

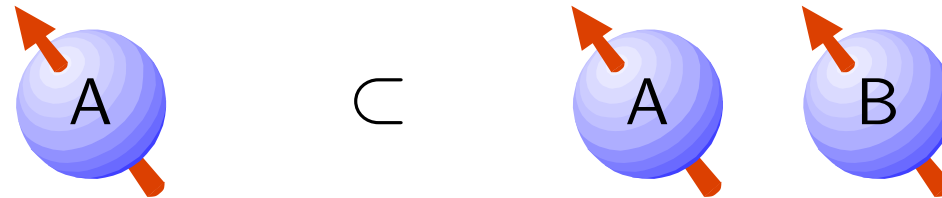
Quantum Error Correction I

Protecting Quantum Information

Manny

- Qubits are subsystems.
 - Error control methods.
 - Algebraic error models.
 - Error detection.
 - Error correction.
 - Stabilizer codes.
-

One of Two Qubits



- State spaces:

$$\alpha|0\rangle_A + \beta|1\rangle_B$$

$\mathcal{Q}$

$\subseteq$

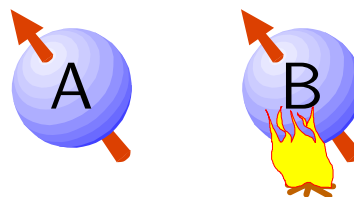
$$\alpha|00\rangle_{AB} + \beta|01\rangle_{AB} + \gamma|10\rangle_{AB} + \delta|11\rangle_{AB}$$

$\mathcal{Q} \otimes \mathcal{Q}$

- Observable algebras:

$$\sigma_x^{(A)}, \sigma_y^{(A)}, \sigma_z^{(A)}, \dots \quad \subset \quad \sigma_x^{(A)}, \dots, \sigma_x^{(B)}, \dots, \sigma_x^{(A)} \sigma_x^{(B)}, \dots$$

Passive Error Control



- Example noise operators:

$$\mathbb{I}, \sigma_x^{(B)}, \sigma_y^{(B)}, \sigma_z^{(B)}.$$

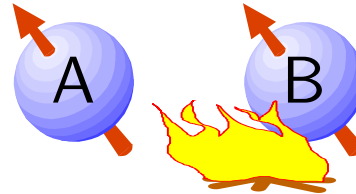
- Information in A is protected.
- No state of AB is protected.

$$|00\rangle_{AB} \xrightarrow{\sigma_x^{(B)}} |01\rangle_{AB}$$

- Observables for A *commute* with errors.

$$\sigma_u^{(A)} \sigma_v^{(B)} = \sigma_v^{(B)} \sigma_u^{(A)}.$$

Active Error Control



- Example noise operators:

$$\mathbb{I}, \text{ **cxnot** } = \sigma_x^{(B)} \text{cnot}^{(BA)}.$$

- Start with B in $|0\rangle_B$.

$$|0\rangle_L = |00\rangle_{AB}, \quad |1\rangle_L = |10\rangle_{AB}$$

- Information of A preserved after one error.
- ... lost after two.

$$|0\rangle_L \xrightarrow{\text{ **cxnot** }} |01\rangle_{AB} \xrightarrow{\text{ **cxnot** }} |10\rangle_{AB} = |1\rangle_L$$

- Solution: Reset B before errors.

Error Control Methods

- Passive error control.
 - Noiseless subsystems.
- Error suppression.
 - Refocusing.
 - Active symmetry enforcement.
 - Decoupling.
 - Reservoir engineering.
- Systematic error control.
 - Rotating frames.
 - Composite pulses.
 - Adiabatic gates.
- Active error control.
 - Periodic error correction.

References

- Prehistory:
 - Quantum Zeno effect: Misra&Sudarshan 1977 [14].
 - Deutsch 1993, Barenco&al. 1996 [3].
- Discovery and Theory:
 - Shor 1995 [17], Steane 1995 [19].
 - Bennett&DiVincenzo&Smolin&Wootters 1996 [4], Knill&Laflamme 1996 [10].
 - Calderbank&Shor 1996 [6], Gottesman 1996 [7], Calderbank&Rains&Shor&Sloane 1997 [5].
- Fault tolerance and threshold accuracies:
 - Shor 1996 [18], Kitaev 1997 [9].
 - Aharonov&Ben-Or 1996 [1, 2], Knill&Laflamme&Zurek 1996 [12], Gottesman&Preskill 1997 [8, 16].
- Toward subsystems:
 - Quasi-particles . . .
 - Zanardi&Rasetti 1997 [23], Lidar&Chuang&Whaley 1998 [13].
 - Viola&Knill&Lloyd 1998 [21, 20, 22].
 - Knill&Laflamme 1996 [10], Knill&Laflamme&Viola 2000 [11].

General reference: (M)ike, Ch. 10.

Nielsen&Chuang 2001 [15]

The Pauli Error Model



- Error operators:

$$\mathcal{E}_1 = \{ \mathbb{I}, \sigma_x^{(1)}, \sigma_y^{(1)}, \sigma_z^{(1)}, \sigma_x^{(2)}, \sigma_y^{(2)}, \dots \}$$

- Weight 2 error operators:

$$\begin{aligned} \mathcal{E}_2 &= \mathcal{E}_1 \mathcal{E}_1 \\ &= \{ \mathbb{I}, \sigma_x^{(1)}, \dots, \sigma_x^{(1)} \sigma_x^{(2)}, \sigma_x^{(1)} \sigma_x^{(3)}, \dots \} \end{aligned}$$

- Higher weights:

$$\begin{aligned} \mathcal{E}_k &= \mathcal{E}_1^k = \overbrace{\mathcal{E}_1 \mathcal{E}_1 \dots}^{k \text{ times}} \\ \mathcal{E} &= \bigcup_{k=1}^{\infty} \mathcal{E}_k \end{aligned}$$

- The linear span of $\mathcal{E}$ contains all operators.

Algebraic Error Models

- Weight 1 error events:

$$\mathcal{E}_1 = \{ \mathbb{I}, E_1, E_2, \dots \}$$

- Weight k error events:

$$\mathcal{E}_k = \mathcal{E}_1^k = \overbrace{\mathcal{E}_1 \mathcal{E}_1 \dots}^{k \text{ times}}$$

- Error algebra:

$$\mathcal{E} = \text{span} \bigcup_{k=1}^{\infty} \mathcal{E}_k$$

Flip Errors

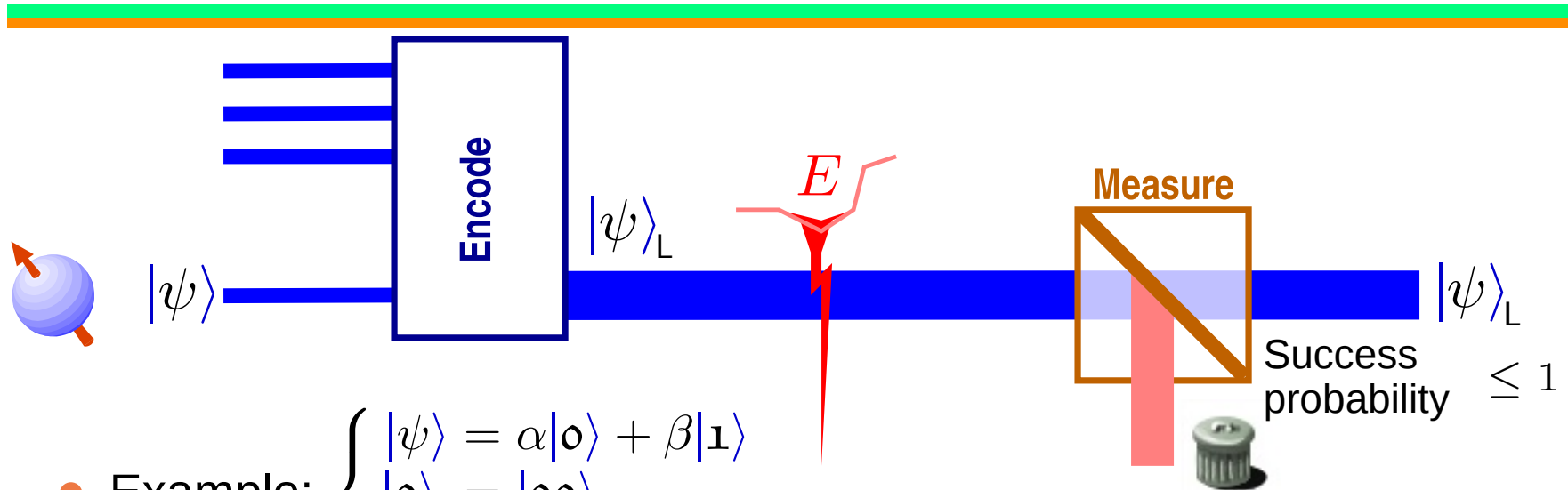
$$\mathcal{E}_1 = \left\{ \mathbb{I}, \sigma_x^{(1)}, \sigma_x^{(2)}, \sigma_x^{(3)}, \dots \right\}$$

- Classical errors + superposition principle.
 - Examples.

$$\begin{array}{ccc}
 |0010\rangle & \xrightarrow{\sigma_x^{(2)}} & |0\mathbf{1}10\rangle \\
 |0010\rangle & \xrightarrow{\sigma_x^{(1)}\sigma_x^{(3)}} & |\mathbf{1}0\mathbf{0}0\rangle \\
 \frac{1}{\sqrt{2}}(|0010\rangle + |0011\rangle) & \xrightarrow{\sigma_x^{(4)}} & \frac{1}{\sqrt{2}}(|001\mathbf{1}\rangle + |001\mathbf{0}\rangle) \\
 & = & \frac{1}{\sqrt{2}}(|0010\rangle + |0011\rangle)
 \end{array}$$

- Size of common eigenspaces of $\sigma_x^{(i)}$?

Error Detection I



• Example:
$$\begin{cases} |\psi\rangle = \alpha|0\rangle + \beta|1\rangle \\ |0\rangle_L = |00\rangle \\ |1\rangle_L = |11\rangle \end{cases}$$

$$\begin{aligned} & \alpha|00\rangle + \beta|11\rangle \\ & \xrightarrow{\mathbb{I}^{(12)}} \alpha|00\rangle + \beta|11\rangle \\ & \xrightarrow{\sigma_x^{(1)}} \alpha|10\rangle + \beta|01\rangle \\ & \xrightarrow{\sigma_x^{(2)}} \alpha|01\rangle + \beta|10\rangle \\ & \xrightarrow{\sigma_x^{(1)}\sigma_x^{(2)}} \alpha|11\rangle + \beta|00\rangle \end{aligned}$$

Error Detection II

- A *quantum code* is a subspace $\mathcal{C}$.
 - Projection operator: $P_{\mathcal{C}}$.
 - Logical basis: $|0\rangle_L, |1\rangle_L, |2\rangle_L, \dots$
- $\mathcal{C}$ detects E if

$$P_{\mathcal{C}} E P_{\mathcal{C}} = \lambda_E P_{\mathcal{C}}$$

- Equivalently:

$$E = \begin{pmatrix} \overbrace{\begin{matrix} \lambda_E & 0 & \dots & 0 \\ 0 & \lambda_E & & \vdots \\ \vdots & & \ddots & \\ 0 & & \dots & \lambda_E \end{matrix}}^c & E_{12} \\ E_{21} & E_{22} \end{pmatrix}$$

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- Equivalently: For all $|\phi\rangle_L$

$$\langle \phi | E | \phi \rangle_L = \lambda_E$$

- Equivalently: For all $|\phi\rangle_L, |\psi\rangle_L$

$$|\phi\rangle_L \perp |\psi\rangle_L \Rightarrow E |\phi\rangle_L \perp |\psi\rangle_L$$

Minimum Distance I

- $\mathcal{C}$ has *minimum distance* $\geq d$ if
 $\mathcal{C}$ detects all errors of weight $d - 1$.
- $\mathcal{C} = \text{span}(|00\rangle, |11\rangle)$ is a $[[2, 1, 2]]_{\sigma_x^{(i)}}$ code.
- $\mathcal{C}$ is a $[[n, k, d]]_{\mathcal{E}_1}$ code means:
 - *Length* n : Total number of qubits is n .
 - k encoded qubits, $\dim \mathcal{C} = 2^k$.
 - Minimum distance at least d for $\mathcal{E}_1$.

Minimum Distance II

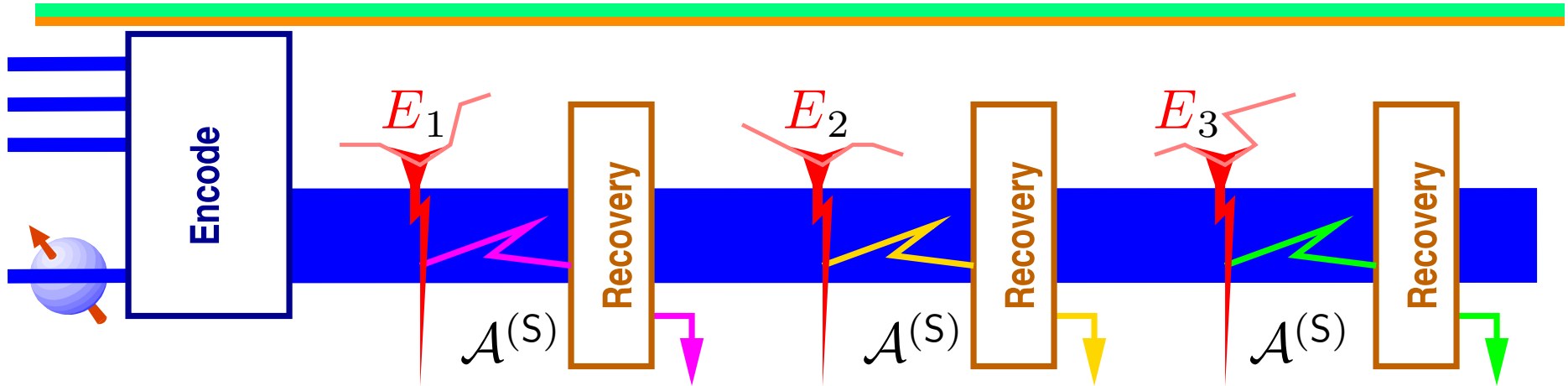
- Construct a $[[3, 1, 3]]_{\sigma_x(i)}$ code — greedily:

- Add: $|0\rangle_L = |000\rangle$.
- $|1\rangle_L$ must be orthogonal to

$$\begin{array}{c} |000\rangle \\ |100\rangle, |010\rangle, |001\rangle \\ |110\rangle, |101\rangle, |011\rangle \end{array}$$

- Choose $|1\rangle_L = |111\rangle$.
- Encode $\alpha|0\rangle + \beta|1\rangle \rightarrow \alpha|000\rangle + \beta|111\rangle$.
- ... the three bit repetition code.

Error Correction Process



- Where is the encoded qubit?
 - Observable algebra always defined:

$$\mathcal{A}_t = \text{span}(\mathbb{I}^{(S_t)}, \sigma_x^{(S_t)}, \sigma_y^{(S_t)}, \sigma_z^{(S_t)})$$
 - $\mathcal{A}^{(S)}$: Algebra between errors and recovery.

Subsystems



- A *subsystem* is a factor of a subspace of $\mathcal{H}$.
- Specifying a subsystem S :
 - Decompose: $\mathcal{H} \simeq (\mathcal{S} \otimes \mathcal{T}) \oplus \mathcal{R}$
 - Observables: $\ast$ -algebra $\mathcal{A}^{(S)} \simeq \text{Matrices}(\dim \mathcal{S})$.
- Example with two qubits:

– Decompose:

$$\begin{aligned} |0\rangle_S |0\rangle_T &= \frac{1}{\sqrt{2}} (|00\rangle + |11\rangle), & |0\rangle_S |1\rangle_T &= \frac{1}{\sqrt{2}} (|00\rangle - |11\rangle) \\ |1\rangle_S |0\rangle_T &= \frac{1}{\sqrt{2}} (|01\rangle + |10\rangle), & |1\rangle_S |1\rangle_T &= \frac{1}{\sqrt{2}} (|01\rangle - |10\rangle) \end{aligned}$$

– Observables: $\begin{cases} \sigma_x^{(S)} &= \sigma_x^{(2)} \\ \sigma_z^{(S)} &= \sigma_z^{(1)} \sigma_z^{(2)} \end{cases}$

Noiseless subsystems

- Subsystem S is *noiseless* for $\mathcal{E}$ if $[\mathcal{E}, \mathcal{A}^{(S)}] = 0$.

- $\mathcal{E} = \text{span}(\mathbb{I}, \sigma_x^{(1)}\sigma_x^{(2)}, \sigma_z^{(1)})$:

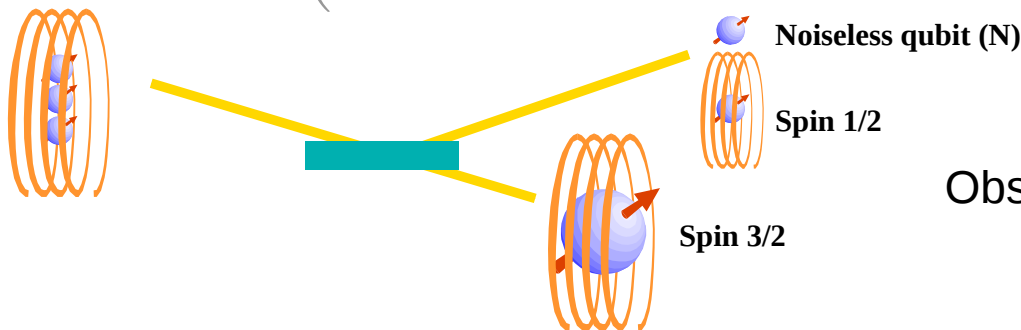
- Observables: $\begin{cases} \sigma_x^{(S)} = \sigma_x^{(2)} \\ \sigma_z^{(S)} = \sigma_z^{(1)}\sigma_z^{(2)} \end{cases}$

- Decompose:

$$|0\rangle_S |0\rangle_T = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle), \quad |0\rangle_S |1\rangle_T = \frac{1}{\sqrt{2}}(|00\rangle - |11\rangle)$$

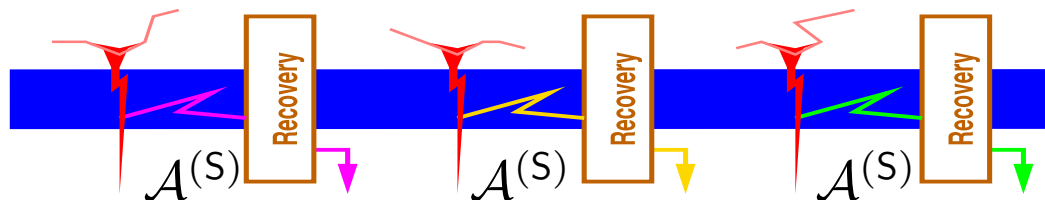
$$|1\rangle_S |0\rangle_T = \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle), \quad |1\rangle_S |1\rangle_T = \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle)$$

- $\mathcal{E} = \text{span}(\mathbb{I}, \sigma_x^{(1)} + \sigma_x^{(2)} + \sigma_x^{(3)}, \sigma_y^{(1)} + \sigma_y^{(2)} + \sigma_y^{(3)}, \sigma_z^{(1)} + \sigma_z^{(2)} + \sigma_z^{(3)})$:



$$\text{Observables: } \begin{cases} \sigma_U^{(N)} = \sigma^{(A)} \cdot \sigma^{(B)} \\ \sigma_V^{(N)} = \sigma^{(A)} \cdot \sigma^{(C)} \end{cases}$$

Error Correcting Subsystems I



- Protection requires:

$$[ER, \mathcal{A}^{(S)}] = 0 \quad R: \text{Any operator of the recovery.}$$

- Error correcting subsystem $(S, |0\rangle_T)$:

$$\mathcal{H} \simeq (\mathcal{S} \otimes \mathcal{T}) \oplus \mathcal{R}, \quad |0\rangle_T$$

- Usage: 1. Reject R . 2. Reset T to $|0\rangle_T$. 3. Wait . . .

- $(S, |0\rangle_T)$ corrects E if

$$E|\psi\rangle_S|0\rangle_T = |\psi\rangle_S|\phi_E\rangle_T$$

Example.

Error Correcting Subsystems II

- The three qubit $[[3, 1, 3]]_{\sigma_x^{(i)}}$ repetition code.

$$\mathcal{C} = \text{span}(|000\rangle, |111\rangle)$$

- As a subsystem:

$$|0\rangle_S |0\rangle_T = |000\rangle \quad |1\rangle_S |0\rangle_T = |111\rangle$$

$$|0\rangle_S |1\rangle_T = |\textcolor{red}{1}00\rangle \quad |1\rangle_S |1\rangle_T = |\textcolor{red}{0}11\rangle$$

$$|0\rangle_S |2\rangle_T = |0\textcolor{red}{1}0\rangle \quad |1\rangle_S |2\rangle_T = |1\textcolor{red}{0}1\rangle$$

$$|0\rangle_S |3\rangle_T = |00\textcolor{red}{1}\rangle \quad |1\rangle_S |3\rangle_T = |11\textcolor{red}{0}\rangle$$

- Detection property:

$$P_{\mathcal{C}} \sigma_x^{(i)\dagger} \sigma_x^{(j)} P_{\mathcal{C}} = \delta_{ij} P_{\mathcal{C}}$$

$$P_{\mathcal{C}} = |0\rangle_T^\top \langle 0|$$

From Correction to Detection

- Suppose $(S, |0\rangle_T)$ corrects errors in $\mathcal{E}$.

Define $\mathcal{C}$ by $P_{\mathcal{C}} = |0\rangle_T \langle 0|$.

Then $\mathcal{C}$ detects every error in $\mathcal{E}^\dagger \mathcal{E}$.

- Proof:

$$\begin{aligned}
 {}^S\langle\psi| {}^T\langle 0| \mathcal{E}^\dagger \mathcal{D} |0\rangle_T |\psi\rangle_S &= {}^S\langle\psi| {}^T\langle 0| \mathcal{E}^\dagger |\phi(\mathcal{D})\rangle_T |\psi\rangle_S \\
 &= {}^S\langle\psi| {}^T\langle \phi(\mathcal{E})| |\phi(\mathcal{D})\rangle_T |\psi\rangle_S \\
 &= {}^S\langle\psi||\psi\rangle_S {}^T\langle \phi(\mathcal{E})||\phi(\mathcal{D})\rangle_T \\
 &= {}^T\langle \phi(\mathcal{E})||\phi(\mathcal{D})\rangle_T \\
 &= \lambda_{\mathcal{E}^\dagger \mathcal{D}}
 \end{aligned}$$

From Detection to Correction

- Suppose $\mathcal{C}$ detects errors in $\mathcal{E}^\dagger \mathcal{E}$.
There exists $(S, |0\rangle_T)$ such that for some unitary U :

$$U^\dagger P_{\mathcal{C}} U = |0\rangle_T^\top \langle 0|$$

$(S, |0\rangle_T)$ corrects $\text{span}(\mathcal{E}U)$.

- Proof:

- $\text{span}(\mathcal{E}) = \text{span}(E_0, E_1, \dots)$.
- $P_{\mathcal{C}} E_i^\dagger E_j P_{\mathcal{C}} = \lambda_{ij} P_{\mathcal{C}}$.
- $\Lambda = (\lambda_{ij})_{ij}$ Hermitian $\Rightarrow$ change basis of $\text{span}(\mathcal{E})$:
 $\lambda_{ij} = \delta_{ij}$.
- Let $|\psi\rangle_L$ be a state of $\mathcal{C}$. Define
 $|\psi\rangle_S |i\rangle_T = E_i |\psi\rangle_L$
- Choose U unitary: $U |\psi\rangle_S |0\rangle_T = |\psi\rangle_L$.
- Compute: $E_i U |\psi\rangle_S |0\rangle_T = E_i |\psi\rangle_L = |\psi\rangle_S |i\rangle_T$

QEC Theorems

Theorem: Given a quantum system. There exists an error-correcting subsystem for $\mathcal{E}$ iff there exists a $\mathcal{E}^\dagger \mathcal{E}$ detecting quantum code.

Corollary: Assume $\mathcal{E}_1^\dagger = \mathcal{E}_1$. If $\mathcal{C}$ has minimum distance $2e + 1$, then $\mathcal{C}$ induces an e -error-correcting subsystem.

- Coding theory lingo: A $[[n, k, 2e + 1]]$ code is e -error correcting.

Stabilizer Codes I

- Conventions:

$$X = \sigma_x, Y = \sigma_y, Z = \sigma_z$$
$$IXIII = \sigma_x^{(2)}, I I Y Z I = \sigma_y^{(3)} \sigma_z^{(4)}$$

- Pauli group*: Products of σ_u up to sign.

- Stabilizer of $\mathcal{C} = \text{span}(|000\rangle, |111\rangle)$:

$$\{III, ZZI, IZZ, ZIZ\} = \langle ZZI, IZZ \rangle$$

- Properties:

$$\begin{array}{ccc} \mathcal{C} & \text{detects} & IXI \\ IXI \cdot ZZI & = & -ZZI \cdot IXI \end{array}$$

Stabilizer Codes II

- A stabilizer code (Pauli code, symplectic code) is a common eigenspace of a commutative subgroup N of the Pauli group.

- Define

$$N^\perp = \{\text{Pauli operators which commute with } N\}.$$

Theorem: A stabilizer code of N detects all Pauli operators except those in $N^\perp \setminus N$.

- Proof: For $\rho \in N$, let $\lambda(\rho)$ be the common eigenvalue.
 - $\sigma \in N$: ok.
 - $\sigma \notin N^\perp$: Choose $\rho \in N$, $\sigma\rho = -\rho\sigma$. For $|\psi\rangle$ in the code:
$$\begin{aligned}\rho|\psi\rangle &= \lambda(\rho)|\psi\rangle \\ \rho\sigma|\psi\rangle &= -\sigma\rho|\psi\rangle \\ &= -\lambda(\rho)\sigma|\psi\rangle \quad \dots \sigma|\psi\rangle \text{ is orthogonal to the code.}\end{aligned}$$

The 5 Qubit Code

- Minimum distance 3 code for Pauli errors:

Stabilizer: $\langle YZZYI, IYZZY, YIYZZ, ZYIYZ \rangle$.

- Example distance check:

- Every weight ≤ 2 Pauli product $UVIII$ is detected:

$$\begin{array}{|c|c|c|c|c|} \hline Y & Z & Z & Y & I \\ \hline I & Y & Z & Z & Y \\ \hline Y & I & Y & Z & Z \\ \hline Z & Y & I & Y & Z \\ \hline \end{array}$$

- Restrict to first two columns:

$\langle YZ, IY, YI, ZY \rangle \dots$ generates all Pauli products.

- $\Rightarrow$ every non-identity $UVIII$ anticommutes with a stabilizer.

- Rules:

$$\begin{array}{llll} X \cdot Y & \sim & Z & 01 \oplus 10 = 11 \\ Y \cdot Z & \sim & X & \Leftrightarrow 10 \oplus 11 = 01 \\ Z \cdot X & \sim & Y & 11 \oplus 01 = 10 \end{array}$$

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