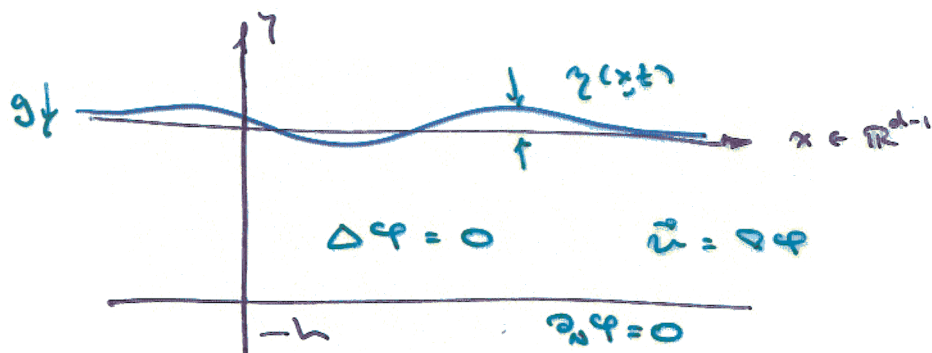
$$R_3(z) = \frac{\frac{1}{3} r_1 r_2 (h+z)^3 [r_1(h+z)^3 + r_2(h-z)^3]}{[r_1(h+z) + r_2(h-z)]^4}$$

linear dispersion coefficients

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(V) surface water waves



$$\xi(x) = \varphi(x, \eta(x))$$

Euler's equations are equivalent to

$$(7) \quad \partial_t \begin{pmatrix} \eta \\ \xi \end{pmatrix} = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix} \delta H$$

where the Hamiltonian is given by

$$H(\eta, \xi) = \frac{1}{2} \int G(\eta) \xi + \frac{\rho}{2} \int \eta^2 dx$$

The Dirichlet-Neumann operator $G(\eta)$ satisfies

$$\begin{aligned} \xi(x) &\mapsto \varphi(x, \eta) \text{ harmonic extension} \\ &\mapsto N \cdot \nabla \varphi|_{\partial \Omega(\eta)} \text{ normal derivative} \\ &:= \underline{G(\eta) \xi} \, dx \end{aligned}$$

2) An unit torus

Take $S \in T$ and ∂_t time

$S \in \mathbb{R}^n$ and ∂_t flow invariant

The freq $\gamma \in \mathbb{R}$

This implies that

$$\partial_t S = J \delta H(S) \quad \text{and} \quad \partial_t S = \Omega \partial_3 S$$

Problem we have this equation for $(S \in \mathbb{R})$

where Ω a bifurcation parameter

This is generally a well-posed problem

Remark γ as

$$J \Omega \partial_3 S = \delta H(S) = 0$$

* A variational problem

Consider the space of mappings

$$S \times = \{ S : \mathbb{T}^m \rightarrow \mathbb{R}^n \}$$

Define functionals

$$I(S) = \int_{\mathbb{T}^m} \langle S, J^{-1} \partial_{\bar{z}_j} S \rangle d\bar{z}$$

$$\delta_{\bar{z}} I = J \partial_{\bar{z}_j} S$$

and the average Hamiltonian

$$H(S) = \int_{\mathbb{T}^m} H(S(z)) d\bar{z}$$

$$\delta_{\bar{z}} H = \partial_{\bar{z}_j} H$$

Consider the subvariety of X defined by

$$\Gamma = \{ S \in X \mid I = a_1, \dots, I_m = a_m \}$$

$$\subseteq$$

Variational problem: critical points of H on the variety Γ_a correspond to solutions of equation $\Delta u = \lambda u$ with Liouville multiplier Ω

NS invariance under the action of π

Two questions :

Do critical points exist?

The functional $\Omega \cdot \mathcal{Q}_2 S$ is *degenerate*

How to understand multiplicity?

Topology of $\Pi_n / \mathbb{T}^m$ and
its equivariant *cohomology*.

Answers — in some cases

(i) study the linearized problem
Fröhlich - Spencer estimates

Nash - Moser method.

(ii) Morse - Bott theory of critical points/*orbit*.

(3) The linearised problem

The linearised problem and $v = v$ given by the quadratic Hamiltonian:

$$H = \sum_n \frac{\omega_n}{2} (v_n p + q_n^2)$$

$$\sum I_n$$

where $v = \begin{pmatrix} q \\ p \end{pmatrix}$

Representing mapping $S \mapsto \pi$ of a time into phase space

$$S = S(x, y) = \sum_n S_n(x) \phi_n$$

$$\sum_{j,k} S_{jk} \phi_j(x) e^{i y}$$

$$j \in \mathbb{Z}^m$$

The linearised equation is then

$$(\delta_v^2 H_{xx} - \Omega \delta_v^2 I) S$$

$$\sum_n \begin{pmatrix} \omega_n & \Omega_j \\ x & \end{pmatrix} \begin{pmatrix} q_{jk} \\ p_{jk} \end{pmatrix} \phi_k e^{i y}$$

Eigenvalues of this 2×2 block diagonal system

$$\mu(j, k) = \omega_k - \Omega_j$$

Null space

Choose $\Omega^0 = (\Omega_1, \dots, \Omega_m) \in \mathbb{R}^m$ a frequency vector which is a solution of the m-many resonance

$$(10) \quad \omega_{k_\ell} - \Omega^0 \cdot j_\ell = 0 \quad \ell = 1, \dots, m$$

This identifies an eigenspace $X_1 \subseteq X$ within the space of mappings X_1 spanned by $\{\phi_{k_\ell} e^{ij \cdot \theta}\}$.

Proposition $X_1 \subseteq X$ is even dimensional $\geq 2m$:
(it could be infinite dimensional, but it is symplectic)

The non-resonant case is when $\dim(X_1) = 2m$.

Otherwise $\dim(X_1) > 2m$, the case is resonant.

The other eigenvalues are

$$\{\mu_{jk} = \omega_k \pm \Omega \cdot j \neq 0\}$$

which typically forms a dense set in $\mathbb{R}$, these are the small divisors.

Lyapunov-Schmidt decomposition

In the case X of mapping $S: \mathbb{R}^n \rightarrow \mathbb{R}^m$ we

decompose the equations $X = X_1 \oplus X_2$

$Q: X_1 \rightarrow X_1$ and space

$P: X_2 \rightarrow (I - Q)X_1 \rightarrow X_2$

The equations to solve are therefore

$$Q[S(\Omega) - S(H)] = 0 \quad \text{bifurcation eq.}$$

$$P[S(\Omega) - S(H)] = 0 \quad \text{null direction}$$

$\Rightarrow$ compose mapping: $S_1: S_1 \rightarrow S_1$

If S_1 can be for $S_2: S(S_1) \rightarrow S_2$ there is

a reduced v. form (see form above)

$$I(S_1) = I(S_1)$$

$$(S_1) = \bar{H}(S_1)$$

$$\in X \quad I(S_1) = \{ \}$$

critical pts of H are solutions of (1)

The linearized operator about s_0 is

$$(iii) \quad (S_{s_0}^2 H(s_0) - \Omega S_{s_0}^2 I) V$$

$$\left[\text{diag}_{\mathbb{Z}^m} \begin{pmatrix} \omega & \Omega \\ \Omega & \omega \end{pmatrix} + W(\omega, \Omega) \right] V$$

where the $\omega, \Omega \in \mathbb{Z}^m \oplus \mathbb{Z}^d$

Definition A lattice site $(j, k) \in \mathbb{Z}^m \oplus \mathbb{Z}^d$

is d_0 -singular for Ω here

$$d_0 \geq \omega_k \pm \Omega$$

is regular otherwise

Proposition For $A \in \mathbb{Z}^m \oplus \mathbb{Z}^d$ having $\frac{1}{2}$ regular sites and for $\omega_{op} < \frac{d}{2}$ then

$$(S_{s_0}^2 H(s_0) - \Omega S_{s_0}^2 I)_{A, op} < \frac{4}{d}$$

Fröhlich-Spencer estimates are used to add the regular sites

Fröhlich - Spencer estimates:

Depend upon two **properties** of the operator

$$(\mathcal{S}_v^2 H(s_0) - \Omega \cdot \mathcal{S}_v^2 I) = \mathcal{D}(\Omega) + W$$

(i) nonresonance : if $(j, k) = \gamma \in \mathbb{Z}^m \otimes \mathbb{Z}^d$
 then $(j', k') = \gamma'$

$$d_n < |\omega_k \pm \Omega \cdot j| < d_0$$

(12) $|\omega_k \pm \Omega \cdot j|$ singular sites

$$R_n < |\gamma|, |\gamma'|$$

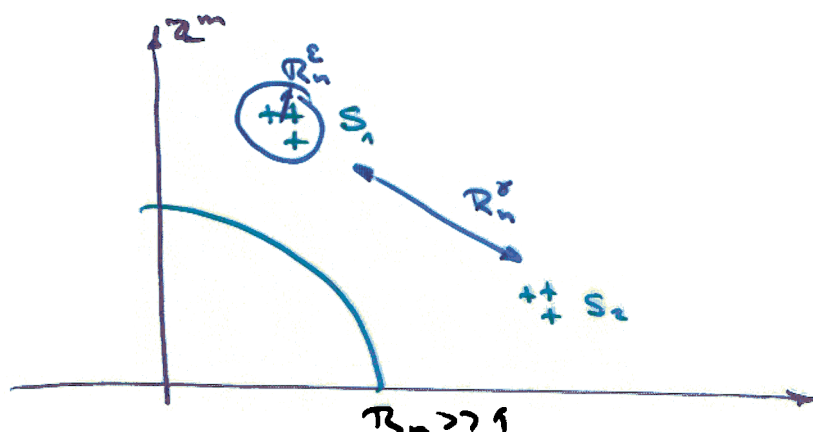
(ii) separation if γ, γ' are singular sites

with $R_n < |\gamma|, |\gamma'|$, then either

$$\text{dist}(\gamma, \gamma') < R_n^z \quad 0 < z < 1$$

or else

$$\text{dist}(\gamma, \gamma') \gg R_n^x \quad 0 < x$$



S_1, S_2 singular regions

(4) Results

nonlinear wave equation

S. Kakei (1997) E. Woy (1999) Dunkel
 W. C. & E. Woy (1993) P. Woy & S.
 J. B. Woy (1999) d >

separation imposed by dispersive conditions

nonlinear Schrödinger equation

K. Kakei (1997)
 W. C. & E. Woy (1994)
 K. Kakei & J. Pöschel (1999)
 J. B. Woy (1996) d >

separation imposed by the dispersion relation

perturbations of KdV

K. Kakei (1997)
 T. Kappeler & Pöschel (2000)

Birkhoff lemma for the linear Schrödinger equation

W. C. & J. D. Kakei & E. Woy (2001)

(v) Solitary water waves

Plotnikov & Toland (1997) (2001)

I. Plotnikov & Toland (1997) (2001) AS)