# A Calculus For Design Of Two-Stage Adaptive Procedures 

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Group Sequential Procedures

## Two-Stage Adaptive Procedures

- The design of Stage II depends on unblinded Stage I data.


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## Two-Stage Adaptive Procedures

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- Stage II sample size and critical value are functions of Stage I data.
- Other modifications are possible.
- All the actions to be taken at the end of Stage I are determined prior to Stage I.


## Prespecification of the Stage II

Without prespecification of the actions

- The sample size behavior is unknown.


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## Prespecification of the Stage II

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- The sample size behavior is unknown.
- The unconditional power cannot be specified.
- The Type I error cannot be rigorously defined.
- Liu, Proschan and Pledger (2002)


## Motivating Example

Lan and Trost's procedure

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Lan and Trost's procedure
Lan and Trost (1996) give a procedure in which the results from Stage I are used to determine the sample size for Stage II.

## Example - Background

Consider testing

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\begin{aligned}
& H_{0}: \mu_{t}-\mu_{c} \leq 0 \\
& H_{1}: \mu_{t}-\mu_{c}>0
\end{aligned}
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$\alpha=.025$ and $\rho \equiv 1-\beta=.85$ at $\mu_{t}-\mu_{c}=1$

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Assume that $\sigma=4$
$\alpha=.025$ and $\rho \equiv 1-\beta=.85$ at $\mu_{t}-\mu_{c}=1$
Then conventional single-stage procedure's sample size is $N=288$ from each group.

## Example - $\boldsymbol{C P}$

In Stage I, a sample of size $n_{1}=0.4 \times N=115$ from each group is taken.

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Their procedure's design is based on $\underline{C P}$

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- If $C P$ is between .05 and .65 , extend the study so that the conditional probability of rejecting $H_{0}$ at the end of Stage II under the Stage I results is $\mathbf{. 6 5}$.


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$C P$


## Example - Characteristics

Characteristics of the resulting design

$$
\text { P[Type I Error] } \left.=\text { P[Reject } \boldsymbol{H}_{0} \text { under } \boldsymbol{H}_{0}\right]=.024
$$

$$
\text { Power } \left.=\text { P[Reject } \boldsymbol{H}_{0} \text { under } \boldsymbol{H}_{1}\right]=.877
$$

## Sample size

## In the Literature

There has been much interest in the field of two-stage adaptive procedures.

- Bauer and Köhne (1994)
- Proschan and Hunsberger (1995)
- Lan and Trost (1997)
- Lehmacher and Wassmer (1999)
- Liu and Chi (2001)


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## Calculus

Hypotheses of interest:

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$\beta=$ P[Type II error] at $\Delta_{1}$.
$\rho=1-\beta$.

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$\alpha=$ P[Type I error]
$\boldsymbol{\beta}=$ P[Type II error] at $\Delta_{1}$.
$\rho=1-\beta$.
Suppose that
$X_{t} \sim \operatorname{Normal}\left(\mu_{t}, \sigma^{2}\right)$
$X_{c} \sim \operatorname{Normal}\left(\mu_{c}, \sigma^{2}\right)$

## Stage I

- Take a sample of size $n_{1}$ from the treatment and control groups.


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We use the notation, $\xi=\frac{\mu_{t}-\mu_{c}}{\sqrt{2} \sigma}$.
Flowchart

## Stage II

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Flowchart

## Summary

- Stage I
- Sample size . . . $n_{1}$
- Critical values $\cdots k_{1}$ and $k_{2}$
- Stage II
- Sample size function $\cdots n_{2}\left(y_{1}\right)$
- Critical value function $\cdots w\left(y_{1}\right)$


## Stage I Error Probabilities

- $\alpha_{1}=$ P[Reject $H_{0}$ in Stage I under $H_{0}$ ]
- $\boldsymbol{\beta}_{1}=\mathrm{P}\left[\right.$ Accept $\boldsymbol{H}_{0}$ in Stage I under $\left.\boldsymbol{H}_{1}\right]$


## Stage I Error Probabilities

- $\alpha_{1}=$ P[Reject $\boldsymbol{H}_{\mathbf{0}}$ in Stage I under $\boldsymbol{H}_{\mathbf{0}}$ ]
- $\boldsymbol{\beta}_{1}=\mathrm{P}\left[\right.$ Accept $\boldsymbol{H}_{0}$ in Stage I under $\boldsymbol{H}_{1}$ ]
- We can write $\alpha_{1}$ as a function of $n_{1}$ and $k_{2}$.
- We can write $\beta_{1}$ as a function of $n_{1}$ and $k_{1}$.


## Stage I Components

Stage I is characterized by the following 5 "specification components" :

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These specification components need to satisfy :

$$
\begin{aligned}
& \text { - } \alpha_{1}=P_{\xi_{0}}\left[Y_{1}>k_{2}\right]=1-\Phi\left[\sqrt{n_{1}}\left(k_{2}-\xi_{0}\right)\right] \\
& \text { - } \beta_{1}=P_{\xi_{1}}\left[Y_{1}<k_{1}\right]=\Phi\left[\sqrt{n_{1}}\left(k_{1}-\xi_{1}\right)\right]
\end{aligned}
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If 3 components are specified, we can obtain the other 2 using the above relationships.

## Stage I Components

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- $\beta_{1}=\Phi\left[\sqrt{n_{1}}\left(k_{1}-\xi_{1}\right)\right]$

If 3 components are specified, we can obtain the other 2 using the above relationships.

At least 1 component needs to come from $\alpha_{1}$ group and $\beta_{1}$ group.

## "Conditional Power Functions"

For Stage II, define the "conditional power functions" as :

$$
A\left(y_{1}, \xi\right)=P_{\xi}\left[\text { Reject } H_{0} \text { in Stage II } \mid Y_{1}=y_{1}\right]
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- $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \xi_{0}\right)=$ Conditional Type I error rate
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- $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}_{0}\right)=$ Conditional Type I error rate
- $A\left(y_{1}, \xi_{1}\right)=$ Conditional power at the original alternative
$\boldsymbol{\xi}$ can depend on $\boldsymbol{y}_{1}$. e.g., $\boldsymbol{\xi}\left(\boldsymbol{y}_{1}\right)=\boldsymbol{y}_{1}$
- $\boldsymbol{A}\left(y_{1}, y_{1}\right)=$ Conditional power at $y_{1}$, an estimate of $\xi$


## Stage II Components

Stage II is characterized by the following 4 "specification components" :

$$
A\left(y_{1}, \xi_{0}\right), A\left(y_{1}, \xi_{1}\right), n_{2}\left(y_{1}\right), w\left(y_{1}\right) .
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\text { - } A\left(y_{1}, \xi_{0}\right)=1-\Phi\left[\sqrt{n_{2}\left(y_{1}\right)}\left(w\left(y_{1}\right)-\xi_{0}\right)\right] \\
\text { - } A\left(y_{1}, \xi_{1}\right)=1-\Phi\left[\sqrt{n_{2}\left(y_{1}\right)}\left(w\left(y_{1}\right)-\xi_{1}\right)\right]
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\text { - } A\left(y_{1}, \xi_{1}\right)=1-\Phi\left[\sqrt{n_{2}\left(y_{1}\right)}\left(w\left(y_{1}\right)-\xi_{1}\right)\right]
\end{array}
$$

- 2 components from these 4 are sufficient to determine the other 2.


## Type I and Type II Error Rates

To control Type I error rate and to specify power, we need

$$
\begin{aligned}
& \alpha_{2} \equiv \alpha-\alpha_{1} \\
&=\int_{k_{1}}^{k_{2}} A\left(y_{1}, \xi_{0}\right) g_{\xi_{0}}\left(y_{1}\right) d y_{1} \\
& \rho_{2} \equiv \rho-\rho_{1}=\int_{k_{1}}^{k_{2}} A\left(y_{1}, \xi_{1}\right) g_{\xi_{1}}\left(y_{1}\right) d y_{1}
\end{aligned}
$$

where $g_{\xi}\left(y_{1}\right)$ is the pdf of $\operatorname{Normal}\left(\xi, 1 / n_{1}\right)$.

## Components

A two-stage adaptive procedure is characterized by the following 9 components:

- Stage I

$$
\alpha_{1}, \beta_{1}, n_{1}, k_{1}, k_{2}
$$

- Stage II

$$
A\left(y_{1}, \xi_{0}\right), A\left(y_{1}, \xi_{1}\right), n_{2}\left(y_{1}\right), w\left(y_{1}\right)
$$

Instead of $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \xi_{0}\right)$ and $\boldsymbol{A}\left(y_{1}, \xi_{1}\right)$, we can choose any $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}\right)$ at two distinct $\boldsymbol{\xi}$ 's.
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## Example

In this example, we show that

- a fairly complicated procedure can be placed under our formulation.


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In this example, we show that

- a fairly complicated procedure can be placed under our formulation.
- our framework allows manipulation of design parameters to control many aspects of the design, such as the Type I error rate, Type II error rate (power), maximum sample size and so on.


## Lan \& Trost's Procedure

$$
\begin{aligned}
& H_{0}: \mu_{t}-\mu_{c} \leq 0 \\
& H_{1}: \mu_{t}-\mu_{c}>0
\end{aligned}
$$

- $\sigma=4$
- $\alpha=.025$
- Power $=.85$ at $\mu_{t}-\mu_{c}=1 .\left(\xi_{1}=.1768\right)$

Conventional single-stage design's sample size is
$N=288$ from each group.
$\underline{A\left(y_{1}, y_{1}\right)}$

## Stage I Components

- $n_{1}=115$
- $k_{1}$ satisfies $C P\left(k_{1}\right)=.05 . \Rightarrow k_{1}=.0405$
- $\boldsymbol{k}_{2}=\infty$
- $(\kappa$ satisfies $C P(\kappa)=.65 . \Rightarrow \kappa=.1332)$


## Stage I Components

- $n_{1}=115$
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- $k_{2}=\infty$
- $(\kappa$ satisfies $C P(\kappa)=.65 . \Rightarrow \kappa=.1332)$

We can calculate the remaining 2 components, $\alpha_{1}$ and $\beta_{1}$ for Stage I.
$\left\{\alpha_{1}=0, \beta_{1}=.072, n_{1}=115, k_{1}=.0405, k_{2}=\infty\right\}$

## Stage II Components

- Stage II is divided into "extension" and "continuation" regions based on $\boldsymbol{y}_{1}$.
- Using $A\left(y_{1}, y_{1}\right)=C P\left(y_{1}\right)$ and the facts that the critical value is constant in terms of $z$-value and that $\boldsymbol{n}_{2}\left(\boldsymbol{y}_{1}\right)$ is constant in the "continuation" region, we can obtain $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}\right), \boldsymbol{n}_{2}\left(\boldsymbol{y}_{1}\right)$ and $\boldsymbol{w}\left(\boldsymbol{y}_{1}\right)$ for the entire range of $y_{1}$ in $\left(k_{1}, \infty\right)$.
$\underline{\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}\right) \text { and sample size }}$


## Problems of Lan \& Trost's Design

- Sample size $\max \left(n_{2}\left(y_{1}\right)\right)=3223$.


## Problems of Lan \& Trost's Design

- Sample size
$\max \left(n_{2}\left(y_{1}\right)\right)=3223$.
- $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \xi_{1}\right)$ is not monotone.

Under $\boldsymbol{H}_{1}$,
conditional power is virtually 1 if $y_{1}=.0403$. conditional power is about .8 if $y_{1}=.1332$.

## Type I Error and Power

Our framework permits numerical integration to find :
Type I Error Rate $=\int_{-\infty}^{\infty} A\left(y_{1}, \xi_{0}\right) g_{\xi_{0}}\left(y_{1}\right) d y_{1}=.024$

$$
\text { Power at } \xi_{1}=\int_{-\infty}^{\infty} A\left(y_{1}, \xi_{1}\right) g_{\xi_{1}}\left(y_{1}\right) d y_{1}=.877
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## Type I Error and Power

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Type I Error Rate $=\int_{-\infty}^{\infty} A\left(y_{1}, \xi_{0}\right) \boldsymbol{g}_{\xi_{0}}\left(\boldsymbol{y}_{1}\right) d y_{1}=.024$

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$$

Lan and Trost were unable to obtain the above probabilities through integration. Their results are based on simulation.

## Modification

Lan and Trost's Design is modified using our calculus.
Our framework allows to design a procedure with the following characteristics:

- $\alpha=.024$
- power $=.877$ at $\xi=\xi_{1}=.1768$
$\rightarrow N=337$.


## Sample Size Restriction

Our framework also permits specification of the minimum and maximum sample size.

- $n_{1}+\max \left(n_{2}\left(y_{1}\right)\right)=442$
- $n_{1}+\min \left(n_{2}\left(y_{1}\right)\right)=317$

The total sample size for Stages I and II when continuing to Stage II is between $N=317$ and $N \times 1.4=442$.

## Stage I Components

We choose :
$n_{1}=115$ (same as the original design)
$k_{1}=.0405$ (same as the original design)
$\alpha_{1}=.005$

## Stage I Components

We choose :
$n_{1}=115$ (same as the original design)
$k_{1}=.0405$ (same as the original design)
$\alpha_{1}=.005$
Then using our framework we can obtain the two remaining components, $\boldsymbol{\beta}_{1}$ and $\boldsymbol{k}_{2}$.
$\left\{\alpha_{1}=.005, \beta_{1}=.072, n_{1}=115, k_{1}=.0405, k_{2}=.2406\right\}$

## Stage II Components

We choose :

$$
A\left(y_{1}, \xi_{0}\right)=.02+6.93\left(y_{1}-k_{1}\right)^{2}
$$

$$
\text { This satisfies } \alpha_{2}=.020=\int_{k_{1}}^{k_{2}} A\left(y_{1}, \xi_{0}\right) g_{\xi_{0}}\left(y_{1}\right) d y_{1}
$$

$A\left(y_{1}, \xi_{1}\right)=.925$
This satisfies $\rho_{2}=.602=\int_{k_{1}}^{k_{2}} \boldsymbol{A}\left(y_{1}, \xi_{1}\right) \boldsymbol{g}_{\xi_{1}}\left(y_{1}\right) d y_{1}$.
$\underline{A\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}\right) \text { and sample size }}$

## Stage II Components

## We choose :

$$
A\left(y_{1}, \xi_{0}\right)=.02+6.93\left(y_{1}-k_{1}\right)^{2}
$$

The same as before

$$
A\left(y_{1}, \xi_{1}\right)=.89+2.4\left(y_{1}-k_{1}\right)^{2}
$$

$\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}\right)$ and sample size

## Stage II Components

Our framework allows modification of the sample size function directly so that it does not exceed the maximum and it does not increase.

Sample size

## Stage II Components

Our framework allows modification of the sample size function directly so that it does not exceed the maximum and it does not increase.

Sample size
We keep $A\left(y_{1}, \xi_{0}\right)=.02+6.93\left(y_{1}-k_{1}\right)^{2}$ unchanged.
Then with this new $n_{2}\left(y_{1}\right)$ function, $A\left(y_{1}, \xi_{1}\right)$ and $w\left(y_{1}\right)$ are modified.
$\underline{A\left(y_{1}, \xi\right)}$

## Comparison of the Two Designs

| the Original Lan and Trost's Design |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stage I <br> $\mu$ |  |  |  |  |  |
| Accept | Continue | Reject | Reject | Power | $n_{1}+E\left[n_{2}\left(Y_{1}\right)\right]$ |  |
| 0.00 | .668 | .332 | 0 | .024 | .024 | 397.4 |
| 0.25 | .484 | .516 | 0 | .178 | .178 | 476.6 |
| 0.50 | .304 | .696 | 0 | .457 | .457 | 501.1 |
| 0.75 | .162 | .838 | 0 | .706 | .706 | 468.7 |
| 1.00 | .072 | .928 | 0 | .877 | .877 | 407.7 |
| 1.25 | .026 | .974 | 0 | .961 | .961 | 350.8 |

the Modified Design

|  | Stage I |  |  | Stage II |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mu$ | Accept | Continue | Reject | Reject | Power | $n_{1}+E\left[n_{2}\left(Y_{1}\right)\right]$ |
| 0.00 | .668 | .327 | .005 | .019 | .024 | 208.1 |
| 0.25 | .484 | .498 | .018 | .103 | .121 | 251.6 |
| 0.50 | .304 | .645 | .051 | .308 | .359 | 284.4 |
| 0.75 | .162 | .715 | .123 | .542 | .665 | 294.3 |
| 1.00 | .072 | .681 | .247 | .630 | .877 | 278.0 |
| 1.25 | .026 | .557 | .417 | .548 | .965 | 242.7 |

## Significant Design Parameters

We conducted a computational experiment to see which design components have significant influence on the characteristics of the resulting design.

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What enabled us to conduct this study is our ability to place many two-stage adaptive procedures under one formulation indexed by the following design parameters:

## Design Parameters

- $\alpha_{1}$
- $\boldsymbol{\beta}_{1}$
- $f$, the ratio of $n_{1}$ to $N$
- $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \xi_{0}\right)$
- $A\left(y_{1}, \xi_{1}\right)$

Also various $\sigma$ 's are included in the study.

## Performance Characteristics

Different combinations of the design parameters yield designs with different performance characteristics (power and expected sample sizes).

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A design parameter that demonstrates relatively substantial variability in the "response surface" is considered influential and thus important.

## Summary of the Results

- $\alpha_{1}, \beta_{1}, f, f \times \alpha_{1}$ and $f \times \beta_{1}$ explain most of variation in power and expected sample sizes.


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- $\alpha_{1}, \beta_{1}, f, f \times \alpha_{1}$ and $f \times \beta_{1}$ explain most of variation in power and expected sample sizes.
- A small $\alpha_{1}$ and a large $\beta_{1}$ seem to perform well.


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- A small $\alpha_{1}$ and a large $\beta_{1}$ seem to perform well.
- When $f$ is large, there are very small differences in the performance characteristics for different choices of $\alpha_{1}$ and $\beta_{1}$.


## Summary of the Results

- $\alpha_{1}, \beta_{1}, f, f \times \alpha_{1}$ and $f \times \beta_{1}$ explain most of variation in power and expected sample sizes.
- A small $\alpha_{1}$ and a large $\beta_{1}$ seem to perform well.
- When $f$ is large, there are very small differences in the performance characteristics for different choices of $\alpha_{1}$ and $\beta_{1}$.
- $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}_{0}\right)$ and $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}_{1}\right)$ are both insignificant.


## Summary of the Results

- $\alpha_{1}, \beta_{1}, f, f \times \alpha_{1}$ and $f \times \beta_{1}$ explain most of variation in power and expected sample sizes.
- A small $\alpha_{1}$ and a large $\beta_{1}$ seem to perform well.
- When $f$ is large, there are very small differences in the performance characteristics for different choices of $\alpha_{1}$ and $\beta_{1}$.
- $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \xi_{0}\right)$ and $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \xi_{1}\right)$ are both insignificant.

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## Summary

Our calculus for two-stage adaptive procedures

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- Comparison of designs to assess the importance of each specification component on the resulting design


## Extensions

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## Future Research

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## Group Sequential Procedures

A two-stage group sequential procedure can be placed under the same formulation using our calculus by noticing :

- The Stage II sample size, $\boldsymbol{n}_{2}$, does not vary with $\boldsymbol{y}_{1}$.


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Jennison and Turnbull (1999) give the Stage I and II critical values in terms of $Z$.

## Specification Components

- Stage I
$\left\{n_{1}, k_{1}, k_{2}\right\}$
- Stage II

$$
\left\{n_{2}\left(y_{1}\right), w\left(y_{1}\right)\right\}
$$

## Example

Suppose that $\mu_{0}=0, \mu_{1}=1, \sigma=4, \alpha=.05, \beta=.10$.

- For Stage I, $n_{1}=143, z_{a}=.2298$ and $z_{b}=2.343$.
- For Stage II, $n_{2}=143$ and $z_{c}=1.657$.


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- For Stage I, $n_{1}=143, k_{1}=.0192, k_{2}=.1959$.
- For Stage II, $n_{2}=143, w\left(y_{1}\right)=.1960-y_{1}$.


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- For Stage II, $n_{2}=143, w\left(y_{1}\right)=.1960-y_{1}$.
$\underline{A\left(y_{1}, \xi_{0}\right), A\left(y_{1}, \xi_{1}\right) \text { for Group Sequential Procedure }}$


## $C P$



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## Total Sample Size



## Flowchart

## Stage I

Sample size $=\boldsymbol{n}_{\mathbf{1}}$

|  |  |  |  | $\boldsymbol{k}_{\mathbf{2}}$ |
| :---: | :---: | :---: | :---: | :---: |
| Accept $\boldsymbol{H}_{0}$ |  |  |  |  |
| Stop | Continue to | Reject $\boldsymbol{H}_{\mathbf{0}}$ |  |  |
| $====$ | Stage II | Stop |  |  |
|  | $\Downarrow$ |  |  |  |
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|  |  |  |  |  |

Stage II
Sample size $=\boldsymbol{n}_{\mathbf{2}}\left(\boldsymbol{y}_{1}\right)$
$\boldsymbol{w}\left(\boldsymbol{y}_{1}\right)$
Accept $\boldsymbol{H}_{\mathbf{0}}$
Reject $\boldsymbol{H}_{\mathbf{0}}$

## Lan and Trosts's $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{y}_{1}\right)$



## Lan and Trosts's $\boldsymbol{A}\left(\boldsymbol{y}_{1}, \boldsymbol{\xi}\right)$



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## Total Sample Size



## $A\left(y_{1}, \xi\right)$



## $n_{1}+n_{2}\left(y_{1}\right)$



## $A\left(y_{1}, \xi\right)$



## $n_{1}+n_{2}\left(y_{1}\right)$



## $n_{1}+n_{2}\left(y_{1}\right)$



## $n_{1}+n_{2}\left(y_{1}\right)$



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